

# Vector Expected Utility and Attitudes towards Variation

Marciano Siniscalchi

Northwestern University

ESSM, Pittsburgh, June 2008

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Einhorn and Hogarth (1985): **Anchoring** and Adjustment as response to ambiguity

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Einhorn and Hogarth (1985): Anchoring and **Adjustment** as response to ambiguity

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = \mathbf{E}_p[u \circ h] + A(\mathbf{E}_p[\zeta_0 \cdot u \circ h], \dots, \mathbf{E}_p[\zeta_{n-1} \cdot u \circ h]).$$

Baseline prior  $p \in \Delta(\Omega)$ : uniquely identified from preferences

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

**Adjustment Factors:** bounded r.v.'s  $\zeta_i$  on  $\Omega$  with  $E_p[\zeta_i] = 0$ .

**Complementarities** among ambiguous events (Epstein and Zhang, 2001). Note  $n \leq \infty$ , finite if  $\Omega$  finite.

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Adjustment function  $A : \mathbb{R}^n \rightarrow \mathbb{R}$ : attitudes towards **variability**, **hedging**. Aversion, appeal, stake-dependence...



## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Adjustments depend upon **variance of  $u \circ h$**  and **correlation with  $\zeta_i$** :

$$E_p[\zeta_i \cdot u \circ h] = \text{Cov}_p[\zeta_i, u \circ h] = \text{Corr}_p[\zeta_i, u \circ h] \cdot \sigma_p(\zeta_i) \cdot \sigma_p(u \circ h).$$

**Utility smoothing, hedging** = variability reduction: key effect in applications of ambiguity-sensitive prefs.

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Cute names: CEU, MEU, PEU, RDEU, SEU, SOSEU, SOCEU,

## Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Cute names: CEU, MEU, PEU, RDEU, SEU, SOSEU, SOCEU, and **VEU**

# Vector Expected Utility: Summary

State space  $\Omega$ . Outcomes  $X$ . Acts  $h : \Omega \rightarrow X$ . Utility  $u : X \rightarrow \mathbb{R}$ .

$$V(h) = E_p[u \circ h] + A(E_p[\zeta_0 \cdot u \circ h], \dots, E_p[\zeta_{n-1} \cdot u \circ h]).$$

Main results:

- 1 Behavioral Characterization of VEU preferences
- 2 Characterizing  $p$ ,  $\zeta$ ,  $n$ , ambiguity attitudes
- 3 Updating and Sophisticated choice

# Ellsberg: Ambiguity and Complementarity

**90** balls: **30** red, **60** green or blue.  $\Omega = \{r, g, b\}$ .  $X = \mathbb{R}$ .

	$r$	$g$	$b$
$1_r$	1	0	0
$1_g$	0	1	0
$1_{rb}$	1	0	1
$1_{gb}$	0	1	1

# Ellsberg: Ambiguity and Complementarity

**90** balls: **30** red, **60** green or blue.  $\Omega = \{r, g, b\}$ .  $X = \mathbb{R}$ .

	$r$	$g$	$b$
$1_r$	1	0	0
$1_g$	0	1	0
$1_{rb}$	1	0	1
$1_{gb}$	0	1	1

Modal prefs are  $1_r \succ 1_g$ ,  $1_{rb} \prec 1_{gb}$ : **not EU (or PS)**

# Ellsberg: Ambiguity and Complementarity

**90** balls: **30** red, **60** green or blue.  $\Omega = \{r, g, b\}$ .  $X = \mathbb{R}$ .

	$r$	$g$	$b$
$1_r$	1	0	0
$1_g$	0	1	0
$1_{rb}$	1	0	1
$1_{gb}$	0	1	1

Modal prefs are  $1_r \succ 1_g$ ,  $1_{rb} \prec 1_{gb}$ : **not EU (or PS)**

Epstein and Zhang (2001): “[t]he intuition for this reversal is the **complementarity** between  $g$  and  $b$ —there is imprecision regarding the likelihood of  $g$ , whereas  $\{b, g\}$  has precise probability  $\frac{2}{3}$ ”

# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform



# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform
- Adjustment function:  $A(\varphi) = -|\varphi|$ .

# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform
- Adjustment function:  $A(\varphi) = -|\varphi|$ .
- Adjustment factor:  $n = 1$  random variable  $\zeta : \Omega \rightarrow \mathbb{R}$  with

$$\zeta(r) = 0, \quad \zeta(g) = 1, \quad \zeta(b) = -1.$$

# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform
- Adjustment function:  $A(\varphi) = -|\varphi|$ .
- Adjustment factor:  $n = 1$  random variable  $\zeta : \Omega \rightarrow \mathbb{R}$  with

$$\zeta(r) = 0, \quad \zeta(g) = 1, \quad \zeta(b) = -1.$$

$$V(h) = E_p[u \circ h] + A(E_p[\zeta \cdot u \circ h])$$

# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform
- Adjustment function:  $A(\varphi) = -|\varphi|$ .
- Adjustment factor:  $n = 1$  random variable  $\zeta : \Omega \rightarrow \mathbb{R}$  with

$$\zeta(r) = 0, \quad \zeta(g) = 1, \quad \zeta(b) = -1.$$

$$V(h) = E_p[u \circ h] + A(E_p[\zeta \cdot u \circ h])$$

Then easy to see that:

- $V(1_r) = \frac{1}{3} - |0| = \frac{1}{3}$  and  $V(1_g) = \frac{1}{3} - |\frac{1}{3}| = 0$

# VEU Representation of Complementarities

- Baseline prior:  $p$  uniform
- Adjustment function:  $A(\varphi) = -|\varphi|$ .
- Adjustment factor:  $n = 1$  random variable  $\zeta : \Omega \rightarrow \mathbb{R}$  with

$$\zeta(r) = 0, \quad \zeta(g) = 1, \quad \zeta(b) = -1.$$

$$V(h) = E_p[u \circ h] + A(E_p[\zeta \cdot u \circ h])$$

Then easy to see that:

- $V(1_r) = \frac{1}{3} - |0| = \frac{1}{3}$  and  $V(1_g) = \frac{1}{3} - |\frac{1}{3}| = 0$
- $V(1_{rb}) = \frac{2}{3} - |0 - \frac{1}{3}| = \frac{1}{3}$  and  $V(1_{gb}) = \frac{2}{3} - |\frac{1}{3} - \frac{1}{3}| = \frac{2}{3}$

## Some MEU Examples

- $\Omega = \{\omega_0, \dots, \omega_k\}$ ,  $p \in \Delta(\Omega)$ ,  $u(x) = x$ .

## Some MEU Examples

- $\Omega = \{\omega_0, \dots, \omega_k\}$ ,  $p \in \Delta(\Omega)$ ,  $u(x) = x$ .
- Mean-Std Deviation:

$$V(h) = E_p(h) - \epsilon \sigma_p(h)$$

## Some MEU Examples

- $\Omega = \{\omega_0, \dots, \omega_k\}$ ,  $p \in \Delta(\Omega)$ ,  $u(x) = x$ .
- **Mean-Std Deviation:**

$$V(h) = E_p(h) - \epsilon \sigma_p(h)$$

- **Mean-Gini** (generalizes to arbitrary  $\Omega$ ): for  $\theta \in [0, 1]$ ,

$$V(h) = E_p[h] - \frac{1}{2}\theta \iint |h(\omega) - h(\omega')| p(d\omega') p(d\omega).$$



## Some MEU Examples

- $\Omega = \{\omega_0, \dots, \omega_k\}$ ,  $p \in \Delta(\Omega)$ ,  $u(x) = x$ .
- Mean-Std Deviation:

$$V(h) = E_p(h) - \epsilon \sigma_p(h)$$

- Mean-Gini (generalizes to arbitrary  $\Omega$ ): for  $\theta \in [0, 1]$ ,

$$V(h) = E_p[h] - \frac{1}{2}\theta \iint |h(\omega) - h(\omega')| p(d\omega') p(d\omega).$$

- “Euclidean robustness”:

$$V(h) = \sum_{i=0}^k h(\omega_i) p_i - \epsilon \sqrt{\sum_{i=0}^k \left( h(\omega_i) - \frac{1}{k+1} \sum_{j=0}^k h(\omega_j) \right)^2}.$$

## Some MEU Examples

- $\Omega = \{\omega_0, \dots, \omega_k\}$ ,  $p \in \Delta(\Omega)$ ,  $u(x) = x$ .
- Mean-Std Deviation:

$$V(h) = E_p(h) - \epsilon \sigma_p(h)$$

- Mean-Gini (generalizes to arbitrary  $\Omega$ ): for  $\theta \in [0, 1]$ ,

$$V(h) = E_p[h] - \frac{1}{2}\theta \iint |h(\omega) - h(\omega')| p(d\omega') p(d\omega).$$

- “Euclidean robustness”:

$$V(h) = \sum_{i=0}^k h(\omega_i) p_i - \epsilon \sqrt{\sum_{i=0}^k \left( h(\omega_i) - \frac{1}{k+1} \sum_{j=0}^k h(\omega_j) \right)^2}.$$

### Result:

$$V(h) = \min \left\{ \int h dq : q \in \Delta(\Omega), \sum_i [q(\omega_i) - p(\omega_i)]^2 \leq \epsilon^2 \right\}.$$

## Examples: Ambiguity and Outcome Size (1)

Einhorn-Hogarth (1986); Koch-Schunk (2007): **stakes affect ambiguity attitudes:**

- Ambiguity-**averse** for **large** stakes;
- Ambiguity-**neutral** or **-seeking** for **small** stakes.

Cf. Prelec-Lowenstein (1991), “peanuts effect.”

# Examples: Ambiguity and Outcome Size (1)

Einhorn-Hogarth (1986); Koch-Schunk (2007): stakes affect ambiguity attitudes:

- Ambiguity-averse for large stakes;
- Ambiguity-neutral or -seeking for small stakes.

Cf. Prelec-Lowenstein (1991), “peanuts effect.”

Match this with differentiable VEU prefs.

$\Omega = \{\omega, \omega'\}$ ;  $p$  uniform,  $u$  linear;  $\zeta$  single adjustment function.

Parameter  $t > 1$ .

# Examples: Ambiguity and Outcome Size (1)

Einhorn-Hogarth (1986); Koch-Schunk (2007): stakes affect ambiguity attitudes:

- Ambiguity-averse for large stakes;
- Ambiguity-neutral or -seeking for small stakes.

Cf. Prelec-Lowenstein (1991), “peanuts effect.”

Match this with differentiable VEU prefs.

$\Omega = \{\omega, \omega'\}$ ;  $p$  uniform,  $u$  linear;  $\zeta$  single adjustment function.

Parameter  $t > 1$ .

$$A(\varphi) = \log(1 + t^2) - \frac{1}{2} \log(1 + (\varphi + t)^2) - \frac{1}{2} \log(1 + (\varphi - t)^2).$$

# Examples: Ambiguity and Outcome Size (2)

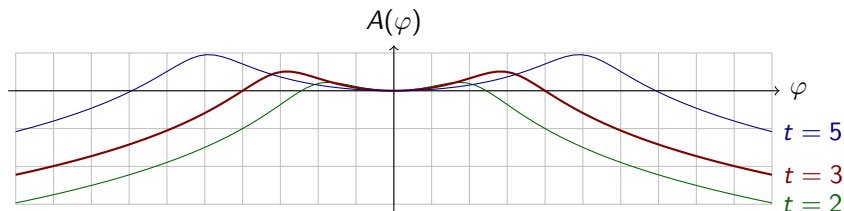


Figure: The Adjustment Function  $A(\varphi)$

# Examples: Ambiguity and Outcome Size (2)

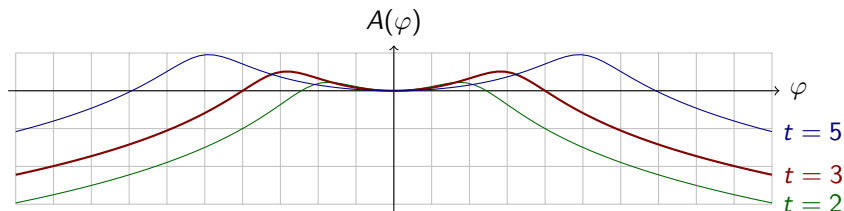


Figure: The Adjustment Function  $A(\varphi)$

- Let  $t = 3$  and  $\zeta(\omega) = -\zeta(\omega') = 0.4$

# Examples: Ambiguity and Outcome Size (2)

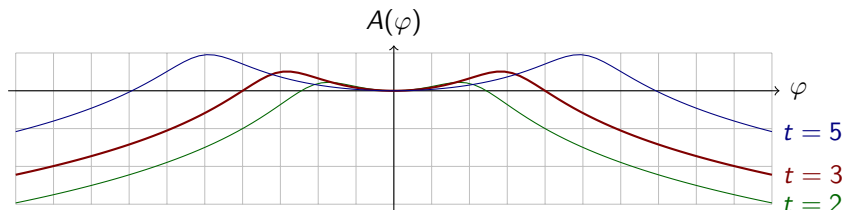


Figure: The Adjustment Function  $A(\varphi)$

- Let  $t = 3$  and  $\zeta(\omega) = -\zeta(\omega') = 0.4$
- **Small bet:**  $f(\omega) = 10, f(\omega') = 0$



# Examples: Ambiguity and Outcome Size (2)

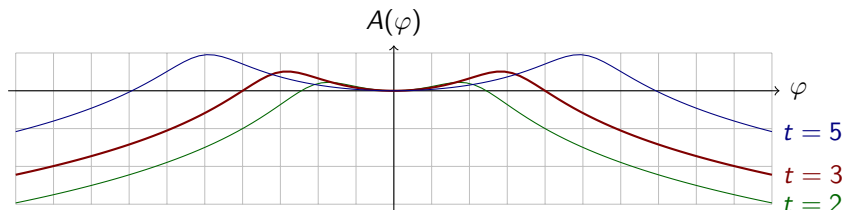


Figure: The Adjustment Function  $A(\varphi)$

- Let  $t = 3$  and  $\zeta(\omega) = -\zeta(\omega') = 0.4$
- Small bet:  $f(\omega) = 10, f(\omega') = 0$
- Large bet:  $g(\omega) = 1000, g(\omega') = 0$

## Examples: Ambiguity and Outcome Size (2)

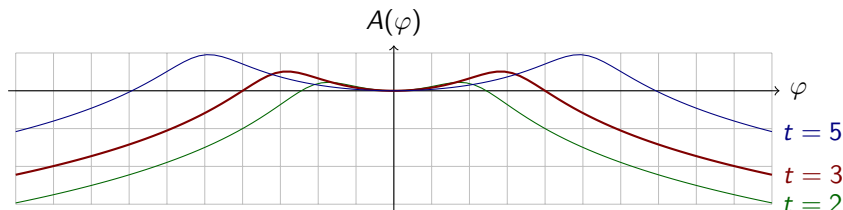


Figure: The Adjustment Function  $A(\varphi)$

- Let  $t = 3$  and  $\zeta(\omega) = -\zeta(\omega') = 0.4$
- **Small bet:**  $f(\omega) = 10$ ,  $f(\omega') = 0$
- **Large bet:**  $g(\omega) = 1000$ ,  $g(\omega') = 0$
- **Baseline** certainty equivalents:  $\int f dp = 5$  and  $\int g dp = 500$ .

# Examples: Ambiguity and Outcome Size (2)

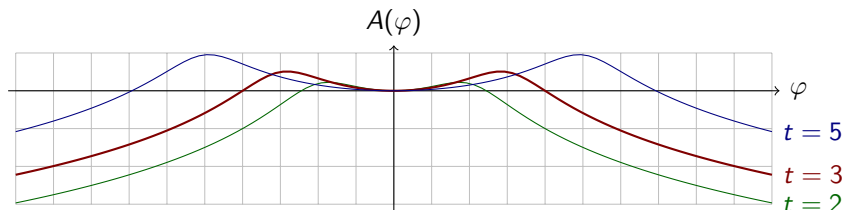


Figure: The Adjustment Function  $A(\varphi)$

- Let  $t = 3$  and  $\zeta(\omega) = -\zeta(\omega') = 0.4$
- **Small bet:**  $f(\omega) = 10$ ,  $f(\omega') = 0$
- **Large bet:**  $g(\omega) = 1000$ ,  $g(\omega') = 0$
- **Baseline** certainty equivalents:  $\int f dp = 5$  and  $\int g dp = 500$ .
- **Actual** certainty equivalents:  $CE[f] = 5.33$ ,  $CE[g] = 471.91$ .

# Axioms and Characterization

Basic axioms: Maccheroni, Marinacci and Rustichini (2006) minus  
Ambiguity Aversion

# Axioms and Characterization

Basic axioms: Maccheroni, Marinacci and Rustichini (2006) minus  
Ambiguity Aversion

Key axiom: Complementary Independence (later)

# Axioms and Characterization

**Basic axioms:** Maccheroni, Marinacci and Rustichini (2006) **minus**  
Ambiguity Aversion

**Key axiom:** Complementary Independence (later)

**Additional axiom:** Complementary Translation Invariance,  
Monotone Continuity.

# Axioms and Characterization

Basic axioms: Maccheroni, Marinacci and Rustichini (2006) minus  
Ambiguity Aversion

Key axiom: Complementary Independence (later)

Additional axiom: Complementary Translation Invariance,  
Monotone Continuity.

## Theorem

*Axioms if and only if representation.*

# Axioms and Characterization

Basic axioms: Maccheroni, Marinacci and Rustichini (2006) minus Ambiguity Aversion

Key axiom: Complementary Independence (later)

Additional axiom: Complementary Translation Invariance, Monotone Continuity.

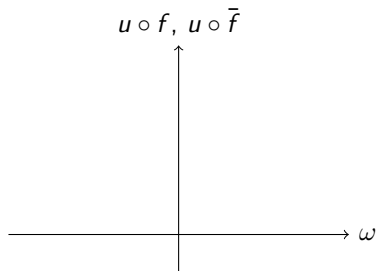
## Theorem

*Axioms if and only if representation.*

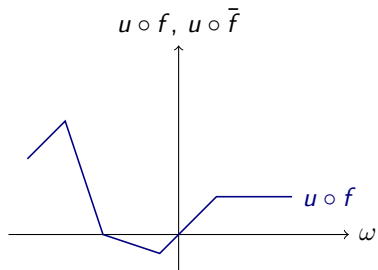
*$p$  unique,  $u$  cardinally unique, minimal  $n$  unique;  $A, \zeta_i$  unique up to linear bijection that preserves adjustments.*



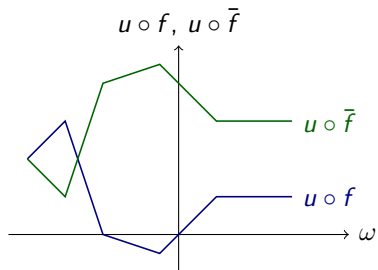
# Complementary Acts



# Complementary Acts

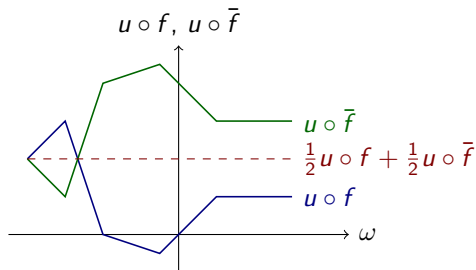


# Complementary Acts



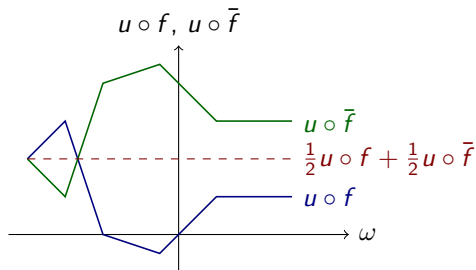
" $\bar{f} = \text{constant} - f$ ". Same "variability"

# Complementary Acts



Therefore,  $\frac{1}{2}f + \frac{1}{2}\bar{f}$  has **constant utility**

# Complementary Acts

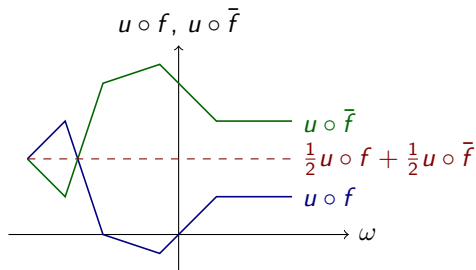


## Definition

Two acts  $f, \bar{f}$  are **complementary** if, for all  $\omega, \omega' \in \Omega$ ,

$$\frac{1}{2}f(\omega) + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}f(\omega') + \frac{1}{2}\bar{f}(\omega').$$

# Complementary Acts



## Definition

Two acts  $f, \bar{f}$  are **complementary** if, for all  $\omega, \omega' \in \Omega$ ,

$$\frac{1}{2}f(\omega) + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}f(\omega') + \frac{1}{2}\bar{f}(\omega').$$

$f, \bar{f}$  and  $g, \bar{g}$  compl.  $\Rightarrow \alpha f + (1 - \alpha)g, \alpha \bar{f} + (1 - \alpha)\bar{g}$  compl.

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .



# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment
- Adjustment depends upon statewise variation around baseline

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment
- Adjustment depends upon statewise variation around baseline
- Complementary acts: same variation, hence same adjustment

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment
- Adjustment depends upon statewise variation around baseline
- Complementary acts: same variation, hence same adjustment
- Therefore prefs driven by baseline evaluations, assumed EU

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment
- Adjustment depends upon statewise variation around baseline
- Complementary acts: same variation, hence same adjustment
- Therefore prefs driven by baseline evaluations, assumed EU
- So, Independence should hold for complementary acts.

# The Key Axiom

## Axiom (Complementary Independence)

If  $f, \bar{f}$  and  $g, \bar{g}$  are complementary pairs and  $f \succcurlyeq \bar{f}$ ,  $g \succcurlyeq \bar{g}$ , then  $\alpha f + (1 - \alpha)g \succcurlyeq \alpha \bar{f} + (1 - \alpha)\bar{g}$  for all  $\alpha \in (0, 1)$ .

- AA Independence  $\Leftrightarrow$  above property for all  $f, \bar{f}, g, \bar{g}$ .
- VEU: rank acts using baseline EU evaluation and adjustment
- Adjustment depends upon statewise variation around baseline
- Complementary acts: same variation, hence same adjustment
- Therefore prefs driven by baseline evaluations, assumed EU
- So, Independence should hold for complementary acts.

Baseline prior has clear behavioral interpretation: yields EU representation of preferences over complementary acts

# Ambiguity Aversion: Classical Definition

Begin with the “classical” notion due to Schmeidler (1989)

## Axiom (Ambiguity Aversion)

For all acts  $f, g \in L_0$  and  $\alpha \in (0, 1)$ :  $f \sim g$  implies  $\alpha f + (1 - \alpha)g \succcurlyeq g$ .

# Ambiguity Aversion: Classical Definition

Begin with the “classical” notion due to Schmeidler (1989)

## Axiom (Ambiguity Aversion)

For all acts  $f, g \in L_0$  and  $\alpha \in (0, 1)$ :  $f \sim g$  implies  $\alpha f + (1 - \alpha)g \succcurlyeq g$ .

## Corollary

$\succcurlyeq$  satisfies Ambiguity Aversion if and only if  $A$  is non-positive and concave.



# Alternative notions of Ambiguity Aversion

GMM's *comparative* definition:

## Definition

$\succsim_1$  is **comparatively ambiguity-averse** iff  $\succsim_2$  conforms to EU and, for all  $f \in L_0$  and  $x \in X$ ,  $f \succsim_1 x$  implies  $f \succsim_2 x$ .

# Alternative notions of Ambiguity Aversion

GMM's *comparative* definition:

## Definition

$\succsim_1$  is **comparatively ambiguity-averse** iff  $\succsim_2$  conforms to EU and, for all  $f \in L_0$  and  $x \in X$ ,  $f \succsim_1 x$  implies  $f \succsim_2 x$ .

Two more quasiconcavity axioms:

## Axiom (Simple Ambiguity Aversion)

For all complementary pairs  $(f, \bar{f})$  and prizes  $x, \bar{x} \in X$  such that  $f \sim x$  and  $\bar{f} \sim \bar{x}$ :  $\frac{1}{2}f + \frac{1}{2}\bar{f} \succsim \frac{1}{2}x + \frac{1}{2}\bar{x}$ .

# Alternative notions of Ambiguity Aversion

GMM's *comparative* definition:

## Definition

$\succsim_1$  is **comparatively ambiguity-averse** iff  $\succsim_2$  conforms to EU and, for all  $f \in L_0$  and  $x \in X$ ,  $f \succsim_1 x$  implies  $f \succsim_2 x$ .

Two more quasiconcavity axioms:

## Axiom (Simple Ambiguity Aversion)

For all complementary pairs  $(f, \bar{f})$  and prizes  $x, \bar{x} \in X$  such that  $f \sim x$  and  $\bar{f} \sim \bar{x}$ :  $\frac{1}{2}f + \frac{1}{2}\bar{f} \succsim \frac{1}{2}x + \frac{1}{2}\bar{x}$ .

## Axiom (Minimal Ambiguity Aversion)

For all complementary pairs  $(f, \bar{f})$  with  $f \sim \bar{f}$ ,  $\frac{1}{2}f + \frac{1}{2}\bar{f} \succsim f$ .

# Ambiguity Aversion: Further Characterization

## Proposition

Let  $\succsim$  be a preference with VEU representation  $(u, p, n, m, A)$ .  
Then the following are equivalent:

- 1  $\succsim$  is *comparatively ambiguity-averse*.
- 2  $\succsim$  *satisfies Simple Ambiguity Aversion*.
- 3  $A \leq 0$ .

If  $u(X)$  is *unbounded* above or below, or if  $\succsim$  satisfies *C-Independence*, then 1–3 are equivalent to

- 4  $\succsim$  *satisfies Minimal Ambiguity Aversion*.

# Updating VEU Preferences: Overview

Behaviorally based updating rule for VEU prefs.

# Updating VEU Preferences: Overview

Behaviorally based updating rule for VEU prefs.

Bayesian updating for  $p$ . But how about adjustments  $\zeta$ ?

# Updating VEU Preferences: Overview

Behaviorally based updating rule for VEU prefs.

Bayesian updating for  $p$ . But how about adjustments  $\zeta$ ?

**Idea:** from  $E_p[u \circ h] + A(\text{Cov}_p[\zeta \cdot u \circ h])...$

...to  $E_p[u \circ h|E] + A(p(E) \cdot \text{Cov}_p[\zeta \cdot u \circ h|E])$

where  $p(E)$  in  $A(\cdot)$  ensures monotonicity.

# Updating VEU Preferences: Overview

Behaviorally based updating rule for VEU prefs.

Bayesian updating for  $p$ . But how about adjustments  $\zeta$ ?

**Idea:** from  $\mathbb{E}_p[u \circ h] + A(\text{Cov}_p[\zeta \cdot u \circ h]) \dots$

...to  $\mathbb{E}_p[u \circ h|E] + A(p(E) \cdot \text{Cov}_p[\zeta \cdot u \circ h|E])$

where  $p(E)$  in  $A(\cdot)$  ensures monotonicity.

“Rescaling and recentering”

$$\zeta_E = p(E) \cdot [\zeta - \mathbb{E}_p[\zeta|E]].$$



# Updating VEU Preferences: Overview

Behaviorally based updating rule for VEU prefs.

Bayesian updating for  $p$ . But how about adjustments  $\zeta$ ?

**Idea:** from  $\mathbb{E}_p[u \circ h] + A(\text{Cov}_p[\zeta \cdot u \circ h]) \dots$

...to  $\mathbb{E}_p[u \circ h|E] + A(p(E) \cdot \text{Cov}_p[\zeta \cdot u \circ h|E])$

where  $p(E)$  in  $A(\cdot)$  ensures monotonicity.

“Rescaling and recentering”

$$\zeta_E = p(E) \cdot [\zeta - \mathbb{E}_p[\zeta|E]].$$

Facilitates recursive analysis of sophisticated choice.

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated
  - Variability on  $\Omega \setminus E$  no longer matters.

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated
  - Variability on  $\Omega \setminus E$  no longer matters.
- Conversely, expect **no change** for acts that have:
  - Same baseline EU evaluation ex-ante and given  $E$

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated
  - Variability on  $\Omega \setminus E$  no longer matters.
- Conversely, expect **no change** for acts that have:
  - Same baseline EU evaluation ex-ante and given  $E$
  - No variation away from baseline outside  $E$ .

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated
  - Variability on  $\Omega \setminus E$  no longer matters.
- Conversely, expect **no change** for acts that have:
  - Same baseline EU evaluation ex-ante and given  $E$
  - No variation away from baseline outside  $E$ .
- **Axiom requires this.** Thus, need to characterize such acts.

# Baseline-Variation Consistency: Intuition

- VEU: ex-ante and  $E$ -contingent evaluation of act  $h$  may change because:
  - The baseline EU evaluation is updated
  - Variability on  $\Omega \setminus E$  no longer matters.
- Conversely, expect **no change** for acts that have:
  - Same baseline EU evaluation ex-ante and given  $E$
  - No variation away from baseline outside  $E$ .
- **Axiom requires this.** Thus, need to characterize such acts.
- **Key idea:** if  $h, \bar{h}$  complementary, constant on  $\Omega \setminus E$ , and

$$\forall \omega \in \Omega \setminus E, \quad \frac{1}{2}h + \frac{1}{2}\bar{h}(\omega) \sim \frac{1}{2}\bar{h} + \frac{1}{2}h(\omega)$$

then  $u(h(\omega)) = \mathbb{E}_p[u \circ h] = \mathbb{E}_p[u \circ h|E]$  for  $\omega \in \Omega \setminus E$



# Baseline-Variation Consistency

## Axiom (Baseline-Variation Consistency)

For all complementary pairs  $(f, \bar{f})$  and  $(g, \bar{g})$  such that:

- $f, \bar{f}, g, \bar{g}$  are constant on  $\Omega \setminus E$

# Baseline-Variation Consistency

## Axiom (Baseline-Variation Consistency)

For all complementary pairs  $(f, \bar{f})$  and  $(g, \bar{g})$  such that:

- $f, \bar{f}, g, \bar{g}$  are constant on  $\Omega \setminus E$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}f + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}\bar{f} + \frac{1}{2}f(\omega)$

# Baseline-Variation Consistency

## Axiom (Baseline-Variation Consistency)

For all complementary pairs  $(f, \bar{f})$  and  $(g, \bar{g})$  such that:

- $f, \bar{f}, g, \bar{g}$  are constant on  $\Omega \setminus E$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}f + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}\bar{f} + \frac{1}{2}f(\omega)$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}g + \frac{1}{2}\bar{g}(\omega) \sim \frac{1}{2}\bar{g} + \frac{1}{2}g(\omega)$ :

# Baseline-Variation Consistency

## Axiom (Baseline-Variation Consistency)

For all complementary pairs  $(f, \bar{f})$  and  $(g, \bar{g})$  such that:

- $f, \bar{f}, g, \bar{g}$  are constant on  $\Omega \setminus E$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}f + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}\bar{f} + \frac{1}{2}f(\omega)$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}g + \frac{1}{2}\bar{g}(\omega) \sim \frac{1}{2}\bar{g} + \frac{1}{2}g(\omega)$ :

$f \succcurlyeq_E g$  if and only if  $f \succcurlyeq g$ .

# Baseline-Variation Consistency

## Axiom (Baseline-Variation Consistency)

For all complementary pairs  $(f, \bar{f})$  and  $(g, \bar{g})$  such that:

- $f, \bar{f}, g, \bar{g}$  are constant on  $\Omega \setminus E$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}f + \frac{1}{2}\bar{f}(\omega) \sim \frac{1}{2}\bar{f} + \frac{1}{2}f(\omega)$
- for every  $\omega \in \Omega \setminus E$ ,  $\frac{1}{2}g + \frac{1}{2}\bar{g}(\omega) \sim \frac{1}{2}\bar{g} + \frac{1}{2}g(\omega)$ :

$f \succcurlyeq_E g$  if and only if  $f \succcurlyeq g$ .

## Proposition

*Bayesian updating plus “Rescaling and recentering” if and only if axioms hold.*

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .



# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .
- $U(c_t, c_{t+1}) = u(c_t) + \beta \{E_p[u(c_{t+1})] + A(E_p[\zeta_{t+1} u(c_{t+1})])\}$ :

$$m = \frac{\beta u'(c_{t+1}) [1 + \zeta_{t+1} A'(E_p[\zeta_{t+1} u(c_{t+1})])]}{u'(c_t)}$$

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .
- $U(c_t, c_{t+1}) = u(c_t) + \beta \{E_p[u(c_{t+1})] + A(E_p[\zeta_{t+1} u(c_{t+1})])\}$ :

$$m = \frac{\beta u'(c_{t+1}) [1 + \zeta_{t+1} A'(E_p[\zeta_{t+1} u(c_{t+1})])]}{u'(c_t)}$$

- HJ bounds: slope of efficient frontier  $\frac{\sigma(m)}{E_p[m]}$ .

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .
- $U(c_t, c_{t+1}) = u(c_t) + \beta \{ E_p[u(c_{t+1})] + A(E_p[\zeta_{t+1} u(c_{t+1})]) \}$ :

$$m = \frac{\beta u'(c_{t+1}) [1 + \zeta_{t+1} A'(E_p[\zeta_{t+1} u(c_{t+1})])]}{u'(c_t)}$$

- HJ bounds: slope of efficient frontier  $\frac{\sigma(m)}{E_p[m]}$ .
- Power utility  $u'(c) = c^{-\gamma}$ ,  $\ln c_{t+1} - \ln c_t \sim N(\mu, \sigma^2)$ .  
Puzzle: slope  $\approx 0.50$ , requires  $\gamma \approx 50$ ; also,  $r_f$  too high.

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .
- $U(c_t, c_{t+1}) = u(c_t) + \beta \{ E_p[u(c_{t+1})] + A(E_p[\zeta_{t+1} u(c_{t+1})]) \}$ :

$$m = \frac{\beta u'(c_{t+1}) [1 + \zeta_{t+1} A'(E_p[\zeta_{t+1} u(c_{t+1})])]}{u'(c_t)}$$

- HJ bounds: slope of efficient frontier  $\frac{\sigma(m)}{E_p[m]}$ .
- Power utility  $u'(c) = c^{-\gamma}$ ,  $\ln c_{t+1} - \ln c_t \sim N(\mu, \sigma^2)$ .  
Puzzle: slope  $\approx 0.50$ , requires  $\gamma \approx 50$ ; also,  $r_f$  too high.
- $\zeta_{t+1} = \text{sign}(\ln c_{t+1} - \ln c_t)$ ,  $A(\varphi) = -\theta|\varphi|$ .

# One-Slide Analysis of the Equity Premium Puzzle

- $\max_{\xi} U(c_t, c_{t+1})$  s. to  $c_t = e_t - p_t \xi$ ,  $c_{t+1} = e_{t+1} + \xi x_{t+1}$ .
- **Stochastic Discount Factor:**  $p_t = E[m x_{t+1}]$
- $U(c_t, c_{t+1}) = u(c_t) + \beta E_p[u(c_{t+1})]$ ,  $m = \frac{\beta u'(c_{t+1})}{u'(c_t)}$ .
- $U(c_t, c_{t+1}) = u(c_t) + \beta \{E_p[u(c_{t+1})] + A(E_p[\zeta_{t+1} u(c_{t+1})])\}$ :

$$m = \frac{\beta u'(c_{t+1}) [1 + \zeta_{t+1} A'(E_p[\zeta_{t+1} u(c_{t+1})])]}{u'(c_t)}$$

- HJ bounds: slope of efficient frontier  $\frac{\sigma(m)}{E_p[m]}$ .
- Power utility  $u'(c) = c^{-\gamma}$ ,  $\ln c_{t+1} - \ln c_t \sim N(\mu, \sigma^2)$ .  
Puzzle: slope  $\approx 0.50$ , requires  $\gamma \approx 50$ ; also,  $r_f$  too high.
- $\zeta_{t+1} = \text{sign}(\ln c_{t+1} - \ln c_t)$ ,  $A(\varphi) = -\theta|\varphi|$ .
- With VEU, can fit with  $\theta = 0.5$ ,  $\gamma = 2$ , and better  $r_f$ , too.