The $H_\infty$ control problem: a state space approach
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• On page 113, in the definition of $\Sigma_\delta$ we have:
  \[ D_{21,S} = -(I - D_{11}S)^{-1}D_{12}(I - \tilde{D}_{22}\tilde{D}_{22})^{-1/2}. \]

• Reference [GK] has appeared in volume 28, number 2, pp. 299-312 in 1992.
• Reference [Ig] has appeared in volume 54, number 5, pp. 1031-1073 in 1991.
• Reference [LMK] has appeared in the Proc. 29th Conf. on Decision and Control, pp. 1786-1793, 1990 held in Honolulu, Hawai.
• Reference [Ni] was published under the title “Loop transfer recovery for general observer architectures” in volume 53, number 5, pp. 1177-1203 in 1991.
• Reference [RNK] was published on pp. 1394-1413.
• Reference [S3] was published on pp. 123-142.
• Reference [S4] was published on pp. 143-166.
• In reference [SK], the first author is N. Sivashankar and the paper was published in pp. 58-69 of volume 38, number 1 of the IEEE Trans. Aut. Contr. in 1993.
• Reference [St6] was published on pp. 182-202.
• Reference [St7] was published on pp. 113-161 of volume 187 of Linear Algebra and its Applications in 1993.
• Reference [St8] was published on pp. 365-370 of volume 1 of “Recent advances in Mathematical Theory of Systems, Control, Networks and Signal Processing”, H. Kimura and S. Kodama (Eds.). Mita Press, Kobe, Japan.

• Reference [St12] has appeared in volume 28, number 3, pp. 627-631.
