



FLUID MODEL OF AN INTERNET ROUTER UNDER THE MIMD CONTROL SCHEME

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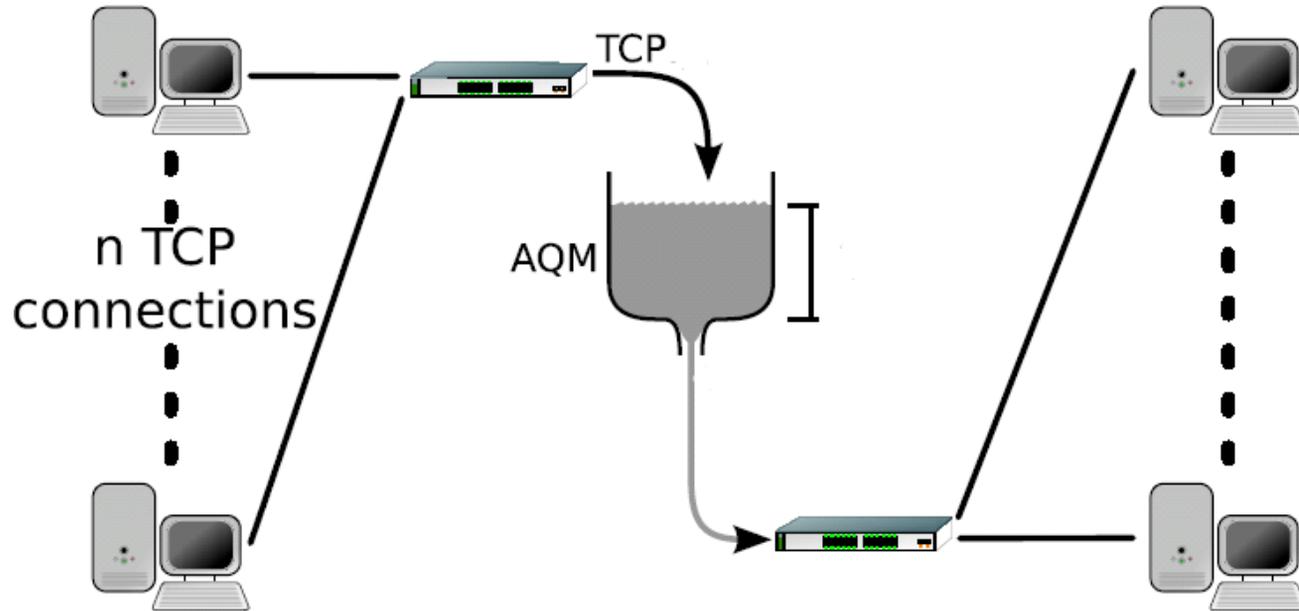
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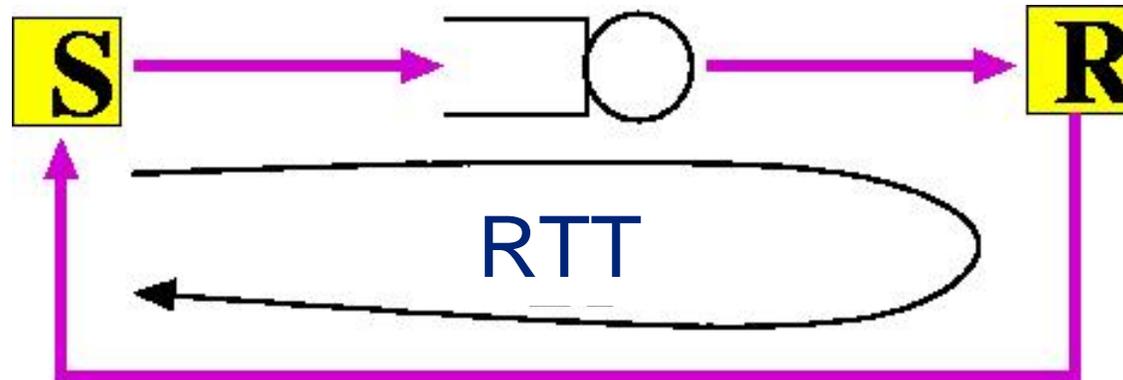
- n TCP connections sharing a bottleneck



- TCP:

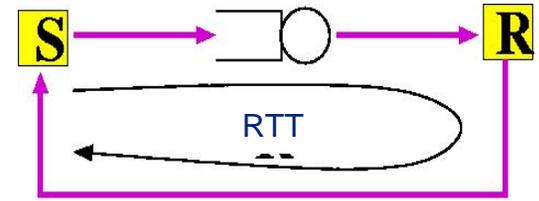
- Distributed Congestion Control algorithm
- The TCP sender detects congestion on the network through the feedback received from the TCP receiver

- The packet sending rate (congestion window) is adapted dynamically
 - Increase in absence of packet losses
 - Decrease upon reception of congestion notification

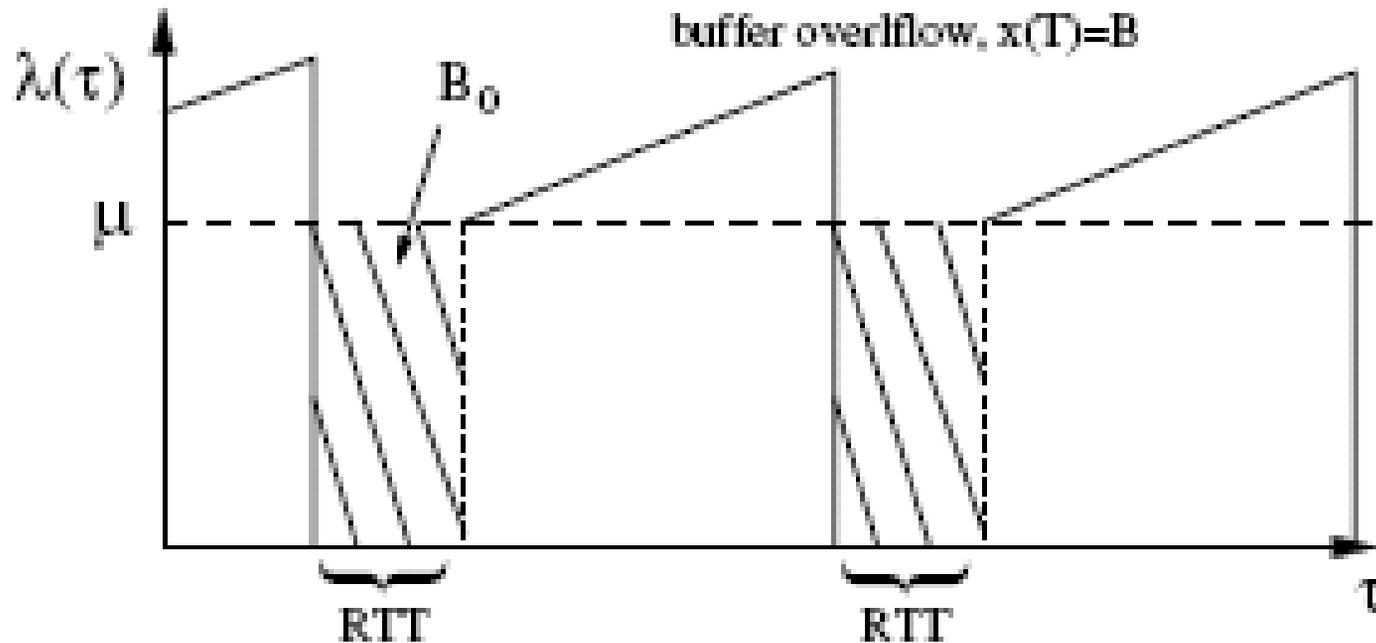


- Current TCP Implementations:
 - AIMD paradigm : The increase is linear in time
 - Problem in fully utilizing the link capacity in the presence of High-Speed links
- The MIMD TCP is one of the possible alternatives
 - MIMD: Exponential Increase in time
 - After a loss, the elapsed time until the congestion window reaches the size before the loss is constant.
 - Scalable TCP is a particular case

Buffer size: BDP rule [VS94]



- One TCP AIMD connection. The minimum buffer size in order to get 100% utilization is $B_0 = RTT \times \mu$.



- Interests in recent years: [AKMcK04] [BHLO03] [DJD05] [W06] [VS07]

Performance criterion

- Maximize throughput: $\bar{\lambda} = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t \lambda(s) ds.$
- Minimize queueing delay: $\bar{x} = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t x(s) ds.$
- Contradictory goals: Example of multicriteria optimization.
We construct the Pareto Set of the unconstrained optimization

$$\max \left\{ \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t c_1 x(s) + c_2 \lambda(s) ds. \right\}$$

- We deal with the optimal impulse control problem of a deterministic system with long-run average optimality criterion.
 - Also, our model can be viewed as a hybrid system.
- In principle, the control policy in our model can depend on $x(t)$ and $\lambda(t)$.
- In practice, however, all currently implemented buffer management schemes send congestion signals based only on the state of the buffer. Thus, we also limit ourselves to this case.
- Furthermore, we assume that one can only control B , the size of the buffer.
- Objective: Determine the buffer size that solves the optimization problem

A fluid model

- Let $\lambda_i(t)$ denote the sending rate of connection i at time t

$$\dot{\lambda}_i(t) = r_i \lambda_i(t)$$

- Assuming the same RTT for all connections

$$\dot{\lambda}(t) = \sum_i \dot{\lambda}_i(t) = r \lambda(t)$$

- Let $x(t)$ denote the queue length at time t . Then

$$\dot{x}(t) = \begin{cases} \lambda(t) - \mu, & \text{if } x(t) > 0, \text{ or if } x(t) = 0 \text{ and } \lambda(t) > \mu, \\ 0, & \text{if } x(t) = 0 \text{ and } \lambda(t) \leq \mu. \end{cases}$$

A Fluid model (cont.)

- When $x(t) = B$ a packet is dropped, and the sending rate of a connection is reduced instantaneously

$$\lambda_i(t + 0) = \beta_0 \lambda_i(t - 0) = \beta_0 \lambda_i(t), \quad \beta_0 < 1$$

- Assuming that the sending rates are uniformly distributed in a congestion epoch:

$$\lambda(t + 0) \approx \beta \lambda(t - 0), \quad \text{where} \quad \beta = (\beta_0 - 1) \frac{\tilde{n}}{n} + 1$$

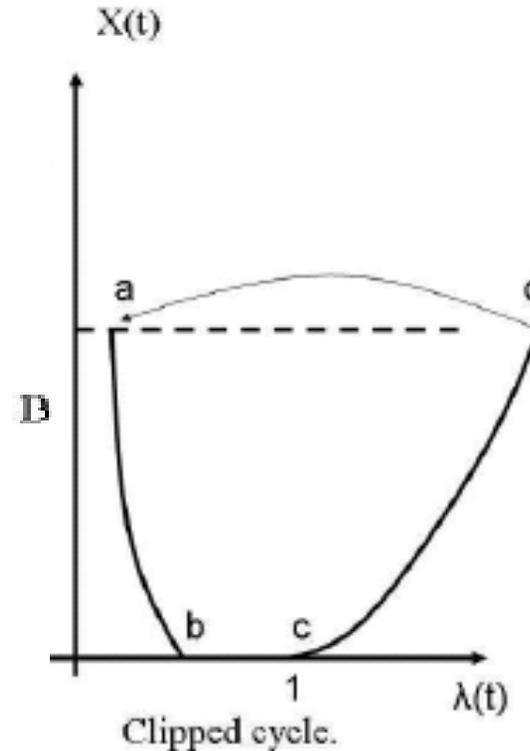
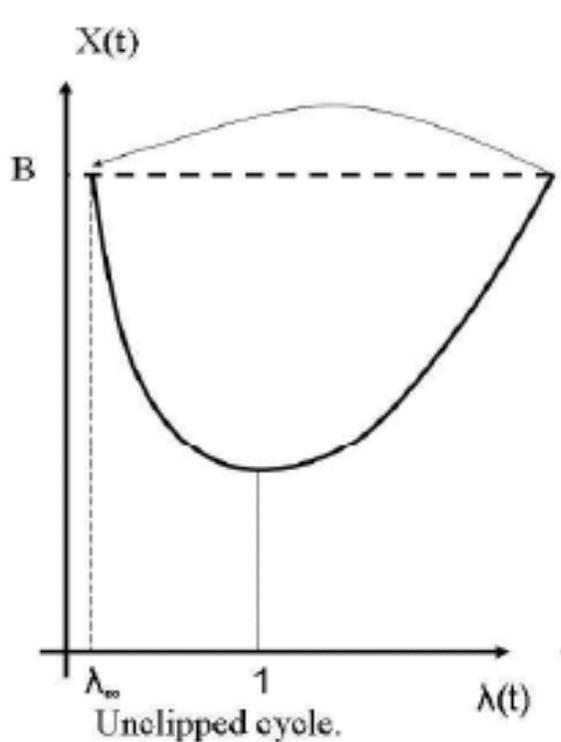
- Hybrid model : Dynamical systems that combine both discrete and continuous behavior.

- Example: Scalable TCP, $r_i = 0.01/RTT$ and $\beta_0 = 0.875$
[Kelly03]

– **Theorem:** Let $B_0 = \frac{\mu}{r} \left(\ln \frac{\beta-1}{\beta \ln \beta} - \frac{\beta \ln \beta}{1-\beta} - 1 \right)$.

Then unclipped (clipped) cycle exists if and only if $B \geq B_0, (B \leq B_0)$.

The duration of the cycle equals $T = -\ln \beta, \quad \forall B \geq 0$.



– **Lemma:** In the desynchronized case, $\beta = 1 - \frac{1}{2n}$, $\lim_{n \rightarrow \infty} n^2 B_0 = \frac{1}{32}$

- meaning that B_0 decreases to zero as $\frac{1}{2n^2}$,

– **Theorem:** Let λ_k be the value of $\lambda(t)$ immediately after the k -th jump. Then, starting from any initial value λ_0 , the limit $\lim_{k \rightarrow \infty} \lambda_k = \lambda_\infty$ exists.

- In addition there exist only simple limiting cycles, i.e. instant series of more than one jump are never realized, and all the values of $\lambda(t)$ immediately after a jump coincide with λ_∞ for the trajectory starting from $x_0 = B$, $\lambda_0 = \lambda_\infty$. The limiting cycle is stable.

– **Theorem:** If $B \geq B_0$ then

$$\bar{\lambda} = \mu; \quad \bar{x} = \frac{\mu}{r} \left(B + \frac{\ln \beta}{2} + \frac{\beta \ln \beta}{1-\beta} + 1 \right),$$

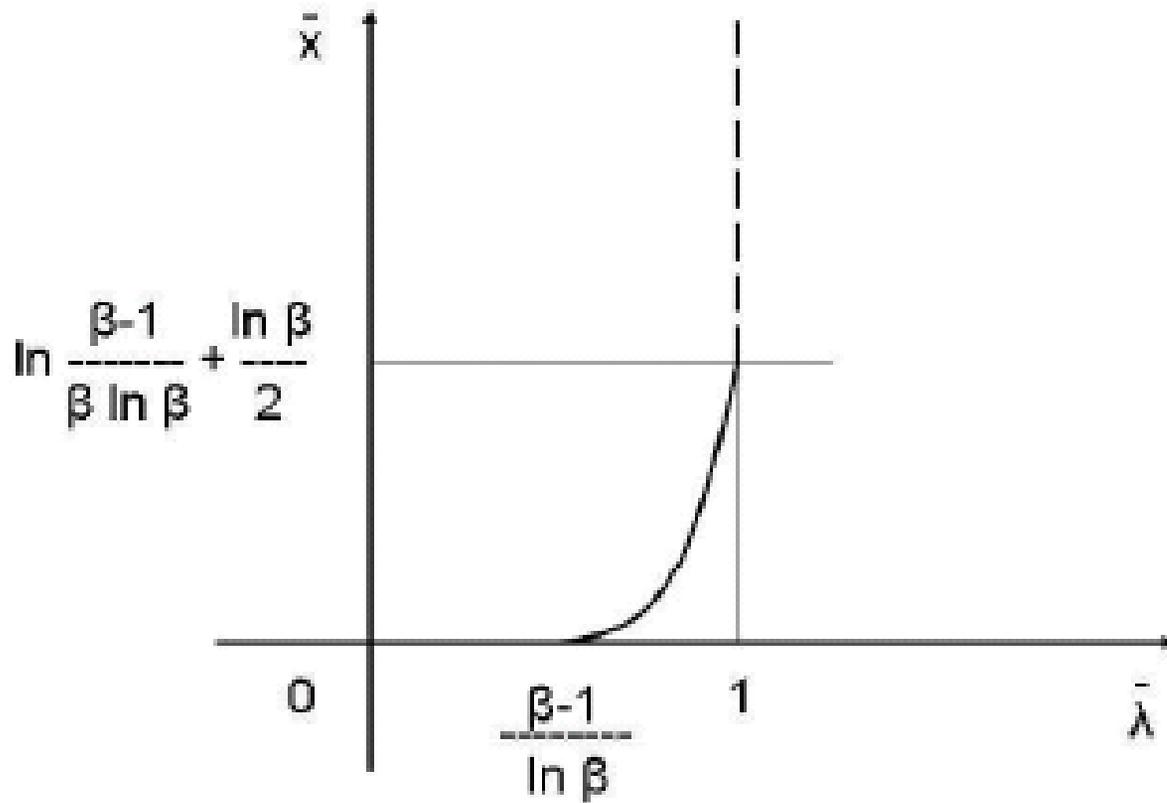
if $B < B_0$ then

$$\bar{\lambda} = \mu \frac{e^{\theta(\beta-1)}}{\ln \beta}; \quad \bar{x} = -\frac{\mu}{r} \frac{\delta e^{\theta(1-\beta)} - \frac{1}{2}(\delta + \theta)^2}{\ln \beta},$$

Pareto Set or Trade-off curve

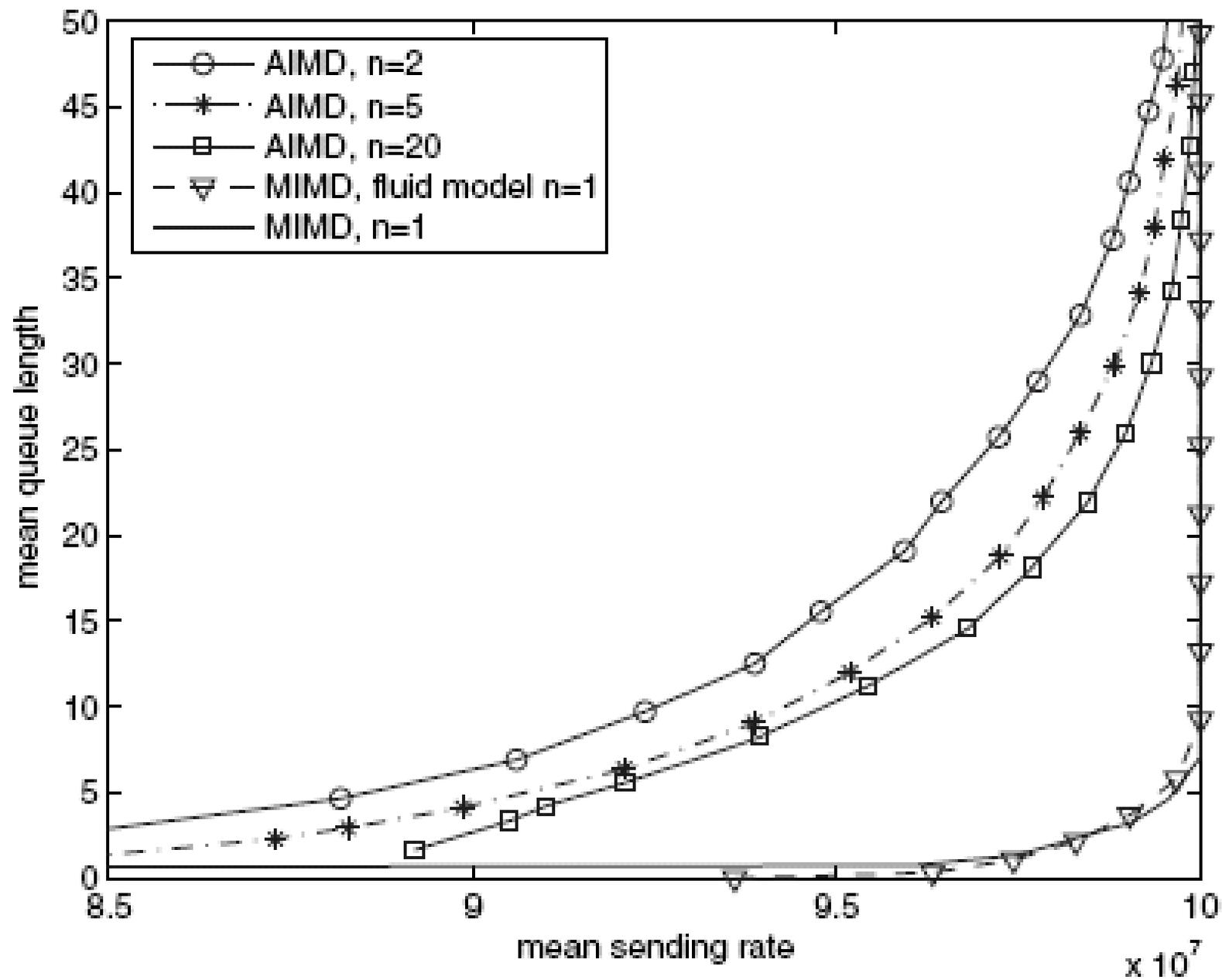
– Corollary: If $B \rightarrow 0$, then $\bar{x} \rightarrow 0$; $\bar{\lambda} \rightarrow \frac{\beta-1}{\ln \beta}$.

If $B \rightarrow B_0$, then $\bar{x} \rightarrow \ln \frac{\beta-1}{\beta \ln \beta} + \frac{\ln \beta}{2}$; $\bar{\lambda} \rightarrow 1$



For every (c_1, c_2) , we can determine the value of the Buffer that maximizes

$$\lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t c_1 x(s) + c_2 \lambda(s) ds.$$



Conclusions

- MIMD : The cycle duration independent of the link capacity (for AIMD it does depend)
- As the number of connections increases, B_0 decreases with $1/n^2$.
- For Scalable TCP and one connection $B_0=0,22 \times \text{RTT} \times \mu$.
- For MIMD, B_0 depends linearly on μ . For AIMD depends on μ^2 .
MIMD not only scales well with capacity, but it also requires smaller buffer sizes in high-speed networks.

Conclusions (cont.)

- When $B \rightarrow 0$, then $\bar{\lambda} \rightarrow \mu(\beta - 1)/\ln(\beta)$. Then if $\beta = \beta_0 = 0.875$ and $n=1$, $\lambda = 0.94\mu$. That is, even with no buffer, the utilization of Scalable TCP would be very high.
- Incorporate to the model : delays, heterogeneous RTT, dynamically arriving and departing connections etc.
- The Pareto Set of the multicriteria optimization problem may be useful in dimensioning routers