A genetic algorithm for the identification of conformationally invariant regions in protein molecules

Understanding macromolecular function often relies on the comparison of different structural models of a molecule. In such a comparative analysis, the identification of the part of the molecule that is conformationally invariant with respect to a set of conformers is a critical step, as the corresponding subset of atoms constitutes the reference for subsequent analysis for example by least-squares superposition. A method is presented that categorizes atoms in a molecule as either conformationally invariant or flexible by automatic analysis of an ensemble of conformers (e.g. crystal structures from different crystal forms or molecules related by non-crystallographic symmetry). Different levels of coordinate precision, both for different models and for individual atoms, are taken explicitly into account via a modified form of Cruickshank’s DPI [Cruickshank (1999), Acta Cryst. D55, 583–601] and are propagated into error-scaled difference distance matrices [Schneider (2000), Acta Cryst. D56, 715–721]. All pairwise error-scaled difference distance matrices are then analysed simultaneously using a genetic algorithm. The algorithm has been tested on several well known examples and has been found to converge rapidly to reasonable results using a standard set of parameters. In addition to the description of the algorithm, a criterion is suggested for testing the identity of two three-dimensional models within experimental error without any explicit superposition.

1. Introduction

Although a single crystal structure normally represents a rather static picture of a protein molecule, the comparison of different conformers of a given molecule as obtained from different structure determinations can provide valuable insight into its flexibility. Such analyses can be based on structures in different crystal forms, under different physico-chemical conditions (using, for example, pH or temperature as a variable) and with and without a substrate molecule bound. Multiple copies of a molecule may also arise from non-crystallographic symmetry or be an ensemble generated by NMR structure analysis. A typical strategy is to first identify the rigid part of the molecule and then in a subsequent step interpret the conformational differences revealed by least-squares superposition of the corresponding atoms in the rigid part. There are, however, several problems with this approach. Firstly, the identification of the rigid or conformationally invariant part of the molecule, here defined as the largest subset of atoms for which all interatomic distances are identical across all models under consideration, is often performed manually and in an iterative fashion and is thus susceptible to preconceived ideas. Secondly, in most cases, the potentially...
very different levels of quality of different models and of the precision of atomic coordinates for different atoms in the same model are not taken into account in the comparison process. A third, more technical, complication is that usually the different models are compared in a pairwise fashion, resulting in massive book-keeping problems if many models are compared. Recently, an approach to identify the conformationally invariant part of a molecule with respect to a set of several conformers by manual interpretation of error-scaled difference distance matrices has been proposed (Schneider, 2000). In principle, this approach can be used to identify the conformationally invariant part of a molecule with respect to any number of conformers; in practice, however, the number and the complexity of the matrices to be interpreted soon become the limiting factor. In the present paper, a computer algorithm that automates this task is described.

The question of how to extract information about the rigidity and flexibility of proteins based on the comparison of two conformers has already been addressed by several authors. The DYNDOM approach developed by Berendsen & Hayward (1998) employs a cluster analysis of interatomic vectors to first subdivide a molecule into domains and then determines hinge axes between these domains. Lesk has described the sieve fitting procedure (Lesk & Chothia, 1984; McPhalen, Vincent & Jansonius, 1992), where the dominant rigid domain of a molecule is found by iterative application of least-squares fits in which after starting from a full superposition in every step poorly matching residues are eliminated. This method has been expanded to the partitioning of a molecule into multiple small domains of preserved geometry in the adaptive selection procedure suggested by Wriggers & Schulten (1997). Here, variable seed sets of atoms are subjected to sieve fitting in order to develop a set of well fitting substructures. Nichols et al. (1995) have recently formulated two algorithms that find rigid domains by analysing the thresholded difference distance matrix corresponding to two conformers and applied this technique to identify rigid regions in haemoglobin based on the comparison of the respective deoxy and oxy structures (Nichols et al., 1997).

A generalization of the sieve fitting procedure to the case of multiple prealigned models of different but homologous proteins has been put forward by Gerstein & Altman (1995) and has subsequently been used to create a library of protein family core structures (Schmidt et al., 1997).

Multiple models of the same molecule also appear in ensembles of conformers derived from an NMR experiment. Kelley and coworkers have recently designed an algorithm for the analysis of such ensembles that finds the core of a molecule by identifying dihedral angles showing small variation across the ensemble. However, as in their definition of the core the parts of the molecule containing stable dihedral angles do not need to be continuously connected, such a core can contain rigid regions that move relative to one another. Kelley and coworkers deal with such situations by further subdividing the core into local structural domains by analysis of a matrix containing the variance of $C^\alpha-C^\alpha$ distances. This matrix effectively summarizes the information present in the difference distance matrices between all possible pairs of conformers and can be rapidly interpreted using a clustering algorithm (Kelley et al., 1996, 1997).

In the context of error-scaled difference distance matrices, finding the largest conformationally invariant part of a molecule with respect to a set of conformers (as opposed to only two conformers) can be formulated as an optimization problem of identifying the largest subset of atoms for which all interatomic distances are identical within error in all models (corresponding to all relevant elements of the error-scaled difference distance matrices being approximately zero). As for a molecule with $N$ atoms the number of possibilities for creating such a subset is $2^N$ (every atom can be a member of the subset or not), a systematic full search of all possibilities is clearly not feasible. Furthermore, the fact that the search parameters assume discrete values prohibits an analytical solution of the problem. The nature of the problem, however, is such that local partial solutions (i.e. small groups of conformationally invariant atoms) can be identified and their combination may yield a better solution (i.e. if two rigid groups do not move relative to one another, their combination will result in a larger rigid group), making a genetic algorithm (GA; Holland, 1975; Goldberg, 1989; Mitchell, 1996) the optimization method of choice. In addition, GAs are also particularly well suited to large search spaces with discrete parameters.

The basic idea of a genetic algorithm is that a population of candidate solutions, or hypotheses, is created and then subjected to an evolutionary process. During the evolution, offspring candidate solutions are generated by combining properties of existing candidate solutions whereby the probability of properties being passed on to the next generation is proportional to a measure of fitness. After a number of generations, the evolutionary search should converge to a homogeneous population with high values of the fitness function for all members of the population. Although there is no guarantee that the global optimum is found, the top-scoring hypothesis of the final population in many cases represents an acceptable solution to the optimization problem.

A number of problems in structural biology have been tackled using GAs in recent years [e.g. protein form reconstruction from X-ray solution scattering (Chacón et al., 2000) and docking of small molecules to macromolecules (Jones et al., 1997)] and several applications in macromolecular crystallography have been reported [e.g. finding heavy-atom sites from Patterson maps (Chang & Lewis, 1994), molecular replacement (Chang & Lewis, 1997; Kissinger et al., 1999) and low-resolution phasing (Webster & Hilgenfeld, 2001)].

The implementation of the search for the largest conformationally invariant part of a molecule as a GA is relatively straightforward. A candidate solution can be conveniently described as a binary string where every bit indicates whether or not the corresponding atom belongs to the conformationally invariant part or not. The fitness of a candidate solution is evaluated by checking its consistency with all error-scaled difference distance matrices that can be constructed between all conformers being analysed. The main difficulty in manual
interpretation, the combination of small conformationally invariant regions, where all atoms are close in sequence, to larger parts connected in three dimensions [while keeping track of a large number of error-scaled difference distance (EDD) matrices], is overcome by the genetic algorithm which, in fact, is centred exactly around the filtering of improved candidate solutions from a large pool of randomly recombined potential partial solutions.

In the following, the algorithm is described and its application to several test cases, for which a careful more manual analysis was available in the literature, is discussed. The examples are (i) comparison of three NCS-related copies of chorismate mutase refined to near atomic resolution, (ii) comparison of two NCS-related copies of an Fab fragment, (iii) determination of the large and small domain of aspartate aminotransferase based on five structures representing different ligation states in four different crystal forms, (iv) derivation of the common core of seven different structures of pig pancreatic α-amylase in four different crystal forms and (v) derivation of rigid and flexible parts of the enzyme epimerase based on ten conformers related by non-crystallographic symmetry.

In all examples, the method is used for comparing Cα atoms only. It should be noted that the method is applicable to any set of atoms, such as, for example, atoms surrounding the active site of an enzyme.

2. Methods

2.1. Formulation of the optimization problem

The standard difference distance matrix contains elements Δ_ab corresponding to the difference in distance between two atoms i and j in two conformers M_a and M_b,

$$\Delta_{ij}^a = d_{ij}^a - d_{ij}^b.$$  

If estimates $\sigma(\Delta_{ij}^a)$ for the uncertainty of the matrix element $\Delta_{ij}^a$ are available, the corresponding error-scaled difference distance with elements $E_{ij}^a$ can be calculated (Schneider, 2000),

$$E_{ij}^a = \Delta_{ij}^a / \sigma(\Delta_{ij}^a).$$  

A rough approximation for $\sigma(\Delta_{ij}^a)$ has been suggested in Schneider (2000) based on the coordinate uncertainty of atoms i and j in models $M_a$ and $M_b$, $\sigma_{ij}^a$, $\sigma_{ij}^b$, $\sigma_{xi}^a$, $\sigma_{xb}^a$, $\sigma_{xi}^b$, and $\sigma_{xb}^b$:

$$\sigma(\Delta_{ij}^a) = \left[ (\sigma_{ij}^a)^2 + (\sigma_{ij}^b)^2 + (\sigma_{xi}^a)^2 + (\sigma_{xb}^a)^2 \right]^{1/2}. $$  

Values for atomic coordinate uncertainties $\sigma_{ij}$ can be calculated rigorously via the inversion of the normal matrix of the refinement (Sheldrick & Schneider, 1997) or estimated using a modified version of Cruickshank’s Diffraction Precision Indicator, DPI (Cruickshank, 1999; Schneider, 2000). According to Cruickshank, the coordinate error of an atom with a mean B value $B_{\text{avg}}$, $\sigma(x, B_{\text{avg}})$, can be estimated based on the number of fully occupied sites $N$, the number of unique reflections $n_{\text{obs}}$, the completeness of the data C, the free R value $R_{\text{free}}$ and the maximum resolution of the data $d_{\text{min}}$ (equation 27 in Cruickshank, 1999),

$$\text{DPI}_a = \sigma_a(x, B_{\text{avg}}) = (N/n_{\text{obs}})^{1/2} C^{-1/3} R_{\text{free}} d_{\text{min}}. $$  

In cases where $R_{\text{free}}$ is not known and the number of parameters $n_{\text{par}}$ is smaller than the number of observables $n_{\text{obs}}$, equation (26) from Cruickshank (1999),

$$\text{DPI}_a = \sigma_a(x, B_{\text{avg}}) = (N/p)^{1/2} C^{-1/3} R_{\text{DPI}} d_{\text{min}}. $$  

where $p = (n_{\text{obs}} - n_{\text{par}})$ and R equals the crystallographic R value, can be used to derive an estimated error. In a first approximation, assuming that coordinate uncertainties and B values are linearly related, the coordinate uncertainty for an individual atom with a B value of $B_a$ can be estimated as

$$\tilde{\sigma}_{a,ij} = \frac{\text{DPI}_{\text{B}a}}{B_{\text{avg}}} B_a, $$  

depending on whether DPI_a or DPI_d has been evaluated. To avoid extremely low errors for atoms with extremely low B values (that may well correspond to refinement artefacts), B values smaller than a certain value $B_{\text{low}}$ can be scaled up to $B_{\text{low}}$. In the computer program implementing the algorithm, the default value of $B_{\text{low}}$ is set to $B_{\text{avg}} - 2\sigma_B$, where $\sigma_B$ is the standard deviation of $B_{\text{avg}}$.

The goal of finding the conformationally invariant part of a molecule with respect to a set of n structural models $M = \{M_1, \ldots, M_n\}$ is equivalent to identifying a subset of the set of all atoms $A = \{a_1, \ldots, a_{n_{\text{par}}}\}$ for which for all pairs of atoms $ij$ the interatomic distance are identical in all models. Allowing for distances being imprecise owing to experimental errors, this condition can be relaxed to the condition that the difference in distances should not be significantly different from zero; in other words, for all pairs of models $ab$ and all pairs of atoms $ij$ belonging to the conformationally invariant subset, the respective elements of the error-scaled difference distance matrices $E_{ij}^{ab}$ should be smaller than a tolerance level $\epsilon_i$.

2.2. Implementation as a genetic algorithm

2.2.1. Encoding, fitness function and population. A candidate solution, or hypothesis, $\mathcal{H}$ about a subset of atoms being conformationally invariant can be conveniently encoded as a string $\mathcal{H}$ of length $n_{\text{atom}}$ over the binary alphabet $\{0, 1\}$,

$$\mathcal{H} = \{h_1 \ldots h_{n_{\text{atom}}}\} $$  

where the value or status of a bit $h_i$ depends on whether or not (0 or 1) an atom $i$ is considered to be a member of the conformationally invariant subset.

Based on the error-scaled distance differences, $E_{ij}^{ab}$, the fitness of an hypothesis can be measured using the following fitness function $S_{\mathcal{H}}$,

$$S_{\mathcal{H}} = \frac{1}{n_{\text{obs}} n_{\text{atom}}} \sum_{ij} \sum_{ab} \left\{ \epsilon_i - |E_{ij}^{ab}| \right\} \text{ for } |E_{ij}^{ab}| < \epsilon_i $$  

$$S_{\mathcal{H}} = p \times \min(|E_{ij}^{ab}|, \epsilon_k) \text{ for } |E_{ij}^{ab}| \geq \epsilon_i $$  

\( ^{\dagger} \text{research papers} \)


Schneider · Identification of conformationally invariant regions 197
This score is a weighted count over all relevant elements of all error-scaled difference matrices (the outer sum running over all possible pairs \(ab\) of models \(M_a\) and \(M_b\), the inner sum running over all elements \(ij\) of the respective EDD matrices that should be zero according to the hypothesis \(\mathcal{H}\)). For every matrix element that is consistent with the hypothesis, i.e. \(|E_{ab}^{ij}| < \epsilon_i\), the score is increased by a term \((\epsilon_i - E_{ab}^{ij})\). For matrix elements not consistent with the hypothesis, i.e. \(|E_{ab}^{ij}| \geq \epsilon_i\), the score is reduced by the size of the respective element scaled by a penalty factor \(p\). The choice of the penalty factor (typically between 5 and 20) allows one to adjust the fraction of non-zero matrix elements allowed for an acceptable solution. The matrix elements entering the penalty term are limited to a maximum of \(\epsilon_i\) in order to avoid instabilities in the evolutionary search caused by inclusion of single well defined atoms with extremely large conformational differences. Without this mechanism, inclusion of a single such atom into a hypothesis would have an extreme effect on the score, possibly rendering an otherwise well performing candidate solution useless. The normalization factor \(1/(n_{hyp}^\text{atom,\epsilon_i})\) is chosen such that for the case where the entire molecule is rigid and all elements of all error-scaled difference matrices are zero, a score of 1.0 is obtained.

Throughout the evolutionary search, a population of \(n_{hyp}\) hypotheses (where a typical value of \(n_{hyp}\) is 20) \(\mathcal{H}_k\) is maintained.

2.2.2. Genetic operators. To modify the population, the following genetic operators are used.

(i) Grow/Shrink. Moving from left to right, each bit of an \(\mathcal{H}\)-string is inverted if it corresponds to the beginning or end of a stretch of atoms continuous in sequence marked as conformationally invariant. The corresponding bit is kept inverted only if it results in an increased fitness. This operation is repeated iteratively until no further improvement of the score is achieved.

(ii) Recombination. Two hypotheses are taken, subdivided into ten non-overlapping regions (genes) of equal length and an offspring is constructed by recombining genes taken randomly from the two parent hypotheses.

(iii) Mutation. The status of a randomly chosen atom is inverted. The mutation is only kept if it leads to an improvement in the score \(S_{\mathcal{H}}\). In principle, in an evolutionary process mutations that lead to a temporary deterioration of the score may be beneficial in the long run, but experience has shown that for the present purpose permitting disadvantageous mutations can sometimes render the optimization process unstable (see §3.1). Permitting only advantageous mutations also speeds up convergence. A typical mutation rate is 5%.

2.2.3. The starting population. A starting population of \(n_{hyp}\) hypotheses is created by marking continuous overlapping stretches of length \(1.2 \times n_{atom}/n_{hyp}\) atoms as conformationally invariant. The Grow/Shrink operator is then applied to all hypotheses of the starting population and the central loop of the evolutionary algorithm implementing selection and reproduction is entered.

2.2.4. Evolution. A new generation is created from an existing population, modified and evaluated in six steps.

(i) Selection. After sorting the hypotheses with respect to their score, the low-scoring 30% of the hypotheses are destroyed and only the top-scoring 70% of the hypotheses are kept for subsequent reproduction.

(ii) Recombination including crossover. The now empty 30% of the slots are replenished by random recombination from the surviving hypotheses using the Recombination operator. To assign a higher mating probability for high-scoring individuals, each parent is selected by taking the highest scoring hypotheses of two successive random draws from the survivors of the previous generation.

(iii) Scoring. All \(n_{hyp}\) hypotheses are scored.

(iv) Mutation. All hypotheses undergo random mutagenesis where only mutations improving the fitness are kept (see Mutation operator above).

(v) Grow/Shrink. All members of the population develop using the Grow/Shrink operator.

(vi) Convergence check. Several criteria to stop the optimization process are evaluated. If no convergence criterion is fulfilled, the next generation is started from (i) (Selection).

2.2.5. Convergence. In most cases, the optimization will be terminated when the population is becoming homogeneous, i.e. most hypotheses are similar. Although identical scores are not necessarily equivalent to identical hypotheses for the general case, in the case of the present algorithm the homogeneity of a population can be measured as the standard deviation of its scores. If this standard deviation is smaller than a user-defined percentage \(p_{\text{std}}\) (by default, \(p_{\text{std}} = 1.0\%\)) of the mean score, further cycles are not likely to add any new information to the top-scoring hypothesis and the iteration is stopped.

To avoid the optimization becoming trapped in an oscillating situation, particularly in cases where very noisy matrices are analysed, the course of the top score is monitored. If the top score does not change for more than a number of generations (typically ten), the search is stopped.

Finally, if the number of generations reaches a user-defined limit (e.g. 50 generations), the search is interrupted.

2.2.6. Constraints. Acceptable solutions are not only characterized by a high score, but also should fulfill certain additional conditions to be physically reasonable. Two such conditions can be formulated: (i) conformationally invariant atoms should appear in consecutive stretches of a certain minimum length \(s_{\text{min}}\) and (ii) continuous stretches of conformationally invariant atoms should not be interrupted by single-atom outliers.

As the overall performance of the algorithm largely depends on the speed of the scoring, no constraints that would complicate the evaluation of the fitness function were implemented in the evolutionary search itself. Constraints are only imposed after the search has finished by modification of the top-scoring hypothesis: stretches shorter than \(s_{\text{min}}\) atoms are marked as flexible and the status of single flexible atoms in otherwise sequence-continuous stretches of conformationally invariant atoms are inverted. These constraints are of course only valid if the order of the atoms analysed has a physical meaning, as for example is normally the case for \(C^{\alpha}\) atoms.
which belong to successive amino-acid residues in a polypeptide chain; for cases where the sequence of atoms analysed is not related to their arrangement in three dimensions, these constraints should not be applied.

2.3. Identification of identical models

An important question that can be answered in terms of error-scaled difference is whether two models as a whole can be considered identical or not. Again, in principle, for two identical models all elements of the EDD matrix should be zero. In reality, this condition can be relaxed twofold to allow for experimental uncertainties: (i) elements whose modulus is smaller than a threshold \( \varepsilon_t \) are considered to be zero within error and (ii) a certain percentage of elements of the EDD matrix is allowed to have values larger than \( \varepsilon_t \).

If we consider two models consisting of \( N \) atoms each, where \( M \) of the \( N \) atoms are in significantly different positions, the number of zero-elements \( n_0 \) in the corresponding EDD matrix should still be larger than

\[
 n_0 = (N - M)^2 \geq N^2 - 2MN + M^2 \tag{9}
\]

where \( (N - M)^2 \) is the number of elements in the block of the matrix that corresponds to the conformationally invariant part of the model, or, expressed as a percentage of zero elements with respect to all elements,

\[
 p_0 = \frac{N^2 - 2MN + M^2}{N^2} = 1 - 2\frac{M}{N} + \left( \frac{M}{N} \right)^2. \tag{10}
\]

If we now replace \( M/N \) by the percentage of atoms that are significantly different, \( p_d = M/N \), we obtain the following equation for the corresponding percentage of EDD-matrix elements that should still be zero if a percentage \( p_d \) of atoms is in different conformations in the two conformers being compared,

\[
 p_{0,p_d} = 1 - 2p_d + p_d^2. \tag{11}
\]

If we allow 1\% of the atoms to be in different relative positions (i.e. \( p_d = 0.01 \)), we obtain

\[
 P_{0.01} = 1 - (2 \times 0.01) + 0.01^2 = 0.9801. \tag{12}
\]

2.4. Computers and other programs used

All calculations were performed on a PC with a Pentium III processor running at 800 MHz under Linux Kernel Version 2.2.16. All least-squares superpositions were performed using LSQKAB (Collaborative Computational Project, Number 4, 1994; Kabsch, 1976). Schematic figures of protein molecules were prepared using MOLSCRIPT (Kraulis, 1991) and Raster3D (Merritt & Murphy, 1994).

3. Examples

3.1. Chorismate mutase

The structure of the functional unit of chorismate mutase from Bacillus subtilis, a homotrimer, has recently been determined to a resolution of 1.3 Å (Ladner et al., 2000). The crystals used belonged to space group \( P2_12_12_1 \) (unit-cell parameters \( a = 52.2, b = 83.8, c = 86.0 \) Å) with three crystallographically independent monomers in the asymmetric unit. Out of the 127 residues in a monomer, the first 116 residues form a compact structure of \( \beta \)-strands and helices; the C-terminal residues 117–127 are found in different conformations in each of the three monomers (Fig. 2).

DPI values were calculated based both on \( R \) and \( R_{free} \) (Table 1) and the resulting \( R_{free} \)-based value was found to be somewhat higher than the value obtained using \( R \). As DPI, is more robust with respect to overfitting (which in fact could be the case to a small extent for a full anisotropic model with data extending to 1.3 Å) than DPI, all subsequent calculations are based on the DPI.

For the three molecules, three error-scaled \( C^\alpha/C^\alpha \) difference distance matrices with 8001 independent elements each were calculated and analysed. The uncertainties for the differences in \( C^\alpha/C^\alpha \) distances \( \sigma(D_{\alpha}^{\alpha}) \) (3) ranged from 0.048 Å for atom pairs with low \( B \) factors to 0.285 Å for atom pairs with high \( B \) factors, with a mean value of 0.097 Å. The corresponding error-scaled difference distance matrix cut at a lower limit of \( \varepsilon_t \) of 5\( \sigma \) (Fig. 1a) very clearly shows that the major difference between the molecules \( A \) and \( B \) is the conformation of about ten residues at the C-terminus. Beside this, the second half of the first helix (residues 28–33) and a short loop preceding the C-terminus (residues 101–104) are marked as having different conformations relative to the major part of the protein.

### Table 1

Data used for the calculation of Cruickshank’s DPI for the structures investigated in this paper.

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<th>( n_{in} )</th>
<th>( P_{cl} ) (%)</th>
<th>( R(%) )</th>
<th>( R_{free} ) (%)</th>
<th>( d_{\min } ) (Å)</th>
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</table>

† As the model was refined with anisotropic displacement parameters for all non-H atoms, \( n_{free} \) was set to 9 \( \times N_i \) and \( cpl. \) was taken from the publication. § All values were taken from the publication (Hohenester & Janssenus, 1994). ‡ Value for cpl. was taken from the publication.
Using standard parameters \( (n_{hyp} = 20, w_p = 20.0, r_{mut} = 5.0\% ) \) and lower and upper tolerance levels of \( \varepsilon_l = 5.0 \) and \( \varepsilon_h = 10.0 \), respectively, the GA identified (using 5.0 s of CPU time), in very good agreement with the manual interpretation of the EDD matrix, 103 of the 127 atoms as conformationally invariant (Fig. 1a). All these residues (2–27, 34–101, 105–113) are located in the N-terminal domain of the protein (Fig. 2).

When the limits for display and the automatic search were reduced to \( \varepsilon_l = 2.0 \) and \( \varepsilon_h = 5.0 \), many more matrix elements showed a signal and manual interpretation became substantially more complicated if not impossible (Fig. 1b). Running the automatic procedure using the smaller tolerance levels and standard parameters otherwise \( (n_{hyp} = 20, w_p = 20.0, r_{mut} = 5.0\% ) \), the rigid part was found to be substantially smaller. Residues 3–13, 48–52 and 86–95, i.e. only 26 residues, exclusively located in a small region of the central \( \beta \)-sheet, were now identified. This subset of residues is not completely continuous in sequence but is nevertheless continuous in three-dimensional space (Fig. 2). Here it should be noted that apart from the application of the constraints to atoms close in primary sequence as described in §2.2.6, no information about connectivity in three dimensions is used in the algorithm.

The C\(^\alpha\) atoms of these 26 residues are sufficient to afford a robust superposition using standard least-squares superposition techniques, yielding mean r.m.s. deviations of 0.10 and 0.11 Å for superimposing molecule B and molecule C onto molecule A, respectively. The overall picture of a floppy C-terminus stays valid, while the superposition based on this small subset reveals small but significant conformational differences in the at first sight rigid N-terminal domain. This observation relates to the fact that at a resolution of 1.3 Å, at least for atoms with low \( B \) factors, changes in relative position of the order of 0.1 Å are definitely significant.

In this example, the differences in interatomic distances are rather large for some atoms in the C-terminal region (up to more than 10 Å corresponding to more than 100\( \sigma \) of the interatomic distance in some cases). In an early version of the algorithm, inclusion of an atom from this region often caused the evolutionary search to become unstable because well performing hypotheses were ruined by inclusion of one ‘wrong’ atom during the phase of random mutation. This

![Figure 1](image-url)

**Figure 1**
Error-scaled difference distance matrices for molecules A and B of chorismate mutase. All changes in distances smaller than a threshold (5\( \sigma \) and 2\( \sigma \) for a and b, respectively) are shown in grey; differences between this lower limit and an upper limit of 10\( \sigma \) (5\( \sigma \) for b) are shown using a colour gradient where red stands for expansion and blue for contraction, light colours represent small changes and dark colours large changes; all differences larger than the upper limit are shown as full blue and full red, respectively. The gradients used for colour coding are also shown separately at the bottom of the figure. The bar underneath the matrix in the foreground shows the secondary structure as white (\( \alpha \)-helices) and black (\( \beta \)-strands) rectangles. The background of the secondary-structure scheme indicates parts of the protein that were identified to be conformationally invariant (dark grey) using a tolerance \( \varepsilon_l \) of 5\( \sigma \) (a) or 2\( \sigma \) (b), respectively. For clarity, the matrices underwent 2 \times 2 binning (maintaining the element with the highest absolute value in the respective binning area) before being displayed.
problem was overcome by limiting the penalty term (8) and by only accepting mutations that improve the score of a hypothesis.

3.2. Fab fragment

Antibodies consist of immunoglobulin domains connected by hinge regions allowing variability in the orientation of the domains with respect to each other. As, owing to this flexibility, the crystallization of intact antibodies is rather difficult, many studies of antibodies are based on the crystal structure of Fab fragments (Branden & Tooze, 1999). In the case of an Fab fragment from human myeloma immunoglobulin studied by Saul & Poljak (1992), orthorhombic crystals in space group \( P_{2_1}2_12_1 \) (unit-cell parameters \( a = 110.6, b = 127.4, c = 66.5 \) Å) contain two Fab fragments in the asymmetric unit.

The DPI value based on the \( R \) value against all data was calculated to be 0.15 Å (Table 1), resulting in estimates for the coordinate errors for \( C^\alpha \) atoms ranging between 0.048 and 0.389 Å.

The error-scaled difference distance matrix for the comparison of the two Fab fragments (Fig. 3a) clearly reveals that the Fab fragment consists of four mostly rigid domains that can move relative to one another: the matrix contains four ‘empty’ blocks along the diagonal corresponding to the variable (N-terminal) and the constant (C-terminal) parts of both the light (chain A) and the heavy (chain B) chain of the antibody.

Using standard parameters \( n_{\text{hyp}} = 20, w_p = 20.0, r_{\text{mut}} = 5.0\% \) and lower and upper tolerance levels of \( \varepsilon_l = 2.0 \) and \( \varepsilon_h = 5.0 \), respectively, the GA identified (using 2.0 s of CPU time to analyse one matrix with 82 215 unique elements) residues \( B_1\ldots B_{11}, B_{14}\ldots B_{101} \) and \( B_{108}\ldots B_{122} \), i.e. most residues of the variable domain of the heavy chain, as the largest conformationally invariant part.

Superposition of the two NCS-related conformers of the heavy chain based on the 114 conformationally invariant \( C^\alpha \) atoms resulted in a mean r.m.s. deviation of 0.213 Å, which is of the order of the experimental error.

Fig. 3(b) clearly shows the difference in relative orientation of the constant and the variable domain arising from localized structural changes in the so-called elbow region. This movement of the domains relative to one another has been observed previously in many cases (e.g. Strong et al., 1991; Kleywegt, 1996). In addition, there is a small but significant movement of residues B12 and B13 that is mediated by a contact of the amide group of Glu13B to the moving part of the elbow region. The other part of the variable half of the heavy chain that is found to be flexible is the CDR 3 region of this chain. This region is known to be the most flexible of the loops involved in antigen recognition (Brändén & Tooze, 1999).

To fully rationalize the flexibility of this Fab fragment, the algorithm used to identify the largest conformationally invariant part should be applied iteratively to identify all rigid domains. This will be the subject of future work.
3.3. Mitochondrial aspartate aminotransferase

Mitochondrial aspartate aminotransferase from chicken is a classic example of an enzyme where binding of a substrate induces a transition from an open to a closed conformation. Following a division suggested by McPhalen, Vincent, Picot et al. (1992), the molecule is composed of a large (residues 48–325) and a small (residues 15–47 and 326–410) domain (Fig. 5a).

In an initial comparison (McPhalen, Vincent & Jansonius, 1992) of an open unliganded (PDB code 7aat) and a closed liganded form (PDB code 1ama) using the sieve fitting procedure (Lesk & Chothia, 1984), the conformationally invariant part of the molecule was determined to contain residues 4–12, 50–161, 167–195, 199–224 and 233–309. 2 y later, Hohenester & Jansonius (1994) presented another detailed conformational analysis of the enzyme with and without substrate, but now based on the comparison of five crystal structures in four different crystal forms. This analysis led to the conclusion that the enzyme exists in only two unique conformations (an open one and a closed one) and the domain structure found earlier was confirmed. An overview of the five structures discussed by Hohenester & Jansonius (1994) is given in Table 2.

The parameters relevant for the calculation of DPI values for the five structures are given in Table 1. Owing to the low resolution for 1tas and 1tat, the number of parameters refined is larger than the number of observables, precluding the use of (5). As there are also no $R_{free}$ values available for these two refinements, (4) also cannot be used. To be able to include these two models in the analysis despite the fact that no reliable indicators of the quality of the models were available, coordinate uncertainties were calculated based on $R_{free}$ values deliberately assumed to be 30.0%. The resulting values for DPI are rather high (0.53 and 0.54 Å for 1tas and 1tat, respectively) reflecting the rather limited information content of the two models.

The first step of the analysis concerned the identification of models representing identical conformations. Towards this objective, EDD matrices for $C^\alpha$ atoms were calculated for all possible pairs of models and the percentage of matrix elements larger than a given tolerance was evaluated (Table 3). Employing the criterion that two models are identical at a given tolerance level $\varepsilon_l$ if for more than 98% of the elements of the respective EDD matrix the absolute value is smaller than $\varepsilon_l$ (see §2.3), the five models could be divided into two groups using a tolerance of $\varepsilon_l = 2.0\sigma$ (Table 3). One group comprises the two models representing the open form, 7aat and 1tar and...
the other group contains the three models representing the closed form, 1ama, 1tas and 1tat. It should be noted that the absence of significant differences between the different models for the closed form partly reflects the relatively high uncertainty assigned to the coordinates of 1tas and 1tat. Taking the most precisely determined representative of each of the two sets, it remained to compare 7aat and 1ama. The error-scaled difference distance matrix (Fig. 4) clearly shows the division of the protein into the two domains as defined earlier. The automatic analysis of the 80 200 matrix elements using a tolerance of $e_1 = 2.0\sigma$ took 6.0 s of CPU time and flagged 281 atoms (residues 4–12, 47–226 and 232–329) as conformationally invariant. This set of conformationally invariant atoms is in very good agreement with the set defined by McPhalen and coworkers (4–12, 50–161, 167–195, 199–224 and 233–309). Apart from small variations at the boundaries of the flagged regions, only two regions, 162–166 and 196–199, located at the interface between the large and the small domain are categorized differently in the present analysis. For residues 162–166, the $B$ values of all C$\alpha$ atoms are above the average $B$ value for C$\alpha$ atoms. As a consequence, the structural differences in this region, although being substantial on an absolute scale, are not considered to be significant in the present analysis. If a second analysis is run employing a lower tolerance level of $e_1 = 1.0\sigma$, residues 196–199 (and also residues 162–166) are in fact excluded from the conformationally invariant part, indicating that the conformational changes observed are on the border of being significant.

**Figure 4**
Error-scaled difference distance matrix for the two most precise models of aspartate aminotransferase in the open and in the closed conformation (7aat and 1ama, respectively). Colour coding, secondary-structure representation and rigid-body marking are as in Fig. 1. Red tickmarks and residue numbers correspond to stretches of residues not present in one or both of the models. The matrix underwent $4 \times 4$ binning before being displayed.

**Figure 5**
(a) Secondary structure of aspartate aminotransferase. Parts identified as conformationally invariant are shown in blue, flexible regions in red, the cofactor PLP and the lysine side chain it is bound to are shown in grey to indicate the the active site. (b) Superposition of 7aat (blue and dark red) and 1ama (blue and light red) using the 281 conformationally invariant atoms. This view is related to the view in (a) by a rotation of 90° about the vertical axis.
The largest discrepancy in categorization is found for residues 309–329, corresponding to the N-terminal half of the long $\alpha$-helix (helix 13, Fig. 5) connecting the two domains. McPhalen and coworkers observed that ‘the first part of helix 13 rotates by $4^\circ$ and shifts by 0.4 Å’ (McPhalen, Vincent, Picot et al., 1992) upon domain closure and therefore did not include this region in the rigid part of the molecule. Furthermore, they found that in the C-terminal part the helix moves around a kink angle whose centre is located in the region of residue 328–330. The movement of the first part of the helix is not detected as being significant in the present analysis. The kink region is clearly indicated by the last residue of the conformationally invariant region being identified as residue 329. In fact, in a recent analysis of the different X-ray conformers of aspartate aminotransferase using the DYNDOM approach, the N-terminal half of helix 13 is also included in the large rigid domain and the domain boundary is located at residue 328 (Hayward, 1999). The DYNDOM analysis also includes residues 162–166 and 196–199 in the rigid part of the molecule.

### 3.4. Pig pancreatic $\alpha$-amylase

Pig pancreatic $\alpha$-amylase is a sugar-cleaving enzyme consisting of 496 residues with a total molecular weight 55.3 kDa. As of January 2001, the PDB contained seven entries for porcine pancreatic amylase (E.C. 3.2.1.1, SwissProt P00690) in four different crystal forms. There is one structure of the native protein alone (1pif) and six structures with different ligands (Table 4). The molecule is composed of a large domain (residues 1–403) consisting of an eightfold $\alpha/\beta$-barrel and a small domain (residues 404–496) folding into a compact Greek key $\beta$-barrel (Fig. 7).

The coordinate errors were estimated using (4) and (5) depending on whether or not free $R$ values were available. The coordinate precision was found to be between 0.12 and 0.20 Å for the majority of the structures (Table 1). Exceptions are 1ppi and 1bvn, for which higher mean coordinate uncertainties of 0.26 and 0.37 Å are observed. In the case of 1ppi, the relatively low solvent content (46%, Table 4) results in a worse ratio of observables to parameters than for structures refined to a comparable resolution but with a higher solvent content, for example, 1pig, 1pif and lose with a solvent content of 72% (Table 4). For 1bvn, the low completeness of the X-ray data (probably owing to experimental difficulties connected with the relatively long $c$ axis of the crystallographic unit cell) has a deleterious effect on the coordinate precision.

### Table 2

Crystallographic data for AATase structures discussed in Hohenester & Jansonius (1994).

7aat and 1tar correspond to the two open structures and 1ama, 1tas and 1tat to the three closed structures (OP1, OP2 and CL1, CL2, CL3, respectively, in Hohenester & Jansonius, 1994). 7aat supersedes the structure determined previously under the same conditions but at lower resolution by Ford et al. (1980). PLP stands for pyridoxal-5'-phosphate.

<table>
<thead>
<tr>
<th>PDB code</th>
<th>Space group</th>
<th>a, b, c (Å)</th>
<th>$\alpha, \beta, \gamma$ (°)</th>
<th>Ligand and reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>7aat</td>
<td>$P_{1}$</td>
<td>55.6, 58.7, 75.9</td>
<td>85.2, 109.2, 115.6</td>
<td>None (McPhalen, Vincent, Picot et al., 1992)</td>
</tr>
<tr>
<td>1tar</td>
<td>$P_{1}$</td>
<td>57.4, 59.4, 65.50</td>
<td>83.1, 104.8, 83.3</td>
<td>None (Hohenester &amp; Jansonius, 1994)</td>
</tr>
<tr>
<td>1ama</td>
<td>$C_{222_{1}}$</td>
<td>69.7, 91.4, 128.5</td>
<td>90.0, 90.0, 90.0</td>
<td>$\alpha$-Methylaspartate (McPhalen, Vincent, Picot et al., 1992)</td>
</tr>
<tr>
<td>1tas</td>
<td>$P_{2}_{1}$</td>
<td>57.4, 52.4, 136.9</td>
<td>90.0, 101.5, 90.0</td>
<td>$\alpha$-Methylaspartate (Hohenester &amp; Jansonius, 1994)</td>
</tr>
<tr>
<td>1tat</td>
<td>$P_{2}(2,2)_{1}$</td>
<td>69.5, 89.6, 144.7</td>
<td>90.0, 90.0, 90.0</td>
<td>Maleate (Hohenester &amp; Jansonius, 1994)</td>
</tr>
</tbody>
</table>

### Table 3

Percentage of error-scaled difference distance matrix elements smaller than 2$\sigma$ for all pairwise comparisons of 7aat, 1tar, 1ama, 1tas and 1tat. Cases for which the percentage is larger than 98.0 are in bold.

<table>
<thead>
<tr>
<th></th>
<th>7aat</th>
<th>1tar</th>
<th>1ama</th>
<th>1tas</th>
<th>1tat</th>
</tr>
</thead>
<tbody>
<tr>
<td>7aat</td>
<td>100.0</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1tar</td>
<td>73.3</td>
<td>76.3</td>
<td>82.0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1ama</td>
<td>81.9</td>
<td></td>
<td>84.5</td>
<td>86.8</td>
<td></td>
</tr>
<tr>
<td>1tas</td>
<td></td>
<td>100.0</td>
<td>100.0</td>
<td>100.0</td>
<td></td>
</tr>
<tr>
<td>1tat</td>
<td></td>
<td></td>
<td>100.0</td>
<td>100.0</td>
<td>100.0</td>
</tr>
</tbody>
</table>
A first round of EDD-matrix analysis including all seven models revealed that four structures (1ppi, lose, 1pif and 1pig) fulfill the criterion for being identical (§2.3) for all their pairwise comparisons at the 2.0σ level (Table 5). Interestingly, this group contains both structures with the largest DPI values: for these two structures the absolute differences in conformation would need to be rather large to be significant. Of this group of identical structures, only one representative, namely the structure with the lowest coordinate uncertainty, 1pig, was retained for further analysis.

1pig and the remaining three models, 1bvn, 1dhk and 1jfh were then subjected to rigid-body analysis with standard parameters (n¬hyp = 20, wp = 20.0, e¬j = 2.0, e¬h = 5.0, r¬mut = 5.0%). The evolutionary search against six EDD matrices containing a total of 855 855 elements converged to homogeneity after 413 out of 495 residues as conformationally invariant. Table 4 highlights the key differences in the structures.

Table 4
Crystallographic data for structures in the PDB containing pig pancreatic α-amylase (as of 31 January 2001).

<table>
<thead>
<tr>
<th>PDB code</th>
<th>Space group</th>
<th>Unit-cell parameters</th>
<th>SC (%)</th>
<th>d¬min (Å)</th>
<th>Ligand and reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>1pig</td>
<td>P212121</td>
<td>a, b, c (Å) 70.5, 114.8, 118.7</td>
<td>90.0, 90.0, 90.0</td>
<td>72</td>
<td>2.2</td>
</tr>
<tr>
<td>1ppi</td>
<td>P212121</td>
<td>a, b, c (Å) 70.7, 114.9, 118.9</td>
<td>90.0, 90.0, 90.0</td>
<td>72</td>
<td>2.3</td>
</tr>
<tr>
<td>llose</td>
<td>P212121</td>
<td>a, b, c (Å) 70.6, 114.7, 118.5</td>
<td>90.0, 90.0, 90.0</td>
<td>72</td>
<td>2.3</td>
</tr>
<tr>
<td>1jfh</td>
<td>P212121</td>
<td>a, b, c (Å) 56.3, 87.8, 103.4</td>
<td>90.0, 90.0, 90.0</td>
<td>45</td>
<td>2.03</td>
</tr>
<tr>
<td>1ppi</td>
<td>P212121</td>
<td>a, b, c (Å) 56.3, 87.8, 103.4</td>
<td>90.0, 90.0, 90.0</td>
<td>46</td>
<td>2.2</td>
</tr>
<tr>
<td>1dhk</td>
<td>C2</td>
<td>a, b, c (Å) 151.6, 79.4, 68.0</td>
<td>90.0, 91.5, 90.0</td>
<td>56</td>
<td>1.85</td>
</tr>
<tr>
<td>1bvn</td>
<td>P622</td>
<td>a, b, c (Å) 77.7, 77.7, 359.5</td>
<td>90.0, 90.0, 120.0</td>
<td>51</td>
<td>2.5</td>
</tr>
</tbody>
</table>

Employing the 205 conformationally invariant Cα atoms for least-squares superposition of all molecules onto molecule A gave mean r.m.s. deviations between 0.11 and 0.18 Å with a pathogenic bacteria. The structure of the enzyme in complex with NADP and ADP-glucose has been determined to a resolution of 2.0 Å using monoclinic crystals (space group P21; unit-cell parameters a = 99.5, b = 109.8, c = 181.5 Å, β = 91.0°) by Deacon et al. (2000). Architecturally, the protein molecule can be subdivided into an N-terminal and a C-terminal domain (residues 1–167, 214–236 and 280–292, and residues 168–213, 237–279 and 293–310, respectively; Fig. 8a). The N-terminal domain binds NADP and consists of a modified Rossmann fold with a central seven-stranded β-sheet flanked on either side by a total of seven helices. The C-terminal domain consists of an arrangement of two small β-sheets and three α-helices. The asymmetric unit contains two pentamers and superposition of the ten crystallographically independent molecules revealed that the individual molecules adopt slightly different conformations depending on the crystal packing. As parts of the sequence could not be built for all of the model, the following analysis is limited to the 271 Cα atoms present in all ten molecules of the model.

An initial inspection of all pairwise comparisons to establish which conformers are identical according to the criterion defined in §2.3 did not reveal any consistent sets of identical molecules.

Running the GA with standard parameters (n¬hyp = 20, wp = 20.0, e¬j = 2.0, e¬h = 5.0, r¬mut = 5.0%), convergence to homogeneity was reached after six generations (20.9 s CPU time) and 205 of 271 Cα atoms were marked as conformationally invariant. The residues selected as rigid (1–21, 24–79, 86–120, 125–177, 210–238 and 278–288) fit well with the domain structure of the protein described above. One half of the protein provides a rigid scaffold in which the cofactor is embedded. An inspection of the residues marked as rigid (271 atoms) shows that they are mostly found for residues 22 and 23 (a glycine and a lysine in a surface loop region) and 80–85 and 121–124 (both loops protruding from the C-terminal towards the substrate binding site). Most of the C-terminal half of the polypeptide chain is flexible. However, the regions of the C-terminal half for which the chain returns into the N-terminal domain are rigid again: these rigid parts include residues 210–238 (adding another helix and the seventh β-sheet to the modified Rossmann fold) and residues 278–288 comprising a short helix interacting with the central β-sheet).

Employing the 205 conformationally invariant Cα atoms for least-squares superposition of all molecules onto molecule A gave mean r.m.s. deviations between 0.11 and 0.18 Å with a
mean value of $0.14 \pm 0.02$ Å. These deviations are comparable to the coordinate error estimated via the DPI method, DPI$_l = 0.17$ Å (Table 1), and are significantly smaller than the mean r.m.s. deviation of 0.39 ± 0.07 Å that was obtained when all 271 C$_\alpha$ atoms present in all molecules were superimposed.

A graphical representation of the superposition of the ensemble of structures highlights the rigidity of the C-terminal domain and the flexibility of the N-terminal domain (Fig. 8b). The superposition also shows that the ensemble of conformers can be divided into two groups, one corresponding to a more open and the other to a more closed form (see also Deacon et al., 2000).

### 4. Conclusions and future perspectives

A genetic algorithm for the identification of the part of a protein molecule that is conformationally invariant with respect to a set of $N$ conformers has been designed, implemented and tested on five examples using a standard set of parameters. As a result of the acceleration provided by the application-specific genetic operators (§2.2.2), the algorithm converges rapidly and the results are in good agreement with elaborate manual analysis. Genetic algorithms are particularly suitable for this problem because hypotheses can be expressed in sequential binary form and partially correct solutions begin to have a positive influence on the fitness at an early stage.

This tool being available, the following general procedure for comparing a set of models of a molecule can be suggested: (i) identification and removal of redundant conformers, (ii) identification of a set of conformationally invariant atoms with respect to the non-redundant set of conformers, (iii) least-squares superposition of all models using the conformationally invariant subset only and (iv) graphical inspection of the results.

The first step can be performed by calculating error-scaled difference distance matrices for all pairs of conformers in the initial set. If groups of conformers turn out to be not significantly different, as indicated by a small number of non-zero elements in the corresponding error-scaled difference distance matrix (see §2.3), only the most precise conformer of each set of identical models is retained for the subsequent analysis. This will speed up the analysis and more importantly will avoid bias in the selection of the conformationally invariant atoms caused by multiple inclusion of identical models. In the future, this clustering analysis could be automated employing clustering algorithms such as that described by Kelley et al. (1996).

The central step of the procedure, the identification of the rigid part of the molecule by simultaneous analysis of a potentially large number of conformers, is facilitated by the genetic algorithm presented. The algorithm can analyse a large number of complex difference distance matrices very rapidly using only moderate computing resources. Moreover, such an automated procedure is more objective than an iterative manual procedure.

A standard set of parameters has been shown to work under rather different circumstances. Nevertheless, in the case that no satisfactory result is obtained with the standard parameter set, the parameters can be changed by the user of the program. One problematic scenario is the comparison of models suffering from serious systematic errors. For such cases, difference distance matrices will be very noisy even after the application of error-scaling and it may be necessary to choose rather high tolerance levels $\varepsilon_j$ to obtain any reasonable results. On the other hand, if well determined crystal structures are used, reduction of $\varepsilon_j$ may be beneficial in order to impose an extremely strict criterion for conformational invariance. Such lower tolerance levels will of course yield smaller sets of atoms to be used for superposition. Theoretically at least, this is not a problem, as in principle three non-collinear atoms are sufficient for a least-squares superposition of molecules in three dimensions. However, in reality a larger number of atoms is advantageous in order to perform a statistically robust superposition. The parameters governing the evolutionary search (number of hypotheses, creation of the starting population, mutation rate etc.) normally do not have to be changed.

The least-squares superposition itself can be performed using classical least-squares methods, such as the one implemented in LSQKAB (Kabsch, 1976). Such standard least-squares methods, however, do not weight the residual coordinate difference with respect to the coordinate precision.

### Table 5

<table>
<thead>
<tr>
<th>Pig amylase structure</th>
<th>EDD elements smaller than 2σ</th>
</tr>
</thead>
<tbody>
<tr>
<td>lbn</td>
<td>95.2 96.3 97.7 97.5 98.8 96.5</td>
</tr>
<tr>
<td>ldb</td>
<td>88.9 93.8 90.9 92.0 89.9</td>
</tr>
<tr>
<td>lpf</td>
<td>99.5 98.5 96.4 97.8</td>
</tr>
<tr>
<td>lppi</td>
<td>99.9 98.6 99.9</td>
</tr>
<tr>
<td>lose</td>
<td>98.9 100.0</td>
</tr>
<tr>
<td>lpf</td>
<td>98.1</td>
</tr>
</tbody>
</table>

Figure 7


---

of the atoms involved, allowing the superposition to be too strongly influenced by large coordinate differences between atoms of high coordinate uncertainty. To alleviate this problem, we are working on the implementation of an uncertainty-weighted least-squares superposition algorithm. Meanwhile, one possibility is to rerun the present algorithm with a very strict tolerance criterion: this will automatically identify a subset of the set of the conformationally invariant atoms that is rigid and has a low coordinate error.

Finally, displaying the results on a computer graphics system in a suitable format will in many cases allow intuitive interpretation of the results.

The entire procedure crucially depends on accurate error-estimates and, of course, on the models employed being essentially correct and the associated statistics being reliable. Although Cruickshank’s DPI gives a good first-order approximation, it would be desirable to have more accurate estimators of coordinate precision. A more complex functional form with empirically optimized parameters could be an improvement (Cruickshank, 1999). Ideally, coordinate uncertainties would be calculated directly from the experimental data, an obvious choice being an estimate based on real-space correlation coefficients (Jones et al., 1991). Technically, such data-based estimates require the diffraction data to be available at the time of the calculation, which unfortunately is not always the case, as diffraction data are not always deposited together with the model coordinates (Jiang et al., 1999). So far, the method has only been applied to C-atoms as ‘representatives’ of overall protein conformation. The algorithm is equally well applicable to, for example, P atoms in RNA structures or to the study of the changes in relative positions of atoms in an active site when different substrates or inhibitors are bound.

Furthermore, iterative application of the method would allow the delineation of not only the largest but also smaller domains in order to characterize multi-domain structures both in terms of the identification of the domains and the description of their relative motions (Verbitsky et al., 1999; Gerstein & Krebs, 1998; Berendsen & Hayward, 1998). This will be the subject of future work.

Currently, the method is limited to the analysis of different conformers of the same molecule. A generalization of the algorithm for cases where closely homologous structures are compared and a robust mapping of corresponding atoms in three dimensions can be achieved using existing methods such as DALI (Holm & Sander, 1993), which is also based on difference distance matrices, is a mostly technical problem [for recent reviews concerning structure alignment see, for example, Lemmen & Lengauer (2000) and Eidhammer et al. (2000)]. Such a superposition of homologous models taking the different level of precision into account would not only be useful from a structure-analysis point of view but could also be used to construct hybrid models for use in difficult molecular-replacement cases as suggested by Read (2001).

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References


