

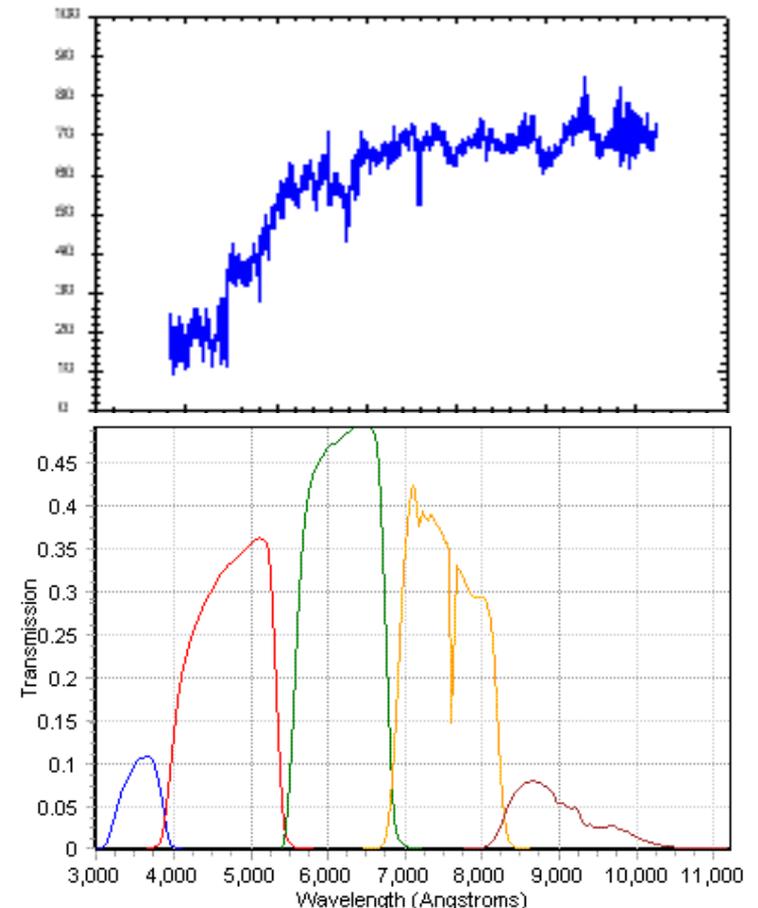
# PHOTOMETRIC REDSHIFTS 50 YEARS AFTER

6/14/2010

Tamás Budavári / The Johns Hopkins University

# Binning Photons

- Space (and time)
  - Position measurements
  
- Wavelength
  - Spectroscopy: narrow bins
  - Photometry: broad bands
  
- For example, SDSS
  - Spectro:  $r < 17.7$  1.6M sources
  - Photo:  $r < 21+$  360M sources
  - In a fraction of the time...





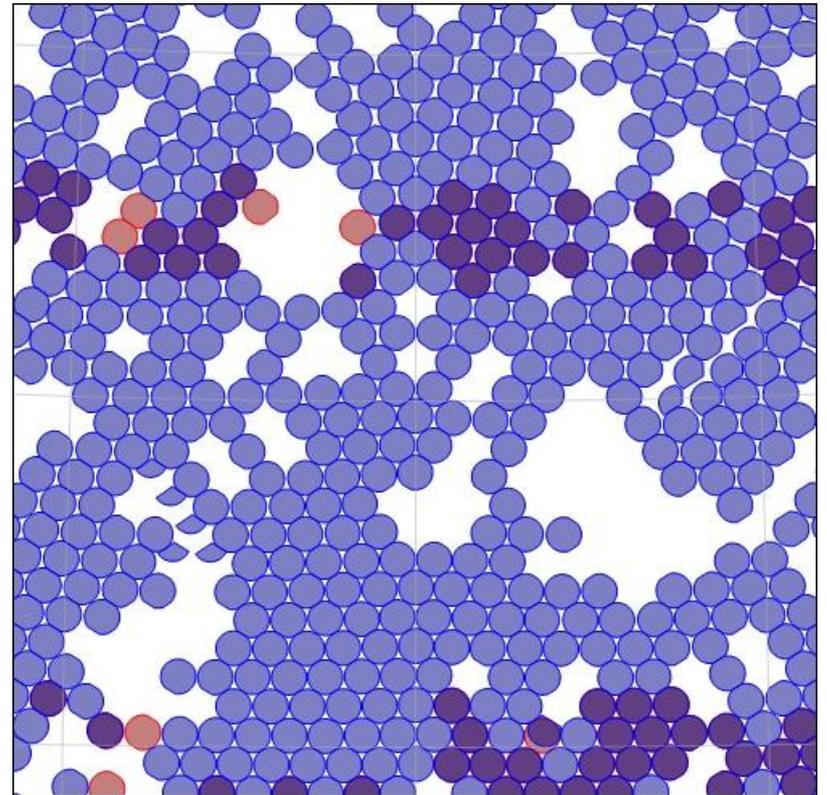
# Multicolor Challenges

- Cross-identification of sources
  - To assemble multicolor catalogs
  
- Constraining physical properties
  - To interpret the data



# Dropouts?

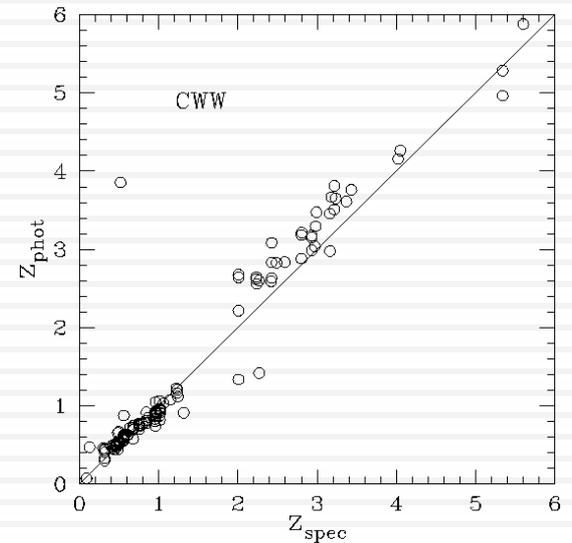
- Measured fluxes
  - ▣ Extract from images
  
- Un-detected
  - ▣ Limit from coverage



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# Photometric Redshifts

- ❑ Empirical methods
- ❑ Template fitting



# Historical Overview

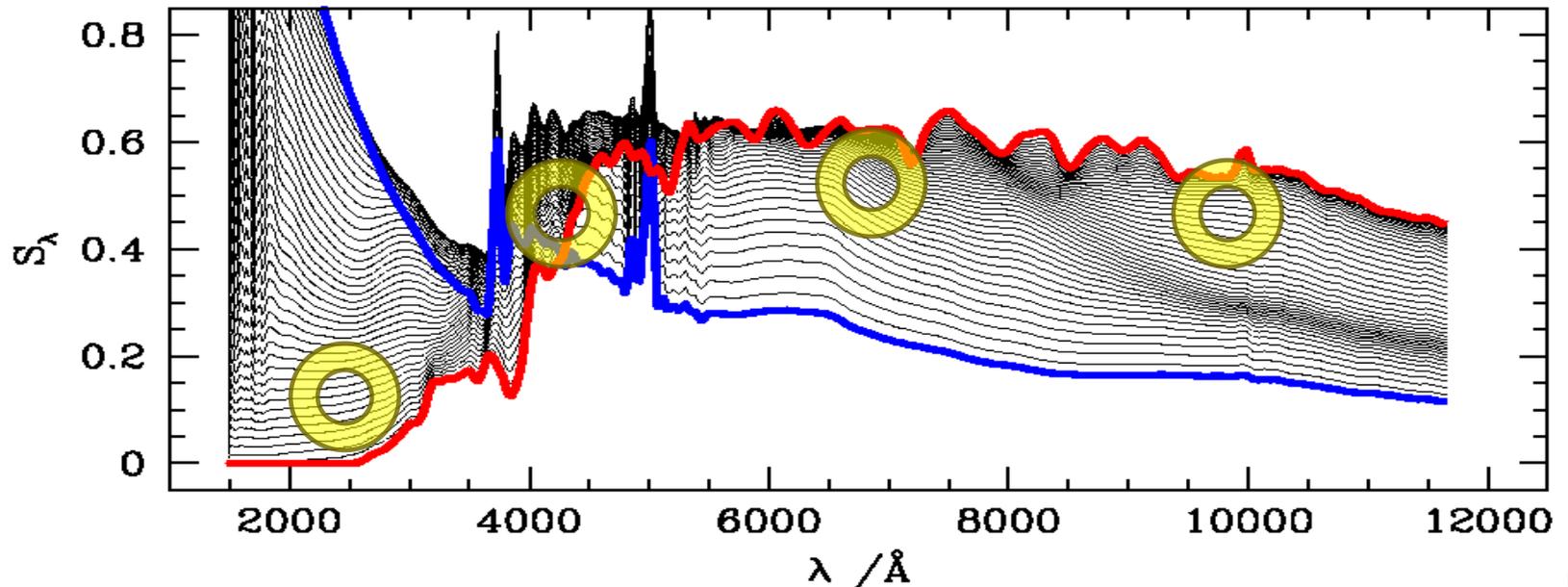
- Baum (1962)
  - Compared average SEDs (9 bands) of ellipticals in clusters
- Koo (1985)
  - Color-shape diagrams of and Bruzual-Charlot iso-z tracks (-U+J+F-N)
- Loh & Spillar (1986)
  - Template fitting with 6 non-standard filters and 34 known galaxies
- Connolly et al. (1995)
  - Redshift assumed to be a linear or quadratic function of magnitudes
- Steidel et al. (1996)
  - U dropout due to Ly-alpha blanketing ( $< 912\text{\AA}$ ) to select  $z > 2.25$

# Empirical Methods

- Regression  $z = F(m)$ 
  - Polynomial fitting
  - Piecewise linear fits
  - Nearest neighbors
  - Neural Nets
  - Support Vector Machines
  
- Errors?

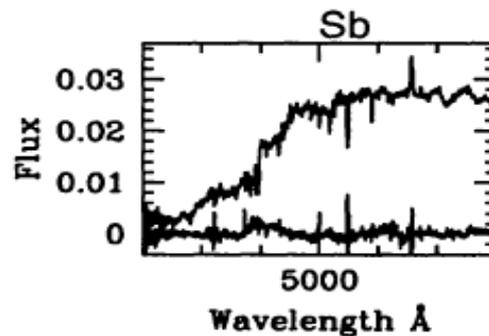
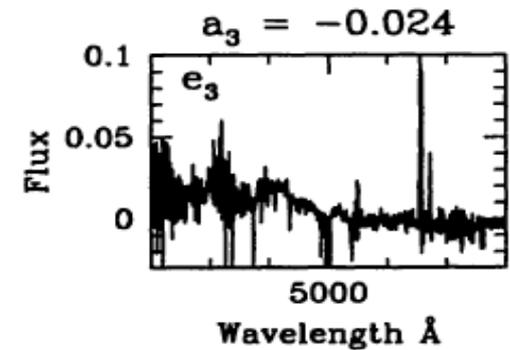
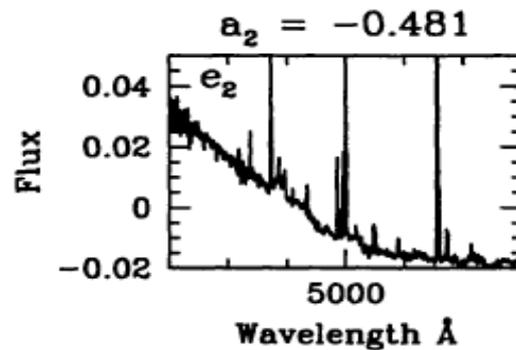
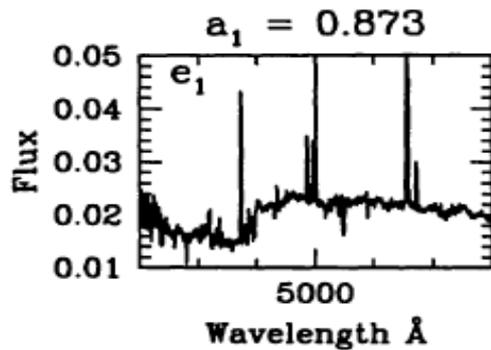
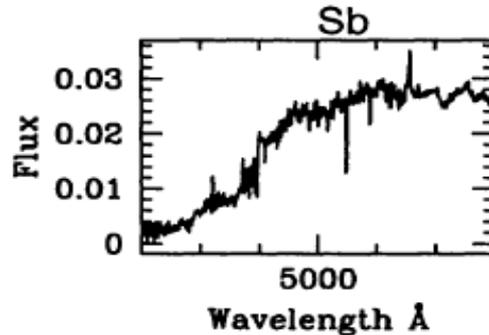
# Template Fitting

- Compare reference spectra to measurements
  - ▣ At different redshifts
  - ▣ MLE with Gaussian



# Linear-combination of Eigenspectra

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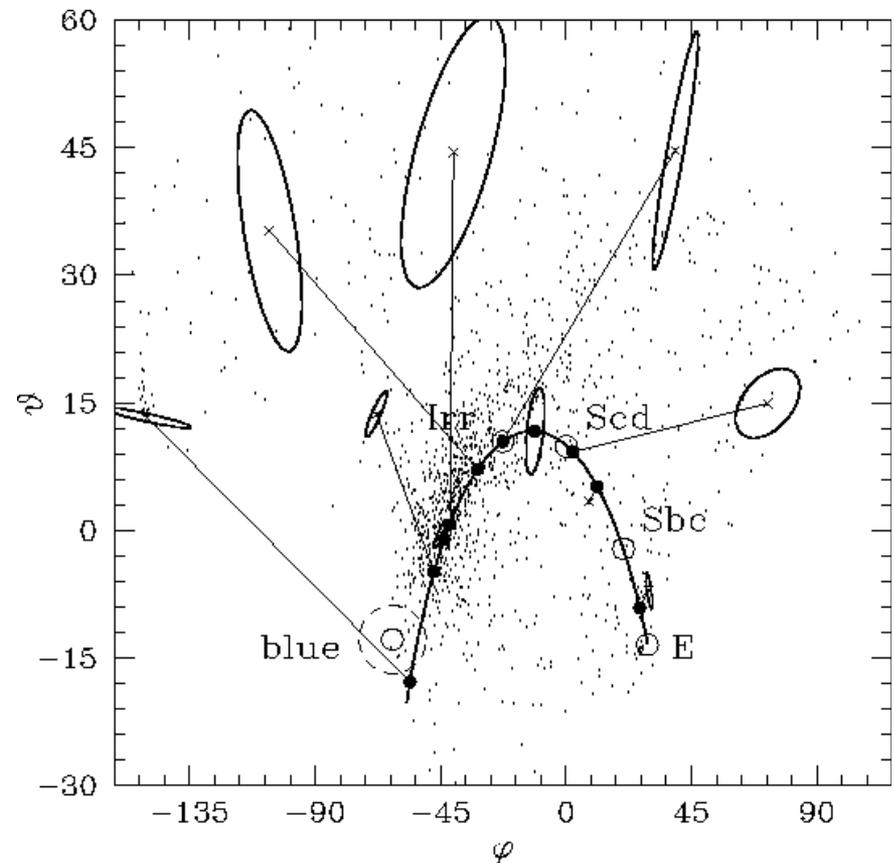


# Interpolation

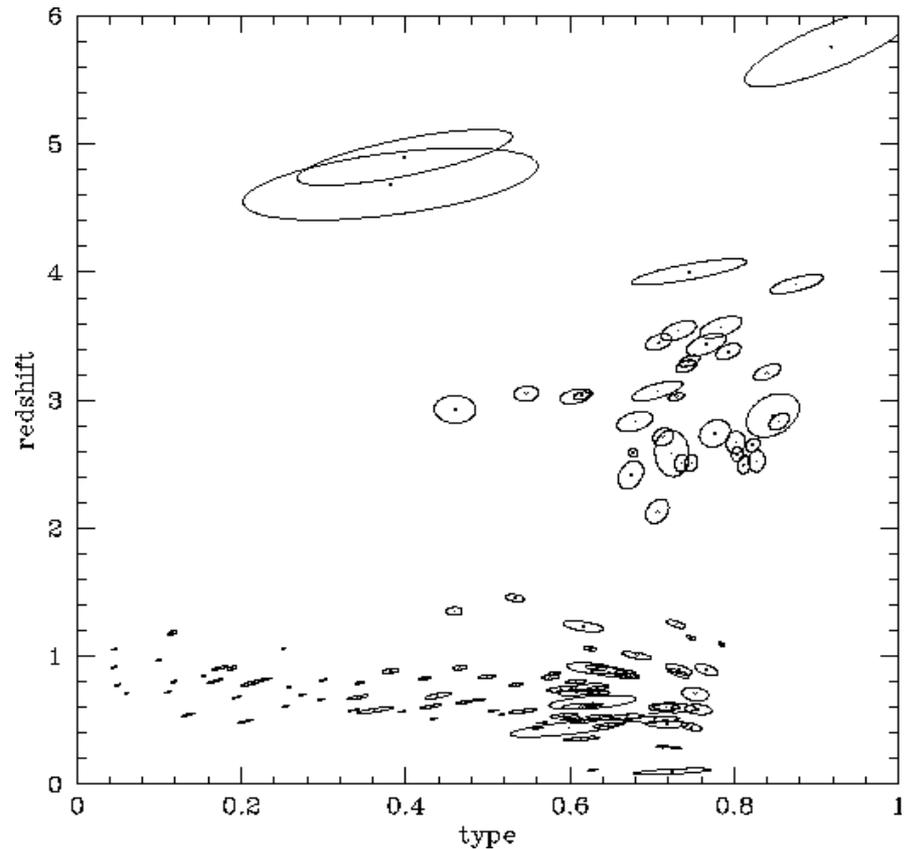
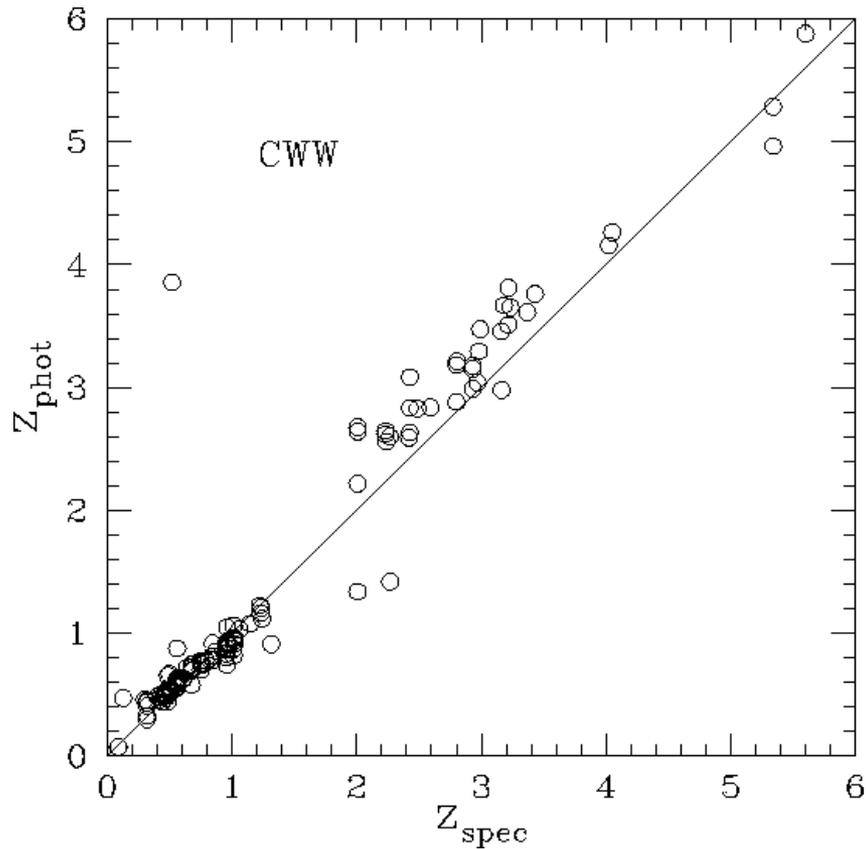
- Two mixing angles encode the spectral type when using 3 eigenspectra

1D type parameter connects the CWW templates

<b>Ell</b>	0
<b>Sbc</b>	0.13
<b>Scd</b>	0.35
<b>Irr</b>	0.56
<b>blue</b>	1



# Consistent Redshift and Type



# Traditional Methods

## Empirical Methods

Pure fit for  $z$  over the color hyper-plane

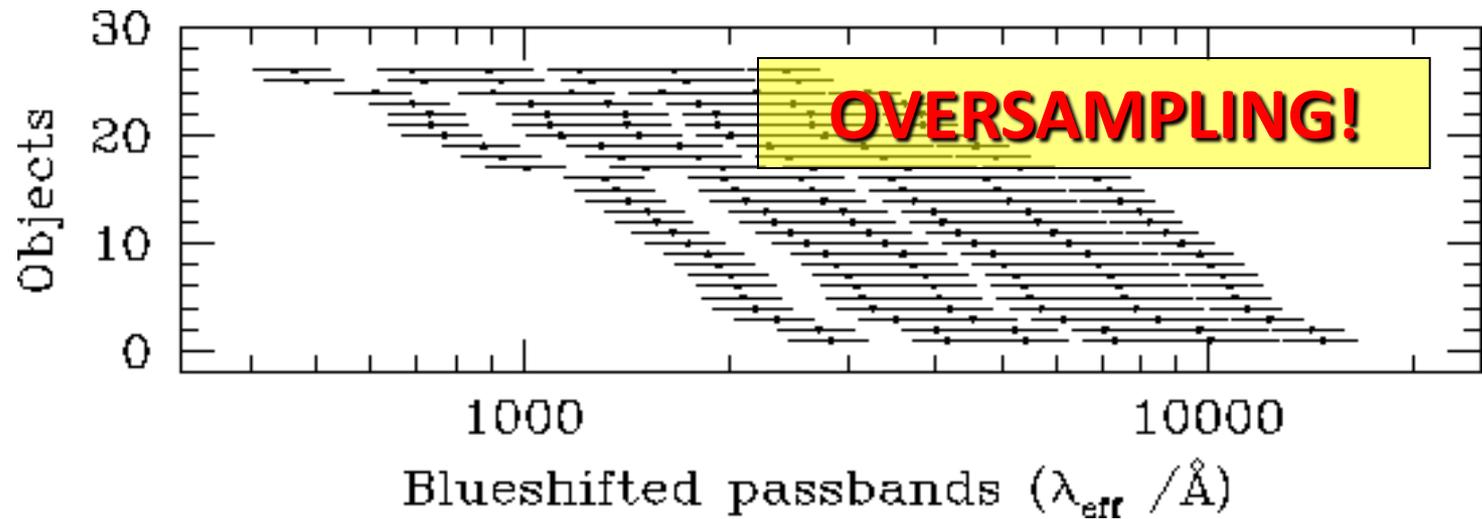
- + fast redshift prediction
- fitting functions and training sets needed for every survey
- unreliable extrapolation

## Template Fitting

Comparison of known SEDs to photometry

- + physics is in templates, no training set required
- + more outcome: spectral type, reddening, etc.
- templates used as come

# Templates from Photometry?

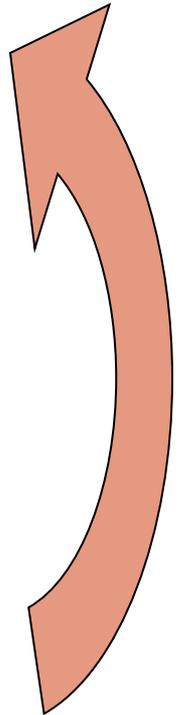


# Simple Repair

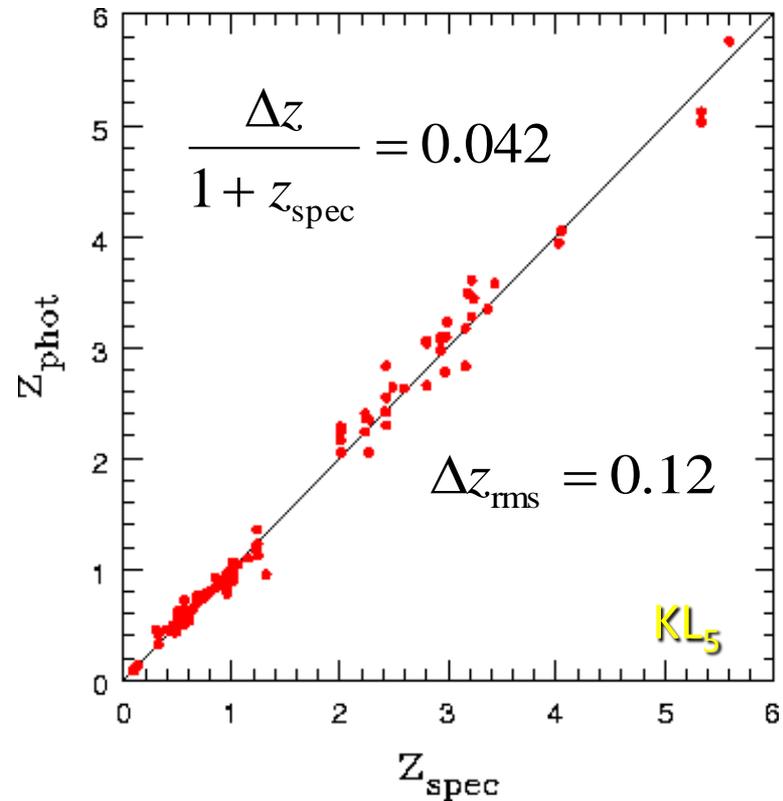
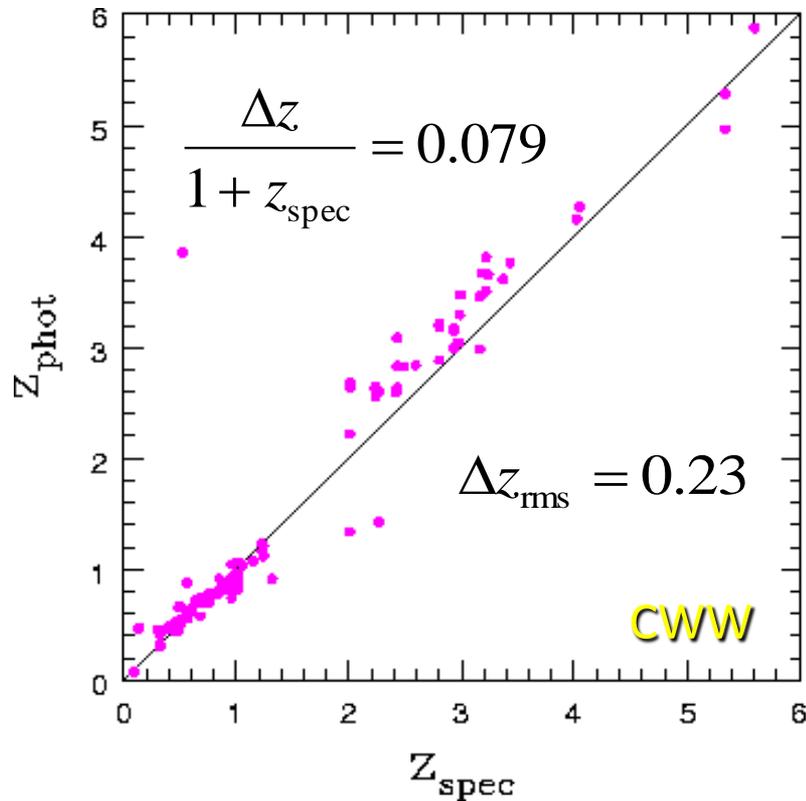
For each galaxy:

1. Compute type from known redshift
2. Derive estimate spectrum
3. Correct spectrum to photometry\*

Build new basis from corrected spectra



# HDF/NICMOS in 1999



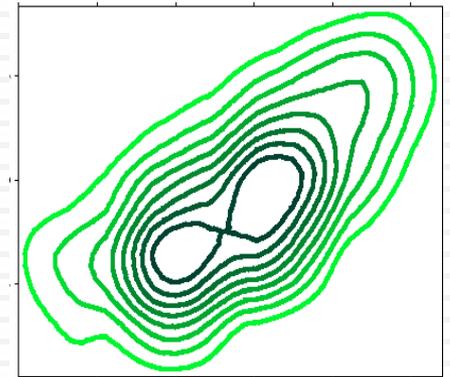
# 50 Years of Pragmatism

- Traditional ways
  - ▣ Empirical methods: assume a fitting function
  - ▣ Template fitting: compare to model spectra
  
- Very different techniques
  - ▣ For no fundamental reason
  
- Many open questions

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# A Unified Framework

Starting from scratch...

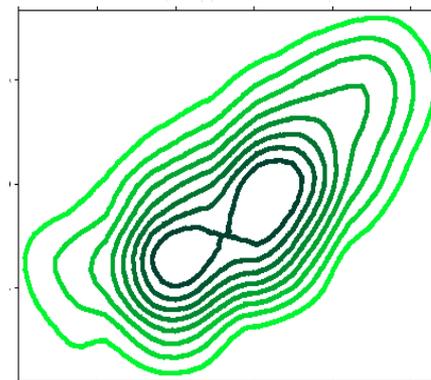
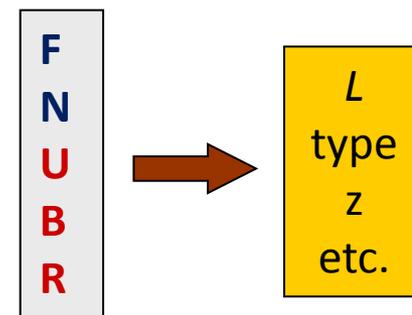


# Photometric Inversion

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- The general inversion problem
  - ▣ Constrain various properties consistently
  - ▣ Propagate their uncertainties and correlations
- Estimates are secondary
  - ▣ Provide probability density functions instead
  - ▣ Scientific analyses to use the full PDFs
- Make best use of observations
  - ▣ Next generation surveys are photometric only



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# A Unified Framework

- Training and Query sets with different observables

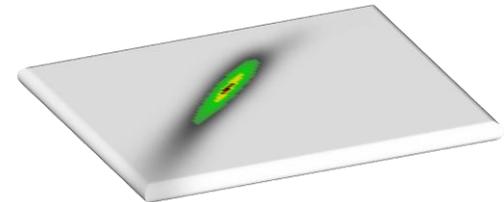
$$T : \{ \mathbf{x}_t, \boldsymbol{\xi}_t \}_{t \in T}$$

$$Q : \{ \mathbf{y}_q \}_{q \in Q}$$

$$M : \boldsymbol{\theta}$$

- Model yields observables for given parameter
  - ▣ Prediction via  $p(\mathbf{x}, \mathbf{y} | \boldsymbol{\theta}, M)$  and has prior  $p(\boldsymbol{\theta} | M)$
  - ▣ Also folds in the photometric accuracy

- We are after  $p(\boldsymbol{\xi} | \mathbf{y}_q, M)$



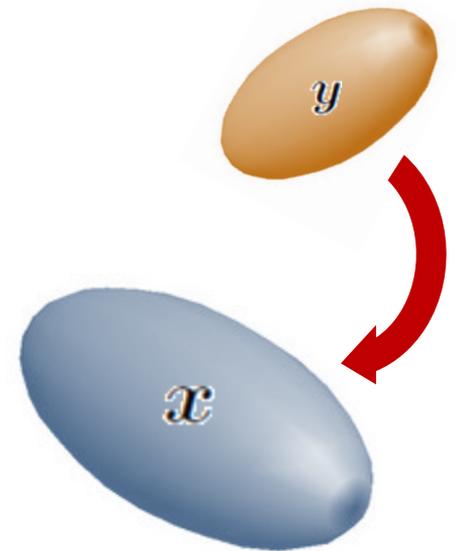
# Mapping Observables

- The model provides the transformation rule

$$p(\mathbf{x}|\mathbf{y}_q, M) = \int d\boldsymbol{\theta} p(\mathbf{x}|\boldsymbol{\theta}, M) p(\boldsymbol{\theta}|\mathbf{y}_q, M)$$

with

$$p(\boldsymbol{\theta}|\mathbf{y}_q, M) = \frac{p(\boldsymbol{\theta}|M) p(\mathbf{y}_q|\boldsymbol{\theta}, M)}{p(\mathbf{y}_q|M)}$$

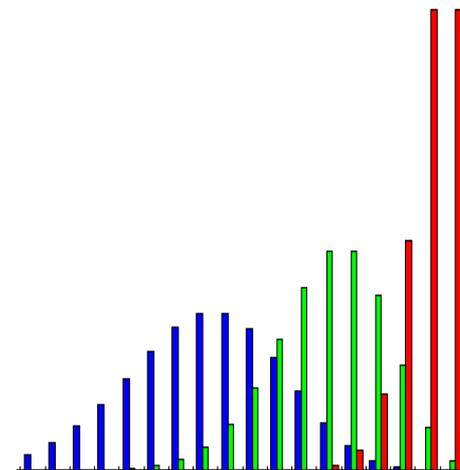


- Think empirical conversion formulas but better
  - For example, from *UJFN* to *ugriz* with errors

# Empirical Relation

- Usually just assume a function  $\xi = \hat{\xi}(x)$ 
  - ▣ Wrong! We know there are degeneracies...
- There is a more general relation  $p(\xi|x)$ 
  - ▣ Usual restriction is  $p(\xi|x) = \delta(|\xi - \hat{\xi}(x)|)$
  - ▣ Correct estimation

$$p(\xi|x) = \frac{p(\xi, x)}{p(x)}$$

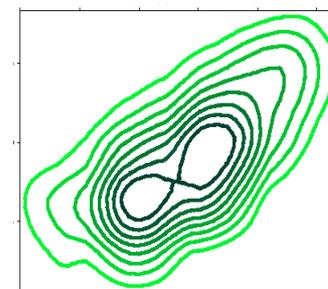


- Straightforward to do if one can estimate densities
  - ▣ Also better direct methods exist

# Properties of Interest

- The final constraint is

$$p(\boldsymbol{\xi}|\mathbf{y}_q, M) = \int d\mathbf{x} p(\boldsymbol{\xi}|\mathbf{x}) p(\mathbf{x}|\mathbf{y}_q, M)$$



- If the result is unimodal (no guarantee)
  - ▣ Estimate by mean, etc.

$$\bar{\boldsymbol{\xi}}(\mathbf{y}_q) = \int d\boldsymbol{\xi} \boldsymbol{\xi} p(\boldsymbol{\xi}|\mathbf{y}_q, M)$$

# Properties of Samples

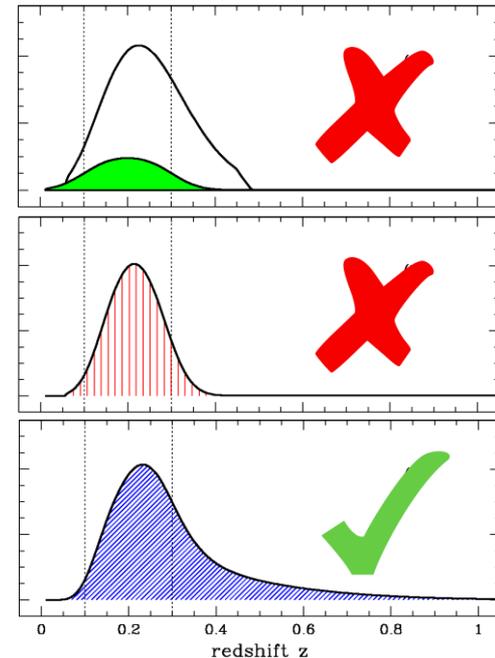
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- Distribution of a sample  $Q$ 
  - ▣ Directly calculated as the mean

$$p(\xi|Q, M) = \langle p(\xi|y_q, M) \rangle_{q \in Q}$$

- Works for sub-samples
- No need for de-convolution →



# Selection Effects

- Measure of reliability is the prob of  $q$  making the cuts

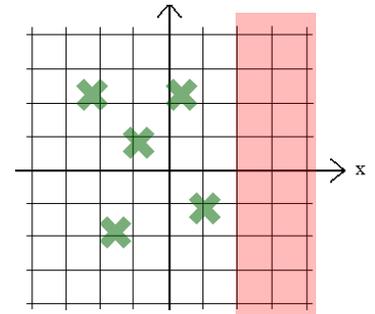
$$P(W|\mathbf{y}_q, M) = \int d\mathbf{x} P(W|\mathbf{x}) p(\mathbf{x}|\mathbf{y}_q, M)$$

- Include observables used in the selection criteria

$$p(\xi|\mathbf{x}, T) = \frac{p(\xi|\mathbf{x}) P(T|\mathbf{x}, \xi)}{P(T|\mathbf{x})}$$

- For instance

- Cannot use just colors, if there was a magnitude cut
- Cannot use just fluxes, if cut on morphology



# Empirical Uncertainty

- Parameters yield observables  $\bar{x}(\theta)$  and  $\bar{y}(\theta)$ 
  - ▣ Say your templates and redshifts sent through the filters
- Photometric accuracy
  - ▣ Normal distribution with full covariance matrix

$$p(\mathbf{x}_t, \mathbf{y}_q | \theta, M) = N_x(\mathbf{x}_t | \bar{x}(\theta), \mathbf{C}_t) \\ \times N_y(\mathbf{y}_q | \bar{y}(\theta), \mathbf{C}_q)$$

- Otherwise approximate with nearest

# Numerical Integration

- Measure of reliability from MCMC
  - ▣ Average over parameter chain from  $p(\boldsymbol{\theta}|\mathbf{y}_q, M)$

$$p(\mathbf{x}|\mathbf{y}_q, M) = \langle N_{\mathbf{x}}(\mathbf{x}|\bar{\mathbf{x}}(\boldsymbol{\theta}_i), \mathbf{C}_t) \rangle$$

- If within boundaries, ignore the effect
  - ▣ Training points naturally drawn from their distribution

$$p(\boldsymbol{\xi}_r|\mathbf{y}_q, T, M) \propto \sum_{t \in T} p(\boldsymbol{\xi}_r|\mathbf{x}_t, T) \frac{p(\mathbf{x}_t|\mathbf{y}_q, M)}{p(\mathbf{x}_t|T)}$$

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# Traditional Methods

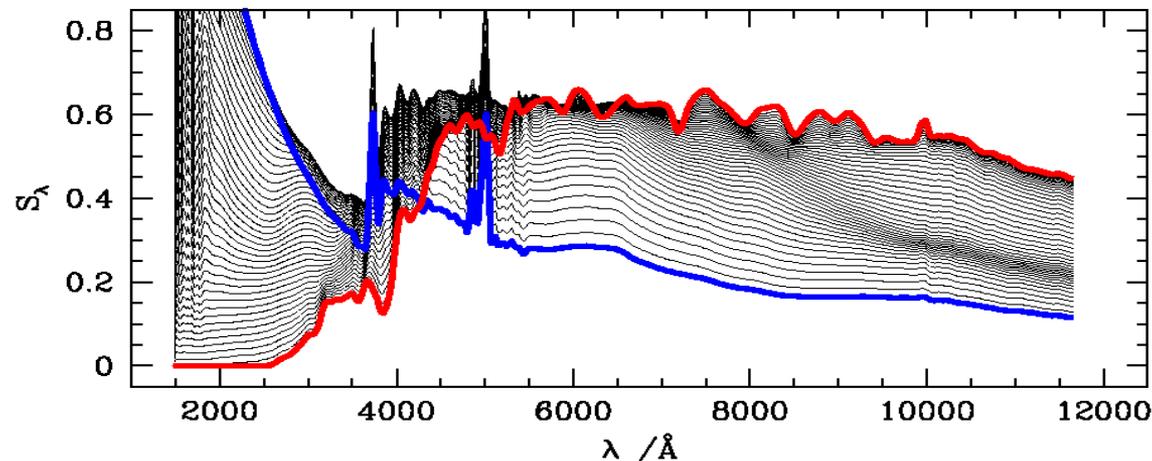
As corner cases of the Unified Framework

# Template Fitting

- Artificial training set  $\{x_t, \xi_t\} = \{\bar{x}(\theta_t), \bar{\xi}(\theta_t)\}$ 
  - ▣ From a grid of model points
  - ▣ No errors  $p(x|\theta, M) = \delta(|x - \bar{x}(\theta)|)$

- Analytic result

$$p(\xi|y_q, M) \propto \sum_{t \in T} \delta(|\xi - \xi_t|) p(\theta_t|M) N(y_q|\bar{y}(\theta_t), C_q)$$



# Improved Empirics

## □ Minimalist model

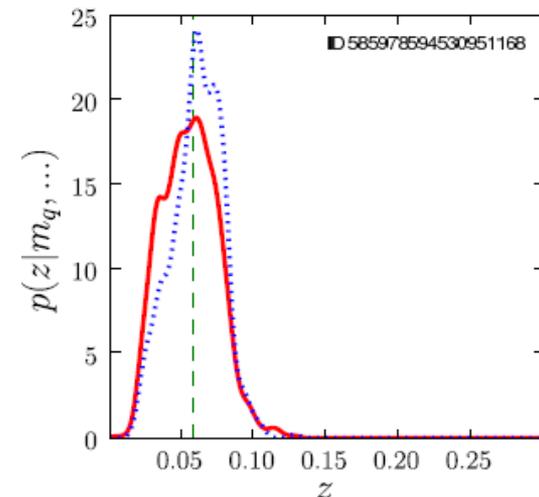
- Normal distributions, same quantities:  $\bar{x}(\theta) = \theta$  and  $\bar{y}(\theta) = \theta$
- With simple prior, the mapping is analytic, e.g., for flat

$$p(\mathbf{x}_t | \mathbf{y}_q, M) = \int d\theta N(\mathbf{x}_t | \theta, \mathbf{C}_t) N(\theta | \mathbf{y}_q, \mathbf{C}_q)$$

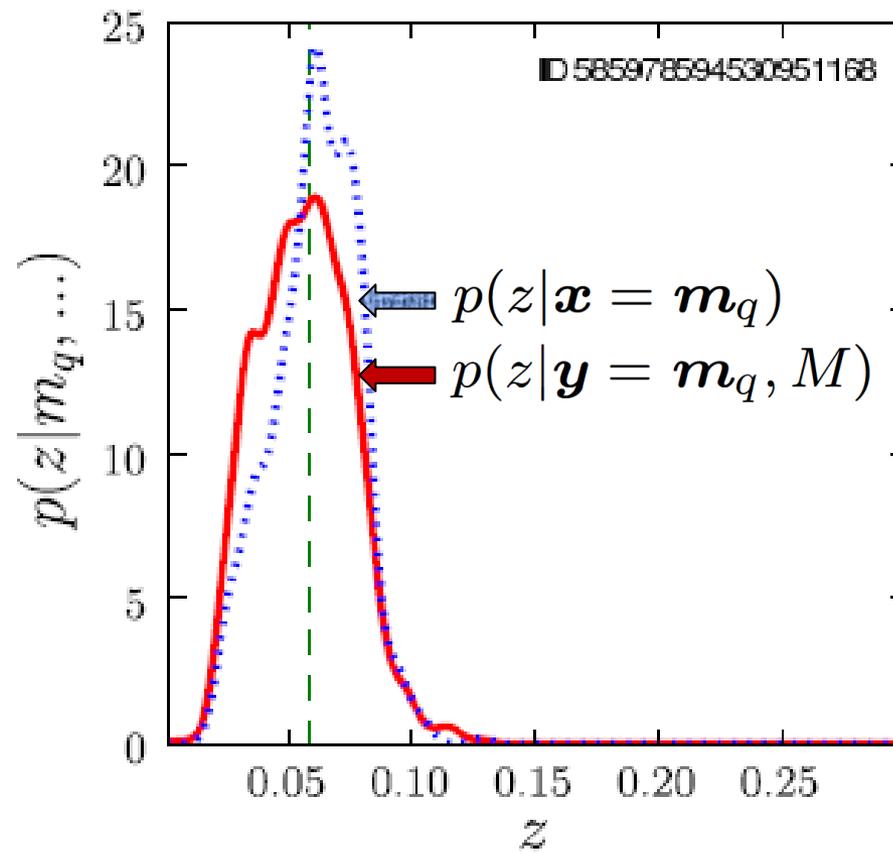
## □ Empirical relation

- Fitting function as before or rather
- General relation from densities

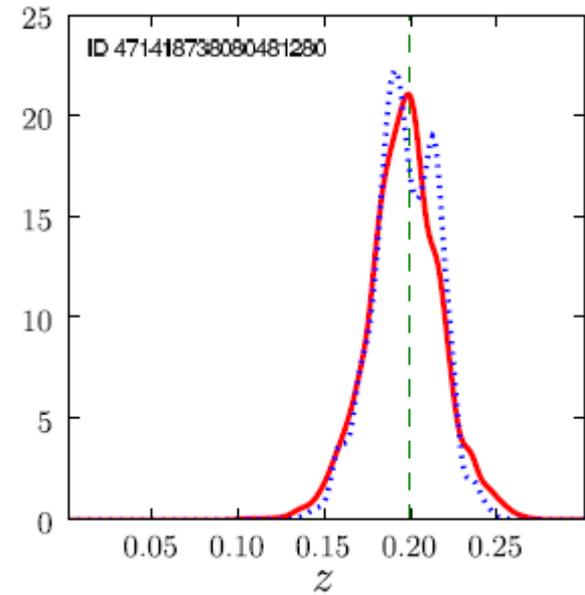
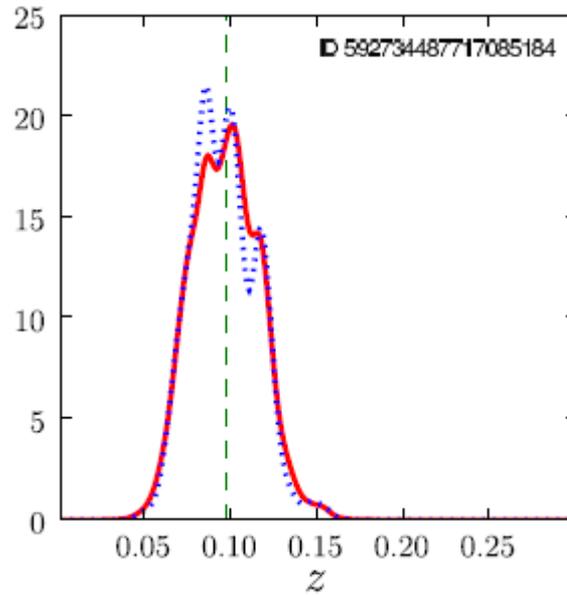
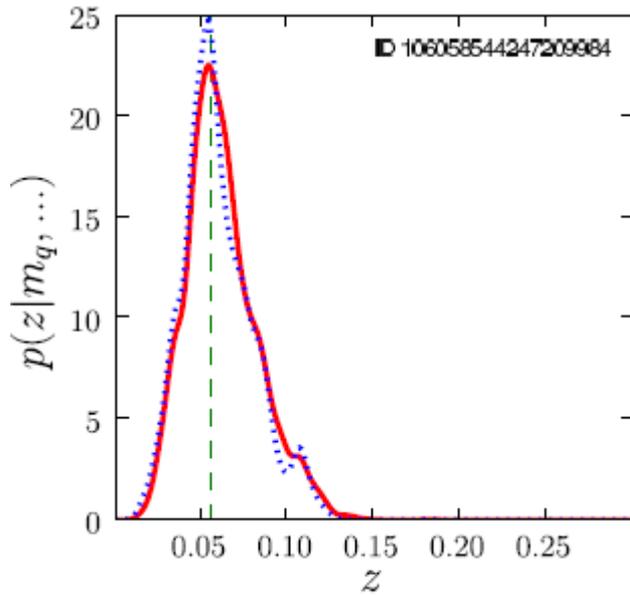
## □ Numerical summation →



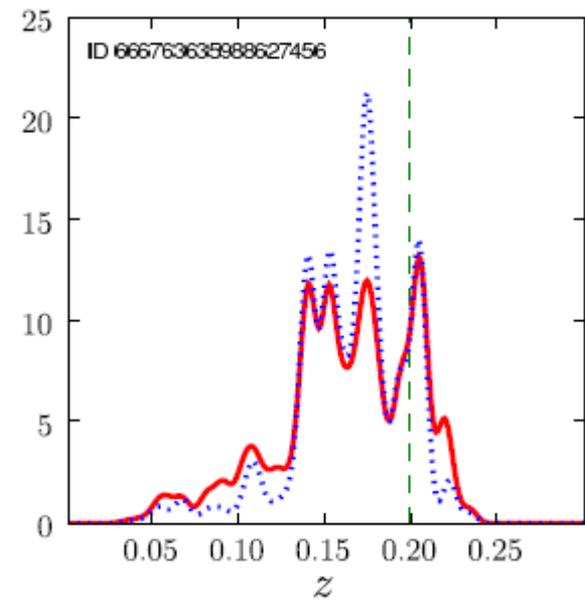
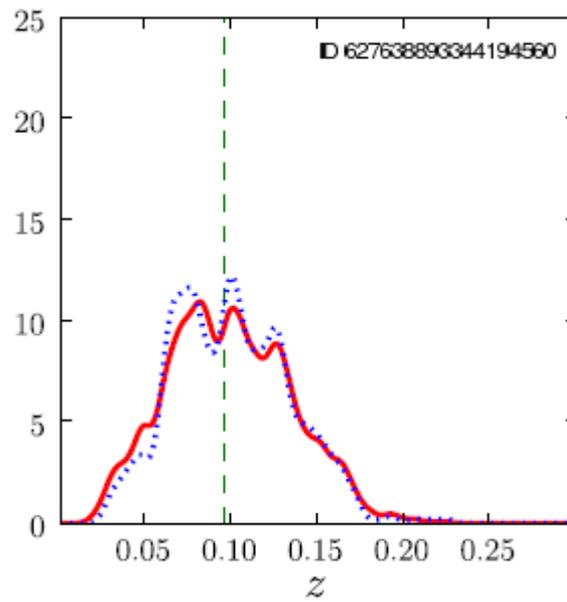
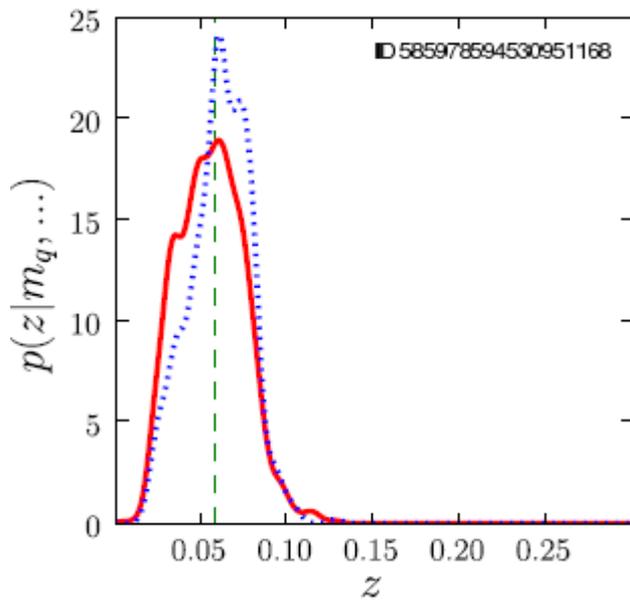
# It works!



# Red Galaxies

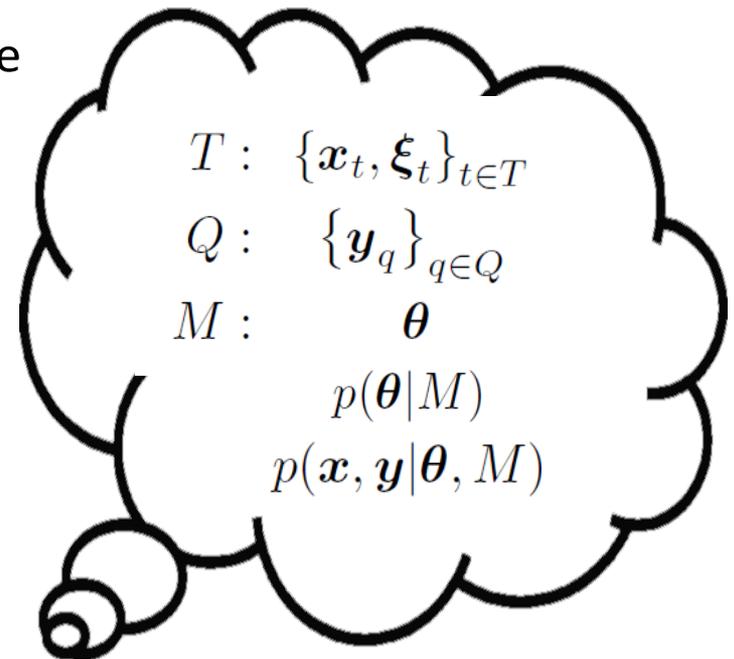


# Blue Galaxies



# Advanced Methods

- Mapping observables via models
  - Any complete basis on wavelength range
  - Physics in the prior
  
- Relation of properties
  - Conditional densities
  
- Empirical but with templates
  - Unified framework at its best



# Concerning Priors

- Measured densities in the Query set

$$p(\mathbf{y}|Q)$$

- Consistent models should match that

$$p(\mathbf{y}|M) = \int d\boldsymbol{\theta} p(\mathbf{y}|\boldsymbol{\theta}, M) p(\boldsymbol{\theta}|M)$$

- Deconvolution yields empirical prior

$$p(\mathbf{y}|M) = p(\mathbf{y}|Q)$$

# Summary

- Solve the photometric inversion problem
  - ▣ Real constraints from first principles
  - ▣ Works with incomplete data
- Put traditional methods in context
  - ▣ Explain their formal relations
  - ▣ Points out their strengths and weaknesses
- Suggests new directions
  - ▣ Next generation photo-z methods
  - ▣ Design better training sets

# Room for Improvements

- Understand photometric uncertainties
  - ▣ No error estimates are reliable today
  
- Better conditional density estimation
  - ▣ In presence of sharp boundaries
  
- Realistic models with good priors
  - ▣ That match the data

