

LINEAR NEUTRAL PARTIAL DIFFERENTIAL EQUATIONS: A SEMIGROUP APPROACH

RAINER NAGEL and NGUYEN THIEU HUY

Received 17 September 2002

We study linear neutral PDEs of the form $(\partial/\partial t)Fu_t = BFu_t + \Phi u_t$, $t \geq 0$; $u_0(t) = \varphi(t)$, $t \leq 0$, where the function $u(\cdot)$ takes values in a Banach space X . Under appropriate conditions on the difference operator F and the delay operator Φ , we construct a C_0 -semigroup on $C_0(\mathbb{R}_-, X)$ yielding the solutions of the equation.

2000 Mathematics Subject Classification: 34K60, 47D06, 34K30, 34G10.

1. Introduction. In this paper, we study linear neutral PDEs of the form

$$\begin{aligned} \frac{\partial}{\partial t}Fu_t &= BFu_t + \Phi u_t \quad \text{for } t \geq 0, \\ u_0(t) &= \varphi(t) \quad \text{for } t \leq 0. \end{aligned} \tag{1.1}$$

Here, B is some linear partial differential operator, while the operators F and Φ are called *difference operator* and *delay operator*, respectively. We refer to Hale [5, 6], Wu [12, Chapter 2.3], Wu and Xia [13], and Adimy and Ezzinbi [1] for concrete examples and propose an abstract treatment of these equations. For that purpose, we choose a Banach space X and consider the solution $u(\cdot)$ as a function from \mathbb{R} to X . Then, the corresponding *history function* is defined as

$$u_t(s) := u(t+s) \quad \forall t \geq 0, s \leq 0. \tag{1.2}$$

Moreover, B is a linear operator on X (representing the partial differential operator), while F and Φ are linear operators from an X -valued function space; for example, $C_0(\mathbb{R}_-, X)$ into X . More precisely, we make the following assumption throughout the paper.

ASSUMPTION 1.1. On the Banach spaces X and $E := C_0(\mathbb{R}_-, X)$, we consider the following operators:

- (i) let $(B, D(B))$ be the generator of a strongly continuous semigroup $(e^{tB})_{t \geq 0}$ on X satisfying $\|e^{tB}\| \leq Me^{\omega_1 t}$ for some constants $M \geq 1$ and $\omega_1 \in \mathbb{R}$;
- (ii) let the *difference operator* $F : E \rightarrow X$ and the *delay operator* $\Phi : E \rightarrow X$ be bounded and linear.

Under these assumptions, we will solve (1.1) by constructing an appropriate strongly continuous semigroup on the space E . This semigroup will be obtained by proving that a certain operator (see Definition 2.3) satisfies the Hille-Yosida conditions as long as we can write the difference operator as $F = \delta_0 - \Psi$ with Ψ being “small” (see (2.7)). If the delay and difference operators act only on a finite interval $[-r, 0]$, it can be shown that the smallness of Ψ can be replaced by the condition “having no mass in 0” (see Definition 3.1).

In the case of ordinary neutral functional differential equations on finite-dimensional spaces X , we refer the readers to Hale and Verduyn Lunel [7, Chapter 9], Engel [3], and Kappel and Zhang [9, 10] for results about well-posedness and asymptotic behavior of the solutions as well as the use of the condition “having no mass in 0” (or, “nonatomic at zero,” see Remark 3.2). In the case of infinite-dimensional spaces X , such a condition appeared in [11] (see also Datko [2]), where the generator property has been shown under dissipativity conditions for ordinary neutral functional differential equations. Hale [5, 6] and Wu [12, Chapter 2.3] assumed B to generate an analytic semigroup and also obtained a semigroup solving (1.1) in a mild sense if Ψ is nonatomic at zero.

2. Neutral semigroups with infinite delay. Under the assumptions from Section 1, we consider the Banach space $E := C_0(\mathbb{R}_-, X)$ endowed with the sup-norm and the operator $(G_m, D(G_m))$ on E , defined by

$$\begin{aligned} D(G_m) &:= \{f \in E \cap C^1(\mathbb{R}_-, X) : f' \in E\}, \\ G_m f &:= f' \quad \text{for } f \in D(G_m). \end{aligned} \tag{2.1}$$

We are now looking for various restrictions of this (maximal) operator yielding generators of strongly continuous semigroups. We start with a simple case.

DEFINITION 2.1. On the space $E = C_0(\mathbb{R}_-, X)$, we define the operator $T_{B,0}(t)$ by

$$[T_{B,0}(t)f](s) = \begin{cases} f(s+t), & s+t \leq 0, \\ e^{(t+s)B}f(0), & s+t \geq 0 \end{cases} \tag{2.2}$$

for $f \in E$ and $t \geq 0$.

Moreover, we define the operator $(G_{B,0}, D(G_{B,0}))$ by

$$\begin{aligned} D(G_{B,0}) &:= \{f \in D(G_m) : f(0) \in D(B), f' \in E, f'(0) = Bf(0)\}, \\ G_{B,0}f &:= f' \quad \text{for } f \in D(G_{B,0}). \end{aligned} \tag{2.3}$$

We then have the following properties of $G_{B,0}$ and $(T_{B,0}(t))_{t \geq 0}$ which can be proved as in [8, Proposition 2.8].

PROPOSITION 2.2. *The following assertions hold:*

- (i) $(T_{B,0}(t))_{t \geq 0}$ is a strongly continuous semigroup on the space E with the generator $(G_{B,0}, D(G_{B,0}))$;
- (ii) the set $\{\lambda \in \mathbb{C} : \operatorname{Re} \lambda > 0, \lambda \in \rho(B)\}$ is contained in $\rho(G_{B,0})$. Moreover, for λ in this set, the resolvent is given by

$$[R(\lambda, G_{B,0})f](t) = e^{\lambda t} R(\lambda, B)f(0) + \int_t^0 e^{\lambda(t-\xi)} f(\xi) d\xi \quad \text{for } f \in E, t \leq 0; \tag{2.4}$$

- (iii) the semigroup $(T_{B,0}(t))_{t \geq 0}$ satisfies

$$\|T_{B,0}(t)\| \leq M e^{\omega_2 t}, \quad t \geq 0 \tag{2.5}$$

with $\omega_2 := \max\{0, \omega_1\}$ for the constants M and ω_1 appearing in Assumption 1.1.

We now take the delay operator Φ and the difference operator F (see Assumption 1.1) to define a different restriction of the operator G_m .

DEFINITION 2.3. The operator $G_{B,F,\Phi}$ is defined by

$$\begin{aligned} G_{B,F,\Phi} f &:= f' \text{ on the domain} \\ D(G_{B,F,\Phi}) &:= \{f \in D(G_m) : Ff \in D(B), F(f') = BFf + \Phi f\}. \end{aligned} \tag{2.6}$$

Our aim is to find conditions on F such that the operator $G_{B,F,\Phi}$ becomes the generator of a strongly continuous semigroup. To do so, we write F in the form

$$Ff := f(0) - \Psi f, \quad f \in E, \tag{2.7}$$

for some bounded linear operator $\Psi : E \rightarrow X$. The domain of $G_{B,F,\Phi}$ can then be rewritten as

$$\begin{aligned} D(G_{B,F,\Phi}) &= \{f \in D(G_m) : f(0) - \Psi f \in D(B), f'(0) = B(f(0) - \Psi f) + \Phi f + \Psi f'\}. \end{aligned} \tag{2.8}$$

It is now our main result that if the operator Ψ is “small,” then $G_{B,F,\Phi}$ is densely defined and satisfies the Hille-Yosida estimates; hence, generates a strongly continuous semigroup.

For that purpose and for $\lambda \in \mathbb{C}$ satisfying $\operatorname{Re} \lambda > 0$, we define the operator $e_\lambda : X \rightarrow E$ by

$$[e_\lambda x](t) := e^{\lambda t} x \quad \text{for } t \leq 0, x \in X. \tag{2.9}$$

THEOREM 2.4. *Assume that the difference operator F is of the form (2.7) such that Ψ satisfies the condition $\|\Psi\| < 1$. Then, the following assertions hold:*

- (i) $\lambda \in \rho(G_{B,F,\Phi})$ for each $\lambda > \omega_2 + M\|\Phi\|/(1 - \|\Psi\|)$ (with the constants ω_2 and M as in Proposition 2.2). For such λ , the resolvent of $G_{B,F,\Phi}$ has the form

$$R(\lambda, G_{B,F,\Phi})f = e_\lambda[\Psi R(\lambda, G_{B,F,\Phi}) + R(\lambda, B)(\Phi R(\lambda, G_{B,F,\Phi}) - \Psi)]f + R(\lambda, G_{B,0})f \quad \text{for } f \in E; \tag{2.10}$$

- (ii) for $L := (M + M\|\Psi\|)/(1 - \|\Psi\|)$ and $\lambda_0 := \omega_2 + M\|\Phi\|/(1 - \|\Psi\|)$,

$$\|R(\lambda, G_{B,F,\Phi})\| \leq \frac{L}{(\lambda - \lambda_0)} \quad \text{for } \lambda > \lambda_0; \tag{2.11}$$

- (iii) for $\lambda > \omega_0 := \max\{2\lambda_0, \omega_2 + L\|\Phi\|\}$ and $P := 3e[(M + L)\|\Psi\| + 2M + 1]$, it follows that

$$\|R(\lambda, G_{B,F,\Phi})^n\| \leq \frac{P}{(\lambda - \omega_0)^n} \quad \forall n \in \mathbb{N}; \tag{2.12}$$

- (iv) the operator $G_{B,F,\Phi}$ is densely defined.

PROOF. (i) We first observe that for $u, f \in E$ and $\lambda \in \mathbb{C}$, we have that $u \in D(G_m)$ and $\lambda u - G_m u = f$ if and only if u and f satisfy

$$u(t) = e^{\lambda(t-s)}u(s) + \int_t^s e^{\lambda(t-\xi)}f(\xi)d\xi \quad \text{for } t \leq s \leq 0. \tag{2.13}$$

Note that for $\lambda > \omega_2$ and by (2.4),

$$u(t) = e^{\lambda t}[\Psi u + R(\lambda, B)(f(0) + \Phi u - \Psi f)] + \int_t^0 e^{\lambda(t-\xi)}f(\xi)d\xi \quad \text{for } t \leq 0 \tag{2.14}$$

is equivalent to

$$u = e_\lambda(\Psi u + R(\lambda, B)\Phi u) - e_\lambda R(\lambda, B)\Psi f + R(\lambda, G_{B,0})f. \tag{2.15}$$

If, for each $f \in E$ and $\lambda > \lambda_0$, the equation (2.15) has a unique solution $u \in E$, then $u(0) = \Psi u + R(\lambda, B)(f(0) + \Phi u - \Psi f)$. This is equivalent to

$$(\lambda - B)(u(0) - \Psi u) = [(\lambda - G_m)u](0) + \Phi u - \Psi(\lambda - G_m)u \tag{2.16}$$

or

$$u'(0) = B(u(0) - \Psi u) + \Phi u + \Psi u'. \tag{2.17}$$

Hence, by the above observation and the definition of $G_{B,F,\Phi}$, we have that $u \in D(G_{B,F,\Phi})$ and $u = R(\lambda, G_{B,F,\Phi})f$. Therefore, to prove (i), we have to verify that for $\lambda > \lambda_0$ and each $f \in E$, (2.14) has a unique solution $u \in E$.

Let $M_\lambda : E \rightarrow E$ be the linear operator defined as

$$M_\lambda := e_\lambda(\Psi + R(\lambda, B)\Phi). \tag{2.18}$$

Since $\lambda > \omega_2 + M\|\Phi\|/(1 - \|\Psi\|)$, we have that M_λ is bounded and satisfies

$$\|M_\lambda\| \leq \|\Psi\| + \frac{M\|\Phi\|}{\lambda - \omega_2} < 1. \tag{2.19}$$

Therefore, the operator $I - M_\lambda$ is invertible, and (2.14) has a unique solution $u = (I - M_\lambda)^{-1}(R(\lambda, G_{B,0})f - e_\lambda R(\lambda, B)\Psi f)$. Thus,

$$R(\lambda, G_{B,F,\Phi})f = M_\lambda R(\lambda, G_{B,F,\Phi})f - e_\lambda R(\lambda, B)\Psi f + R(\lambda, G_{B,0})f \tag{2.20}$$

and (2.10) follows.

(ii) By the Neumann series $(I - M_\lambda)^{-1} = \sum_{n=0}^\infty M_\lambda^n$, we have that

$$\begin{aligned} \|R(\lambda, G_{B,F,\Phi})\| &= \left\| \sum_{n=0}^\infty M_\lambda^n (R(\lambda, G_{B,0}) - e_\lambda R(\lambda, B)\Psi) \right\| \\ &\leq \left(\sum_{n=0}^\infty \|M_\lambda^n\| \right) \frac{M + M\|\Psi\|}{(\lambda - \omega_2)} \\ &\leq \frac{M + M\|\Psi\|}{(\lambda - \omega_2)} \sum_{n=0}^\infty \left(\|\Psi\| + \frac{M\|\Phi\|}{\lambda - \omega_2} \right)^n \\ &= \frac{M + M\|\Psi\|}{(1 - \|\Psi\|)(\lambda - \omega_2 - M\|\Phi\|/(1 - \|\Psi\|))} \\ &= \frac{L}{\lambda - \lambda_0}. \end{aligned} \tag{2.21}$$

(iii) For $\lambda > \lambda_0$ and $u := R(\lambda, G_{B,F,\Phi})f$, we have

$$\begin{aligned} u(t) &= e^{\lambda t} [\Psi R(\lambda, G_{B,F,\Phi})f + R(\lambda, B)(\Phi R(\lambda, G_{B,F,\Phi})f - \Psi f + f(0))] \\ &\quad + \int_t^0 e^{\lambda(t-\xi)} f(\xi) d\xi \quad \text{for } t \leq 0. \end{aligned} \tag{2.22}$$

We extend u and f to functions on \mathbb{R} by

$$\begin{aligned} \tilde{u}(t) &:= \begin{cases} u(t) & \text{for } t \leq 0, \\ e^{\lambda t} g(t) & \text{for } t > 0, \end{cases} \\ \tilde{f}(t) &:= \begin{cases} f(t) & \text{for } t \leq 0, \\ -e^{\lambda t} g'(t) & \text{for } t > 0, \end{cases} \end{aligned} \tag{2.23}$$

where we take $g(t) := u(0) + \int_0^t \varphi(\tau) d\tau$ with

$$\varphi(t) := \begin{cases} 6t[t\lambda^2 - \lambda] \left[\lambda u(0) - \frac{1}{2} f(0) \right] + [\lambda t - 1] f(0) & \text{for } 0 \leq t \leq \frac{1}{\lambda}, \\ 0 & \text{for } t \geq \frac{1}{\lambda}. \end{cases} \tag{2.24}$$

Then, g is continuously differentiable with compact support contained in the interval $[0, 1/\lambda]$ satisfying $g(0) = u(0)$, $g'(0) = -f(0)$, and

$$\|e^{\lambda t} g'(t)\| \leq 3e[(M + L)\|\Psi\| + 2M + 1]\|f\| \tag{2.25}$$

for $\lambda > \max\{2\lambda_0, \omega_2 + L\|\Phi\|\}$ and all $t \in \mathbb{R}_+$. Hence, the functions \tilde{u} and \tilde{f} defined by (2.23) belong to the Banach space $C_0(\mathbb{R}, X)$ and satisfy

$$\tilde{u}(t) = e^{\lambda(t-s)} \tilde{u}(s) + \int_t^s e^{\lambda(t-\xi)} \tilde{f}(\xi) d\xi \quad \text{for } t \leq s, \tag{2.26}$$

$$\|\tilde{f}\| \leq 3e[(M + L)\|\Psi\| + 2M + 1]\|f\|. \tag{2.27}$$

We now look at the left translation semigroup $(\tilde{T}(t))_{t \geq 0}$ on the Banach space $\tilde{E} := C_0(\mathbb{R}, X)$, that is,

$$(\tilde{T}(t)\tilde{f})(s) := \tilde{f}(s+t) \quad \forall \tilde{f} \in \tilde{E}, s \in \mathbb{R}, t \geq 0. \tag{2.28}$$

This semigroup is strongly continuous on \tilde{E} and its generator is $\tilde{G}_m := d/ds$ on the domain $D(\tilde{G}_m) := \{f \in \tilde{E} \cap C^1(\mathbb{R}, X) : f' \in \tilde{E}\}$ (see [4, Chapter II.2]). Furthermore, we observe that for $v, w \in \tilde{E}$ and $\lambda \in \mathbb{C}$, we have that $v \in D(\tilde{G}_m)$ and $\lambda v - \tilde{G}_m v = w$ if and only if v and w satisfy (2.26). Since $\lambda \in \rho(\tilde{G}_m)$ for $\lambda > \lambda_0$, we obtain that $\tilde{u} = R(\lambda, \tilde{G}_m)\tilde{f}$ for $\lambda > \lambda_0$, where \tilde{u} and \tilde{f} are defined as in (2.23).

Therefore, by (2.23), we have that

$$[R(\lambda, G_{B,F,\Phi})f](t) = u(t) = \tilde{u}(t) = [R(\lambda, \tilde{G}_m)\tilde{f}](t) \tag{2.29}$$

for $t \leq 0$ and $\lambda > \max\{2\lambda_0, \omega_2 + L\|\Phi\|\} =: \omega_0$.

By induction, we obtain

$$\left[R(\lambda, G_{B,F,\Phi})^n f \right](t) = \left[R(\lambda, \tilde{G}_m)^n \tilde{f} \right](t) \quad \text{for } t \leq 0, \lambda > \omega_0. \tag{2.30}$$

Using the fact that \tilde{G}_m is the generator of the strongly continuous semigroup $(\tilde{T}(t))_{t \geq 0}$ on \tilde{E} , and by inequality (2.27), we have

$$\begin{aligned} \left\| \left[R(\lambda, G_{B,F,\Phi})^n f \right](t) \right\| &= \left\| \left[R(\lambda, \tilde{G}_m)^n \tilde{f} \right](t) \right\| \\ &\leq \frac{\|\tilde{f}\|}{\lambda^n} \leq \frac{3e[(M+L)\|\Psi\| + 2M + 1]}{(\lambda - \omega_0)^n} \|f\| \end{aligned} \tag{2.31}$$

for all $t \leq 0, \lambda > \omega_0$, and all $n \in \mathbb{N}$. Therefore, putting $P := 3e[(M+L)\|\Psi\| + 2M + 1]$, we obtain

$$\left\| R(\lambda, G_{B,F,\Phi})^n f \right\| \leq \frac{P}{(\lambda - \omega_0)^n} \|f\| \quad \text{for } \lambda > \omega_0, n \in \mathbb{N}. \tag{2.32}$$

(iv) For $\lambda > \lambda_0$, we consider the operator $S : E \rightarrow E$ defined by

$$Sf := -e_{\lambda}R(\lambda, B)\Psi f + R(\lambda, G_{B,0})f, \quad f \in E. \tag{2.33}$$

Observe that if its range ImS is dense in E , then we have, by (2.20), that $D(G_{B,F,\Phi}) = R(\lambda, G_{B,F,\Phi})E = (I - M_{\lambda})^{-1}ImS$ is dense in E . Therefore, it is enough to verify that ImS is dense in E . Since $D(G_m)$ is dense in E , we only need to show that $\overline{ImS} \supset D(G_m) = D(\lambda - G_m)$.

In fact, for $u \in D(\lambda - G_m)$, there exists $f \in E$ such that

$$u(t) = e^{\lambda t}u(0) + \int_t^0 e^{\lambda(t-\xi)}f(\xi)d\xi \quad \text{for } t \leq 0. \tag{2.34}$$

Since the operator B is densely defined, there exists a sequence $(y_n) \subset D(B)$ such that $\lim_{n \rightarrow \infty} y_n = u(0)$. Let $(x_n) \subset X$ be a sequence such that $R(\lambda, B)x_n = y_n$.

For each $n \in \mathbb{N}$, we choose a real-valued, continuous function $\alpha_n(t)$ with support contained in $[\max\{-1/n, -1/n\|x_n\|\}, 0]$ satisfying $\alpha_n(0) = 1$ and $\sup_{t \leq 0} |\alpha_n(t)| \leq 1$.

By the condition $\|\Psi\| < 1$, we have that the functions

$$f_n(\cdot) := (I - \alpha_n(\cdot)\Psi)^{-1}(\alpha_n(\cdot)(x_n - f(0)) + f(\cdot)), \quad n \in \mathbb{N}, \tag{2.35}$$

belong to E . Moreover, these functions satisfy

$$\begin{aligned} f_n(t) &= \alpha_n(t)(x_n + \Psi(f_n) - f(0)) + f(t), \\ f_n(0) - \Psi(f_n) &= x_n, \\ \|f_n\| &\leq \frac{\|x_n\| + 2\|f\|}{1 - \|\Psi\|}. \end{aligned} \tag{2.36}$$

We now put

$$u_n(t) := e^{\lambda t}R(\lambda, B)(f_n(0) - \Psi f_n) + \int_t^0 e^{\lambda(t-\xi)} f_n(\xi) d\xi. \tag{2.37}$$

Then, $u_n = S f_n$; hence $u_n \in ImS$, and for $\lambda > \lambda_0$, we obtain

$$\begin{aligned} &\|u_n(t) - u(t)\| \\ &= \left\| e^{\lambda t}(R(\lambda, B)x_n - u(0)) + \int_t^0 e^{\lambda(t-\xi)}(f_n(\xi) - f(\xi)) d\xi \right\| \\ &\leq \|y_n - u(0)\| + \int_t^0 |\alpha_n(t)| (\|x_n\| + \|\Psi\| \|f_n\| + \|f(0)\|) dt \\ &\leq \|y_n - u(0)\| + \int_{\max\{-1/n, -1/n\|x_n\|\}}^0 \left(\|x_n\| + \frac{\|\Psi\|(\|x_n\| + 2\|f\|)}{1 - \|\Psi\|} + \|f\| \right) dt \\ &\leq \|y_n - u(0)\| + \frac{1}{n(1 - \|\Psi\|)} + \frac{(1 + \|\Psi\|)\|f\|}{n(1 - \|\Psi\|)} \xrightarrow{n \rightarrow \infty} 0 \quad \text{uniformly } \forall t \in \mathbb{R}_-. \end{aligned} \tag{2.38}$$

This means that $\lim_{n \rightarrow \infty} u_n = u$. Thus, ImS is dense in E . □

The Hille-Yosida theorem now yields the following corollary.

COROLLARY 2.5. *Let the difference operator F have the form (2.7) with Ψ satisfying $\|\Psi\| < 1$. Then the operator $G_{B,F,\Phi}$ generates a strongly continuous semigroup $(T_{B,F,\Phi}(t))_{t \geq 0}$ on E satisfying*

$$\|T_{B,F,\Phi}(t)\| \leq P e^{\omega_0 t}, \quad t \geq 0, \tag{2.39}$$

where the constants P and ω_0 are defined as in [Theorem 2.4](#).

We now conclude this section by a corollary about well-posedness of (1.1). To this end, we denote by $t \mapsto u_t(\cdot, \varphi)$ the classical solution of (1.1) corresponding to the initial condition $u_0 = \varphi$, that is, $t \mapsto u_t(\cdot, \varphi)$ is continuously differentiable and satisfies (1.1).

COROLLARY 2.6. *Assume that the difference operator F is of the form (2.7) such that Ψ satisfies $\|\Psi\| < 1$. Then, (1.1) is well posed. More precisely, for every $\varphi \in D(G_{B,F,\Phi})$, there exists a unique classical solution $u_t(\cdot, \varphi)$ of (1.1) given by*

$$u_t(\cdot, \varphi) = T_{B,F,\Phi}(t)\varphi, \tag{2.40}$$

and for every sequence $(\varphi_n)_{n \in \mathbb{N}} \subset D(G_{B,F,\Phi})$ satisfying $\lim_{n \rightarrow \infty} \varphi_n = 0$,

$$\lim_{n \rightarrow \infty} u_t(\cdot, \varphi_n) = 0 \tag{2.41}$$

uniformly in compact intervals.

PROOF. By Corollary 2.5, the operator $(G_{B,F,\Phi}, D(G_{B,F,\Phi}))$ defined by (2.6) is the generator of the strongly continuous semigroup $(T_{B,F,\Phi}(t))_{t \geq 0}$.

For $\varphi \in D(G_{B,F,\Phi})$, we put $u_t := T_{B,F,\Phi}(t)\varphi$. Then, it is clear that $u_t \in D(G_{B,F,\Phi}) \subset D(G_m)$. We now show that u_t satisfies (1.1). Indeed, we have

$$\begin{aligned} \frac{d}{dt}Fu_t &= \lim_{h \rightarrow 0} \frac{Fu_{t+h} - Fu_t}{h} = \lim_{h \rightarrow 0} \frac{FT(t+h)\varphi - FT(t)\varphi}{h} \\ &= F \lim_{h \rightarrow 0} \frac{T(h)T(t)\varphi - T(t)\varphi}{h} = FG_{B,F,\Phi}T(t)\varphi \\ &= BFT(t)\varphi + \Phi T(t)\varphi = BFu_t + \Phi u_t. \end{aligned} \tag{2.42}$$

For the uniqueness of the solution, we prove that if v_t is a classical solution of (1.1) satisfying $v_0 = 0$, then $v_t = 0$ for all $t \geq 0$. In fact, since v_t satisfies (1.1) and $v_t \in D(G_m)$, we have that

$$BFv_t + \Phi v_t = \frac{d}{dt}Fv_t = \lim_{h \rightarrow 0} \frac{Fv_{t+h} - Fv_t}{h} = F \lim_{h \rightarrow 0} \frac{v_{t+h} - v_t}{h} = Fv'_t. \tag{2.43}$$

Therefore, $v_t \in D(G_{B,F,\Phi})$ satisfies the Cauchy problem

$$\begin{aligned} \frac{d}{dt}v_t &= G_{B,F,\Phi}v_t \quad \text{for } t \geq 0, \\ v_0 &= 0. \end{aligned} \tag{2.44}$$

Since $G_{B,F,\Phi}$ is the generator of a strongly continuous semigroup, this Cauchy problem has a unique solution $v_t = 0$ (see [4, Theorem II.6.7]).

Finally, the last assertion, called the *continuous dependence on the initial data* of the solutions, follows from the uniform boundedness of the strongly continuous semigroup $(T_{B,F,\Phi}(t))_{t \geq 0}$ on compact intervals. \square

3. Neutral semigroups with finite delay. In this section, we study (1.1) on a finite delay interval $[-r, 0]$, that is,

$$\begin{aligned} \frac{\partial}{\partial t}Fu_t &= BFu_t + \Phi u_t \quad \text{for } t \geq 0, \\ u_0 &= \varphi \in C([-r, 0], X). \end{aligned} \tag{3.1}$$

We again assume the difference operator F to be given as in (2.7), that is,

$$F\varphi = \varphi(0) - \Psi\varphi, \quad \varphi \in C([-r, 0], X) \tag{3.2}$$

for some bounded linear operator $\Psi : C([-r, 0], X) \rightarrow X$. However, instead of assuming Ψ to be “small,” we suppose that Ψ has no mass in 0 (see Definition 3.1). Our main idea is to renorm the space $C([-r, 0], X)$ such that, with the new equivalent norm, the norm of Ψ is small, so we can adapt the arguments from the previous section. This idea has been used, for example, by Schwarz [11] to study ordinary neutral functional differential equations via dissipativity conditions. We begin with the definition of “no mass in 0.”

DEFINITION 3.1. A bounded linear operator $\Psi \in \mathcal{L}(C([-r, 0], X), X)$ is said to have no mass in 0 if for every $\epsilon > 0$, there exists a positive number $\delta \leq r$ such that

$$\|\Psi(f)\|_X \leq \epsilon \|f\|_\infty \quad \forall f \in C([-r, 0], X) \text{ satisfying } \text{supp } f \subseteq [-\delta, 0]. \tag{3.3}$$

REMARK 3.2. This definition is taken from [11, Definition II.2.1]. We note that, if $\Psi \in \mathcal{L}(C([-r, 0], X), X)$ has the form

$$\Psi(f) = \int_{-r}^0 [d\eta(\theta)]f(\theta) \tag{3.4}$$

for some function $\eta(\cdot)$ of bounded variation, then the above definition is equivalent to the fact that the function $\eta(\cdot)$ is nonatomic at 0 in the sense of Hale and Verduyn Lunel [7, Chapter 9.2] or Wu [12, Chapter 2.3].

We are now prepared to renorm the space $C := C([-r, 0], X)$. Indeed, for each positive number ω , the new norm $\|\cdot\|_\omega$ defined by

$$\|f\|_\omega := \sup_{-r \leq s \leq 0} \|f(s)e^{-\omega s}\|_X, \quad f \in C \tag{3.5}$$

is equivalent to the supnorm. Furthermore, C_ω denotes the space $C([-r, 0], X)$ endowed with the norm $\|\cdot\|_\omega$.

LEMMA 3.3. *Let the operator $\Psi \in \mathcal{L}(C, X)$ have no mass in 0. Then there exists a positive number ω such that the norm of the operator Ψ , as a bounded linear operator from C_ω into X , is smaller than 1.*

PROOF. We first prove that there exists a number $\omega > 0$ such that

$$\|\Psi(f)\|_X \leq \frac{1}{2} \quad \forall f \in C([-r, 0], X) \text{ satisfying } \|f(s)\| \leq e^{\omega s} \quad \forall s \in [-r, 0]. \tag{3.6}$$

Indeed, since Ψ has no mass in 0, there exists a positive number $\delta \leq r$ such that $\|\Psi(f)\|_X \leq (1/8)\|f\|$ if $\text{supp } f \subseteq [-\delta, 0]$. For this δ , we take an $\omega > 0$ such that

$\|\Psi\| < (1/4)e^{\delta\omega}$. Now, for a given $f \in C([-r, 0], X)$ satisfying $\|f(s)\|_X \leq e^{\omega s}$ for all $s \in [-r, 0]$, we prove that $\|\Psi(f)\|_X \leq 1/2$. For that purpose, we put

$$f_1(s) := \begin{cases} f(s) & \text{for } s \in [-r, -\delta], \\ f(-\delta) & \text{otherwise,} \end{cases} \tag{3.7}$$

and $f_2(s) := f(s) - f_1(s)$. Then, $\text{supp } f_2 \subseteq [-\delta, 0]$. Therefore, we have that

$$\begin{aligned} \|\Psi(f)\|_X &\leq \|\Psi(f_1)\|_X + \|\Psi(f_2)\|_X \\ &\leq \|\Psi\| \|f_1\|_\infty + \frac{1}{8} (\|f_1\|_\infty + \|f\|_\infty) \\ &< \frac{1}{2} \end{aligned} \tag{3.8}$$

and (3.6) follows.

Denote by $\|\Psi\|_\omega$ the norm of Ψ as a bounded linear operator in $\mathcal{L}(C_\omega, X)$. Then, by inequality (3.6), we have that

$$\|\Psi\|_\omega = \sup_{\|f\|_\omega \leq 1} \|\Psi f\| = \sup_{\substack{\|f(s)\| e^{-\omega s} \leq 1 \\ -r \leq s \leq 0}} \|\Psi f\| \leq \frac{1}{2} < 1. \tag{3.9}$$

□

This renorming allows us to adapt the arguments from the proof of [Theorem 2.4](#) to prove that the operator corresponding to (3.1) is the generator of a C_0 -semigroup on the space $C([-r, 0], X)$. Note that the generator property of an operator is preserved when passing to an equivalent norm.

THEOREM 3.4. *Assume that the difference operator F has the form $F\varphi = \varphi(0) - \Psi\varphi$ with the bounded linear operator $\Psi : C([-r, 0], X) \rightarrow X$ having no mass in 0, and let the operator B generate a strongly continuous semigroup on X . Then, the operator $(G, D(G))$ defined by*

$$\begin{aligned} Gf &:= f' \quad \text{on the domain} \\ D(G) &:= \{f \in C([-r, 0], X) \cap C^1([-r, 0], X) : Ff \in D(B), Ff' = BFf + \Phi f\} \end{aligned} \tag{3.10}$$

is the generator of a strongly continuous semigroup $(T(t))_{t \geq 0}$ on $C([-r, 0], X)$.

PROOF. Let C_ω be the space $C([-r, 0], X)$ normed by the new norm $\|\cdot\|_\omega$ for ω as in [Lemma 3.3](#). Then, the norm of the operator Ψ , as a bounded linear operator from C_ω into X , is smaller than 1. Therefore, as in [Theorem 2.4](#), we show that the operator $(G, D(G))$ defined by (3.10) is densely defined and satisfies the Hille-Yosida estimates; hence, it generates a strongly continuous semigroup. □

Analogously to [Corollary 2.6](#), we have the following result about the existence, uniqueness, and continuous dependence on initial data of the solutions to the neutral PDE (3.1).

COROLLARY 3.5. *Assume that the difference operator F is of the form (3.2) such that Ψ has no mass in 0. Then, for every $\varphi \in D(G)$, there exists a unique classical solution $u_t(\cdot, \varphi)$ of (3.1), given by $u_t(\cdot, \varphi) = T(t)\varphi$, where the strongly continuous semigroup $(T(t))_{t \geq 0}$ is generated by the operator G as in Theorem 3.4. Moreover, for every sequence $(\varphi_n)_{n \in \mathbb{N}} \subset D(G)$ satisfying $\lim_{n \rightarrow \infty} \varphi_n = 0$, $\lim_{n \rightarrow \infty} u_t(\cdot, \varphi_n) = 0$ uniformly in compact intervals.*

Having established the well-posedness of (3.1), we now consider the robustness of the exponential stability of the solution semigroup. This can be done by using the constants appearing in the Hille-Yosida estimates of the operator G .

COROLLARY 3.6. *Let the assumptions of Theorem 3.4 be satisfied. In addition, let the operator B generate an exponentially stable C_0 -semigroup and the norm of the operator Ψ satisfy $\|\Psi\| < 1$. Then, if the norm of the delay operator Φ is sufficiently small, the solution semigroup $(T(t))_{t \geq 0}$ generated by $(G, D(G))$ is exponentially stable.*

PROOF. We note that in the case of the finite delay interval $[-r, 0]$, the operators e_λ defined as in (2.9) are well defined for all $\lambda \in \mathbb{C}$, and the exponent ω_2 in the exponential estimate (2.5) can be chosen as $\omega_2 := \omega_1$ with the constant M being replaced by $K := \max\{M, Me^{-\omega_1 r}\}$, where the constant ω_1 appears in Assumption 1.1. Therefore, for (3.1) on the finite delay interval $[-r, 0]$, we can adapt the arguments in the proof of Theorem 2.4 to obtain an analogue of Corollary 2.5, that is, the generator $(G, D(G))$ defined by (3.10) generates a strongly continuous semigroup $(T(t))_{t \geq 0}$ satisfying

$$\|T(t)\| \leq Pe^{\omega_0 t}, \quad t \geq 0 \tag{3.11}$$

with the constant P defined as in Theorem 2.4 and the constant

$$\omega_0 := \max \left\{ 2\omega_1 + \frac{2K\|\Phi\|}{1 - \|\Psi\|}, \omega_1 + \frac{K + K\|\Psi\|}{1 - \|\Psi\|} \|\Phi\| \right\}. \tag{3.12}$$

Now, the assumption that $(e^{tB})_{t \geq 0}$ is exponentially stable means that $\omega_1 < 0$. Therefore, if $\|\Phi\| < -\omega_1(1 - \|\Psi\|)/(K + K\|\Psi\|)$, then the solution semigroup is exponentially stable. □

REMARK 3.7. In order to show the robustness of the exponential stability of the solution semigroup as in the above corollary, we need the condition $\|\Psi\| < 1$. This is due to the fact that in the renorming Lemma 3.3, the constant $\omega > 0$, which appears in the exponential bound of the solution semigroup, does not depend on the operator B . Moreover, we do not have an explicit estimate for this constant. This somehow corresponds to the fact considered by Hale [6, Theorem 1.2] that one needs some additional conditions on the difference operator F to develop a qualitative theory of the neutral PDE (3.1).

ACKNOWLEDGMENT. The second author gratefully acknowledges the support of the Vietnamese government.

REFERENCES

- [1] M. Adimy and K. Ezzinbi, *A class of linear partial neutral functional-differential equations with nondense domain*, J. Differential Equations **147** (1998), no. 2, 285-332.
- [2] R. Datko, *Linear autonomous neutral differential equations in a Banach space*, J. Differential Equations **25** (1977), no. 2, 258-274.
- [3] K.-J. Engel, *Spectral theory and generator property for one-sided coupled operator matrices*, Semigroup Forum **58** (1999), no. 2, 267-295.
- [4] K.-J. Engel and R. Nagel, *One-Parameter Semigroups for Linear Evolution Equations*, Graduate Texts in Mathematics, vol. 194, Springer-Verlag, New York, 2000.
- [5] J. K. Hale, *Coupled oscillators on a circle. Dynamical phase transitions (São Paulo, 1994)*, Resenhas **1** (1994), no. 4, 441-457.
- [6] ———, *Partial neutral functional-differential equations*, Rev. Roumaine Math. Pures Appl. **39** (1994), no. 4, 339-344.
- [7] J. K. Hale and S. M. Verduyn Lunel, *Introduction to Functional-Differential Equations*, Applied Mathematical Sciences, vol. 99, Springer-Verlag, New York, 1993.
- [8] N. T. Huy, *Resolvents of operators and partial functional differential equations with non-autonomous past*, Tübinger Berichte zur Funktionalanalysis **11** (2002), 239-252.
- [9] F. Kappel and K. P. Zhang, *Equivalence of functional-differential equations of neutral type and abstract Cauchy problems*, Monatsh. Math. **101** (1986), no. 2, 115-133.
- [10] ———, *On neutral functional-differential equations with nonatomic difference operator*, J. Math. Anal. Appl. **113** (1986), no. 2, 311-343.
- [11] M. Schwarz, *Lineare Funktionaldifferentialgleichungen und ihre Lösungshalbgruppen*, Ph.D. thesis, Universität Tübingen, Tübingen, 1989.
- [12] J. Wu, *Theory and Applications of Partial Functional-Differential Equations*, Applied Mathematical Sciences, vol. 119, Springer-Verlag, New York, 1996.
- [13] J. Wu and H. Xia, *Self-sustained oscillations in a ring array of coupled lossless transmission lines*, J. Differential Equations **124** (1996), no. 1, 247-278.

Rainer Nagel: Arbeitsgemeinschaft Funktionalanalysis (AGFA) Mathematisches Institut der Universität Tübingen, Auf der morgenstelle 10, 72076 Tübingen, Germany
E-mail address: rana@fa.uni-tuebingen.de

Nguyen Thieu Huy: Arbeitsgemeinschaft Funktionalanalysis (AGFA) Mathematisches Institut der Universität Tübingen, Auf der morgenstelle 10, 72076 Tübingen, Germany
E-mail address: hung@fa.uni-tuebingen.de

Special Issue on Modeling Experimental Nonlinear Dynamics and Chaotic Scenarios

Call for Papers

Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from "Qualitative Theory of Differential Equations," allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the *Mathematical Problems in Engineering* aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

Authors should follow the Mathematical Problems in Engineering manuscript format described at <http://www.hindawi.com/journals/mpe/>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/> according to the following timetable:

Manuscript Due	December 1, 2008
First Round of Reviews	March 1, 2009
Publication Date	June 1, 2009

Guest Editors

José Roberto Castilho Piqueira, Telecommunication and Control Engineering Department, Polytechnic School, The University of São Paulo, 05508-970 São Paulo, Brazil; piqueira@lac.usp.br

Elbert E. Neher Macau, Laboratório Associado de Matemática Aplicada e Computação (LAC), Instituto Nacional de Pesquisas Espaciais (INPE), São José dos Campos, 12227-010 São Paulo, Brazil ; elbert@lac.inpe.br

Celso Grebogi, Center for Applied Dynamics Research, King's College, University of Aberdeen, Aberdeen AB24 3UE, UK; grebogi@abdn.ac.uk