# Distributed Optimization in Adaptive Networks: Appendix

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#### **1** Markov Decision Processes

Consider a Markov chain (w(k), a(k)) defined for k = 0, 1, ... and with  $w(k) \in \mathbb{W}$ , a(k) in A, where W and A are finite sets representing the system state space and the action space, respectively. The transition probabilities are defined by the function

$$P_{\theta}(w', a', w, a) = \Pr\left\{w(k+1) = w, a(k+1) = a | w(k) = w', a(k) = a'\right\}.$$

Here,  $\theta \in \mathbb{R}^N$  is a vector of policy parameters.

We will make the following assumption regarding the dynamics.

**Assumption 1.1.** For all  $\theta$ , the Markov chain (w(k)) is ergodic (aperiodic, irreducible).

While the system is in state  $w \in W$  and action  $a \in A$  is applied, a reward r(w, a) is accrued. We will use the shorthand r(k) = r(w(k), a(k)). Given Assumption 1.1, we can define the long term average reward by

$$\begin{split} \lambda(\theta) &= \lim_{K \to \infty} \frac{1}{K} \operatorname{E} \left[ \sum_{k=0}^{K-1} r(k) \right] \\ &= \sum_{w \in \mathbb{W}, a \in \mathbb{A}} \eta_{\theta}(w, a) r(w, a), \end{split}$$

where  $n_{\theta}(w, a)$  is the steady-state distribution corresponding to the transition function  $P_{\theta}(w', a', w, a)$ .

Define the differential reward function

$$q_{\theta}(w, a) = \lim_{K \to \infty} \mathbb{E}\left[ \sum_{k=0}^{K-1} \left( r(w(k), a(k)) - \lambda(\theta) \right) \middle| w(0) = w, a(0) = a \right].$$

The following result provides a crucial expression for the gradient of  $\lambda(\theta)$ . It is important in that it does not rely on terms of the form  $\nabla_{\theta}\eta_{\theta}(w, a)$ , which would be difficult to estimate over finite sample paths. It is a standard result in Markov decision process theory, see [3], for example, for a proof.

**Theorem 1.1.** Assume that  $P_{\theta}(w', a', w, a)$  is continuously differentiable with respect to  $\theta$ . Then,

(1.1) 
$$\nabla_{\theta}\lambda(\theta) = \sum_{w \in \mathbb{W}, a \in \mathbb{A}} \sum_{w' \in \mathbb{W}, a' \in \mathbb{A}} \eta_{\theta}(w', a') \nabla_{\theta} P_{\theta}(w', a', w, a) q_{\theta}(w, a).$$

### 2 Network Structure

Assume the network has *n* components. Corresponding to each component *i*, there is a subset  $\mathbb{W}_i \in \mathbb{W}$ . At the *k*th epoch, there are a set of control actions  $a_1(k) \in \mathbb{A}_1, \ldots, a_n(k) \in \mathbb{A}_n$ , where each  $\mathbb{A}_1, \ldots, \mathbb{A}_n$  is a finite set. We will denote the entire action vector  $(a_1(k), \ldots, a_n(k))$  as  $a(k) \in \mathbb{A} = \mathbb{A}_1 \times \cdots \times \mathbb{A}_n$ . Actions are governed by a set of policies  $\pi^1_{\theta_1}, \ldots, \pi^n_{\theta_n}$ , where the policy  $\pi^i_{\theta_i}$  at component *i* is parameterized by a vector  $\theta_i \in \mathbb{R}^{N_i}$ . Each *i*th action process transitions only if the state w(k) is an element of  $\mathbb{W}_i$ . At the time of transition, the probability that  $a_i(k)$ becomes any  $a_i \in \mathbb{A}_i$  is given by  $\pi^i_{\theta_i}(a_i|w(k))$ . Hence, the corresponding action sequence evolves according to

$$a_i(k) = \begin{cases} a'_i & \text{with probability } \pi^i_{\theta_i}(a'_i|w(k)), \text{ if } w(k) \in \mathbb{W}_i, \\ a_i(k-1) & \text{otherwise.} \end{cases}$$

The state transitions depend on the prior state and action vector. In particular, there is a transition kernel P that defines the state dynamics:

$$\Pr\left\{w(k) = w | w(k-1) = w', a(k-1) = a'\right\} = P(w', a', w).$$

Hence, if  $\theta = (\theta_1, \ldots, \theta_n)$ , we have

(2.1) 
$$P_{\theta}(w', a', w, a) = P(w', a', w) \prod_{i:w \in \mathbb{W}_i} \pi^i_{\theta_i}(a_i|w) \prod_{i:w \notin \mathbb{W}_i} \mathbf{1}_{\{a'_i=a_i\}}.$$

Finally, we will assume that the reward is an average of rewards occurring at each component, that is

$$r(w,a) = \frac{1}{n} \sum_{i=1}^{n} r_i(w,a).$$

We will use the shorthand  $r_i(k) = r_i(w(k), a(k))$ .

We will make the following assumption regarding the policies.

**Assumption 2.1.** For all *i* and every  $w \in W_i$ ,  $a_i \in A_i$ ,  $\pi_{\theta_i}^i(a_i|w)$  is a continuously differentiable function of  $\theta_i$ . Further, for every *i*, there exists a bounded function  $L_i(w, a_i, \theta)$  such that for all  $w \in W_i, a_i \in A_i$ ,

$$\nabla_{\theta_i} \pi^i_{\theta_i}(a_i|w) = \pi^i_{\theta_i}(a_i|w) L_i(w, a_i, \theta)$$

The latter part of the assumption is satisfied, for example, if there exists a constant  $\epsilon > 0$  such that for each  $i, w \in W_i, a_i \in A_i$ ,

either 
$$\forall \theta_i, \pi^i_{\theta_i}(a_i|w) = 0 \text{ or } \forall \theta_i, \pi^i_{\theta_i}(a_i|w) \ge \epsilon.$$

Without loss of generality, we will assume that  $\pi_{\theta_i}^i(a_i|w) > 0$ , and hence define a bound L by

$$\sup_{i,\theta_i,w\in\mathbb{W}_i,a_i\in\mathbb{A}_i} \left\| \frac{\nabla_{\theta_i} \pi^i_{\theta_i}(a_i|w)}{\pi^i_{\theta_i}(a_i|w)} \right\| < L.$$

In this framework, the gradient expression of Theorem 1.1 becomes significantly simpler.

#### Theorem 2.1. For all i,

$$\nabla_{\theta_i} \lambda(\theta) = \sum_{w \in \mathbb{W}_i, a \in \mathbb{A}} \eta_{\theta}(w, a) \frac{\nabla_{\theta_i} \pi_{\theta_i}^i(a_i | w)}{\pi_{\theta_i}^i(a_i | w)} q_{\theta}(w, a).$$

*Proof.* Examining (2.1), it is clear that

$$\nabla_{\theta_i} P_{\theta}(w', a', w, a) = P_{\theta}(w', a', w, a) \frac{\nabla_{\theta_i} \pi^i_{\theta_i}(a_i | w)}{\pi^i_{\theta_i}(a_i | w)} \mathbf{1}_{\{w \in \mathbb{W}_i\}}.$$

Combining with Theorem 1.1, we have

$$\begin{aligned} \nabla_{\theta_i}\lambda(\theta) &= \sum_{\substack{w,a\\w',a'}} \eta_{\theta}(w',a')P_{\theta}(w',a',w,a) \frac{\nabla_{\theta_i}\pi^i_{\theta_i}(a_i|w)}{\pi^i_{\theta_i}(a_i|w)} \mathbf{1}_{\{w\in\mathbb{W}_i\}}q_{\theta}(w,a) \\ &= \sum_{w,a} \frac{\nabla_{\theta_i}\pi^i_{\theta_i}(a_i|w)}{\pi^i_{\theta_i}(a_i|w)} \mathbf{1}_{\{w\in\mathbb{W}_i\}}q_{\theta}(w,a) \sum_{w',a'} \eta_{\theta}(w',a')P_{\theta}(w',a',w,a) \\ &= \sum_{w\in\mathbb{W}_i,a\in\mathbb{A}} \eta_{\theta}(w,a) \frac{\nabla_{\theta_i}\pi^i_{\theta_i}(a_i|w)}{\pi^i_{\theta_i}(a_i|w)}q_{\theta}(w,a). \end{aligned}$$

## **3** Centralized Gradient Estimation

For  $\beta \in (0, 1]$ , define the eligibility vector

(3.1) 
$$z_i^{\beta}(k) = \sum_{\ell=0}^k \beta^{k-\ell} \frac{\nabla_{\theta_i} \pi_{\theta_i}^i(a_i(\ell)|w(\ell))}{\pi_{\theta_i}^i(a_i(\ell)|w(\ell))} \mathbf{1}_{\{w(\ell)\in\mathbb{W}_i\}}$$

(3.2) 
$$= \beta z_i^{\beta}(k-1) + \frac{\nabla_{\theta_i} \pi_{\theta_i(k)}^i(a_i(k)|w(k))}{\pi_{\theta_i(k)}^i(a_i(k)|w(k))} \mathbf{1}_{\{w(k) \in \mathbb{W}_i\}}.$$

We can define a centralized estimate of the gradient  $\nabla_{\theta_i}\lambda(\theta)$  by

$$\bar{\chi}_i(k) = r(k) z_i^\beta(k),$$

where we are using the shorthand r(k) = r(w(k), a(k)).

Define  $\nabla_i(k)$  as shorthand for

$$\frac{\nabla_{\theta_i} \pi^i_{\theta_i}(a_i(k)|w(k))}{\pi^i_{\theta_i}(a_i(k)|w(k))} \mathbf{1}_{\{w(k)\in\mathbb{W}_i\}}.$$

The following lemma will be useful in subsequent analysis.

**Lemma 3.1.** If  $\ell < k$ ,  $E[\nabla_i(k)|\mathcal{F}_{\ell}] = 0$ .

*Proof.* Note that for  $\ell < k$ ,

$$\begin{split} \mathbf{E}[\nabla_{i}(k)|\mathcal{F}_{\ell}] &= \sum_{w \in \mathbb{W}_{i}} \sum_{a_{i} \in \mathbb{A}_{i}} \Pr\left\{w(k) = w|\mathcal{F}_{\ell}\right\} \pi_{\theta_{i}}^{i}(a_{i}|w) \left[\frac{\nabla_{\theta_{i}}\pi_{\theta_{i}}^{i}(a_{i}|w)}{\pi_{\theta_{i}}^{i}(a_{i}|w)}\right] \\ &= \sum_{w \in \mathbb{W}_{i}} \Pr\left\{w(k) = w|\mathcal{F}_{\ell}\right\} \sum_{a_{i} \in \mathbb{A}_{i}} \nabla_{\theta_{i}}\pi_{\theta_{i}}^{i}(a_{i}|w) \\ &= \sum_{w \in \mathbb{W}_{i}} \Pr\left\{w(k) = w|\mathcal{F}_{\ell}\right\} \nabla_{\theta_{i}} \left(\sum_{a_{i} \in \mathbb{A}_{i}} \pi_{\theta_{i}}^{i}(a_{i}|w)\right) \\ &= \sum_{w \in \mathbb{W}_{i}} \Pr\left\{w(k) = w|\mathcal{F}_{\ell}\right\} \nabla_{\theta_{i}}\left(1\right) \\ &= 0. \end{split}$$

We will now establish convergence of long term averages of the discounted gradient estimator. Note that a stronger result is proved in [1], however the following is sufficient for our purposes.

**Theorem 3.1.** For any *i* and  $0 < \beta < 1$ ,

$$\lim_{K \to \infty} \frac{1}{K} \mathbb{E}\left[\sum_{k=0}^{K-1} \bar{\chi}_i(k)\right] = \sum_{w \in \mathbb{W}_i, a \in \mathbb{A}} \eta_\theta(w, a) \frac{\nabla_{\theta_i} \pi^i_{\theta_i}(a_i|w)}{\pi^i_{\theta_i}(a_i|w)} q_\theta^\beta(w, a),$$

where  $q_{\theta}^{\beta}(w, a)$  is the discounted differential reward function

$$q_{\theta}^{\beta}(w,a) = \lim_{K \to \infty} \mathbb{E}\left[ \left| \sum_{k=0}^{K-1} \beta^k \left( r(w(k), a(k)) - \lambda(\theta) \right) \right| w(0) = w, a(0) = a \right].$$

Further,

$$\lim_{\beta \uparrow 1} \lim_{K \to \infty} \frac{1}{K} \mathbb{E} \left[ \sum_{k=0}^{K-1} \bar{\chi}_i(k) \right] = \nabla_{\theta_i} \lambda(\theta).$$

Proof. Note that

$$\begin{split} \frac{1}{K} \mathbf{E} \left[ \sum_{k=0}^{K-1} \bar{\chi}_i(k) \right] &= \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \nabla_i(\ell) \sum_{k=\ell}^{K-1} \beta^{k-\ell} r(k) \right] \\ &= \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \nabla_i(\ell) \sum_{k=\ell}^{K-1} \beta^{k-\ell} \left( r(k) - \lambda(\theta) \right) \right] \\ &= \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \nabla_i(\ell) q_{\theta}^{\beta}(w(\ell), a(\ell), K - \ell) \right], \end{split}$$

where we use the fact the  $E[\nabla_i(\ell)] = 0$ , from Lemma 3.1, and where

$$q_{\theta}^{\beta}(w, a, K) = \mathbb{E}\left[\left|\sum_{k=0}^{K-1} \beta^{k} \left(r(w(k), a(k)) - \lambda(\theta)\right)\right| w(0) = w, a(0) = a\right].$$

It is clear the  $q_{\theta}^{\beta}(w, a, K) \rightarrow q_{\theta}^{\beta}(w, a)$  as  $K \rightarrow \infty$ , then, since  $\nabla_i(\ell)$  is bounded, it follows that

$$\begin{split} \lim_{K \to \infty} \frac{1}{K} \operatorname{E} \left[ \sum_{k=0}^{K-1} \bar{\chi}_i(k) \right] &= \lim_{K \to \infty} \frac{1}{K} \operatorname{E} \left[ \sum_{\ell=0}^{K-1} \nabla_i(\ell) q_{\theta}^{\beta}(w(\ell), a(\ell)) \right] \\ &= \sum_{w \in \mathbb{W}, ia \in \mathbb{A}} \eta_{\theta}(w, a) \frac{\nabla_{\theta_i} \pi_{\theta_i}^i(a_i | w)}{\pi_{\theta_i}^i(a_i | w)} q_{\theta}^{\beta}(w, a), \end{split}$$

where the last step follows since  $(w(\ell), a(\ell))$  is ergodic (Assumption 1.1). The balance of the result follows from the fact that  $\lim_{\beta \uparrow 1} q_{\theta}^{\beta}(w, a) = q_{\theta}(w, a)$ .

### 4 Distributed Gradient Estimation

Consider the following gradient estimator:

(4.1) 
$$\chi_i(k) = z_i^\beta(k) \frac{1}{n} \sum_{j=1}^n \sum_{\ell=0}^k d_{ij}^\alpha(\ell, k) r_j(\ell),$$

Here, the random variables  $\{d_{ij}^{\alpha}(\ell, k)\}$ , with parameter  $\alpha \in (0, 1)$ , represent an arrival process describing the communication of rewards across the network. Indeed,  $d_{ij}^{\alpha}(\ell, k)$  is the fraction of the reward  $r_j(\ell)$  at component *j* that is learned by component *i* at time  $k \ge \ell$ . We will assume the arrival process satisfies the following conditions.

**Assumption 4.1.** For each  $i, j, \ell$ , and  $\alpha \in (0, 1)$ , the process  $\{d_{ij}^{\alpha}(\ell, k) | k = \ell, \ell + 1, \ell + 2, ...\}$  satisfies:

- 1.  $d_{ij}^{\alpha}(\ell, k)$  is  $\mathcal{F}_k$ -measurable.
- 2. There exists a scalar  $\gamma \in (0, 1)$  and a random variable  $c_{\ell}$  such that for all  $k \geq \ell$ ,

$$\left|\frac{d_{ij}^{\alpha}(\ell,k)}{(1-\alpha)\alpha^{k-\ell}} - 1\right| < c_{\ell}\gamma^{k-\ell},$$

with probability 1. Further, we require that the distribution of  $c_{\ell}$  given  $\mathcal{F}_{\ell}$  depend only on  $(w(\ell), a(\ell))$ , and that there exist a constant  $\bar{c}$  such that

$$\mathbf{E}\left[c_{\ell} | w(\ell) = w, a(\ell) = a\right] < \bar{c} < \infty,$$

with probability 1 for all initial conditions  $w \in \mathbb{W}$  and  $a \in \mathbb{A}$ .

3. The distribution of  $\{d_{ij}^{\alpha}(\ell,k)|k = \ell, \ell+1, \ldots\}$  given  $\mathcal{F}_{\ell}$  depends only on  $w(\ell)$  and  $a(\ell)$ .

Note that from Assumption 4.1(2), it is clear that  $\sum_{k=\ell}^{\infty} d_{ij}^{\alpha}(\ell, k)$  converges absolutely with probability 1. Further, we have

$$\begin{aligned} \left| \sum_{k=\ell}^{\infty} \left( d_{ij}^{\alpha}(\ell,k) - (1-\alpha)\alpha^{k-\ell} \right) \right| &< \sum_{k=\ell}^{\infty} c_{\ell}(1-\alpha)\alpha^{k-\ell}\gamma^{k-\ell} \\ &= \frac{c_{\ell}(1-\alpha)}{1-\alpha\gamma}. \end{aligned}$$

Hence, with probability 1,

(4.2) 
$$\lim_{\alpha \uparrow 1} \sum_{k=\ell}^{\infty} d_{ij}^{\alpha}(\ell,k) = \lim_{\alpha \uparrow 1} \sum_{k=\ell}^{\infty} (1-\alpha) \alpha^{k-\ell} = 1.$$

# 5 Relation to Centralized Gradient Estimation

For convenience, define  $R = \max_{i,a,w} |r_i(w,a)|$ . The following lemma will be useful throughout this analysis.

**Lemma 5.1.** There exists constants C and  $\eta \in (0, 1)$  such that, for all k, l, and any functions g and f,

$$\begin{split} |\mathbf{E} \left[ g(w(\ell), a(\ell)) f(w(k), a(k)) \right] - \mathbf{E} \left[ g(w(\ell), a(\ell)) \right] \mathbf{E} \left[ f(w(k), a(k)) \right] | \\ & \leq \max_{w, a} |f(w, a)| \max_{w, a} |g(w, a)| C \eta^{|k-\ell|}. \end{split}$$

In particular, for an arbitrary function f,

$$\left\| \mathbb{E}\left[ f(w(\ell), a(\ell) \nabla_i(k) \right] \right\| \le \max_{w, a} |f(w, a)| LC \eta^{|k-\ell|},$$

*Proof.* The first statement follows immediately from Assumption 1.1. The second statement follows from the first once we observe (from Lemma 3.1) that

$$\mathbf{E}[\nabla_i(k)] = 0.$$

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**Lemma 5.2.** For each i, j,  $k \ge \ell$ ,  $\alpha \in (0, 1)$  and  $\beta \in (0, 1)$ ,

$$\mathbf{E}\left[\left\|z_{i}^{\beta}(k)d_{ij}^{\alpha}(\ell,k)\right\|\right|\mathcal{F}_{\ell}\right] < \frac{(1-\alpha)(1+\bar{c})L\alpha^{k-\ell}}{1-\beta}.$$

Proof. From Assumption 4.1(2),

$$|d_{ij}^{\alpha}(\ell,k)| < (1-\alpha)(1+c_{\ell})\alpha^{k-\ell}.$$

Then,

$$\begin{aligned} \left\| z_i^{\beta}(k) d_{ij}^{\alpha}(\ell, k) \right\| &\leq (1 - \alpha)(1 + c_{\ell}) L \alpha^{k-\ell} \sum_{u=0}^{k} \beta^{k-u} \\ &< \frac{(1 - \alpha)(1 + c_{\ell}) L \alpha^{k-\ell}}{1 - \beta}. \end{aligned}$$

The result follows after taking a conditional expectation.

Let

$$\hat{z}_{ij}^{\alpha\beta}(\ell,K) = \mathbb{E}\left[\left|\sum_{k=\ell}^{K-1} z_i^{\beta}(k) d_{ij}^{\alpha}(\ell,k)\right| \mathcal{F}_{\ell}\right].$$

By Lemma 5.2, for  $\alpha \in (0, 1)$  and  $\beta \in (0, 1)$ ,  $\{\hat{z}_{ij}^{\alpha\beta}(\ell, K) | K = \ell, \ell + 1, \ell + 2, \ldots\}$  is a Cauchy sequence, and therefore,

$$\hat{z}_{ij}^{\alpha\beta}(\ell) = \lim_{K \to \infty} \hat{z}_{ij}^{\alpha\beta}(\ell, K),$$

is well-defined and finite. The following lemma follows immediately.

**Lemma 5.3.** For any *i* and *j*,  $\alpha \in (0, 1)$ , and  $\beta \in (0, 1)$ ,

$$\lim_{K \to \infty} \left\| \frac{1}{K} \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell, K) - \hat{z}_{ij}^{\alpha\beta}(\ell) \right) \right] \right\| = 0.$$

**Lemma 5.4.** For any i,  $\ell$ , and  $\alpha \in (0,1)$ ,  $\lim_{K\to\infty} \hat{z}_{ij}^{\alpha 1}(\ell, K)$  is well-defined. Further, if we define  $\hat{z}_{ij}^{\alpha 1}(\ell) = \lim_{K\to\infty} \hat{z}_{ij}^{\alpha 1}(\ell, K)$ , then for any j,

$$\limsup_{\alpha \uparrow 1} \limsup_{K \to \infty} \left\| \frac{1}{K} \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( \hat{z}_{ij}^{\alpha 1}(\ell) - z_i^1(\ell) \right) \right] \right\| = 0.$$

Proof. Note that

$$\begin{split} \hat{z}_{ij}^{\alpha 1}(\ell, K) &= \mathbf{E}\left[\left.\sum_{k=\ell}^{K-1} \sum_{s=0}^{k} \nabla_{i}(s) d_{ij}^{\alpha}(\ell, k)\right| \mathcal{F}_{\ell}\right] \\ &= \mathbf{E}\left[\left.\sum_{s=0}^{\ell} \nabla_{i}(s) \sum_{k=\ell}^{K-1} d_{ij}^{\alpha}(\ell, k)\right| \mathcal{F}_{\ell}\right] + \mathbf{E}\left[\left.\sum_{s=\ell+1}^{K-1} \nabla_{i}(s) \sum_{k=s}^{K-1} d_{ij}^{\alpha}(\ell, k)\right| \mathcal{F}_{\ell}\right] \\ &= G_{ij}^{\alpha}(\ell, K) + H_{ij}^{\alpha}(\ell, K). \end{split}$$

For the term  $G_{ij}^{\alpha}(\ell, K)$ , note that

$$\lim_{K \to \infty} G_{ij}^{\alpha}(\ell, K) = z_i^1(\ell) \lim_{K \to \infty} f_{ij}^{\alpha}(w(\ell), a(\ell), K - \ell),$$

where, using Assumption 4.1(3), we define

$$f_{ij}^{\alpha}(w, a, K) = \mathbb{E}\left[\left|\sum_{k=0}^{K-1} d_{ij}^{\alpha}(0, k)\right| w(0) = w, a(0) = a\right].$$

Note that for J < K, from Assumption 4.1(2),

$$\begin{aligned} \left| f_{ij}^{\alpha}(w,a,K) - f_{ij}^{\alpha}(w,a,J) \right| &\leq (1-\alpha)(1+\bar{c}) \sum_{k=J}^{K-1} \alpha^k \\ &\leq (1+\bar{c})\alpha^J. \end{aligned}$$

Hence, for  $\alpha \in (0,1)$ ,  $\{f_{ij}^{\alpha}(w,a,K) | K = 1,2,\ldots\}$  is a Cauchy sequence, and we can define the limit

$$f_{ij}^{\alpha}(w,a) = \lim_{K \to \infty} f_{ij}^{\alpha}(w,a,K).$$

Further, the following limit exists,

$$\lim_{K \to \infty} \mathbb{E} \left[ \left[ G_{ij}^{\alpha}(\ell, K) \right| \mathcal{F}_{\ell} \right] = z_i^1(\ell) f_{ij}^{\alpha}(w(\ell), a(\ell)).$$

For the term  $H^{\alpha}_{ij}(\ell, K)$ , note that for J < K,

$$\begin{split} \left\| \mathbb{E} \left[ \left. H_{ij}^{\alpha}(\ell, K) - H_{ij}^{\alpha}(\ell, J) \right| \mathcal{F}_{\ell} \right] \right\| \\ &= \left\| \mathbb{E} \left[ \left[ \sum_{s=J}^{K-1} \nabla_{i}(s) \sum_{k=s}^{K-1} d_{ij}^{\alpha}(\ell, k) + \sum_{s=\ell+1}^{J-1} \nabla_{i}(s) \sum_{k=J}^{K-1} d_{ij}^{\alpha}(\ell, k) \right| \mathcal{F}_{\ell} \right] \right\| \\ &\leq L(1-\alpha)(1+\bar{c}) \left( \sum_{s=J}^{K-1} \sum_{k=s}^{K-1} \alpha^{k-\ell} + \sum_{s=\ell+1}^{J-1} \sum_{k=J}^{K-1} \alpha^{k-\ell} \right) \\ &\leq L(1+\bar{c}) \left( \sum_{s=J}^{K-1} \alpha^{s-\ell} + \sum_{s=\ell+1}^{J-1} \alpha^{J-\ell} \right) \\ &\leq L(1+\bar{c}) \left( \frac{\alpha^{J}}{1-\alpha} + (J-\ell+1)\alpha^{J-\ell} \right). \end{split}$$

Hence,  $\{H_{ij}^{\alpha}(\ell,K)|K=\ell+1,\ell+2,\ldots\}$  is a Cauchy sequence. Then, we can define

$$\hat{z}_{ij}^{\alpha 1}(\ell) = \lim_{K \to \infty} \hat{z}_{ij}^{\alpha 1}(\ell, K).$$

To establish the balance of the result, note that

$$\begin{split} \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( \hat{z}_{ij}^{\alpha 1}(\ell) - z_i^1(\ell) \right) \right] \right\| \\ &= \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \left( G_{ij}^{\alpha}(\ell, M) + H_{ij}^{\alpha}(\ell, M) - z_i^1(\ell) \right) \right] \right\| \\ &\leq \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( 1 - f_{ij}^{\alpha}(w(\ell), a(\ell)) \right) z_i^1(\ell) \right] \right\| \\ &+ \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{k=0}^{K-1} r_j(\ell) \lim_{M \to \infty} H_{ij}^{\alpha}(\ell, M) \right] \right\| \\ &= (\mathbf{A}) + (\mathbf{B}). \end{split}$$

For term (A), note that

$$\begin{split} & \left| \frac{1}{K} \operatorname{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( 1 - f_{ij}^{\alpha}(w(\ell), a(\ell)) \right) z_i^1(\ell) \right] \right\| \\ & = \left\| \frac{1}{K} \operatorname{E} \left[ \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} r_j(\ell) \left( 1 - f_{ij}^{\alpha}(w(\ell), a(\ell)) \right) \nabla_i(u) \right] \right\| \\ & \leq \left. \frac{RLC}{K} \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} \eta^{\ell-u} \max_{w \in \mathbb{W}, a \in \mathbb{A}} \left| 1 - f_{ij}^{\alpha}(w, a) \right| \\ & \leq \left. \frac{RLC}{1 - \eta} \max_{w \in \mathbb{W}, a \in \mathbb{A}} \left| 1 - f_{ij}^{\alpha}(w, a) \right|. \end{split}$$

Note that this bound is independent of K, and, by the Dominated Convergence Theorem and (4.2),  $\lim_{\alpha \uparrow 1} f_{ij}^{\alpha}(w, a) = 1$ , hence the (A) term vanishes.

For term (**B**), note that for  $s > \ell$ ,  $\mathbb{E}\left[\left. \nabla_i(s) \right| \mathcal{F}_\ell \right] = 0$  from Lemma 3.1. Hence,

$$\begin{split} \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{k=0}^{K-1} r_j(\ell) \lim_{M \to \infty} H_{ij}^{\alpha}(\ell, K) \right] \right\| \\ &= \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{k=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \mathbf{E} \left[ \sum_{s=\ell+1}^{M-1} \nabla_i(s) \sum_{k=s}^{K-1} d_{ij}^{\alpha}(\ell, k) \middle| \mathcal{F}_{\ell} \right] \right] \right\| \\ &= \left\| \mathbf{E} \left[ \sum_{s=\ell+1}^{K-1} \nabla_i(s) \sum_{k=s}^{K-1} \left( d_{ij}^{\alpha}(\ell, k) - (1-\alpha)\alpha^{k-\ell} \right) \middle| \mathcal{F}_{\ell} \right] \right\| \\ &\leq \sum_{s=\ell+1}^{K-1} L \sum_{k=s}^{K-1} \mathbf{E} \left[ c_{\ell}(1-\alpha)\alpha^{k-\ell}\gamma^{k-\ell} \middle| \mathcal{F}_{\ell} \right] \\ &\leq \bar{c}(1-\alpha)L \sum_{s=\ell+1}^{K-1} \frac{\alpha^{s-\ell}\gamma^{s-\ell}}{1-\alpha\gamma} \\ &\leq \bar{c}(1-\alpha)L \frac{\alpha\gamma}{(1-\alpha\gamma)^2}. \end{split}$$

Note that this bound is independent of K and tends to 0 as  $\alpha \uparrow 1$ . Hence, term (B) vanishes and the result is established.

Because the limit is well-defined, we extend our definition of  $\hat{z}_{ij}^{\alpha\beta}(\ell)$  to the case of  $\beta=1$ :

$$\hat{z}_{ij}^{\alpha 1}(\ell) = \lim_{K \to \infty} \hat{z}_{ij}^{\alpha 1}(\ell, K).$$

Lemma 5.5. For any i and j,

$$\limsup_{\beta \uparrow 1} \limsup_{K \to \infty} \left\| \frac{1}{K} \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( z_i^1(\ell) - z_i^\beta(\ell) \right) \right] \right\| = 0.$$

Proof. We have

$$\mathbb{E}\left[\sum_{\ell=0}^{K-1} r_{j}(\ell) \left(z_{i}^{1}(\ell) - z_{i}^{\beta}(\ell)\right)\right] = \mathbb{E}\left[\sum_{\ell=0}^{K-1} r_{j}(\ell) \sum_{k=0}^{\ell} (1 - \beta^{\ell-k}) \nabla_{i}(k)\right]$$
$$= \sum_{\ell=0}^{K-1} \sum_{k=0}^{\ell} (1 - \beta^{\ell-k}) \mathbb{E}\left[r_{j}(\ell) \nabla_{i}(k)\right]$$

From Lemma 5.1,

$$\|\mathbf{E}[r_j(\ell)\nabla_i(k)]\| \le RLC\eta^{\ell-k}.$$

It follows that

$$\begin{split} \left\| \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( z_i^1(\ell) - z_i^\beta(\ell) \right) \right] \right\| &\leq RLC \sum_{\ell=0}^{K-1} \sum_{k=0}^{\ell} \left( 1 - \beta^{\ell-k} \right) \eta^{\ell-k} \\ &\leq KRLC \left( \frac{1}{1-\eta} - \frac{1}{1-\beta\eta} \right), \end{split}$$

The result follows.

**Lemma 5.6.** For any *i*, *j*, and  $\alpha \in (0, 1)$ ,

$$\limsup_{\beta \uparrow 1} \limsup_{K \to \infty} \left\| \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell) - \hat{z}_{ij}^{\alpha1}(\ell) \right) \right] \right\| = 0.$$

Proof. Note that

$$\begin{split} \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell) - \hat{z}_{ij}^{\alpha1}(\ell) \right) \right] \\ &= \left[ \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \mathbf{E} \left[ \sum_{k=\ell}^{M-1} \left( z_i^{\beta}(k) - z_i^{1}(k) \right) d_{ij}^{\alpha}(\ell, k) \middle| \mathcal{F}_{\ell} \right] \right] \\ &= \left[ \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \mathbf{E} \left[ \sum_{k=\ell}^{M-1} \left( \beta^{k-\ell} z_i^{\beta}(\ell) - z_i^{1}(\ell) \right) d_{ij}^{\alpha}(\ell, k) \middle| \mathcal{F}_{\ell} \right] \right] \\ &+ \frac{1}{K} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \mathbf{E} \left[ \sum_{k=\ell}^{M-1} \left( z_i^{\beta}(k) - \beta^{k-\ell} z_i^{\beta}(\ell) - z_i^{1}(k) + z_i^{1}(\ell) \right) d_{ij}^{\alpha}(\ell, k) \middle| \mathcal{F}_{\ell} \right] \right] \\ &= (\mathbf{A}) + (\mathbf{B}). \end{split}$$

Consider term (A). From Assumption 4.1(3), we can define

$$g_{ij}^{\alpha\beta}(w,a,M) = \mathbb{E}\left[\left.\sum_{k=0}^{M-1} \beta^k d_{ij}^{\alpha}(0,k)\right| w(0) = w, a(0) = a\right].$$

By Assumption 4.1(2), for  $\alpha \in (0,1)$  and  $\beta \in [0,1]$ , and for J < K

$$\begin{split} \left| g_{ij}^{\alpha\beta}(w,a,K) - g_{ij}^{\alpha\beta}(w,a,J) \right| \\ &\leq \mathbf{E} \left[ (1-\alpha)(1+c_0) \sum_{k=J}^{K-1} \alpha^k \beta^k \right| w(0) = w, a(0) = a \right] \\ &\leq \frac{(1-\alpha)(1+\bar{c})\alpha^J \beta^J}{1-\alpha\beta}. \end{split}$$

Hence,  $\{g_{ij}^{\alpha\beta}(w,a,M)|M=1,2,\ldots\}$  is a Cauchy sequence, and we can define the limit

$$g_{ij}^{\alpha\beta}(w,a) = \lim_{M \to \infty} g_{ij}^{\alpha\beta}(w,a,M).$$

Then, term (A) becomes

$$\begin{split} \frac{1}{K} \left\| \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \lim_{M \to \infty} \mathbf{E} \left[ \sum_{k=\ell}^{M-1} \left( \beta^{k-\ell} z_i^{\beta}(\ell) - z_i^{1}(\ell) \right) d_{ij}^{\alpha}(\ell, k) \middle| \mathcal{F}_{\ell} \right] \right] \right\| \\ &= \frac{1}{K} \left\| \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( g_{ij}^{\alpha\beta}(w(\ell), a(\ell)) z_i^{\beta}(\ell) - g_{ij}^{\alpha1}(w(\ell), a(\ell)) z_i^{1}(\ell) \right) \right] \right\| \\ &= \frac{1}{K} \left\| \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} r_j(\ell) \left( \beta^{\ell-u} g_{ij}^{\alpha\beta}(w(\ell), a(\ell)) - g_{ij}^{\alpha1}(w(\ell), a(\ell)) \right) \nabla_i(u) \right] \right\| \end{split}$$

Note that

$$\begin{aligned} \left| \beta^{\ell-u} g_{ij}^{\alpha\beta}(w(\ell), a(\ell)) - g_{ij}^{\alpha1}(w(\ell), a(\ell)) \right| \\ &\leq \lim_{M \to \infty} \mathbb{E} \left[ (1-\alpha)(1+c_0) \sum_{k=0}^{M-1} (1-\beta^{k+\ell-u}) \alpha^k \right| w(0) = w, a(0) = a \\ &\leq (1-\alpha)(1+\bar{c}) \left( \frac{1}{1-\alpha} - \frac{\beta^{\ell-u}}{1-\alpha\beta} \right) \end{aligned}$$

From Lemma 5.1,

$$\begin{aligned} &\left| \mathbb{E} \left[ r_j(\ell) \left( \beta^{\ell-u} g_{ij}^{\alpha\beta}(w(\ell), a(\ell)) - g_{ij}^{\alpha1}(w(\ell), a(\ell)) \right) \nabla_i(u) \right] \\ &\leq RLC(1-\alpha)(1+\bar{c}) \eta^{\ell-u} \left( \frac{1}{1-\alpha} - \frac{\beta^{\ell-u}}{1-\alpha\beta} \right). \end{aligned}$$

Applying this to term (A),

$$\begin{split} \frac{1}{K} \left\| \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} r_j(\ell) \left( \beta^{\ell-u} g_{ij}^{\alpha\beta}(w(\ell), a(\ell)) - g_{ij}^{\alpha1}(w(\ell), a(\ell)) \right) \nabla_i(u) \right] \right| \\ &\leq \left. \frac{RLC(1-\alpha)(1+\bar{c})}{K} \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} \eta^{\ell-u} \left( \frac{1}{1-\alpha} - \frac{\beta^{\ell-u}}{1-\alpha\beta} \right) \right. \\ &\leq \left. \frac{RLC(1-\alpha)(1+\bar{c})}{K} \sum_{\ell=0}^{K-1} \left( \frac{1}{(1-\alpha)(1-\eta)} - \frac{1}{(1-\alpha\beta)(1-\eta\beta)} \right) \right. \\ &= \left. RLC(1-\alpha)(1+\bar{c}) \left( \frac{1}{(1-\alpha)(1-\eta)} - \frac{1}{(1-\alpha\beta)(1-\eta\beta)} \right), \end{split}$$

which is a constant over K and vanishes as  $\beta\uparrow 1.$ 

We are left with term (B). Note that

$$\begin{split} & \mathsf{E}\left[r_{j}(\ell)\lim_{M\to\infty}\mathsf{E}\left[\sum_{k=\ell}^{M-1}\left(z_{i}^{\beta}(k)-\beta^{k-\ell}z_{i}^{\beta}(\ell)-z_{i}^{1}(k)+z_{i}^{1}(\ell)\right)d_{ij}^{\alpha}(\ell,k)\bigg|\,\mathcal{F}_{\ell}\right]\right] \\ & \leq RL\,\mathsf{E}\left[\lim_{M\to\infty}\mathsf{E}\left[\sum_{k=\ell}^{M-1}(1-\alpha)(1+c_{\ell})\alpha^{k-\ell}\sum_{u=\ell+1}^{k}(1-\beta^{k-u})\bigg|\,\mathcal{F}_{\ell}\right]\right] \\ & \leq RL\,\mathsf{E}\left[\lim_{M\to\infty}\sum_{k=\ell}^{M-1}(1-\alpha)(1+\bar{c})\alpha^{k-\ell}\left(k-\ell-\frac{1-\beta^{k-\ell}}{1-\beta}\right)\right] \\ & \leq RL\,\mathsf{E}\left[(1-\alpha)(1+\bar{c})\left(\frac{\alpha}{(1-\alpha)^{2}}-\frac{1}{1-\beta}\left(\frac{1}{1-\alpha}-\frac{1}{1-\alpha\beta}\right)\right)\right] \\ & = RL(1-\alpha)(1+\bar{c})\left(\frac{\alpha}{(1-\alpha)^{2}}-\frac{\alpha}{(1-\alpha)(1-\alpha\beta)}\right), \end{split}$$

which, is a constant independent of  $\ell$  and goes to 0 as  $\beta \uparrow 1$ . The result follows.  $\Box$ Lemma 5.7. For all *i*, and  $\alpha \in (0, 1)$ ,  $\beta \in (0, 1)$ ,

$$\lim_{K\to\infty}\frac{1}{K}\operatorname{E}\left[\sum_{k=0}^{K-1}\chi_i(k)\right],$$

exists.

Proof. We have

$$\begin{split} \frac{1}{K} \mathbf{E} \left[ \sum_{k=0}^{K-1} \chi_i(k) \right] \\ &= \frac{1}{K} \mathbf{E} \left[ \sum_{j=1}^n \sum_{\ell=0}^{K-1} r_j(\ell) \sum_{k=\ell}^{K-1} z_i^{\beta}(k) d_{ij}^{\alpha}(\ell, k) \right] \\ &= \frac{1}{K} \mathbf{E} \left[ \sum_{j=1}^n \sum_{\ell=0}^{K-1} r_j(\ell) z_i^{\beta}(\ell) \sum_{k=\ell}^{K-1} \beta^{k-\ell} d_{ij}^{\alpha}(\ell, k) \right] \\ &+ \frac{1}{K} \mathbf{E} \left[ \sum_{j=1}^n \sum_{\ell=0}^{K-1} r_j(\ell) \sum_{k=\ell}^{K-1} \left( z_i^{\beta}(k) - \beta^{k-\ell} z_i^{\beta}(\ell) \right) d_{ij}^{\alpha}(\ell, k) \right] \\ &= (\mathbf{A}) + (\mathbf{B}). \end{split}$$

We will first examine term (A). Define

$$f_{ij}^{\alpha\beta}(w,a,K) = \mathbb{E}\left[\sum_{k=0}^{K-1} \beta^k d_{ij}^{\alpha}(0,k) \middle| w(0) = w, a(0) = a\right].$$

By Assumption 4.1(2), for J < K,

$$\begin{split} \left| f_{ij}^{\alpha\beta}(w,a,K) - f_{ij}^{\alpha\beta}(w,a,J) \right| \\ &= \left| \mathsf{E} \left[ \sum_{k=J}^{K-1} \beta^k d_{ij}^{\alpha}(0,k) \right| w(0) = w, a(0) = a \right] \right| \\ &\leq \left| \mathsf{E} \left[ (1-\alpha)(1+c_0) \sum_{k=J}^{K-1} \beta^k \alpha^k \right| w(0) = w, a(0) = a \right] \right| \\ &\leq \frac{(1-\alpha)(1+\bar{c})\alpha^J \beta^J}{(1-\alpha\beta)}. \end{split}$$

Hence,  $\{f_{ij}^{\alpha\beta}(w, a, K)|K = 1, 2, ...\}$  is a Cauchy sequence, and we can define the limit

$$f_{ij}^{\alpha\beta}(w,a) = \lim_{K \to \infty} f_{ij}^{\alpha\beta}(w,a,K).$$

Hence, we can define a constant

$$C_{ij}^{\alpha\beta} = \sup_{w \in \mathbb{W}, a \in \mathbb{A}, K > 0} \left| f_{ij}^{\alpha\beta}(w, a, K) \right|.$$

Define

$$g_{ij}^{\alpha\beta}(w,a,K) = \mathbb{E}\left[\sum_{\ell=0}^{K-1} \beta^{\ell} r_j(\ell) f_{ij}^{\alpha\beta}(w(\ell),a(\ell),K-\ell) \middle| w(0) = w, a(0) = a\right].$$

Then, for J < K,

$$\begin{aligned} \left| g_{ij}^{\alpha\beta}(w,a,K) - g_{ij}^{\alpha\beta}(w,a,J) \right| &\leq 2C_{ij}^{\alpha\beta}R\sum_{\ell=J}^{K}\beta^{\ell} \\ &\leq \frac{2C_{ij}^{\alpha\beta}R\beta^{J}}{1-\beta}. \end{aligned}$$

Hence,  $\{g_{ij}^{\alpha\beta}(w, a, K)|K = 1, 2, ...\}$  is a Cauchy sequence, and we can define the limit

$$g_{ij}^{\alpha\beta}(w,a) = \lim_{K \to \infty} g_{ij}^{\alpha\beta}(w,a,K).$$

Since  $\mathbb{W}$  and  $\mathbb{A}$  are finite, this convergence is uniform over w and a.

Returning to term (A), note that using Assumption 4.1(3),

$$\begin{split} \frac{1}{K} \mathbf{E} \left[ \sum_{j=1}^{n} \sum_{\ell=0}^{K-1} r_j(\ell) z_i^{\beta}(\ell) \sum_{k=\ell}^{K-1} \beta^{k-\ell} d_{ij}^{\alpha}(\ell, k) \right] \\ &= \frac{1}{K} \sum_{j=1}^{n} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} \sum_{u=0}^{\ell} r_j(\ell) \beta^{\ell-u} \nabla_i(u) \sum_{k=\ell}^{K-1} \beta^{k-\ell} d_{ij}^{\alpha}(\ell, k) \right] \\ &= \frac{1}{K} \sum_{j=1}^{n} \mathbf{E} \left[ \sum_{u=0}^{K-1} \nabla_i(u) \sum_{\ell=u}^{K-1} r_j(\ell) \beta^{\ell-u} f_{ij}^{\alpha\beta}(w(\ell), a(\ell), K-\ell) \right] \\ &= \frac{1}{K} \sum_{j=1}^{n} \mathbf{E} \left[ \sum_{u=0}^{K-1} \nabla_i(u) g_{ij}^{\alpha\beta}(w(u), a(u), K-\ell) \right] \end{split}$$

Since  $\nabla_i(u)$  is bounded, we have

$$\lim_{K \to \infty} \frac{1}{K} \left\| \mathbb{E} \left[ \sum_{u=0}^{K-1} \nabla_i(u) \left( g_{ij}^{\alpha\beta}(w(u), a(u)) - g_{ij}^{\alpha\beta}(w(u), a(u), K-u) \right) \right] \right\| = 0.$$

Yet, since  $(w(\ell), a(\ell))$  is ergodic, the limit

$$\lim_{K \to \infty} \frac{1}{K} \sum_{j=1}^{n} \mathbb{E} \left[ \sum_{u=0}^{K-1} \nabla_i(u) g_{ij}^{\alpha\beta}(w(u), a(u)) \right],$$

exists, hence the limit of term (A) exists as  $K \rightarrow \infty$ . We are left with term (B). Note that

$$\begin{split} &\frac{1}{K} \mathbf{E} \left[ \sum_{j=1}^{n} \sum_{\ell=0}^{K-1} r_j(\ell) \sum_{k=\ell}^{K-1} \left( z_i^{\beta}(k) - \beta^{k-\ell} z_i^{\beta}(\ell) \right) d_{ij}^{\alpha}(\ell,k) \right] \\ &= \frac{1}{K} \sum_{j=1}^{n} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \sum_{k=\ell}^{K-1} d_{ij}^{\alpha}(\ell,k) \sum_{u=\ell+1}^{k} \beta^{k-u} \nabla_i(u) \right] \\ &= \frac{1}{K} \sum_{j=1}^{n} \mathbf{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) h_{ij}^{\alpha\beta}(w(\ell), a(\ell), K - \ell) \right], \end{split}$$

where

$$h_{ij}^{\alpha\beta}(w,a,K) = \mathbb{E}\left[\left|\sum_{k=0}^{K-1} d_{ij}^{\alpha}(0,k) \sum_{u=1}^{k} \beta^{k-u} \nabla_{i}(u)\right| w(0) = w, a(0) = a\right].$$

Then, for J < K,

$$\begin{split} \left\| h_{ij}^{\alpha\beta}(w,a,K) - h_{ij}^{\alpha\beta}(w,a,J) \right\| \\ &\leq \mathbf{E} \left[ L(1-\alpha)(1+c_0) \sum_{k=J}^{K-1} \alpha^k \sum_{u=1}^k \beta^{k-u} \middle| w(0) = w, a(0) = a \right] \\ &\leq \frac{L(1-\alpha)(1+\bar{c})\alpha^J}{(1-\alpha)(1-\beta)}. \end{split}$$

Hence,  $\{h_{ij}^{\alpha\beta}(w, a, K)|K = 1, 2, ...\}$  is a Cauchy sequence, and we can define the limit

$$h_{ij}^{\alpha\beta}(w,a) = \lim_{K \to \infty} h_{ij}^{\alpha\beta}(w,a,K)$$

Then, we have

$$\lim_{K \to \infty} \frac{1}{K} \left\| \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) \left( h_{ij}^{\alpha\beta}(w(\ell), a(\ell)) - h_{ij}^{\alpha\beta}(w(\ell), a(\ell), K-\ell) \right) \right] \right\| = 0.$$

Yet, since  $(w(\ell), a(\ell))$  is ergodic, the limit

$$\lim_{K \to \infty} \frac{1}{K} \sum_{j=1}^{n} \mathbb{E} \left[ \sum_{\ell=0}^{K-1} r_j(\ell) h_{ij}^{\alpha\beta}(w(\ell), a(\ell)) \right],$$

exists, hence the limit of term (**B**) exists as  $K \rightarrow \infty$ .

**Theorem 5.1.** Holding  $\theta$  fixed, for all  $i, \alpha \in (0, 1)$ , and  $\beta \in (0, 1)$ , define

$$\nabla_{\theta_i}^{\alpha\beta}\lambda(\theta) = \lim_{K \to \infty} \frac{1}{K} \operatorname{E}\left[\sum_{k=0}^{K-1} \chi_i(k)\right]$$

exists. Further,

$$\limsup_{\alpha\uparrow 1}\limsup_{\beta\uparrow 1}\left\|\nabla_{\theta_{i}}^{\alpha\beta}\lambda(\theta)-\nabla_{\theta_{i}}\lambda(\theta)\right\|=0.$$

Proof. From Theorem 3.1, it suffices to prove that

$$\limsup_{\alpha\uparrow 1} \limsup_{\beta\uparrow 1} \lim_{K\to\infty} \mathcal{L}_i^{\alpha\beta}(K) = 0,$$

where

$$\mathcal{L}_{i}^{\alpha\beta}(K) = \left\| \frac{1}{K} \mathbb{E}\left[ \sum_{k=0}^{K-1} \chi_{i}(k) \right] - \frac{1}{K} \mathbb{E}\left[ \sum_{k=0}^{K-1} \overline{\chi}_{i}(k) \right] \right\|.$$

Note that from Lemma 5.7 and Theorem 3.1,  $\lim_{K\to\infty} \mathcal{L}_i^{\alpha\beta}(K)$  exists when  $\alpha \in (0,1)$  and  $\beta \in (0,1)$ .

We have

$$\begin{split} \limsup_{\beta\uparrow 1} \sup_{K\to\infty} \lim_{K\to\infty} \mathcal{L}_{i}^{\alpha\beta}(K) \\ &= \limsup_{\beta\uparrow 1} \lim_{K\to\infty} \left\| \frac{1}{nK} \operatorname{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell,K) - z_{i}^{\beta}(\ell) \right) \right] \right\| \\ &\leq \limsup_{\beta\uparrow 1} \sup_{K\to\infty} \left\| \frac{1}{nK} \operatorname{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell,K) - \hat{z}_{ij}^{\alpha\beta}(\ell) \right) \right] \right\| \\ &+ \limsup_{\beta\uparrow 1} \limsup_{K\to\infty} \left\| \frac{1}{nK} \operatorname{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( \hat{z}_{ij}^{\alpha\beta}(\ell) - \hat{z}_{ij}^{\alpha1}(\ell) \right) \right] \right\| \\ &+ \limsup_{\beta\uparrow 1} \limsup_{K\to\infty} \left\| \frac{1}{nK} \operatorname{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( \hat{z}_{ij}^{\alpha1}(\ell) - z_{i}^{1}(\ell) \right) \right] \right\| \\ &+ \limsup_{\beta\uparrow 1} \limsup_{K\to\infty} \left\| \frac{1}{nK} \operatorname{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( z_{i}^{1}(\ell) - z_{i}^{\beta}(\ell) \right) \right] \right\| \\ &= (\mathbf{A}) + (\mathbf{B}) + (\mathbf{C}) + (\mathbf{D}). \end{split}$$

From Lemma 5.3, term (A) equals 0. From Lemma 5.6, term (B) equals 0. From Lemma 5.5, term (D) equals 0. Hence, taking a limit as  $\alpha \uparrow 1$ ,

$$\begin{aligned} 0 &\leq \lim_{\alpha \uparrow 1} \limsup_{\beta \uparrow 1} \lim_{K \to \infty} \mathcal{L}_{i}^{\alpha \beta}(K) \\ &\leq \lim_{\alpha \uparrow 1} \sup_{\beta \uparrow 1} \sup_{K \to \infty} \lim_{K \to \infty} \mathcal{L}_{i}^{\alpha \beta}(K) \\ &\leq \lim_{\alpha \uparrow 1} \sup_{K \to \infty} \lim_{K \to \infty} \left\| \frac{1}{nK} \mathbb{E} \left[ \sum_{j=1}^{n} \sum_{k=0}^{K-1} r_{j}(\ell) \left( \hat{z}_{ij}^{\alpha 1}(\ell) - z_{i}^{1}(\ell) \right) \right] \right\| \\ &= 0, \end{aligned}$$

where we use Lemma 5.4.

### 6 Communication Protocol

In this section, we will describe a simple protocol that allows communication of rewards in a fashion that satisfies the requirements of Assumption 4.1. This protocol communicates the rewards across the network over time using a distributed averaging procedure.

In order to motivate our protocol, consider a different problem. Imagine each component i in the network is given a real value  $R_i$ . Our goal is to design an asynchronous distributed protocol through which each node will obtain the average

$$\overline{R} = \frac{1}{n} \sum_{i=1}^{n} R_i.$$

To do this, define the vector  $Y(0) \in \mathbb{R}^n$  by  $Y_i(0) = R_i$  for all *i*. For each edge (i, j), define a matrix  $Q^{(i,j)} \in \mathbb{R}^{n \times n}$  by

$$Q_{\ell}^{(i,j)}Y = \begin{cases} \frac{Y_i + Y_j}{2} & \text{if } \ell \in \{i,j\}, \\ Y_{\ell} & \text{otherwise.} \end{cases}$$

At each time t, choose an edge (i, j), and set  $Y(k+1) = Q^{(i,j)}(Y(k))$ . If the graph is connected and every edge is sampled infinitely often, then  $\lim_{k\to\infty} Y(t) = \overline{Y}$ , where  $\overline{Y}_i = \overline{R}$ . To see this, note that the operators  $Q^{(i,j)}$  preserve the average value of the vector, hence

$$\frac{1}{n}\sum_{i=1}^{n}Y_{i}(k)=\overline{R}.$$

Further, for any k, either Y(k + 1) = Y(k) or  $||Y(k + 1) - \overline{Y}|| < ||Y(k) - \overline{Y}||$ . Further,  $\overline{Y}$  is the unique vector with average value  $\overline{R}$  that is a fixed point for all operators  $Q^{(i,j)}$ . Hence, as long as the graph is connected and each edge is sampled infinitely often,  $Y_i(k) \rightarrow \overline{R}$  as  $k \rightarrow \infty$  and the components agree to the common average  $\overline{R}$ .

In the context of distributed optimization protocol, we will assume that each component *i* maintains a scalar value  $Y_i(k)$  at time *k* representing an estimate of the total global reward. We will define a structure by which nodes communicate. In particular, for an ordered set of distinct edges  $S = ((i_i, j_1), \ldots, (i_{|S|}, j_{|S|}))$ , we will define a set  $\mathbb{W}_S \subset \mathbb{W}$ . Let  $\sigma(E)$  be the set of all possible ordered sets of disjoint edges *S*, including the empty set. We will assume that the sets  $\{W_S | S \in \sigma(E)\}$  are disjoint and together form a partition of  $\mathbb{W}$ .

If  $w(k) \in W_S$ , for some set S, we will assume that the components along the edges in S communicate in the order specified by S. Define

$$Q^S = Q^{(i_{|S|}, j_{|S|})} \cdots Q^{(i_1, j_1)}$$

where the terms in the product are taken over the order specified by S. Define  $R(k) = (r_1(k), \ldots, r_n(k))$  as the vector of rewards occurring at time k. The update rule for the vector Y(k) is given by

$$Y(k+1) = R(k+1) + \alpha Q^{S(k+1)}Y(k),$$

where S(k + 1) is the element of  $\sigma(E)$  that contains w(k + 1). We will make the following assumption.

**Assumption 6.1.** Define the set of edges  $\hat{E}$  by

$$E = \{(i, j) | (i, j) \in S \text{ and } \mathbb{W}_S \neq \emptyset\}.$$

The graph  $(V, \hat{E})$  is connected.

Since the process (w(k), a(k)) is aperiodic and has a single recurrent class (Assumption 1.1), this assumption guarantees that every edge on a connected subgraph is sampled infinitely often.

Policy parameters are updated at each component according to the rule:

$$\theta_i(k+1) = \theta_i(k) + \epsilon z_i^\beta(k)(1-\alpha)Y_i(k).$$

Note that, for this scheme, in relation to (4.1), we have

(6.1) 
$$d_{ji}^{\alpha}(\ell,k) = n(1-\alpha)\alpha^{k-\ell} \left[\hat{Q}(\ell,k)\right]_{ij},$$

where

$$\hat{Q}(\ell,k) = Q^{S(k-1)} \cdots Q^{S(\ell)},$$

**Lemma 6.1.** The variables  $d_{ii}^{\alpha}(\ell, k)$  defined by (6.1) satisfy Assumption 4.1.

*Proof.* By definition, Assumption 4.1(1) is satisfied. Assumption 4.1(3) is also clearly satisfied.

Define the matrix  $\mathcal{E}$  by  $\mathcal{E}_{ij} = 1/n$  for all i, j. Then, Assumption 4.1(2) is equivalent to

(6.2) 
$$\left\| \hat{Q}(\ell,k) - \mathcal{E} \right\| < c_{\ell} \gamma^{k-\ell},$$

for a constant  $\gamma \in (0, 1)$  and a random variable  $c_{\ell}$ , such that the distribution of  $c_{\ell}$  given  $\mathcal{F}_{\ell}$  depends only on  $(w(\ell), a(\ell))$ , and with  $\mathbb{E}[c_{\ell}|\mathcal{F}_{\ell}] \leq \bar{c}$  for a constant  $\bar{c} < \infty$ .

From Assumption 1.1 and Assumption 6.1, there must be some set of states  $w_0, \ldots, w_{m-1}$  and corresponding edge sets  $\bar{S}_0, \ldots, \bar{S}_{m-1}$ , such that for each i,  $w_i \in W_{\bar{S}_i}$ ,

$$\bigcup_{i=0}^{m-1} \bar{S}_i = \hat{E},$$

and for some  $\ell > 0$ ,

$$\Pr\{w(\ell) = w_0, \dots, w(\ell + m - 1) = w_{m-1}\} > 0.$$

Since this event occurs once with positive probability, it must occur infinitely often with probability 1. Define N(k) to be the number of non-overlapping occurrences at or before time k, that is

$$N(k) = \sum_{\ell=0}^{k} \mathbf{1}_{\{w(\ell) \in \mathbb{W}_{\bar{S}_0}, \dots, w(\ell+m-1) \in \mathbb{W}_{\bar{S}_{m-1}}\}}$$

Define matrix  $\overline{Q}$  and the set  $\{(i_0, j_0), \ldots, (i_M, j_M)\}$  by

$$\overline{Q} = Q^{\overline{S}_m} \cdots Q^{\overline{S}_0} = \prod_{\ell=0}^M Q^{(i_\ell, j_\ell)}.$$

and let

$$\overline{\gamma} = \left\| \overline{Q} - \mathcal{E} \right\|.$$

We wish to show that  $\overline{\gamma} < 1$ . Assume otherwise, and let  $\hat{x}$  be a vector such that  $\|\hat{x}\| = 1$  and  $\|(\overline{Q} - \mathcal{E})\hat{x}\| \ge 1$ . Note that for every (i, j),  $\mathcal{E}Q^{(i,j)} = Q^{(i,j)}\mathcal{E} = \mathcal{E}$ , and  $\mathcal{E}^2 = \mathcal{E}$ . Hence,

$$\overline{Q} - \mathcal{E} = \prod_{\ell=0}^{M} \left( Q^{(i_{\ell}, j_{\ell})} - \mathcal{E} \right).$$

Further, for any (i, j) and any vector x, either  $Q^{(i,j)}x = x$  or  $||(Q^{(i,j)} - \mathcal{E})x|| < ||(I - \mathcal{E})x||$ . Since

$$||(I - \mathcal{E})x||^2 = x^T (I - \mathcal{E})x = x^T (I - \mathcal{E}^2)x = ||x||^2 - ||\mathcal{E}x||^2 \le ||x||^2,$$

we have

$$1 \le \left\| (\overline{Q} - \mathcal{E}) \hat{x} \right\| \le \left\| \left( \prod_{\ell=0}^{M} \left( Q^{(i_{\ell}, j_{\ell})} - \mathcal{E} \right) \right) \hat{x} \right\| \le \prod_{\ell=0}^{M} \left\| Q^{(i_{\ell}, j_{\ell})} - \mathcal{E} \right\| \le 1.$$

Then, it follows that for every  $(i, j) \in \hat{E}$ ,  $Q^{(i,j)}\hat{x} = \hat{x}$ . Since the set of edges  $\hat{E}$  connects every node in the graph, if, for some pair of components p and q,  $\hat{x}_p \neq \hat{x}_q$ , we could construct a path of edges in  $\hat{E}$  between p and q, and for some edge (i, j) along this path,  $Q^{(i,j)}\hat{x} \neq \hat{x}$ . Hence, the vector  $\hat{x}$  must be constant. Then,  $\|(\overline{Q} - \mathcal{E})\hat{x}\| = 0$ . We have a contradiction, hence  $\overline{\gamma} < 1$ .

Set

$$t_{\ell} = \min\{k \ge 0 | N(k) = \ell\}$$

Define  $\overline{\Delta} = \mathbb{E}[t_{\ell+1} - t_{\ell}]$  (for  $\ell \geq 1$ ) to be the expected time between nonoverlapping observations of the communication pattern associated with  $\overline{Q}$ , and pick arbitrary  $\epsilon \in (0,1)$  and  $\delta \in (0,1/\overline{\Delta})$ . Define  $\gamma = \overline{\gamma}^{\delta} \in (0,1)$ , and note that  $\overline{\gamma} < \gamma^{\overline{\Delta}} < 1$ . Returning to (6.2), we have, for  $\ell < k$ ,

where

$$c_{\ell} = \gamma^{-(1-\epsilon)m} \left( 1 + \sup_{\tau > 0} \gamma^{\bar{\Delta}(N(\ell+\tau) - N(\ell)) - (1-\epsilon)\tau} \right)$$

We wish to consider  $E[c_{\ell}|\mathcal{F}_{\ell}]$ . Note that the distribution of  $c_{\ell}$  given  $\mathcal{F}_{\ell}$  depends only on  $(w(\ell), a(\ell))$ . It suffices consider the case where  $\ell = 0$  over varying initial conditions (w(0), a(0)). Then, we have

$$\begin{split} & \operatorname{E}\left[\sup_{\tau} \gamma^{\bar{\Delta}N(\tau)-(1-\epsilon)\tau} \middle| \mathcal{F}_{0}\right] \\ &= \int_{1}^{\infty} \operatorname{Pr}\left\{\sup_{\tau} \gamma^{\bar{\Delta}N(\tau)-(1-\epsilon)\tau} > x \middle| \mathcal{F}_{0}\right\} dx \\ &= (-\log\gamma) \int_{0}^{\infty} \operatorname{Pr}\left\{\sup_{\tau} \gamma^{\bar{\Delta}N(\tau)-(1-\epsilon)\tau} > \gamma^{-u} \middle| \mathcal{F}_{0}\right\} \gamma^{-u} du \\ &= (-\log\gamma) \int_{0}^{\infty} \operatorname{Pr}\left\{\sup_{\tau} (1-\epsilon)\tau - \bar{\Delta}N(\tau) > u \middle| \mathcal{F}_{0}\right\} \gamma^{-u} du \\ &= (-\log\gamma) \int_{0}^{\infty} \left(1 - \operatorname{Pr}\left\{(1-\epsilon)\tau - \bar{\Delta}N(\tau) \le u, \forall\tau \middle| \mathcal{F}_{0}\right\}\right) \gamma^{-u} du \end{split}$$

Define

$$b_{\ell} = (1 - \epsilon)t_{\ell} - \Delta\ell,$$

and note that

$$\Pr\left\{\sup_{\ell} b_{\ell} \leq u + (1+\epsilon) - \bar{\Delta} \middle| \mathcal{F}_0\right\} = \Pr\left\{(1-\epsilon)\tau - \bar{\Delta}N(\tau) \leq u, \forall \tau \middle| \mathcal{F}_0\right\}.$$

Let  $\Delta_{\ell} = (1 - \epsilon)(t_{\ell+1} - t_{\ell}) - \overline{\Delta}$ , so that  $b_{\ell} = \sum_{s=0}^{\ell-1} \Delta_s$ . Since the process is generated by a finite state irreducible Markov chain, the

Since the process is generated by a finite state irreducible Markov chain, the tail of the interarrival times  $t_{\ell+1} - t_{\ell}$  is bounded by a decaying exponential. Hence, the moment generating function  $\mathbb{E}[e^{\eta \Delta_{\ell}}]$  of  $\Delta_{\ell}$  is finite for  $\eta \in (-\infty, \overline{\eta})$  for some  $\overline{\eta} > 0$ . It follows that  $b_{\ell}$  has a finite-valued moment generating function

$$\mathbf{E}[e^{\eta b_{\ell}}|\mathcal{F}_0] = \mathbf{E}[e^{\eta \Delta_0}|\mathcal{F}_0](\mathbf{E}[e^{\eta \Delta_1}])^{(\ell-1)},$$

for  $\eta \in (-\infty, \overline{\eta})$ . (Note that since the system is starting in an arbitrary initial state,  $\Delta_0$  has a different distribution than  $\Delta_\ell$  for  $\ell > 0$ .) By the Chernoff bound, for any  $\eta \in (-\infty, \overline{\eta})$  and  $x \ge 0$ ,

$$\Pr\{b_{\ell} \ge x | \mathcal{F}_0\} \le e^{-\eta x} \operatorname{E}[e^{\eta \Delta_0} | \mathcal{F}_0](\operatorname{E}[e^{\eta \Delta_1}])^{(\ell-1)} = e^{-\eta x + \rho_0(\beta) + (\ell-1)\rho_1(\eta)},$$

where  $\rho_i(\eta) = \log \mathbb{E}[e^{\eta \Delta_i}]$ . Since  $\rho'_1(0) = \mathbb{E}[\Delta_1] = -\epsilon < 0$ , there exist scalars  $A > 0, \zeta > 0$  and  $\kappa = -\rho(\zeta) > 0$  such that

$$\Pr\left\{ \left. b_{\ell} \ge x \right| \mathcal{F}_0 \right\} \le A e^{-\zeta x - \kappa \ell}.$$

Then,

$$1 - \Pr\left\{\sup_{\ell} b_{\ell} \le u(1+\epsilon) - \bar{\Delta}\right\} \le \sum_{\ell=0}^{\infty} \Pr\left\{b_{\ell} > u - (1+\epsilon)\bar{\Delta}\right\}$$
$$\le \sum_{\ell=0}^{\infty} A e^{-\zeta(u+(1+\epsilon)-\bar{\Delta})-\kappa k}$$
$$= \frac{A}{1-e^{-\kappa}} e^{-\zeta(u+(1+\epsilon)-\bar{\Delta})}.$$

Thus,

$$\begin{split} & \mathsf{E}\left[\sup_{\tau} \gamma^{\bar{\Delta}N(\tau)-(1-\epsilon)\tau} \middle| \,\mathcal{F}_{0}\right] \\ &= \left(-\log\gamma\right) \int_{0}^{\infty} \left(1 - \Pr\left\{\left(1-\epsilon\right)\tau - \bar{\Delta}N(\tau) \le u, \forall\tau \middle| \,\mathcal{F}_{0}\right\}\right) \gamma^{-u} du \\ & \le \left(-\log\gamma\right) \int_{0}^{\infty} \frac{A}{1-e^{-\kappa}} e^{-\zeta(u+(1+\epsilon)-\bar{\Delta})} \gamma^{-u} du. \end{split}$$

The final term is finite if  $\gamma > e^{-\zeta}$ . Note, however, by choosing  $\delta$  sufficiently small,  $\gamma$  can be made arbitrarily close to 1. Hence, for such a choice of  $\gamma$ ,  $E[c_0|\mathcal{F}_0]$  is finite.

# 7 Convergence Analysis

We will first introduce tools from the theory of stochastic approximation. Using these tools, we will be able to establish the convergence of the two algorithms presented earlier.

#### 7.1 Stochastic Approximation

Stochastic approximation provides an iterative method to solve equations of the form

$$\bar{g}(\theta) = 0$$

for some continuous function  $\bar{g}(\theta)$ . In our instance, if we set  $\bar{g}(\theta) = \nabla_{\theta} \lambda(\theta)$ , stochastic approximation will allow us to find policy parameters which are local optima of the expected average reward function.

In particular, consider the iterative scheme

(7.1) 
$$\theta(k+1) = \theta(k) + \epsilon g(\theta(k), \xi(k)).$$

Here,  $g(\theta(k), \xi(k))$  is an estimate of  $\overline{g}(\theta(k))$  at time k, and  $\xi(k)$  is a process that captures the underlying state and whatever additional noise memory is required to compute the estimate. In our framework, we will require that  $\xi(k)$  has a Markov structure: given  $\theta(k)$ , the distribution of  $\xi(k+1)$  depends only on  $\xi(k)$ . In other words,

(7.2) 
$$\Pr\left(\xi(k+1) \in \cdot | \mathcal{F}_k\right) = \mathcal{P}\left(\xi(k), \cdot | \theta(k)\right),$$

for some transition function  $\mathcal{P}$ .

We have not yet defined the relationship between the estimators  $g(\theta, \xi)$  and the function  $\bar{g}(\theta)$ . We will require that, when  $\theta$  is held fixed, the values  $g(\theta, \xi(k))$  locally average to  $\bar{g}(\theta)$ . In order to make this notion precise, note that for a fixed value of  $\theta$ , the transition function  $\mathcal{P}(\cdot, \cdot|\theta)$  defines a Markov chain we shall call the fixed- $\theta$  chain and denote by  $\xi_{\theta}(k)$ . The local averaging condition requires that

(7.3) 
$$\lim_{K \to \infty} \frac{1}{K} \operatorname{E} \left[ \sum_{k=0}^{K-1} g(\theta, \xi_{\theta}(k)) \right] = \bar{g}(\theta),$$

for each initial condition  $\xi_{\theta}(0)$ .

Consider the ordinary differential equation

(7.4) 
$$\bar{\theta}(t) = \bar{g}(\bar{\theta}(t))$$

Define  $\mathcal{L}$  to be the set of limit points of (7.4) over all initial conditions. Let  $\theta^{\epsilon}(k)$  be the sequence of parameters resulting from (7.1) with a particular fixed  $\epsilon$ . Finally, define a continuous-time interpolation  $\bar{\theta}^{\epsilon}(t)$  if  $\theta^{\epsilon}(k)$  by setting  $\bar{\theta}^{\epsilon}(t) = \theta^{\epsilon}(k)$  if  $t \in [k\epsilon, k\epsilon + \epsilon)$ . In the following lemma, we will establish conditions for the weak convergence of  $\bar{\theta}^{\epsilon}(t)$  to a solution  $\bar{\theta}(t)$  of the ODE (7.4) as  $\epsilon \rightarrow 0$ , such that the fraction of the time interval [0, T] that  $\theta^{\epsilon}(t)$  spends in a small neighborhood of  $\mathcal{L}$ will go to 1 in probability as  $\epsilon \rightarrow 0$  and  $T \rightarrow \infty$ .

Note that when  $\bar{g}(\theta) = \nabla_{\theta} \lambda(\theta)$ , the function  $\lambda(\theta)$  is a Lyapunov function for the ODE. Then, the set of limit points L is the set of stationary points  $\theta$  for which

$$\nabla_{\theta} \lambda(\theta) = 0.$$

Hence, the limit points are local optima of  $\lambda(\theta)$ .

Lemma 7.1. Assume the following conditions:

- 1. The iterates  $\{\theta^{\epsilon}(k)|k,\epsilon\}$  are bounded.
- 2. There exists an  $\mathcal{F}_t$ -measurable process  $\xi(t) \in I \subset \Xi$ , where I is a compact set in a complete separable metric space  $\Xi$ , and a transition function  $\mathcal{P}(\cdot, \cdot | \theta)$  such that the Markov condition (7.2) holds.

3.  $\mathcal{P}(\xi, \cdot | \theta)$  is weakly continuous in  $(\theta, \xi)$ , that is, for every bounded and continuous real-valued function F on  $\Re^S$ , the value of the integral

$$\int F(\tilde{\xi}) \mathcal{P}(\xi, d\tilde{\xi}|\theta)$$

*is continuous in*  $(\theta, \xi)$ *.* 

- 4. The set of invariant measures under transition functions  $\mathcal{P}(\xi, \cdot | \theta)$  is tight over all  $\theta$ .
- 5. The estimate function  $g(\theta, \xi)$  is continuous, bounded, and measurable, and satisfies the local averaging condition (7.3) for a fixed- $\theta$  chain.

Then, for any sequence of processes  $\{\bar{\theta}^{\epsilon}(t)|\epsilon \rightarrow 0\}$  there exists a subsequence that weakly converges to  $\bar{\theta}(t)$  as  $\epsilon \rightarrow 0$ , where  $\bar{\theta}(t)$  is a solution to the ODE (7.4). Further, for  $\delta > 0$ , define  $N_{\delta}(\mathcal{L})$  to be a neighborhood of radius  $\delta$  around the limit set  $\mathcal{L}$ . The fraction of time that  $\hat{\theta}^{\epsilon}(t)$  spends in  $N_{\delta}(\mathcal{L})$  over the time interval [0,T]goes to 1 in probability as  $\epsilon \rightarrow 0$  and  $T \rightarrow \infty$ .

*Proof.* The result follows directly from Theorem 8.4.3 in [2].

#### 7.2 Convergence of the Distributed Algorithm

We wish to prove convergence of the stochastic approximation scheme corresponding to our distributed optimization algorithm:

(7.5) 
$$\theta_i^{\epsilon}(k+1) = \theta_i^{\epsilon}(k) + \epsilon z_i^{\beta}(k)(1-\alpha)Y_i(k).$$

**Theorem 7.1.** Assume that the set of iterates  $\{\theta^{\epsilon}(k)|k,\epsilon\}$  from (7.5) are bounded. *Then, the conclusions of Lemma 7.1 hold.* 

Proof. We will use the framework provided by Lemma 7.1. Define

$$\xi(k) = (w(k), a(k), z_1^{\beta}(k), \dots, z_n^{\beta}(k), Y(k)),$$

 $\Xi = \mathbb{X} \times \mathbb{A} \times \mathbb{R}^{N+n}$ . To see that  $\xi(t)$  takes values in a compact subset of  $\Xi$ , it suffices to prove that  $z_i^{\beta}(k)$  and Y(k) are bounded. Yet,

$$\begin{split} \left\| z_i^{\beta}(k) \right\| &= \left\| \sum_{\ell=0}^k \beta^{k-\ell} \nabla_i(\ell) \right\| \le L \sum_{\ell=0}^k \beta^{k-\ell} \le \frac{L}{1-\beta} \\ \|Y(k)\| &= \left\| \sum_{\ell=0}^k \alpha^{k-\ell} \hat{Q}(\ell,k) R(\ell) \right\| \le \frac{\hat{R}}{1-\alpha}, \end{split}$$

where

$$\bar{R} = \max_{w \in \mathbb{W}, a \in \mathbb{A}} \left| \sum_{i=1}^{n} r_i(w, a)^2 \right|^{1/2}.$$

Further, since (w(k), a(k)) form a Markov chain and from (3.2) and the definition of Y(k), clearly  $\xi(t)$  is an  $\mathcal{F}_k$ -measurable Markov chain. The fact that the associated transition function is weakly continuous follows from the smoothness conditions on  $\pi_{\theta}(a|x)$  provided by Assumption 2.1. Define the function

$$g(\theta,\xi) = (g_1(\theta,\xi),\ldots,g_n(\theta,\xi)),$$

where

$$g_i(\theta,\xi) = (1-\alpha)z_i(t)y_i(t)$$

Boundedness of  $g(\theta, \xi)$  is clear, further

$$\chi_i(t) = g_i(\theta(t), \xi(t)).$$

Finally, Theorem 5.1 provides the appropriate averaging condition for the fixed- $\theta$  chain.

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