

Top-k Keyword Search over Wikipedia-based RDF Knowledge Graphs

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Abstract: Effective keyword search over RDF knowledge graphs is still an ongoing endeavor. Most existing techniques have their own limitations in terms of the unit of retrieval, the type of queries supported or the basis on which the results are ranked. In this paper, we develop a novel retrieval model for general keyword queries over Wikipedia-based RDF knowledge graphs. Our model retrieves the top-k *scored* subgraphs for a given keyword query. To do this, we develop a scoring function for RDF subgraphs and then we deploy a graph searching algorithm that only retrieves the top-k scored subgraphs for the given query based on our scoring function. We evaluate our retrieval model and compare it to state-of-the-art approaches using YAGO, a large Wikipedia-based RDF knowledge graph.

1 INTRODUCTION

Many large RDF knowledge graphs such as YAGO (Suchanek et al., 2008), DBpedia (Auer et al., 2007), and Google’s knowledge graph have been constructed from Wikipedia. These graphs are labeled graphs consisting of billions of edges where node labels are either URIs representing resources or literals, and edge labels are URIs representing predicates. For example, Figure 1 shows a snippet of an RDF knowledge graph about books. Such RDF knowledge graphs can be typically queried using a graph-pattern query language such as SPARQL. The results of a SPARQL query are subgraphs from the knowledge graph that are isomorphic to the graph pattern in the query.

Even though graph-pattern query languages are very powerful, they are also very restrictive. They require some expertise as well as familiarity with the underlying data (i.e., the exact URIs of resources and predicates). Enabling keyword search over RDF knowledge graphs can increase the usability of such data sources. In addition, it enables adapting state-of-the-art Information Retrieval searching and ranking techniques.

In this paper, we propose a top-k retrieval model for keyword queries over large Wikipedia-based RDF knowledge graphs such as YAGO or DBpedia. Our model takes as input a keyword query and retrieves the top-k *subgraphs* that match the query. For example, Table 1 shows the top-3 subgraphs for the query

“books by Pulitzer prize winners” from our example knowledge graph in Figure 1, where the goal is to find books by Pulitzer prize winners. In a nutshell, our approach works as follows. First, we create inverted indices for the resources and the predicates in the knowledge graph (i.e., node and edge labels). We also associate each edge in our knowledge graph with a weight reflecting the importance of the edge, which is derived from the Wikipedia link structure as well as the degrees of the nodes. We then develop a novel scoring function for RDF subgraphs, which is based on the edge weights. Finally, we develop a top-k searching algorithm that explores the knowledge graph starting from the query keywords and stops once the top-k scored subgraphs are retrieved. Our search algorithm is easily parallelizable and we use the parallelized version in our experiments.

Our contributions can be summarized as follows:

1. We develop a novel scoring function for general keyword queries over Wikipedia-based RDF knowledge graphs.
2. We develop a graph search algorithm that retrieves only the top-k scored subgraphs for a given keyword query.
3. We prove that our search algorithm terminates only when the top-k subgraphs are retrieved.

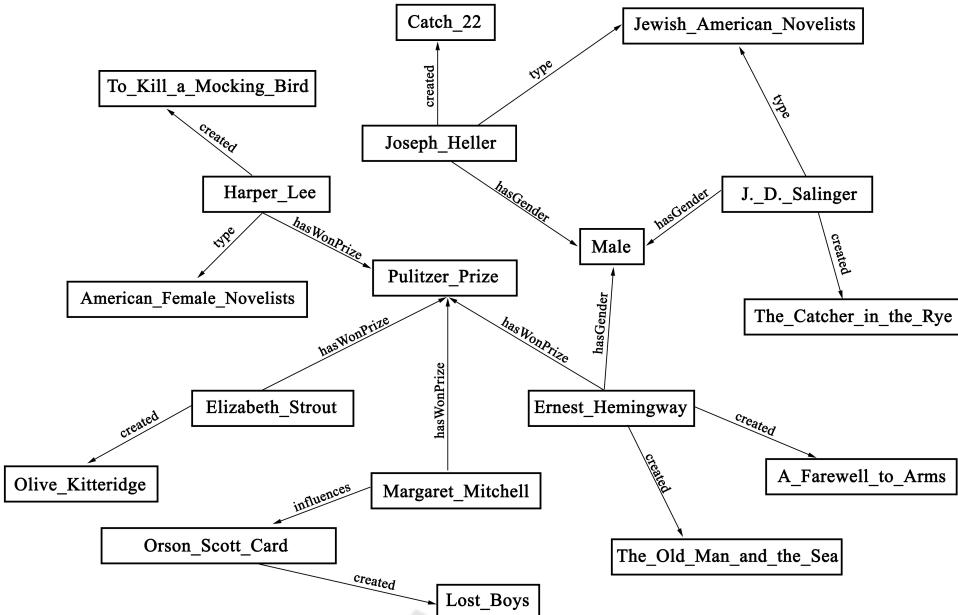


Figure 1: An example RDF knowledge graph about books.

Table 1: Top-3 subgraphs for the query “books by Pulitzer prize winners”.

1	Ernest_Hemingway created The_Old_Man_and_the_Sea Ernest_Hemingway hasWonPrize Pulitzer_Prize
2	Ernest_Hemingway created A_Farewell_to_Arms Ernest_Hemingway hasWonPrize Pulitzer_Prize
3	Harper_Lee created To_Kill_a_Mocking_Bird Harper_Lee hasWonPrize Pulitzer_Prize

2 RELATED WORK

Many techniques have been proposed for keyword search over graphs (Sima and Li, 2016; He et al., 2007; Kargar and An, 2011; Le et al., 2014; Dalvi et al., 2008; Mass and Sagiv, 2016; Tran et al., 2009; Li et al., 2008; Fu and Anyanwu, 2011; Golenberg et al., 2008; Kasneci et al., 2009; Bhalotia et al., 2002; Dass et al., 2016; Yuan et al., 2017). Most of these techniques have their own limitations. For instance, some techniques assume the unit of retrieval to be (Steiner) trees (Golenberg et al., 2008; Kasneci et al., 2009; Bhalotia et al., 2002; Sima and Li, 2016; Mass and Sagiv, 2016), while in the case of searching RDF knowledge graphs, the results should not be restricted to only tree-shaped subgraphs. Others assume the keyword queries to consist of references to nodes only and completely ignore edge labels (He et al., 2007; Kargar and An, 2011; Le et al., 2014; Dalvi et al., 2008; Tran et al., 2009; Li et al., 2008; Fu and Anyanwu, 2011; Kasneci et al., 2009). This is a strong assumption in the case of labeled graphs such

as RDF knowledge graphs since user queries could contain references to certain predicates (i.e., edge labels) and these predicates should be taken into consideration when searching the graph. In our approach, we treat edge labels as first-class citizens and we can handle the case when the user query consists of a reference to one or more predicates. Finally, many previous approaches do not provide any means for result ranking, apart from the size of the results (Le et al., 2014; Tran et al., 2009), degrees of nodes (Bhalotia et al., 2002), which are both inadequate in the case of RDF graphs as we show in our experiments. Other works focused on other aspects of keyword search such as the diversity of the results (Dass et al., 2016), or distributed query processing (Yuan et al., 2017).

Keyword search on structured and semi-structured data have been also studied (Nie et al., 2007; Blanco et al., 2010; Kim et al., 2009; Xu and Papakonstantinou, 2005; Schuhmacher and Ponzetto, 2014). Some of these approaches have been adopted to the RDF setting. For instance, the Web Object Retrieval approaches have been used to retrieve a set of resources

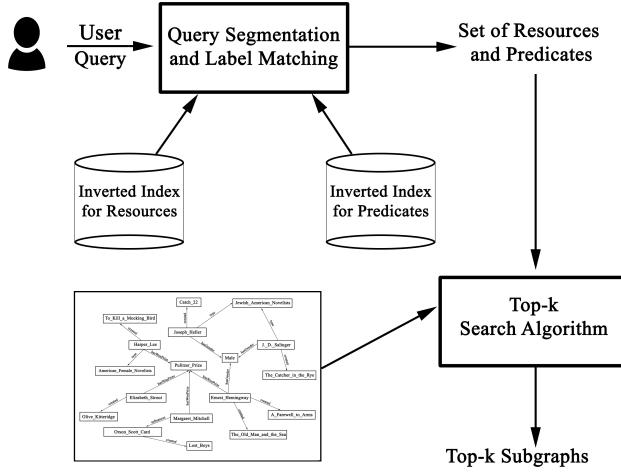


Figure 2: System Architecture.

(i.e., nodes) for a given keyword query, where results are typically ranked using IR techniques such as BM25 (Blanco et al., 2010) or language models (Nie et al., 2007). We compare our approach to one of these techniques ((Nie et al., 2007)) in our experiments.

Similar to our approach, the closely-related work (Elbassuoni and Blanco, 2011) takes into consideration both node and edge labels during the retrieval of results and provides a model for result ranking. However, this approach is not applicable for large RDF graphs such as Wikipedia-based ones as it does not involve a top-k search algorithm and its ranking model is not adequate as we show in our experiments.

Finally, there has been significant work on Natural Language Question Answering over RDF Knowledge graphs (for instance (Yahya et al., 2012; Lopez et al., 2007; Bao et al., 2014)). Most of these techniques utilize natural-language processing tools to translate a user’s question into the most-likely SPARQL query. This is an orthogonal problem to ours where we do not want to rely heavily on the quality of the translation process.

3 APPROACH

Our system architecture is depicted in Figure 2. In a nutshell, our approach works as follows. First, the input keyword query is segmented and matched to a set of resources and predicates (i.e., node and edge labels or URIs). This is done by consulting the inverted indices of the resources and predicates as the query is being segmented. We explain how we build our inverted indices in Section 3.1 and how the segmenta-

tion and matching process works in Section 3.2. Next, we explore the knowledge graph, to retrieve the top-k scored subgraphs that connect all the nodes representing the resources mentioned in the query, and such that these subgraphs contain for each predicate referred to in the query, a corresponding edge that is labeled by this predicate. We describe the scoring function that the algorithm uses in Section 3.3, and describe the algorithm itself in Section 3.4. We then prove the correctness of the algorithm’s termination condition in Section 3.5.

3.1 Indexing

To be able to process keyword queries over an RDF knowledge graph, we make use of two types of inverted indices. The first consists of resources or node labels and their surface names, where surface names are keywords that can be used to refer to a particular resource. Resource surface names are readily available information in many RDF knowledge graphs such as YAGO or DBpedia. For example, in YAGO, the resource `Ernest_Hemingway` is associated with the surface names “Ernest Hemingway”, “Ernest” and “Hemingway”, where the first is typically referred to as the preferred label. Similarly, `Pulitzer_Prize` is associated with the surface names “Pulitzer Prize” and “Pulitzer Award”.

More precisely, for each resource in our knowledge graph, we extract the *preferred* surface name and then create an inverted index for the resources using Apache Lucene¹. This inverted index contains the surface name and the corresponding resource it refers to. Note that we only extract the preferred surface

¹<https://lucene.apache.org/>

name of each resource and hence each surface name would be associated with only one resource. We also do not tokenize the surface names and assume each surface name (as a whole) is a key in the inverted index. This means that we assume that in the user query, the user will use the whole preferred surface name to refer to a resource. Alternatively, we could extract all the surface names of the resources and tokenize them before indexing. In that case, some changes should be done to our segmentation and label matching procedure described in the next section. Since, the main focus of the paper is on result ranking and top-k search, we defer this to future work.

Similarly, for predicates (i.e., edge labels), we create an inverted index that contains textual representations for predicates and the predicates they refer to, again using Apache Lucene. To do this, we first extract for each predicate in the knowledge graph, the possible textual representations that can be used to express that predicate. This can be done in various ways. For example, for some knowledge graphs such as YAGO, we can use existing sources of predicate textual representations such as PATTY (Nakashole et al., 2012), which is a collection of semantically-typed relational patterns mined from large corpora (Wikipedia and the New York Times archive). Other knowledge graphs, such as DBpedia, contain textual representations of their predicates just like surface names of resources, which can be directly used. A third option is to let human experts manually suggest potential textual representations for each predicate. A crowdsourcing activity would be helpful in this maneuver. In our case, we opted for the third option and retrieved for each predicate, a list of textual representations using crowdsourcing. We then tokenized the textual representations we obtained and ended up with an inverted index that consists of single-words as keys and lists of predicates as values. For example, one entry in this inverted index is the word “birth” and the corresponding value is `<wasBornIn, wasBornOn>`.

3.2 Query Segmentation and Label Matching

In this section, we describe in details the steps we perform for query segmentation and how the query segments are then matched to node and edge labels from the knowledge graph (i.e., resources and predicates). Given a keyword query, our segmentation and matching process works as follows. First, we start by marking words that refer to predicates in the query. To do this, we scan the query word by word from left to right and for each word we consult the inverted index for predicates and if a word matches one or more predi-

cates in the inverted index, it is marked as a predicate word.

Next, for all phrases (consecutive words) that are delimited by predicate words (i.e., before or after a word marked as a predicate word), we consult the inverted index for resources to see if this phrase or the longest substring of the phrase matches any resources in the knowledge graph. Doing so will result in a set of resources R .

Finally, to output the set of predicates P referred to in the query, we try to resolve words marked as predicate words to only one predicate. In case the word was matched to only one predicate, we just add this to P . In case the word matched more than one predicate, we use the closest identified resource to the predicate (i.e., immediately preceding or succeeding the predicate in the query) and count the edges in the knowledge graph that are labeled by the predicate and contains the closest resource as a node. The predicate word is then matched to the predicate with the highest number of edges, and it is added to P . In this fashion, we jointly resolve predicates and resources to identify the most likely ones referred to in the user query.

For example, consider our example query “books by Pulitzer prize winners”. Our segmentation and matching process starts by marking the words “books” and “winners” as two predicate words. Then it tries to match the longest substring of the phrase “by Pulitzer prize” to a resource in the knowledge graph, which would result in a match to `Pulitzer_Prize`. Finally, the predicate words “books” and “winners” are matched to the predicates `created` and `hasWonPrize`, respectively. Thus, $P = \{\text{created}, \text{hasWonPrize}\}$ and $R = \{\text{Pulitzer_Prize}\}$.

We have described the general case for our segmentation and matching process, where the user query consists of words referring to both resources and predicates. In the extreme cases, the user query might refer to only predicates or only resources. In the former, we again scan the query and mark any words that match a predicate in the inverted index as a predicate word. In case a predicate word match more than one predicate, we pick the predicate which occurs the most as an edge label in our knowledge graph.

In the latter, we try to match the longest substrings of the query to resources in the knowledge graph by scanning the query from left to right until a resource is matched. Once a resource is matched, its matching substring is removed from the query string and whatever is left in the query is again scanned from left to right in an attempt to match other resources.

We acknowledge that our segmentation and matching process is ad-hoc, however our focus in this paper is mainly the top-k searching. In an orthogonal

work, we are currently developing more robust segmentation and matching techniques that utilize deep learning for this task. The results of this work can then be adopted by our framework by replacing the described segmentation and labeling process above.

3.3 Scoring Function

Once a keyword query is segmented and we have identified a set of resources R and a set of predicates P mentioned in the query, our goal is to find all *connected* subgraphs such that each subgraph g_i contains: (1) one and only one node for each resource $r_j \in R$, and (2) one and only one edge whose label corresponds to one of the predicate $p_k \in P$. For instance, consider running our example query “books by Pulitzer prize winners” on the example knowledge graph in Figure 1. Table 2 shows some subgraphs that satisfy the above two properties. Recall that our segmentation and matching process will output the resource `Pulitzer_Prize` and the predicates `created` and `hasWonPrize` for the example query.

For Wikipedia-based knowledge graphs such as YAGO or DBpedia, the number of results returned for many queries could be overwhelming and thus result ranking is crucial. The most obvious aspect based on which the subgraphs can be ranked is the size of the subgraph (i.e., the number of nodes or edges). This is the strategy adopted by most previous work (e.g., (Le et al., 2014)). We argue that this is not sufficient as a basis for result ranking in Wikipedia-based RDF knowledge graphs. Consider the first three subgraphs in Table 2. They all have the same size, namely 2 edges. However, it is intuitive that when a user is searching for “books by Pulitzer prize winners”, she expects books by more famous authors such as Ernest Hemingway to be ranked before books by those who are less known such as Elizabeth Strout.

To be able to capture this, we associate each edge $e = (u, p, v)$, where u and v are the nodes connected by e and p is the edge label, with a weight $w(e)$ which is computed as follows.

$$w(e) = \text{inLinks}(u, v) \quad (1)$$

where $\text{inLinks}(u, v)$ is the number of Wikipedia articles that link to both resources denoted by the nodes u and v . The intuition behind this is that the more articles that mention the resources in the edge, the more important this edge is in the knowledge graph.

Moreover, our scoring function takes into consideration the *degrees* of the nodes. This is motivated by the following example. Consider running the query “J. D. Salinger Joseph Heller”. This query consists of no predicate phrases and will thus

be segmented into the following set of resources $R = \{\text{J._D._Salinger}, \text{Joseph_Heller}\}$. Running this query over our example knowledge graph in Figure 1 will return the two subgraphs shown in Table 3.

Clearly, subgraph g_1 in Table 3 is more *informative* than subgraph g_2 , since it is very obvious that both writers are males. However, both subgraphs have the exact same size (2 edges) and moreover the weights of the edges of the second subgraph will be higher than those of the edges of the first subgraph if we just rely on the number of Wikipedia links to compute the edge weights (i.e., Equation 1). Consequently, we take into consideration another aspect when ranking the subgraphs, namely the degrees of the nodes in the subgraph. To do this, we add for each edge $e = (u, p, v)$ in the knowledge graph another weight computed as follows.

$$\text{degree}(e) = \text{degree}(u) + \text{degree}(v) \quad (2)$$

where $\text{degree}(x)$ is the number of edges in the knowledge graph that contains x as a node. This way, an edge such as $e_1 = \text{J._D._Salinger} \text{ hasGender Male}$ would have a higher degree than $e_2 = \text{J._D._Salinger} \text{ type Jewish_American_Novelists}$, provided that the degree of the node labeled `Male` is higher than that of the node labeled `Jewish_American_Novelists`, which is very well-expected.

Finally, given a subgraph $g = (e_1, e_2, \dots, e_n)$, its total score is computed as follows.

$$s(g) = \sum_{i=1}^n \alpha \left(1 - \frac{w(e_i)}{\sum_{e \in E} w(e)} \right) + (1 - \alpha) \frac{\text{degree}(e_i)}{\sum_{e \in E} \text{degree}(e)} \quad (3)$$

where E is the set of all edges and α is a weighting parameter that combines the weights of edges and their degrees, which is set empirically to a value between 0 and 1 as we describe in the experiments section. The denominators in Equation 3 are used for normalization so that the weight and degree of each edge is a value between 0 and 1.

Note that using scoring function above, a subgraph with a *lower* score will be ranked *higher* than a subgraph with a higher score. This is intuitive since we want subgraphs which have 1) smaller sizes, 2) edges with higher weights $w(e)$, and 3) edges with lower degrees $\text{degree}(e)$ to be ranked higher. Since our scoring functions sums the scores of each individual edge in a subgraph g , then subgraphs with more edges will have higher scores provided that the other two factors (edge weights and degrees) are kept constant. Similarly, since our scoring function subtracts the normalized weight of an edge from 1 (first part of Equation 3), the higher the weights of edges in g are, the lower the score of the subgraph. Finally, the second part in Equation 3 ensures that subgraphs whose edges have higher degrees will have higher scores.

Table 2: Some subgraphs retrieved for the query “books by Pulitzer prize winners”.

<i>g1</i>	Elizabeth_Strout hasWonPrize Pulitzer_Prize Elizabeth_Strout created Olive_Kitteridge
<i>g2</i>	Ernest_Hemingway hasWonPrize Pulitzer_Prize Ernest_Hemingway created The_Old_Man_and_the_Sea
<i>g3</i>	Harper_Lee hasWonPrize Pulitzer_Prize Harper_Lee created To_Kill_a_Mocking_Bird
<i>g4</i>	Margaret_Mitchell hasWonPrize Pulitzer_Prize Margaret_Mitchell influences Orson_Scott_Card Orson_Scott_Card created Lost_Boys

Table 3: The subgraphs retrieved for the query “J. D. Salinger Joseph Heller”.

<i>g1</i>	J..D..Salinger type Jewish_American_Novelists Joseph_Heller type Jewish_American_Novelists
<i>g2</i>	J..D..Salinger hasGender Male Joseph_Heller hasGender Male

3.4 Top-k Search Algorithm

Our top-k search algorithm (Algorithm 1) is inspired by the backward search algorithm proposed previously (Le et al., 2014). It takes as input a set of resources R and a set of predicates P , which were identified in the user query using the segmentation and matching process described in Section 3.2. It returns the top-k lowest scored subgraphs that contain 1) a node and only node for each resource $r_i \in R$, and 2) for each predicate $p_j \in P$, an edge and only one edge labeled with p_j .

The algorithm maintains two main data structures, which are necessary for book keeping. The first is a set of minimum heaps L_1, L_2, \dots, L_n , one for each resource $r_i \in R$. The second is a look-up table M that is used to keep track of information about each node visited during the algorithm. Particularly, it contains a row for each node u visited during the search and a column for each resource r_i . Both data structures are empty in the beginning of the algorithm.

In the first loop of the algorithm, the node u representing each query resource r_i is expanded by retrieving all the edges that contain u and for each retrieved edge $e = (u, p, v)$ or $e = (v, p, u)$, a single-edged subgraph $g = (e)$ is inserted in the minimum heap L_i along with its score as computed based on Equation 3. We also note in the minimum heap that the next node to be expanded for the subgraph g is the node v .

Moreover, if the look-up table M does not contain the node v , a new row is created for v and we insert g and its score $s(g)$ in the cell $M[v][i]$ and nil in all the other cells. In case M already consists of an entry for v , we insert the pair $(g, s(g))$ in the cell $M[v][i]$.

Finally, for each row in M which does not contain any entries equal to nil and which contains $\forall j$

$\in 1, 2, \dots, m$, an edge labeled $p_j \in P$, the concatenation of the subgraphs stored in the cells of this row represent a candidate result. We then pick the k lowest-scored candidates and add them to the topk list using the procedure $\text{getTopK}(M, P)$. Note that this procedure takes P as input to ensure that candidate subgraphs which contain an edge for each predicate $p_j \in P$ are the only ones considered and the rest of candidates are discarded.

In the second loop of Algorithm 1, we pop from the minimum heaps the subgraph with the lowest score and we further expand the next unexpanded node of this subgraph. For instance, assume that the subgraph with the lowest score g was popped from L_i , where the node to be expanded is u . We again retrieve all the edges $e = (u, p, v) \in E$ or $e = (v, p, u) \in E$ and for each such edge, we append g to get a new subgraph g' where $s'(g) = s(g) + s(e)$. We then reinsert each new subgraph g' back in L_i . We also update the look-up table M the same way as in the first loop. Finally, we update the topk list as follows. For any candidate subgraph c in M , we check its score against the k th subgraph g_k in the current topk list. If $s(c) < s(g_k)$, we replace g_k with c in the topk list. If the topk list contains less than k candidates, we append to it the candidates with the lowest scores until we have exactly k subgraphs in the topk List.

In the next section, we explain our termination condition which guarantees that we only stop exploring the knowledge graph when the k lowest-scored candidates are retrieved. However, before we do this, we explain how the algorithm works in case there are no resource mentions in the user queries. That is, if $R = \emptyset$. In that case, we modify Algorithm 1 so that it contains a minimum heap for each predicate $p_i \in P$, and the look-up table contains a column for each pred-

Algorithm 1: Top-k Search Algorithm.

Input: $R = \{r_1, r_2, \dots, r_n\}$, $P = \{p_1, p_2, \dots, p_m\}, k$
Output: Top- k lowest-scored subgraphs
Initialize n min-heaps L_1, L_2, \dots, L_n ; $M \leftarrow \emptyset$;
 $topk \leftarrow \emptyset$
for $i = 1$ to n **do**
 u = node denoting r_i
 for $e = (u, p, v) \in E$ or $e = (v, p, u) \in E$ **do**
 $g \leftarrow e$; $s(g) = \alpha(1 - \frac{w(e)}{\sum_{e' \in E} w(e')}) + (1 - \alpha)\frac{\text{degree}(e)}{\sum_{e' \in E} \text{degree}(e')}$
 $L_i.\text{Insert}(v, g, s(g));$
 if $v \notin M$ **then**
 $M[v] \leftarrow \{nil, \dots, (g, s(g)), \dots, nil\}$
 else
 $M[v][i] \leftarrow (g, s(g))$
 end if
 end for
 $topk \leftarrow \text{getTopK}(M, P)$
end for
while termination condition not met **do**
 $(u, g, s(g)) \leftarrow \text{pop}(\text{argmin}_{i=1}^n \{L_i.\text{top}\})$
 for $v \in V$ and $(e = (u, p, v) \in E$ or $e = (v, p, u) \in E)$ and $u \notin g$ **do**
 $g \leftarrow g \cup e$; $s(g) = s(g) + \alpha(1 - \frac{w(e)}{\sum_{e' \in E} w(e')}) + (1 - \alpha)\frac{\text{degree}(e)}{\sum_{e' \in E} \text{degree}(e')}$
 $L_i.\text{Insert}(v, g, s(g));$
 if $v \notin M$ **then**
 $M[v] \leftarrow \{nil, \dots, (g, s(g)), \dots, nil\}$
 else
 $M[v][i] \leftarrow (g, s(g))$
 end if
 end for
 $topk \leftarrow \text{getTopK}(M, P)$
end while
return $topk$

icate p_i . In the first loop of the algorithm, for each predicate p_i , we retrieve all edges $e = (u, p_i, v) \in E$ and then we add the edges e to the minimum heaps as described before. We also add both nodes u and v to the look-up table M exactly as before. The rest of the algorithm also behaves in the exact same way as in the general case where we have both resources and predicates.

Note that our algorithm can be efficiently parallelized by creating multiple parallel threads for the graph exploration steps. We use this parallelized version in our experiments, where all the threads work in parallel to expand the nodes but share the same data structures, namely the look-up table M and the minimum heaps L_1, L_2, \dots, L_n .

3.5 Termination Condition

To guarantee that our top- k algorithm returns the k lowest-scored subgraphs for a given user query, we need to ensure two things:

1. For those rows in M with one or more *nil* value, the subgraphs in these rows if concatenated with subgraphs that contain the resource corresponding to a *nil* value will never have a score lower than those in the returned $topk$ list.
2. There are no more rows that can be inserted in M in the future and the concatenation of these subgraphs would have a score lower than those in the returned $topk$ list.

To guarantee that the first condition above holds, we use the look-up table M as follows. For each row in M where there is at least one cell with a *nil* value, let $b(i)$ be an indicator function that returns 0 if the i th cell of the row is *nil* and 1 otherwise. Furthermore, let g_i be the subgraph stored in the i th cell, in case it does not contain *nil*. Finally, let the score of the subgraph in the top of the minimum heap L_i be $s(L_i.\text{top})$. The best score of any subgraph g formed by concatenating the subgraphs in the cells that do not contain *nil* values can then be computed as follows.

$$\text{bestscore}(g) = \sum_{i=1}^n s(g_i) \times b(i) + s(L_i.\text{top}) \times (1 - b_i) \quad (4)$$

As for the second condition, to compute the best score any subgraph g' in the knowledge graph can have at a certain stage of the exploration, we use the following equation.

$$\tau = \sum_{i=1}^n s(L_i.\text{top}) \quad (5)$$

Finally, to check if the k subgraphs in the current $topk$ list are indeed the k lowest-scored subgraphs possible and thus can successfully terminate the graph exploration, we check if the following inequality holds:

$$s(g_k) \leq \min \left(\min_{g \in NC} (\text{bestscore}(g)), \tau \right) \quad (6)$$

where NC is the set of (not necessarily connected) subgraphs which are retrieved from the look-up table M by going through the rows with *nil* values and concatenating the subgraphs in those cells that do not contain *nil* values, $\text{bestscore}(g)$ is computed using Equation 4, τ is the best score any candidate subgraph that might be constructed later can have, which can be computed using Equation 5, and $s(g_k)$ is the score of the k th subgraph in the current $topk$ list.

Table 4: Query Benchmark.

ron howard actor director	woody allen actor director creator
woody allen wife birthday	married albert einstein
woody allen	acted judy davis woody allen
actor director woody allen scarlett johansson	albert einstein isaac newton
boston university albert einstein	frank b. morse albert einstein
judy davis woody allen	taylor swift nicki minaj kendrick lamar
woody allen scarlett johansson	actor director
actor wife birthday	born wife actor director
germany population	country london capital
elton john	dogma and chasing amy
gone with the wind director	doctor zhivago actors
jessica alba jennifer aniston	jessica alba ioan gruffudd
meryl streep mamma mia!	australia leader
russia leader wife birthplace	england capital population
germany england	pierce brosnan meryl streep
leader birthplace	birth death dates actors

Table 5: Average NDCG values for different values of α .

α	0	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1
NDCG	0.979	0.982	0.981	0.985	0.981	0.981	0.979	0.980	0.979	0.981	0.971

4 EVALUATION

We conducted two main experiments to evaluate our top-k retrieval model. The first experiment was used to tune the parameter α in our scoring function (which is used in Equation 3). Once this parameter was tuned, a second experiment was conducted to compare our approach to state-of-the-art approaches for keyword search over RDF data. In all our experiments, we use YAGO (Suchanek et al., 2008) as our knowledge graph. YAGO is a large-scale general-purpose RDF knowledge graph derived from Wikipedia and WordNet. It contains more than 120 million edges about 10 million resources (e.g., persons, organizations, cities) and consists of 75 distinct predicates.

4.1 Parameter Tuning

To be able to tune our single parameter α used in our scoring function described in Section 3.3, we created a benchmark composed of 32 keyword queries. Table 4 displays all the queries in the benchmark. We resorted to creating our own benchmark since most of the benchmarks available assume the results to be entities rather than subgraphs. In addition, all the available benchmarks consider only binary relevance (i.e., result either correctly answer the query or not). In our case, we want to assess the relevance of the results on a multilevel scale.

For each query in our benchmark, we ran our top-

-k search algorithm to retrieve the top-10 subgraphs, varying the value of α from 0 to 1 with a scale of 0.1. We pooled the top-10 results for each value of α and presented them in random order to five human judges² which were asked to assess the relevance of the results with respect to the query on a four-point scale: 3 for highly relevant and popular results, 2 for highly relevant results, 1 for marginally relevant results, and 0 for non-relevant results³.

We calculated the Fleiss' kappa coefficient (Fleiss, 1971) to measure the agreement between our human judges and acquired a value of $\kappa = 0.66$, which is in the range of substantial agreement. We also used three gold queries during our assessment tasks and all human judges assessed all the results of the three gold queries exactly as specified in the gold assessments.

Finally, we used a majority vote to aggregate the assessments of the five judges and used these aggregated assessments as a relevance level for the results. Next, we calculated the average Normalized Discounted Cumulative Gain (NDCG) for each value of α , which can be seen in Table 5. We conclude from the table that the best value for α is 0.3, based on the average NDCG. This indicates that relying solely on the degrees of nodes for ranking as some previous approaches do is inadequate.

²All judges were graduate computer science students

³The guidelines and the relevance assessments will be made publicly available

Table 6: Average NDCG values for our approach versus state-of-the-art approaches.

Our Approach	Backward Search	WOR	KBR
0.985	0.898	0.141	0.157

4.2 Comparison to State-of-the-art

In this experiment, we compare our approach with the value of α set to 0.3 to three different approaches. The first approach is the backward search approach (Le et al., 2014), which uses a very similar top-k search algorithm to ours, however it does not take into consideration predicates and only relies on the size of the subgraphs for scoring.

The second approach we compared ours to is the Web Object Retrieval (WOR)(Nie et al., 2007), which retrieves a list of resources for a given keyword query and ranks them based on statistical language models. This approach represents the family of approaches which retrieve a list of resources in response to a keyword query. To be able to run this approach on our knowledge graph, we first associate each edge $e = (u, p, v)$ in the knowledge graph with a set of keywords which are the surface names of all resources linked to by either u or v as well as the textual representation of the predicate p . To be comparable to our approach, we also associate each edge-keyword pair (e, t) with a weight $w(e, t)$ reflecting the importance of the edge e with respect to the keyword t which is computed as the number of Wikipedia pages that link to both u and v and contain the keyword t .

Now, given a keyword query $q = \{q_1, q_2, \dots, q_n\}$ where q_i is a single keyword, we start by retrieving all the edges which are associated with each keyword q_i . Next, we extract all the unique resources r_1, r_2, \dots, r_m that are nodes in any of these edges. Finally, we score each resource r using the below scoring function and rank them descendingly based on their scores.

$$s(r) = \prod_{i=1}^n \sum_{e \in E} P(q_i|e) \times P(e|r) \quad (7)$$

where $P(q_i|e)$ is set to $\frac{w(e, q_i)}{\sum_{e' \in E} w(e', q_i)}$ and $P(e|r)$ is equal to 1 if e consists of a node representing resource r , and 0 otherwise.

The third approach we compared against is the keyword-based retrieval model over RDF graphs (KBR) (Elbassuoni and Blanco, 2011). This approach first retrieves edges that contain any of the keywords in the user query, and then proceed by joining these edges to construct connected minimal subgraphs which are then ranked based on a hierarchical language modeling approach.

For each of the above three approaches as well as our approach (with α set to 0.3 for our approach),

we ran all the queries in our benchmark and retrieved the top-10 results for each query. These results were then pooled together and presented to the same five human judges, which again assessed their relevance with respect to the queries on the same 4-point scale. Note that in the case of the Web Object Retrieval approach, we also provided the human judges with the Wikipedia link to each resource retrieved in order to help them assess the relevance of the resources with the respect to the queries.

Similar to the previous experiment, our human judges had a substantial agreement as measured by Fleiss' Kappa coefficient. We again aggregated the assessments for each result using a majority vote and then computed the *average* NDCG for each approach. As can be seen from Table 6, our approach significantly outperforms all other approaches based on the average NDCG (with a p-value ≤ 0.026).

For the case of WOR and KBR, the average NDCG is very low for the following reasons. WOR assumes independence between the query keywords and it treats each resource as a bag-of-words ignoring the structure in the underlying data. KBR on the other hand does not take into consideration the link-structure or degrees when ranking subgraphs.

Finally, we report on the time it took to run our 35 queries and retrieve the top-10 results. The average execution time for a non-parallelized version of our search algorithm is 18.069 seconds and the average execution time for the parallelized version is 13.17 seconds.

5 CONCLUSION

In this paper, we presented a top-k search algorithm for keyword queries over Wikipedia-based RDF knowledge graphs. Our approach utilizes a novel scoring function to score a subgraph, which takes into consideration the size of the subgraph as well as its edge weights. The edge weights are computed using a careful combination of the degrees of the nodes as well as the number of Wikipedia articles that point to them. Our top-k algorithm guarantees that for a given k , the returned subgraphs are indeed the lowest-scored. We have compared our approach to various state-of-the-art approaches and it significantly outperformed all the other approaches based on the average NDCG of a benchmark consisting of 32 queries.

In future work, we plan to use a more robust segmentation and label matching process than the one we used here, which will rely on deep learning to identify candidate resources and predicates referred to in a given keyword query. Moreover, we plan to improve the efficiency of our top-k search algorithm by making use of graph summarization techniques as well as developing a distributed version of our search algorithm. We also plan to generalize our ranking model to be applicable to a wider range of RDF knowledge graphs, that are not necessarily based on Wikipedia.

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