Inferring Types for Asynchronous Arrows in JavaScript

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1. Introduction

Event programming is prevalent in JavaScript. As the *lingua franca* of the web, it is responsible for driving a huge amount of user-interactive web applications. Because JavaScript is commonly executed in a single thread, blocking or long-running computations can often cause the page or entire browser to appear unresponsive. As a result, JavaScript programs are written in an event-driven style where programs register callback functions with the event loop. A callback function is dispatched by the event loop when an external event occurs, and control returns to the event loop once a callback function completes execution. Heavy use of callbacks make control flow difficult to trace. Application logic becomes intimately mixed with sequencing logic. A single unit of application code may no longer be confined to one easily-readable function, but split arbitrarily far across a number of functions. This greatly decreases code understandability and maintainability.

The introduction of Promises in ES6 demonstrates a desire to reduce the complexity of callback-driven programs. Promises allow callbacks to be chained instead of nested, regaining some imperative flow of control. Similarly, Arrowlets [6] has demonstrated an elegant solution to composing callback functions by wrapping them in opaque units of execution using continuation functions. These units of execution encode *arrows* [5], which is a generalization of monads [10].

However, JavaScript lacks properties that make function, arrow, or promise composition palatable. Illegal compositions are not forbidden at composition time and often crash or lead to subtle behavioral issues at runtime. Frustratingly, the source location which displays incorrect behavior is often completely independent of the source location of the actual error, making the associated stack trace less than helpful. These errors force the developer to trace the arrow execution path backwards from the source of a runtime error, continuation-function by continuation-function, until the erroneous composition presents itself. Despite the benefits, this seems to leave the developer no better off than using callbacks during debugging.

Fortunately, there is a clear separation between the composition time and the execution time of arrows. It is possible to detect errors after the arrows have been composed but before their actual execution starts. To this end, we have developed an optional type-checker which infers and attaches a type to every arrow at composition time describing its input and output constraints and forbids the composition of two arrows that are not type-composable. This reduces a rather large class of errors during composition related to input/output clashes and requires only that the user adds an annotation to functions which are lifted into arrows.

This type-checker runs in pure JavaScript at program runtime and thus requires no pre-processing step. While the type-checker does not find errors prior to runtime, it does find errors prior to *arrow execution-time*. This technique effectively moves the source of errors from the point where an error may be observed to the point where an erroneous composition occurs. We have found this relocation of error messages invaluable and feel that moving errors earlier in runtime (without moving them completely outside of runtime) still provides a great benefit. The type-checker may be disabled, returning the program to the original runtime semantics without dynamic type-checks.

**Our Contributions** The main contributions of this paper are

1. an encoding of arrows which handles asynchronous errors in a manner similar to ES6 Promises, and
2. an optional type system to aid developers with type-directed composition of asynchronous arrows.

The remainder of this paper is organized as follows. Section 2 provides a motivating example. Section 3 introduces the arrow constructors and combinators in our library and discusses their runtime semantics and encoding. Section 4 provides details of the type inference system and presents typing rules. Section 5 discusses the runtime cost and the development overhead of our library. Section 6 presents related work and Section 7 concludes. Our arrows library, the type-checker, and some sample applications are freely available. [1]

[1] https://pantherfile.uwm.edu/fritz/www/arrows
const makeConf = (resource, id) => {
    "url" : "/api/v1/" + resource + "/" + id,
    "dataType": "json"
};

var ajaxA = new AjaxArrow(id => {
    /* @conf :: Number */
    $resp :: ({a: Number}) */
    return makeConf("a", id);
});

var ajaxB = new AjaxArrow(id => {
    /* @conf :: Number */
    $resp :: ({b: Number}) */
    return makeConf("b", id);
});

var ajaxC = new AjaxArrow(id => {
    /* @conf :: Number */
    $resp :: ({c: Number}) */
    return makeConf("c", id);
});

function log() {
    console.log(arguments);
}

const getId = () => /* @arrow :: {c: 'x'} */ o.b;
const onErr = ex => {
    /* @arrow :: AjaxError */
    console.log("Remote server problem.");
}

const getA = o => /* @arrow :: {a: 'x'} */ o.a;
const getB = o => /* @arrow :: {b: 'x'} */ o.b;
const getU = o => /* @arrow :: {c: 'x'} */ o.c;

Arrow.catch( Arrow.seq( Arrow.lift(getId),
    ajaxA, Arrow.lift(getA),
    ajaxB, Arrow.lift(getB),
    ajaxC, Arrow.lift(getU),
    Arrow.lift(onErr),
    Arrow.lift(onErr)
).run()}

Figure 1. Arrow example

2. Example

To illustrate the utility of our type inference tool, consider the example in Figure 1. Three Ajax calls are made to retrieve data from a remote sever, and the resource path of each call depends on a result from the previous call. The final result is printed to the console, and any errors are caught and logged.

The details of the arrow methods are explained in Section 3. For now, it is sufficient to understand that lift converts a function into an arrow, seq chains two or more arrows in sequence, catch executes the first arrow and uses the second as an exception handler, and an arrow does not begin execution until its run method is called. Functions which are lifted into arrows are generally annotated with a type. If a function does not have an annotation we assume that the function can accept anything and may return anything.

Without type-checking, a number of runtime errors could occur from this example. Composition of arrows could be misaligned such that the output of one arrow does not conform the input of another. There are at least seven points of potential failures in this small example. As remote requests take a long time to complete, runtime debugging for these kinds of programs may be particularly frustrating.

Using our type inference tool, developers can add type annotations for functions which are transformed into arrows. This enables typing errors to be discovered as early as possible. In particular, illegal composition of arrows would be discovered at composition time before any Ajax request is attempted. For example, getA expects its input to have a record type \( \{ a : 'x' \} \), where \( 'x' \) is a type variable. We ensure that the result type \( \{ a : Number \} \) of the preceding arrow ajaxA can be unified with this type.

The result of ajaxA is type-checked at arrow execution time to ensure that the result matches the annotated type. Even though this dynamic type-check takes place after composition time, it still moves a possible error from the point where an unexpected value is read to the point where it is created. Such runtime checks can be disabled after testing.

3. Arrows

An arrow is a composable, opaque unit of execution which, in this context, generally runs in an asynchronous manner. An arrow may receive a number of arguments, but may only receive them from another arrow. Similarly, an arrow may produce a value, but that value may only be consumed by another arrow.

We embed a typed domain-specific language based on arrow operations into JavaScript. The host language may lift a function into an arrow, run an arrow, or cancel a running arrow. Arrows are meant to replace operations in JavaScript which were primarily asynchronous or callback-driven. As a result, values cannot flow from arrows back into the host language.

Definition 3.1 (Async Point). The point in the execution of an arrow which requires an external event to continue is called an async point. These events include timers (e.g. setTimeout), network event (e.g. click, keydown), and certain arrow-specific actions (discussed in Section 3.2). Concurrent execution of other arrows or host-language code may occur within a blocked arrow’s async point.

Definition 3.2 (Asynchronicity). We say an arrow is asynchronous if its execution contains at least one async point. A running arrow may be canceled only if it is asynchronous, and it may be canceled only at an async point. Canceling an arrow effectively unregisters all of its active event handlers so that it is never notified to resume execution when an external event occurs.

Definition 3.3 (Progress Event). An arrow may emit a progress event if it successfully resumes execution after blocking at an async point. These events may be explicitly suppressed (discussed in Section 3.2).

An overview of the primitives of our library follows. The arrow primitives consist of constructors and combinators. Arrow constructors create simple arrows from composition-time values. These arrows can transform data synchronously and handle asynchronous events. Arrow combinators compose a set of arrows to form workflow that can be linear, parallel, or repeating. The design and implementation of the library is heavily inspired by both Arrowlets [6] and ES6 Promises. We have, however, made a few major interface changes which are discussed in Section 6.

3.1 Constructors

We provide seven arrow constructors, detailed below.

Ajax The ajax arrow, denoted ajax(c), produces a value by issuing a remote HTTP request. The request parameters (e.g. url, method, headers, request body) are returned by the host-language configuration function c. If type-checking is enabled, it is expected that c is annotated with the input constraints of c and the expected result from the remote server. Dynamic type-checks are inserted following a successful response from the remote server to ensure the shape of the data matches the annotated type.
Delay The delay arrow, denoted delay(duration), passes along its own input, unmodified, after delay milliseconds pass. This arrow is asynchronous.

Elem The element arrow, denoted elem(selector), produces a jQuery object (or possibly empty set of objects) matching the given selector.

Event The event arrow, denoted event(name), takes an element as input and produces a name-event value once that event occurs on the given element. This arrow is asynchronous.

Lift A lifted arrow, denoted lift(f), produces a value determined by f(x), where x is the input of the arrow and f is a host-language function. If type-checking is enabled, it is expected that f is annotated with the input and output constraints of f. Dynamic type-checks are inserted following the invocation of f to ensure the return value matches the annotated type.

Nth The nth arrow, denoted nth(n), takes a tuple of at least n elements as input and extracts its nth element.

Split The split arrow, denoted split(n), takes a single value v as input and converts it to an n-tuple, where each element of the tuple is v. This arrow attempts to preclude aliasing by creating n clones of the value v. This avoids problems with covariant datatypes which are mutated by subsequent arrows.

Try The try combinator, denoted try(a, as, af), attempts to execute a with the input of the combinator. If no error occurs during the execution of a, its output is fed into the success arrow, as. Otherwise, the error value is fed into the failure arrow, af. The result of the combinator is either the result of arrow as or arrow af, depending on which one executed at runtime.

Any The any combinator, denoted any(a1,..., an), composes n asynchronous arrows such that only the arrow that first emits a progress event, as, runs to completion. This combinator executes each arrow with the input of the combinator, in order, in a synchronous loop. Once arrow ai reaches an async point, arrow ai+1 immediately begins execution. Because the loop running each arrow is synchronous, the event which resumes the execution of any arrow ai will not be observed until after ai begins listening for an event. Once some arrow ai emits a progress event, the remaining arrows \{a1,..., an\} \ {ai} are canceled and the execution of ai continues. The result of the combinator is the result of ai.

This combinator generalizes the binary combinator

\[(a \gg b) : (A \sim B) \rightarrow (B \sim C) \rightarrow (A \sim C)\]

in the arrow calculus [5].

This combinator is definitely asynchronous if both arrow as and arrow af are asynchronous. We cannot safely consider async points within a as we do not know at what point the execution of a may halt with an error.

Promise’s then and catch methods can be encoded by the try combinator. The statement p.then(resolve) executes p and then the callback resolve on successful execution. The statement p.catch(reject) executes p and, if an error occurs, calls reject with the error as input. The statement p.then(resolve, reject) executes p and then calls either the callback resolve or reject on successful or unsuccessful execution, respectively. The reject callback is not executed if an error occurs in resolve.

We can encode these statements with the seq combinator, the try combinator, and an identity arrow, id, as follows, where the arrow a is functionally equivalent to the promise p.

\[p.then(s) \equiv seq(a, lift(s))\]
\[p.catch(f) \equiv try(a, id, lift(f))\]
\[p.then(s, f) \equiv try(a, lift(s), lift(f))\]

This combinator is necessary asynchronous. The first async point of the combinator is the set of first async points of each arrow ai, which occur immediately after arrow an begins to yield. Once
The no-emit combinator, denoted \texttt{noemit}(a), suppresses the emission of progress events from \( a \). This combinator creates an additional sync point (and emits a progress event) after \( a \) finishes execution. Although \( a \) emits no events, it can still be preempted or canceled at its async points.

\textbf{NoEmit} The no-emit combinator, denoted \texttt{noemit}(a), suppresses the emission of progress events from \( a \). This combinator creates an additional sync point (and emits a progress event) after \( a \) finishes execution. Although \( a \) emits no events, it can still be preempted or canceled at its async points.

We can simulate the semantics of Promise’s \texttt{race} method (with added cancellation of slow arrows) by applying the \texttt{noemit} combinator to the arguments of the any combinator, where the arrow \( a_i \) is functionally identical to the promise \( p_i \).

\[
\text{race}(p_1, \ldots, p_n) \equiv \text{any}(\text{noemit}(p_1), \ldots, \text{noemit}(p_n))
\]

The pairing of these combinators appear much more expressive than either the any combinator or Promise’s \texttt{race} method alone. As an example, consider two arrows representing the halves of a game, \( \text{game}_1 \) and \( \text{game}_2 \), where each arrow is composed of a non-trivial sequence of user interactions. A time-limit to the first portion of the game can be encoded the following.

\[
\text{any}(\text{delay}(\text{limit}), \text{seq}(\text{noemit}(\text{game}_1), \text{game}_2))
\]

Here, the \texttt{delay} arrow will register a listener for a timer event and immediately yield, where \( \text{game}_1 \) begins to execute. If the timer runs out before \( \text{game}_1 \) finishes, then \( \text{game}_1 \) is canceled at its next async point. If \( \text{game}_1 \) finishes before the timer runs out, then the timer is canceled and the execution path of any continues unobstructed towards \( \text{game}_2 \).

\textbf{All} The all combinator, denoted \texttt{all}(\( a_1, \ldots, a_n \)), composes \( n \) arrows that execute concurrently. This combinator begins executing each arrow, in order, in a synchronous loop. Once arrow \( a_i \) completes or reaches an async point, arrow \( a_{i+1} \) immediately begins execution. Once all arrows have been started, they may progress through their execution in any order until they all complete, at which point the combinator completes.

The input to the combinator is an \( n \)-element tuple, where the input of each arrow \( a_i \) is the \texttt{i}th element of the tuple. The result of the combinator is also an \( n \)-element tuple, where the \texttt{i}th element of the tuple is the result of \( a_i \).

This combinator is asynchronous if any \texttt{arrow} \( a_i \) is asynchronous. The set of async points of the combinator is the union of the async points of each \texttt{arrow} \( a_i \).

We can construct a combinator equivalent to the unary combinator

\[
\texttt{first} : (A \rightarrow B) \rightarrow (A \times C \rightarrow B \times C)
\]

in the arrow calculus [5] using this combinator and an identity arrow

\[
\text{first } a \equiv \text{all}(a, \text{id})
\]

\textbf{Repeat} The repeat combinator, denoted \texttt{repeat}(a), executes the arrow \( a \) at least once. The input of the combinator is fed into \( a \). The result of \( a \) must be a tagged union of the form

\[
\{ \text{"repeat"} : \text{rep}, \text{"value"} : \text{val} \}
\]

where \( \text{rep} \) is either \texttt{true} or \texttt{false}. When \( \text{rep} \equiv \text{true} \), the combinator reinvokes itself with the value \( \text{val} \) as input. Otherwise, the combinator halts, resulting in the value \( \text{val} \).

This combinator creates an async point (denoted by the double-slash lines) following each invocation of the arrow \( a \). This async point may progress immediately. This async point enables preemption and cancellation between iterations, and prevents synchronous arrows from looping indefinitely.

\section{CPS Encoding}

Arrows are implemented in continuation-passing style (CPS). Each arrow has an associated \texttt{call} function accepting a value argument \( x \), a progress object \( p \), a continuation function \( k \), and an error handling function \( h \). Instead of returning a value produced by the arrow, it is simply passed to \( k \) (on success) or \( h \) (on error). The progress object \( p \) is used to track async points for cancellation and emits progress events (unless suppressed) which are observed by the any combinator.

To demonstrate the use of the progress object \( p \), we give the CPS encoding for the \texttt{delay} constructor in Figure 8. The any combinator creates a fresh progress object for each of its children. When one progress object emits a progress event, its sibling arrows are canceled. The \texttt{noemit} combinator creates a fresh progress object which does not emit events.

To demonstrate the use of the error callback \( h \), we give the CPS encodings for the \texttt{lift} constructor and the \texttt{try} combinator in Figure 9 and Figure 10 respectively.
call(x, p, k, h) {
    // Invoke original error callback "h" if either
    // Emit progress event and remove canceler
    try {
        k(f(x));
        p.advance(cancel);
    } catch (err) {
        h(err);
    }
}

Figure 8. Encoding for \texttt{delay}(\texttt{duration}).

call(x, p, k, h) {
    // Spread arguments over parameters, if possible
    if (x && x.constructor === Array && f.length > 1) {
        kf.apply(null, x);
    } else {
        k(f(x));
    }
}

Figure 9. Encoding for \texttt{lift}(f) - dynamic type-checks omitted.

call(x, p, k, h) {
    // This allows nesting of error callbacks.
    a.call(x, y => as.call(y, p, k, h),
    z => af.call(z, x, p, k, h));
}

Figure 10. Encoding for \texttt{try}(a, a_i, a_f).

4. Type Inference

In this section, we introduce the type system of our arrows library. We define the types of values which can be consumed or produced by arrows in Section 4.1. We define the types of arrows and give the typing rules for arrow constructors and arrow combinator in Section 4.2.

4.1 Value Types

Given a set of named types \( B \) which includes both JavaScript primitives (e.g. \texttt{Number, Bool, String}) as well as event primitives (e.g. \texttt{Elem, Event}), we define the type of primitive values, denoted \( b \), as follows.

\[
b ::= t \in B \mid \ell_1 + \cdots + t_n
\]

A sum type consisting solely of named types is represented by \( \ell_1 + \cdots + t_n \), where each \( \ell_i \) is unique. The order of the types in a sum type is insignificant, and any permutation represents an equivalent type. A sum type of \( n = 1 \) elements is equivalent to its unique type.

Given an infinite set of type variables \( A \), we define the types of values consumed or produced by arrows, denoted \( \tau \), as follows.

\[
\tau ::= b \mid \alpha, \beta \in A \mid \emptyset \mid (\text{loop} : \tau_1, \text{halt} : \tau_2) \mid \{\tau\} \mid \{\ell_1 : \tau_1, \ldots, \ell_n : \tau_n\}
\]

The unit (any possible) type is represented by \( \emptyset \). The loop type is a tagged union represented by \( (\text{loop} : \tau_1, \text{halt} : \tau_2) \) used primarily by the \texttt{repeat} combinator. An arrow \( a \) produces a value \( v_1 \) of type \( \tau_1 \) when it expects to be called again with \( v_1 \) as an argument. Otherwise, \( a \) produces a value \( v_2 \) of type \( \tau_2 \), which is the final result of the arrow. We represent this tagged union in JavaScript as a simple object with a tag and a value field, as noted in Section 2.2.

An array type with homogeneous elements is represented by \( [\tau_1] \), a tuple type is represented by \( (\tau_1, \ldots, \tau_n) \), and a record type is represented by \( \{\ell_1 : \tau_1, \ldots, \ell_n : \tau_n\} \). The order of the labels in a record is insignificant, and any permutation of the labels represents an equivalent type.

4.2 Arrow Types

We define the types of arrows, denoted by \( \tilde{\tau} \), as follows, where \( C \) is a set of constraints of the form \( \tau \leq \tau' \) and \( E \) is the set of types which may be produced in exceptional cases.

\[
\tilde{\tau} ::= \tau_{in} \leadsto \tau_{out} \setminus (C, E)
\]

If \( C \) and \( E \) are both empty, \( \tau_{in} \leadsto \tau_{out} \) may be written for short. If the constraint set \( C \) is not consistent, then the type is considered malformed and the associated composition is rejected during type-checking. The appendix (Sections A and B) contains details for constraint set consistency and a technique for simplifying arrow types.

The constrained arrow type is similar to the constrained type \( \tau \setminus C \) introduced by Eifrig et al. [1], where the set \( C \) contains subtyping constraints on the type variables occurring in \( \tau \). A constrained type inference system generalizes unification-based inference to languages with subtyping - a feature that we found necessary for arrow type inference.

We assume that if a constrained arrow type contains a type variable \( \alpha \) in \( \tau_{in}, \tau_{out}, C, \) or \( E \), that the type variable is understood to be existentially quantified with respect to the arrow type, i.e.

\[
\forall \alpha. \tau_{in} \leadsto \tau_{out} \setminus (C, E)
\]

Typing rules for arrow constructors and combinators appear in Figure 11 and Figure 12, respectively. For brevity, the typing rules have the implicit assumption that if \( \alpha : \tau \leadsto \tau' \setminus (C, E) \), then \( C \) is consistent.

When an arrow type is used as the input of a combinator, a unique instantiation of that type is created in order to prevent unintended clashing of type variables. A unique instantiation of a constrained arrow type is created by substituting the set of type variables occurring in the type as well as the constraint set and set of error types with a set of fresh type variables.

Rule (T-LIFT) assumes that each lifted function \( f \) is annotated with a constrained arrow type describing the input and output types of \( f \), and Rule (T-JAX) assumes that each \( Ajax \) configuration function \( c \) is annotated with two constrained types: one describing the input to \( c \), and one describing the response from the remote server. We assume the existence of an implicit function \( \text{annotate}(t, f) \) which reads the annotation named \( t \) of the function \( f \) and produces a unique instantiation of the type it describes.

Rule (T-NTH) shows how the \texttt{nth}(n) combinator selects the \( n \)-th element from a tuple with \( m \geq n \) elements. The argument to this combinator may be a wider tuple, as \( \tau_{in} : \tau_1, \ldots, \tau_n \leq (\tau'_1, \ldots, \tau'_m) \) is a consistent constraint. Note that the application of this rule happens at arrow composition time when \( n \) is a known value.

5. Discussion

We have implemented several small but non-trivial programs using the abstractions provided by our library with type-checking enabled during development. Among these were an implementation for the game Memory, which requires the user to select two cards from a grid with the same face value until all pairs of cards are selected, and an application which demonstrates \texttt{Fischer-Yates Shuffle} and Bubble Sort algorithms through timed animations.
During this time, we observed a large number of instances where the type system forbid us from composing arrows illegally. In many cases the composition was illegal in a way that was trivial to fix yet non-obvious to discover. For example, our game *Memory* used an arrow with the type

\[
\text{selectOne :: Elem } \leadsto ()
\]

which was meant to be executed twice in a row with the same input. The intuition when composing such arrows is to simply seq them together, but this unfortunately causes a type clash between the first and second invocations. The correct solution is to remember the input to the first invocation, and use it as the input of the second invocation. This became a common idiom and was encoded as a derived combinator in our API.

\[
\text{remember(a) } \equiv \text{ seq(split(2), all(a, id), nth(2))}
\]

**Annotation Burden** The annotation burden required by developers seems to be minimal. Our implementation of *Memory* required only eight annotations in total, but our type-checker inferred the type of 126 arrows at startup. This number is not surprising if you consider many combinators (such as the remember combinator defined above) are built from the foundational combinators discussed in Section 3. Similarly, our implementation for the sorting and shuffling animation required only four annotations, but types for 124 arrows were inferred.

**Inference Overhead** We measured the runtime overhead of the type inference algorithm. We used the Ajax example from Section 3 as well as the programs described in this section. Each measurement given in milliseconds and measures the arrow composition portion of the program only, averaged over 1000 runs.

We also measured a small benchmark application which composed an arrow with itself \(2^{10}\) times. The arrow’s type is variable-size and has form \(\{T_i : \alpha_i\} \leadsto \{T_i : \alpha'_i\} \setminus \{(\alpha_i \leq \alpha'_i)\}\).

Based on these results, the overhead of type inference grows linearly with the number of arrows and superlinearly (but less than quadratically) with the size of the arrow types. We expect arrow type sizes to remain small as the user only annotates the fields which are necessary for the arrow, and arrows are given simplified types during inference.

**Dynamic Type-check Overhead** We also measured the runtime overhead of the dynamic type-checks during an arrow’s execution. We used the benchmark program described above. Each measurement is given in milliseconds and measures the dynamic type-checking portion of the program only, averaged over 1000 runs.

Without dynamic type-checks, the program ran in an invariant \(1.762ms\). There are 1025 dynamic type-checks performed (the number of lifted arrows) in a single run.

### Table: Type Inferring Overhead

<table>
<thead>
<tr>
<th>Application</th>
<th># Arrows</th>
<th>Disabled (ms)</th>
<th>Enabled (ms)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ajax</td>
<td>13</td>
<td>0.125</td>
<td>0.905</td>
</tr>
<tr>
<td>Shuffle</td>
<td>62</td>
<td>0.837</td>
<td>3.957</td>
</tr>
<tr>
<td>Shuffle &amp; Sort</td>
<td>124</td>
<td>1.638</td>
<td>8.118</td>
</tr>
<tr>
<td>Memory Game</td>
<td>126</td>
<td>1.566</td>
<td>10.989</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th># Fields</th>
<th>1</th>
<th>10</th>
<th>20</th>
<th>30</th>
<th>40</th>
<th>50</th>
</tr>
</thead>
<tbody>
<tr>
<td>Time (ms)</td>
<td>1.10</td>
<td>3.39</td>
<td>6.88</td>
<td>11.82</td>
<td>17.32</td>
<td>25.48</td>
</tr>
</tbody>
</table>

Based on these results, the overhead of dynamic type-checking grows linearly with the number of dynamic checks as well as the size of the type and value being checked.

It is important to keep in mind that application using these abstractions are asynchronous and often blocked waiting for user or remote server responses, which vastly dominate the runtime of an
application. We find this performance overhead during development to be negligible.

6. Related Work

Arrows Arrows [5] were first formalized as a generalization of monads [10]. As a monadic type \((m a)\) represents a computation delivering an \(a\), the arrow type \((a b c)\) represents a computation with input of type \(b\) delivering a \(c\). Arrows are formally defined by extending simply-typed lambda calculus with three constants satisfying nine laws. The constants \(\text{arr}\) and \((\bowtie\bowtie)\) are lift and compose operations, respectively. The constant \(\text{first}\) converts an arrow from \(b\) to \(c\) into an arrow on pairs. Our \(\text{lift}\) constructor and the combinators \(\text{seq}\) and \(\text{all}\) encompass all three operations.

Alternate arrow calculi exist with five obvious laws [7] [8]. The laws of these calculus follow from beta and eta laws of the lambda calculus and fit into well-known patterns. The calculi are equivalent, and a translation scheme from one calculus to the other exists.

Arrowlets Arrowlets is a JavaScript library for using arrows [5], providing programs the means to elegantly structure event-driven web components that are easy to understand, modify, and reuse. The implementation of our arrows library was heavily inspired by the continuation-passing style used by Arrowlets, as well as the asynchronous semantics of the combinators it provides.

Regarding execution semantics only, there are two major differences between our arrows library and Arrowlets. First, we have generalized binary combinators to support \(n\) arrows, leading to code which favors generalized \(n\)-tuples over simple pairs. Second, we have altered the encoding of arrows to carry along an error continuation in addition to the normal-path continuation. This allowed us to add the \(\text{try}\) combinator, which subsumes the semantics of ES6 Promises.

ES6 Promises Promises allow a sequence of callbacks to be chained together, flattening the dreaded ‘pyramid of doom’ into a sequence of Promise \(\text{then}\) calls. Promises also provide a means of error handling, where the \(\text{then}\) method accepts an optional error callback.

Our arrows library also encode the core mechanism of Promises, but there are some obvious differences in execution semantics. For one, when a Promise object is created it attempts to resolve immediately. If a Promise object is composed with a callback after its resolution, it simply forwards the memoized result. Arrows separate composition and execution behind an explicit \(\text{run}\) method. This allows an arrow to be called multiple times, like a regular function, and enables features such as the \(\text{repeat}\) combinator. Promises place emphasis on the values which they \(\text{proxy}\), where arrows place emphasis on the \(\text{computation}\). It would be trivial to adapt our arrows library to support the \(\text{lazy}\) nature of Promises with the addition of a memoizing combinator.

Promises also implement two methods which are strongly related to the arrow combinators presented here. The method \(\text{Promise.all}(ps)\), similar to the \(\text{all}\) combinator, takes an iterable of promises, \(ps\), and resolves once each promise resolves or rejects if any promise rejects. Its resolved value is an array of the resolved values of each promise. The method \(\text{Promise.race}(ps)\), similar to the \(\text{any}\) combinator when the arrow inputs are wrapped in \(\text{mem}\), takes an iterable of promises, \(ps\), and resolves once any promise \(p\) resolves or rejects once any promise \(p\) rejects. The value of the promise is the value of the first resolved arrow. Unlike the \(\text{any}\) combinator, \(\text{Promise.race}\) does not abort the execution of the remaining arrows. We believe the semantics of the \(\text{any}\) combinator to be more useful in practice.

Coincidently, because we can simulate Promises semantics so closely with arrows, our typing judgments can also apply almost directly to a Promises library. However, type-checking with Arrows is much more elegant than with Promises because the composition time and execution time of arrows has a clear delineation, where Promises may begin immediately following their creation.

Promise and Arrowlets attack the problem of callback composition in similar ways, but provide a disjoint set of orthogonal features. Arrowlets provide a means to abort an asynchronous operation, where Promises follow a fire-and-forget convention. Promises provide a means of catching an error, where Arrowlets focus only on happy-path composition. Our implementation of arrows chooses to support both sets of features.

7. Conclusion

We have presented an arrows library which encodes semantics similar to ES6 Promises and a composition-time type-checker which enables type-directed development. We believe this tool greatly reduces the friction of development using a functional style in a language with no compile-time checks.

Future Work We intend to explore additional methods of static analysis to provide greater confidence in correct arrow compositions. We are currently exploring typestate analysis with relation to the semantics of concurrently executing arrows with interesting results.

Acknowledgments

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References

In this section we present the definition of constraint set consistency. For example, a set of constraints describing an impossible lower bound for some type variable \( \alpha \) (e.g. \( C = \{ \alpha \leq \text{String}, \alpha \leq \text{Number} \} \), where no lower bound of both \text{String} and \text{Number} exists). This case is handled by type simplification, discussed in Section \[A\].

### A. Consistency

In this section we present the definition of constraint set consistency. If an arrow has the type \( \tau \sim \tau' \setminus (C, E) \) and \( C \) is inconsistent, then there is either some type variable \( \alpha \) which has a set of unsatisfiable bounds, or there is a type clash between the output and input of two child arrows.

**Definition A.1** (Closed). A set of constraints \( C \) is closed if it satisfies the closure rules given in Figure 13. We refer to the closure of \( C \) as closure(\( C \)).

**Definition A.2** (Consistent). A constraint set \( C \) is consistent if every constraint in closure(\( C \)) is consistent. A consistent constraint must match one of the forms given in Figure 14.

![Figure 13. Constraint set closure rules.](image)

![Figure 14. Constraint set consistency rules.](image)

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**Rule (CLS-TRANS)** ensures that subtype constraints are transitive. For example, \( C = \{ \text{String} \leq \alpha, \alpha \leq \text{Number} \} \) contains only consistent constraints. However, due to the unsatisfiable bounds of \( \alpha \), \( \text{String} \leq \text{Number} \in \text{closure}(\( C \)) \) and the constraint set is considered inconsistent.

The remaining closure and consistency rules describe a simple subtyping join-semilattice. The unit type occupies the top of the lattice, by Rule (CNS-UNIT); there is no bottom type (and hence no greatest lower bound for some sets of types). This allows an arrow consuming any type to be composed with any arrow, which is a useful property when sequencing.

Named types are neither subtypes nor supertypes of another named type. Named types are subtypes of any sum type which contains them, and sum types are subtypes of their own supersets, by Rule (CNS-SUM). This allows an arrow producing a set of types \( T \) and an arrow consuming a set of types \( T' \) to be composed when \( T \subseteq T' \).

Rules (CLS-LOOP), (CLS-ARRAY), (CLS-TUPLE), and (CLS-RECORD) ensure that composite datatypes are consistent only with composite datatypes with the same outermost type constructor. Tuple and record width subtyping is enabled by Rules (CLS-TUPLE) and (CLS-RECORD). Array, tuple, and record depth subtyping is enabled by Rules (CLS-LOOP), (CLS-ARRAY), (CLS-TUPLE), and (CLS-RECORD).

Type variables are never immediately inconsistent with another type, by Rule (CNS-VAR). This makes it possible to have a set of constraints describing an impossible lower bound for some type variable \( \alpha \) (e.g. \( C = \{ \alpha \leq \text{String}, \alpha \leq \text{Number} \} \), where no lower bound of both \text{String} and \text{Number} exists). This case is handled by type simplification, discussed in Section \[A\].

**B. Type Simplification**

In this section we present a type simplification technique for arrow types. Our goal is to remove as many unnecessary constraints from the constraint set of an arrow type as possible. This keeps the size of arrow types small, decreasing memory overhead and runtime overhead. Without simplification, arrow types are noticeably larger and type inference is noticeably slower as closure calculation and consistency checks are at least linear with the size of the arrow type.

As a motivating example, consider the following composition involving an arrow \( a \) of type \( \text{Event} \sim \text{Event} \).

\[
\text{remember(seq(event(click), a))}
\]

The resulting arrow takes as input an \text{Elem} value, waits until a \text{click} event occurs on that value, invokes the arrow \( a \) with the resulting event, and then yields the original \text{Elem} value. This is useful as it allows multiple events to be sequenced on the same event.

Without type simplification, the type of the resulting arrow is given by the following.

\[
\alpha \sim \delta \setminus \{ \text{Event} \leq \text{Event}, \alpha, \alpha \leq \text{Elem}, \beta \},
\]

\[
(\text{Event}, \beta) \leq (\gamma, \delta), \alpha \leq \text{Elem}, \alpha \leq \beta, \gamma \leq \delta, \delta \leq \alpha \}
\]

The first constraint, \( \text{Event} \leq \text{Event} \), is introduced by the inner \text{seq} operator. The next two constraints \( \{ \text{Event} \leq \text{Event}, \alpha, \alpha \leq \text{Elem}, \beta \} \) and \( (\text{Event}, \beta) \leq (\gamma, \delta) \), are introduced by the \text{remember} combinator, which involves a \text{seq} with an \text{split} and \text{nth} arrow. The remaining constraints are introduced by closure rule described in Section \[A\].

After type simplification we are given the following, which is much smaller and more easily understandable.

\[
\alpha \sim \delta \setminus \{ \alpha \leq \delta, \alpha \leq \text{Elem} \}, \emptyset
\]

The \text{Memory} application mentioned in Section \[5\] creates an arrow with 1414 distinct constraints involving 56 type variables with type simplification disabled, and no constraints after minimization.
\textbf{Definition B.1} (Simplified). An arrow type is simplified if it is bound-minimal (Definition B.2), variable-minimal (Definition B.3), and pruned (Definition B.5).


\textbf{Definition B.2} (Bound Minimal). An arrow type $\tau_{in} \sim \tau_{out} \setminus (C)$ is bound-minimal if every type variable $\alpha$ in the arrow type has at most one concrete upper bound and at most one concrete lower bound. A type is concrete if it contains no type variables. We can bound-minimize an arrow type by collapsing the concrete bounds of a type variable.

We can collect the concrete lower and upper bounds of a type variable $\alpha$, denoted $b_l(\alpha)$ and $b_u(\alpha)$, respectively.

\begin{align*}
    b_l(\alpha) &= \{ \tau_i \mid \tau_i \leq \alpha \in C \text{ and } \tau_i \text{ contains no type variables} \} \\
    b_u(\alpha) &= \{ \tau_i \mid \tau_i \leq \alpha \in C \text{ and } \tau_i \text{ contains no type variables} \}
\end{align*}

We can then bound-minimize a constraint set $C$ by collapsing the lower and upper bounds for each type variable $\alpha$. We can collapse the lower bounds of a type variable $\alpha$ by applying the following transformation to $C$.

\begin{align*}
    (C \setminus \{ \tau_i \leq \alpha \mid \tau_i \in b_l(\alpha) \}) \cup (\{ \forall i. b_l(\alpha) \} \leq \alpha)
\end{align*}

Similarly, we can collapse the upper bounds of a type variable $\alpha$ by applying the following transformation to $C$.

\begin{align*}
    (C \setminus \{ \alpha \leq \tau_i \mid \tau_i \in b_u(\alpha) \}) \cup (\{ \alpha \leq (\forall i. b_u(\alpha)) \}
\end{align*}

\begin{figure}[h]
\centering
\begin{tabular}{|c|c|c|c|c|}
\hline
\textbf{ULES-UNIT} & \textbf{ULES-SELF} & \textbf{ULES-UPPER} & \textbf{ULES-LOWER} \\
\hline
$\tau \leq \Omega$ & $\tau \leq \tau$ & $\alpha^+ \leq \tau$ & $\tau \leq \alpha^-$ \\
\hline
\textbf{ULES-NONVAR} & \textbf{ULES-LOWERUNKNOWN} & \textbf{ULES-UPPERUNKNOWN} \\
\hline
$\tau \notin A \land \tau' \notin A$ & $\alpha \notin \tau_{in} \land \alpha \notin \tau_{out}$ & $\alpha \notin \tau_{in} \land \alpha \notin \tau_{out}$ \\
\hline
$\tau \leq \tau'$ & $\alpha \leq \beta$ & $\beta \leq \alpha$ \\
\hline
\end{tabular}
\caption{Useless constraint elimination rules.}
\end{figure}

If a non-existent lower bound is needed to simplify an arrow type, then there is a type variable $\alpha$ for which no concrete type satisfying the set of constraints exists. We consider such arrow types malformed. For example, an arrow of the following type accepts an (impossible) value whose type must be simultaneously a lower bound of Int and a lower bound of String.

$$\alpha \sim Number \setminus \{ \alpha \leq Int, \alpha \leq String \}, \emptyset$$

Such an arrow type, while consistent, results in a composition error as it cannot be supplied any reasonable value at runtime.

\textbf{Definition B.3} (Type Variable Position). A type variable $\alpha$ may occur in negative position, denoted $\alpha^-$, in positive position, denoted $\alpha^+$, in both positions simultaneously, denoted $\alpha^\pm$, or in neither position, denoted $\alpha$, relative to an arrow type $\tau_{in} \sim \tau_{out} \setminus (C, E)$.

Given a constraint $\tau \leq \tau'$ and a type variable $\alpha$ occurring in $\tau$ and a type variable $\beta$ occurring in $\tau'$, we say that $\alpha$ lower-bounds $\beta$ and $\beta$ upper-bounds $\alpha$.

A type variable $\alpha$ occurs in negative position if either $\alpha$ occurs in $\tau_{in}$ or if $\alpha$ upper-bounds some type variable $\beta^+$ or $\beta^\pm$. Symmetrically, a type variable $\alpha$ occurs in positive position if $\alpha$ occurs in $\tau_{out}$ or if $\alpha$ lower-bounds some type variable $\beta^-$ or $\beta^\pm$.

\textbf{Definition B.4} (Variable-Minimal). We can variable-minimize an arrow type $\tau_{in} \sim \tau_{out} \setminus (C, E)$ by constructing a substitution $\sigma = [\tau_i/\alpha_i]$ by the rules below and replacing all occurrences of the type variable $\alpha_i$ by the type $\tau_i$ in $\tau_{in}, \tau_{out}, C$, and $E$. An arrow type is variable-minimal if no such substitution can be created.

We add the mapping $[\tau/\alpha]$ to the substitution $\sigma$ if one of the following rules holds.

- $\{ \tau \leq \alpha, \alpha \leq \tau \} \subseteq C$
- $\alpha^- \leq \tau \in C \land \forall (\tau' \neq \tau), \alpha \leq \tau' \notin C$
- $\tau \leq \alpha^+ \in C \land \forall (\tau' \neq \tau), \tau' \leq \alpha \notin C$

If $[\beta/\alpha]$ is being added to a substitution $\sigma$ which already contains the mapping $[\tau/\alpha]$, then we instead add the mapping $[\tau/\beta]$ to avoid re-introducing a type variable being substituted.

We substitute a type variable $\alpha$ with the type $\tau$ if $\tau$ is both an upper and lower bound of $\alpha$, as $\tau = \tau$ is a necessary condition for a solution to the constraint set.

We substitute type variable in negative position with their sole lower bound, and type variables in positive position with their sole upper bound. Negative position variables represent a constraint on the input of an arrow, as positive position variables represent a constraint on the output of an arrow. Therefore, negative position variables are concerned only with an upper bound, and positive position variables are concerned only with a lower bound.

Applying a substitution may alter the closure or consistency properties of a set of constraints and may require the closure set to be recalculated and the consistency rechecked.

\textbf{Definition B.5} (Pruned). An arrow type $\tau_{in} \sim \tau_{out} \setminus (C, E)$ is pruned if every constraint $c \in C$ is not immediately useless. Constraints matching a form in Figure [13] are considered useless. A constraint set can be pruned by repeatedly removing all useless constraints.