

Polarimetric Phased Array Beamforming and Calibration

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Goals of Polarimetric Beamforming

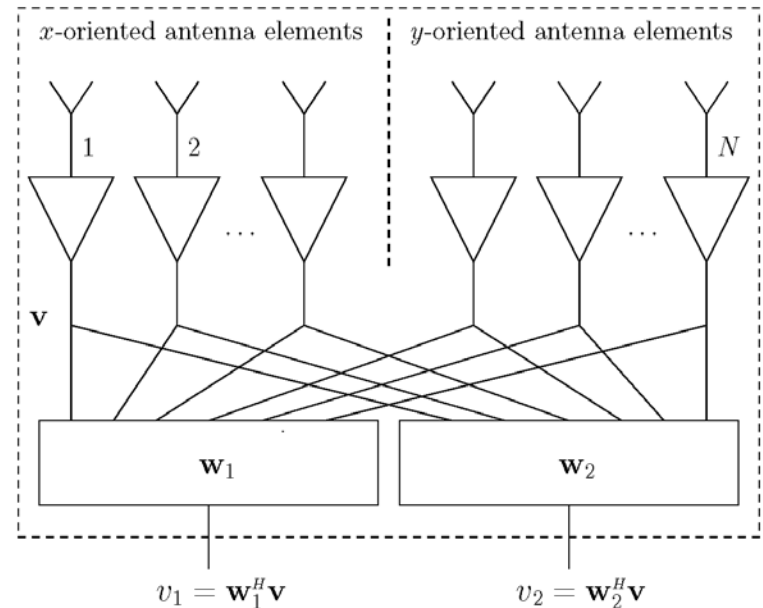
- Polarization purity, accurate determination of Stokes parameters
 - Good XPD, XPI, axial ratio
- Low and/or stable cross-pol response pattern
- High sensitivity
- Practical calibration scheme (time)

Problems I and II

- I. Modeling: What are the optimal beamformer weights for an exactly known polarimetric phased array system?
- II. Experimental: How to estimate the optimal beamformer weight pair using sky sources?

$$\overline{\mathbf{E}}(\mathbf{r}, t) = E_u(\mathbf{r}, t)\hat{u} + E_v(\mathbf{r}, t)\hat{v}$$

(Rob Maaskant)



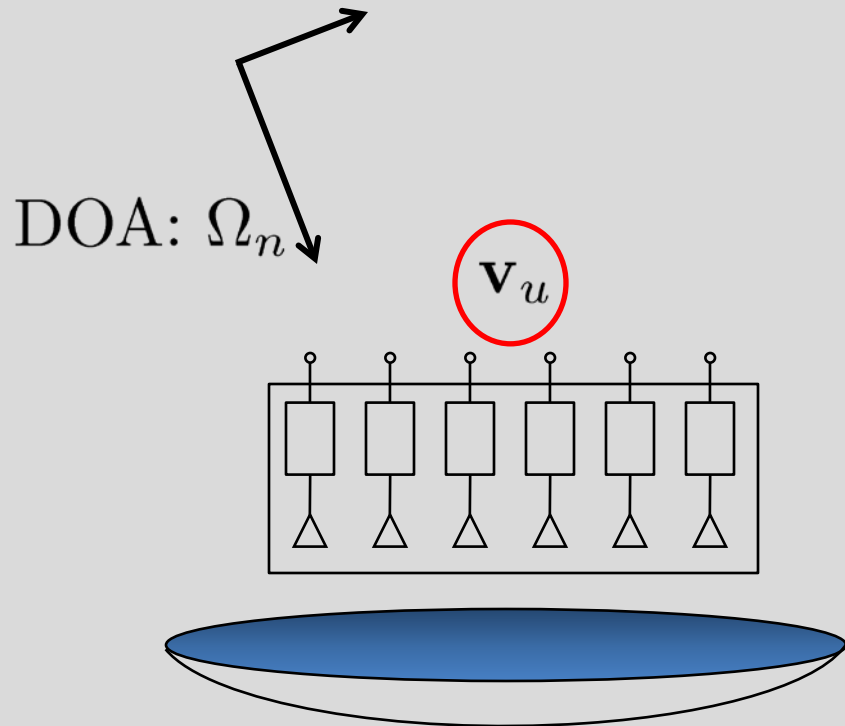
Incident field: $\overline{\mathbf{E}}(\mathbf{r}, t) = E_u(\mathbf{r}, t)\hat{u} + E_v(\mathbf{r}, t)\hat{v}$

Coherency matrix: $\mathbf{R}_{\overline{\mathbf{E}}} = \begin{bmatrix} R_{uu} & R_{uv} \\ R_{vu} & R_{vv} \end{bmatrix} = \begin{bmatrix} \langle |E_u|^2 \rangle & \langle E_u E_v^* \rangle \\ \langle E_u^* E_v \rangle & \langle |E_v|^2 \rangle \end{bmatrix}$

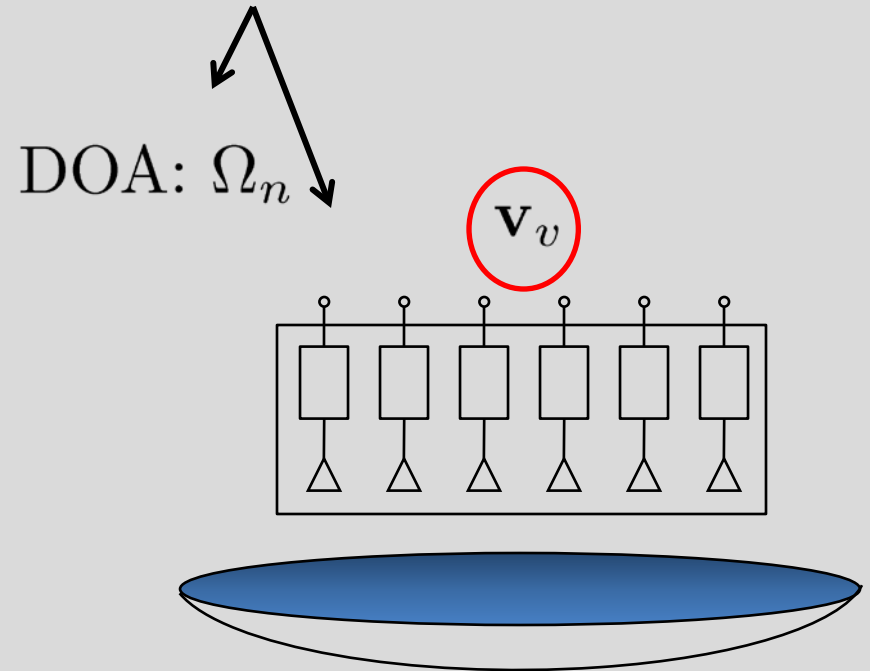
Stokes parameters: $\mathbf{S} = \begin{bmatrix} I \\ Q \\ U \\ V \end{bmatrix} = \begin{bmatrix} \langle |E_u|^2 \rangle + \langle |E_v|^2 \rangle \\ \langle |E_u|^2 \rangle - \langle |E_v|^2 \rangle \\ 2 \operatorname{Re} \langle E_u E_v^* \rangle \\ 2 \operatorname{Im} \langle E_u E_v^* \rangle \end{bmatrix}$

Known PAF responses for two orthogonal, linearly polarized waves:

$$\overline{E}(\mathbf{r}) = E_u(\mathbf{r})\hat{u}$$

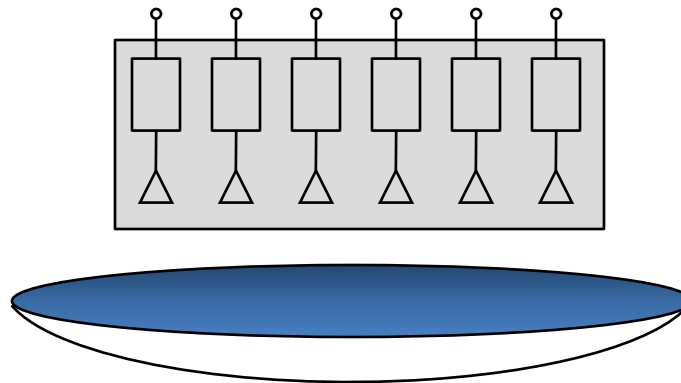
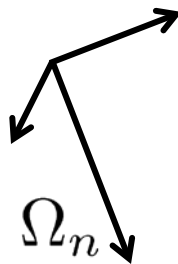


$$\overline{E}(\mathbf{r}) = E_v(\mathbf{r})\hat{v}$$



$$\bar{E}(\mathbf{r}, t) = E_u(\mathbf{r}, t)\hat{u} + E_v(\mathbf{r}, t)\hat{v}$$

DOA: Ω_n



Array Response for an Arbitrary Pol. State

$$\mathbf{R}_{\bar{E}} = \begin{bmatrix} R_{uu} & R_{uv} \\ R_{vu} & R_{vv} \end{bmatrix} = \begin{bmatrix} \langle |E_u|^2 \rangle & \langle E_u E_v^* \rangle \\ \langle E_u^* E_v \rangle & \langle |E_v|^2 \rangle \end{bmatrix}$$

$$\begin{aligned} \mathbf{R}_{\text{sig}} &= \langle \mathbf{v} \mathbf{v}^H \rangle \\ &= \mathbf{v}_u \mathbf{v}_u^H R_{\bar{E},uu} + \mathbf{v}_u \mathbf{v}_v^H R_{\bar{E},uv} + \mathbf{v}_v \mathbf{v}_u^H R_{\bar{E},vu}^* + \mathbf{v}_v \mathbf{v}_v^H R_{\bar{E},vv} \\ &= \begin{bmatrix} \mathbf{v}_u & \mathbf{v}_v \end{bmatrix} \mathbf{R}_{\bar{E}} \begin{bmatrix} \mathbf{v}_u^H \\ \mathbf{v}_v^H \end{bmatrix} \end{aligned}$$

$$= \mathbf{V} \mathbf{R}_{\bar{E}} \mathbf{V}^H$$

Beam pair outputs:

$$v_1 = \mathbf{w}_1^H \mathbf{v}$$
$$v_2 = \mathbf{w}_2^H \mathbf{v}$$

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix} \begin{bmatrix} E_u \\ E_v \end{bmatrix}$$

$$\begin{aligned}\mathbf{J} &= \begin{bmatrix} \mathbf{w}_1^H \mathbf{v}_u & \mathbf{w}_1^H \mathbf{v}_v \\ \mathbf{w}_2^H \mathbf{v}_u & \mathbf{w}_2^H \mathbf{v}_v \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{w}_1^H \\ \mathbf{w}_2^H \end{bmatrix} \begin{bmatrix} \mathbf{v}_u & \mathbf{v}_v \end{bmatrix}\end{aligned}$$

$$= \mathbf{W}^H \mathbf{V}$$

$$\begin{aligned}\mathbf{R}_p &= \left\langle \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \begin{bmatrix} v_1^* & v_2^* \end{bmatrix} \right\rangle \\ &= \begin{bmatrix} \langle |v_1|^2 \rangle & \langle v_1 v_2^* \rangle \\ \langle v_1^* v_2 \rangle & \langle |v_2|^2 \rangle \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{w}_1^H \mathbf{R}_{\text{sig}} \mathbf{w}_1 & \mathbf{w}_1^H \mathbf{R}_{\text{sig}} \mathbf{w}_2 \\ \mathbf{w}_2^H \mathbf{R}_{\text{sig}} \mathbf{w}_1 & \mathbf{w}_2^H \mathbf{R}_{\text{sig}} \mathbf{w}_2 \end{bmatrix}\end{aligned}$$

$$= \mathbf{J} \mathbf{R}_{\bar{E}} \mathbf{J}^H$$

$$\mathbf{S}_{\text{out}} = \mathbf{M}\mathbf{S}_{\text{in}}$$

$$\mathbf{S}_{\text{in}} = \mathbf{T} \text{vec} \left(\mathbf{R}_{\mathbf{E}}^* \right)$$

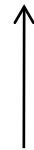
$$= \begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 0 \\ 0 & -j & j & 0 \end{bmatrix} \begin{bmatrix} \langle |E_u|^2 \rangle \\ \langle E_u E_v^* \rangle \\ \langle E_u^* E_v \rangle \\ \langle |E_v|^2 \rangle \end{bmatrix}$$

$$\mathbf{S}_{\text{out}} = \mathbf{T} \text{vec} \left(\mathbf{R}_p^* \right)$$

$$\mathbf{M} = \mathbf{T}(\mathbf{J} \otimes \mathbf{J}^*)\mathbf{T}^{-1}$$

$$\mathbf{R}_p = \mathbf{R}_{p,\text{sig}} + \mathbf{R}_{p,\text{n}} \quad (2 \times 2 \text{ Matrices})$$

$$= \mathbf{W}^H \mathbf{V} \mathbf{R}_{\bar{E}} \mathbf{V}^H \mathbf{W} + \mathbf{W}^H \mathbf{R}_n \mathbf{W}$$



Array system signal
voltage response

$$\mathbf{V}(\Omega)$$

$$2 \times N$$



Array system noise
correlation matrix

$$N \times N$$

- Goals:

- Find beamformer weight pair for which Jones matrix is the identity
- Simultaneously minimize system noise

(1) $\mathbf{J} = \mathbf{I}$

(2) Minimize $\mathbf{W}^H \mathbf{R}_n \mathbf{W}$

$$\operatorname{argmin}_{\mathbf{W}} \mathbf{W}^H \mathbf{R}_n \mathbf{W}, \text{ subject to } \mathbf{W}^H \mathbf{V} = \mathbf{I}$$

- Matrix of Lagrange multipliers...
- Take derivatives, set to zero...
- Use the constraint to find the Lagrange multipliers...

$$\mathbf{W} = \underbrace{\mathbf{R}_n^{-1} \mathbf{V}}_{\text{Max-sensitivity beamformer}} \underbrace{(\mathbf{V}^H \mathbf{R}_n^{-1} \mathbf{V})^{-1}}_{\text{2 x 2 optimal polarimetric calibration matrix}}$$

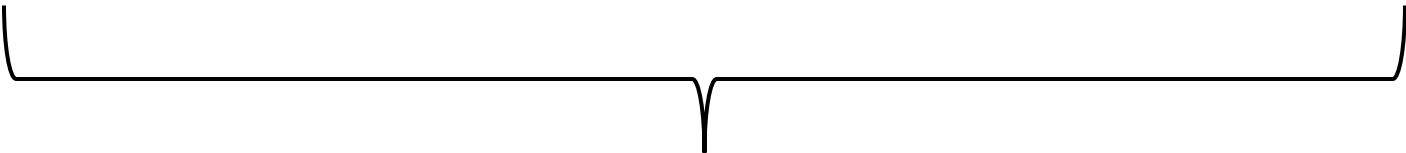
Max-sensitivity
beamformer

2 x 2 optimal polarimetric
calibration matrix

- Numerically, this solution works nicely
- Sensitivity is essentially equal to that of max sensitivity beamformer, but cross-pol response is zero (Jones matrix is the identity)
- Solves Problem I

- In practice, the responses to two orthogonal, linearly polarized waves is not available

- What is available?
 - Array response (output correlation matrix) for unpolarized sources
 - Array response for partially polarized sources
 - Array response for calibrator signals
 - Modeled responses for linearly polarized sources
 - Two sets of nominally orthogonally polarized elements



Use this to find weight vectors as close to the optimal solution as possible, without taking up too much observing time

Rank 2 Subspace Approach (Bruce Veidt)

$$\begin{aligned} \mathbf{R}_{\text{sig}} &= \mathbf{v}_u \mathbf{v}_u^H R_{\overline{E},uu} + \mathbf{v}_u \mathbf{v}_v^H R_{\overline{E},uv} + \mathbf{v}_v \mathbf{v}_u^H R_{\overline{E},vu}^* + \mathbf{v}_v \mathbf{v}_v^H R_{\overline{E},vv} \\ &= \begin{bmatrix} \mathbf{v}_u & \mathbf{v}_v \end{bmatrix} \mathbf{R}_{\overline{E}} \begin{bmatrix} \mathbf{v}_u^H \\ \mathbf{v}_v^H \end{bmatrix} \\ &\quad \uparrow \\ &\quad 2 \times 2 \text{ Matrix} \end{aligned}$$

- General form for a rank 2 matrix
- Two principal eigenvectors
- Span polarization subspace for the given DOA
- Use principle eigenvectors as CFM weights, or combine with max-SNR approach:

$$\mathbf{w}_1 = \mathbf{R}_n^{-1} \mathbf{v}_1, \quad \mathbf{w}_2 = \mathbf{R}_n^{-1} \mathbf{v}_2$$

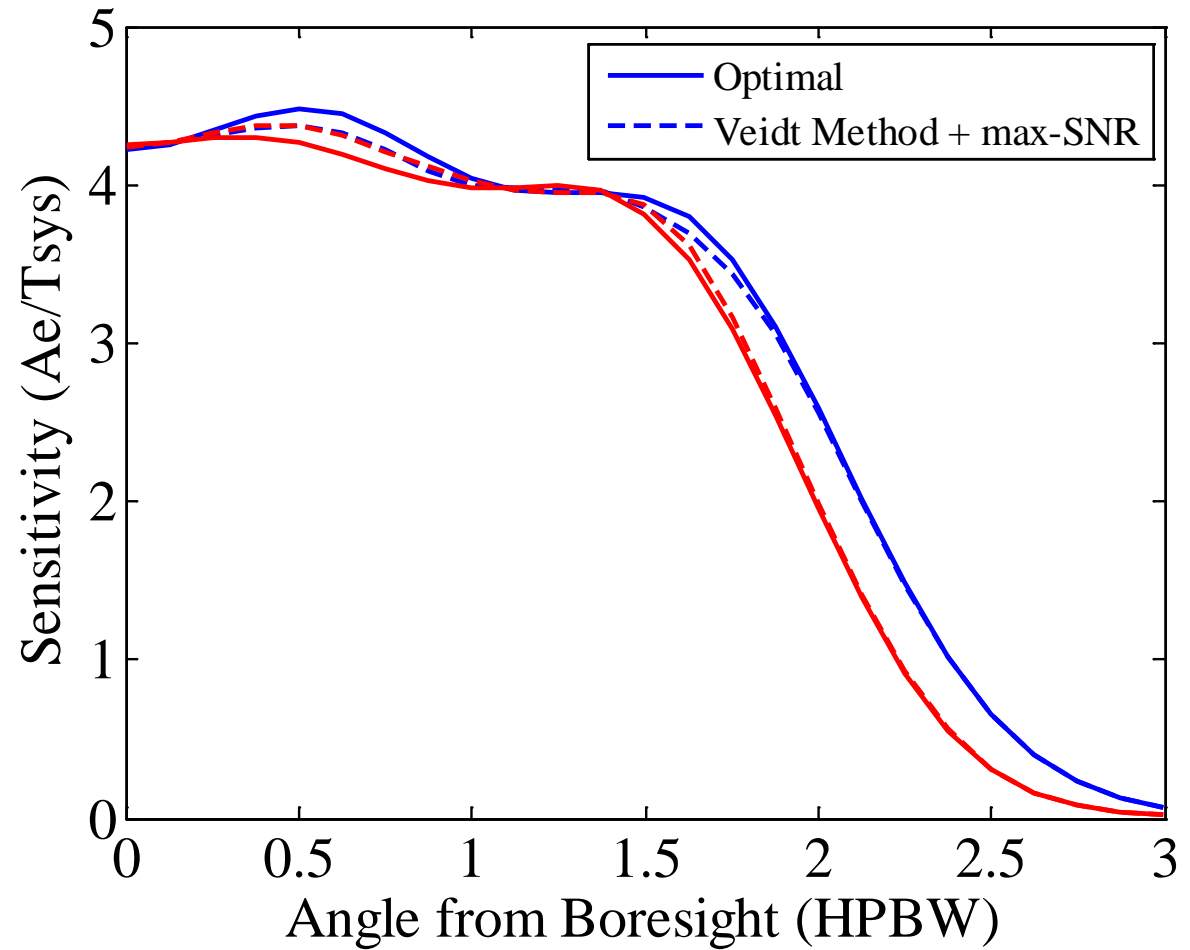
Two possibilities:

$$\mathbf{R}_{\text{sig}} \mathbf{v} = \lambda \mathbf{R}_n^{-1} \mathbf{v} \quad (\text{Generalized eigenproblem})$$

These approaches result in...

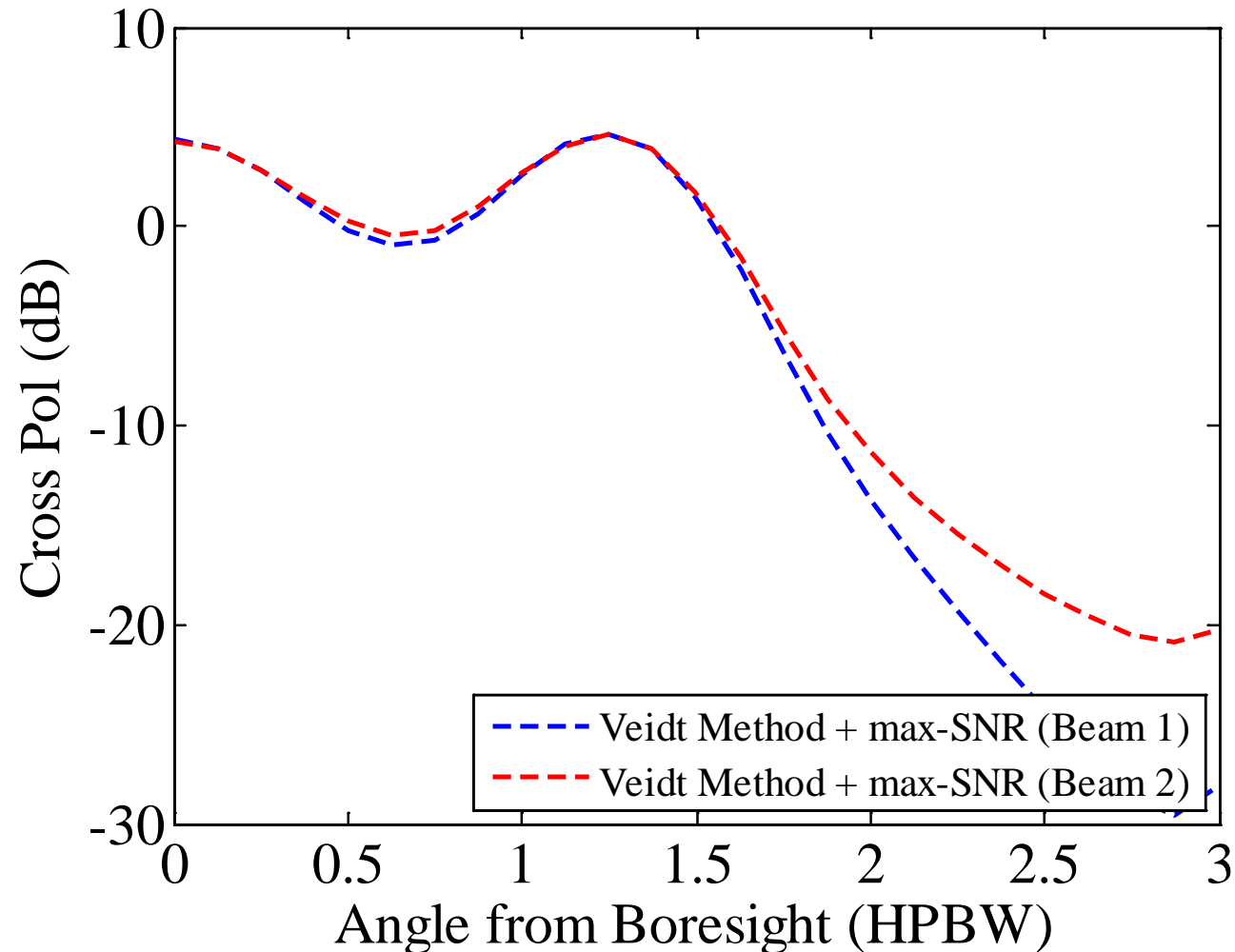
- Beam pair that is not polarization pure
- Calibrate using standard techniques?
 - Requires multiple partially polarized sources, or
 - Long polarized source observation at each beam center, or
 - Interpolation across array (calibrate only a few beams), or
- The beams may be good enough...
 - (Assuming known polrotation)

- 19 x 2 PAF
- 5% polarized cal source



Cross Pol Discrimination

- Cross pol of optimal solution is effectively infinite
- Keep in mind that the optimal solution knows the response of the array to x and y polarized waves, but the Veidt method does not



- We understand Problem I
 - Ideally, PAF beams can be perfectly polarization aligned without sensitivity loss
- Problem II requires further study