### Axiomatic semantics

Semantics and Application to Program Veri cation

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### Introduction

### Operational semantics

Models precisely program execution as low-level transitions between internal states

(transition systems, execution traces, big-step semantics)

#### **Denotational semantics**

Maps programs into objects in a mathematical domain (higher level, compositional, domain oriented)

### Aximoatic semantics (today)

Prove properties about programs

- programs are annotated with logical assertions
- a rule-system defines the validity of assertions (logical proofs)
- clearly separates programs from specifications
   (specification ≃ user-provided abstraction of the behavior, it is not unique)
- enables the use of logic tools (partial automation, increased confidence)

## Overview

- Specifications (informal examples)
- Floyd-Hoare logic
- Dijkstra's predicate transformers (weakest precondition, strongest postcondition)
- Verification conditions
   (partially automated program verification)
- Advanced topics
  - Total correctness (termination)

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# **Specifications**

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```
example in C + ACSL
 int mod(int A, int B) {
   int Q = 0;
   int R = A;
   while (R >= B) {
    R = R - B;
     Q = Q + 1;
   return R;
```

```
example in C + ACSL
 //@ ensures \result == A mod B;
 int mod(int A, int B) {
   int Q = 0;
   int R = A;
   while (R >= B) {
    R = R - B;
     Q = Q + 1;
   return R;
```

express the intended behavior of the function

(returned value)

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```
example in C + ACSL
 //@ requires A>=0 && B>=0;
 //@ ensures \result == A mod B;
 int mod(int A, int B) {
   int Q = 0;
   int R = A;
   while (R >= B) {
     R = R - B:
     Q = Q + 1;
   return R;
```

- express the intended behavior of the function (returned value)
- add requirements for the function to actually behave as intended (a requires/ensures pair is a function contract)

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```

- express the intended behavior of the function (returned value)
- add requirements for the function to actually behave as intended (a requires/ensures pair is a function contract)
- strengthen the requirements to ensure termination

# Example: program annotations

```
example with full assertions
 //@ requires A>=0 && B>0;
 //@ ensures \result == A mod B;
 int mod(int A, int B) {
   int Q = 0:
   int R = A:
   //@ assert A>=0 && B>0 && Q=0 && R==A;
   while (R >= B) {
     //@ assert A>=0 && B>0 && R>=B && A==Q*B+R;
     R = R - B;
     0 = 0 + 1:
   //@ assert A>=0 && B>0 && R>=0 && R<B && A==Q*B+R:
   return R:
```

Assertions give detail about the internal computations why and how contracts are fulfilled

```
(Note: r = a \mod b means \exists q: a = qb + r \land 0 \le r \le b)
```

# Example: ghost variables

```
example with ghost variables
 //@ requires A>=0 && B>0;
 //@ ensures \result == A mod B;
 int mod(int A, int B) {
   int R = A;
   while (R >= B) {
     R = R - B;
   // \exists Q: A = QB + R and 0 \le R \le B
   return R;
```

The annotations can be more complex than the program itself

# Example: ghost variables

```
example with ghost variables
 //@ requires A>=0 && B>0;
 //@ ensures \result == A mod B;
 int mod(int A, int B) {
   //@ ghost int q = 0;
   int R = A;
   //@ assert A>=0 && B>0 && q=0 && R==A;
   while (R >= B) {
     //@ assert A>=0 && B>0 && R>=B && A==q*B+R;
     R = R - B:
     //0 ghost q = q + 1;
   //@ assert A>=0 && B>0 && R>=0 && R<B && A==q*B+R;
   return R;
```

The annotations can be more complex than the program itself and require reasoning on enriched states (ghost variables)

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# Example: class invariants

```
example in ESC/Java
 public class OrderedArray {
   int all:
   int nb:
   //@invariant nb >= 0 \&\& nb <= 20
   //@invariant (\forall int i; (i >= 0 && i < nb-1) ==> a[i] <= a[i+1])
   public OrderedArray() { a = new int[20]; nb = 0; }
   public void add(int v) {
     if (nb >= 20) return;
     int i; for (i=nb; i > 0 \&\& a[i-1] > v; i--) a[i] = a[i-1];
     a[i] = v; nb++;
```

#### class invariant: property of the fields true outside all methods

it can be temporarily broken within a method but it must be restored before exiting the method

## Language support

#### Contracts (and class invariants):

- built in few languages (Eiffel)
- available as a library / external tool (C, Java, C#, etc.)

#### Contracts can be:

- checked dynamically
- checked statically (Frama-C, Why, ESC/Java)
- inferred statically (CodeContracts)

#### In this course:

deductive methods (logic) to check (prove) statically (at compile-time) partially automatically (with user help) that contracts hold

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## Floyd-Hoare logic

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## Hoare triples

### **Hoare triple:** $\{P\}$ prog $\{Q\}$

- prog is a program fragment
- P and Q are logical assertions over program variables (e.g.  $P \stackrel{\text{def}}{=} (X \ge 0 \land Y \ge 0) \lor (X < 0 \land Y < 0)$ )

#### A triple means:

- if P holds before prog is executed
- then Q holds after the execution of proq
- unless prog does not terminate or encounters an error

*P* is the precondition, *Q* is the postcondition

(does not rule out errors and non-termination)

Hoare triples serve as judgements in a proof system (introduced in [Hoare69])

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## Language

```
Stat ::= X \leftarrow expr (assignment)

| skip (do nothing)

| fail (error)

| stat; stat (sequence)

| if expr then stat else stat (conditional)

| while expr do stat (loop)
```

- $X \in \mathbb{V}$ : integer-valued variables
- *expr*: integer arithmetic expressions we assume that:
  - expressions are deterministic (for now)
  - expression evaluation does not cause error

for instance, to avoid division by zero, we can: either define 1/0 to be a valid value, such as 0 or systematically guard divisions (e.g.: if X=0 then fail else  $\cdots/X\cdots$ )

## Hoare rules: axioms

#### **Axioms:**

$${P \over {P \over skip} {P \over {P}}}$$

$$\overline{\{P\} \text{ fail } \{Q\}}$$

- any property true before **skip** is true afterwards
- any property is true after fail

## Hoare rules: axioms

### Assignment axiom:

$$\overline{\{P[e/X]\}\ X \leftarrow e\ \{P\}}$$

for P over X to be true after  $X \leftarrow e$ P must be true over e before the assignment

P[e/X] is P where free occurrences of X are replaced with e e must be deterministic

the rule is "backwards" (P appears as a postcondition)

## Hoare rules: consequence

#### Rule of consequence:

$$\frac{P \Rightarrow P' \qquad Q' \Rightarrow Q \qquad \{P'\} \ c \ \{Q'\}}{\{P\} \ c \ \{Q\}}$$

we can weaken a Hoare triple by:

```
weakening its postcondition Q \Leftarrow Q'
strengthening its precondition P \Rightarrow P'
```

we assume a logic system to be available to prove formulas on assertions, such as  $P \Rightarrow P'$  (e.g., arithmetic, set theory, etc.)

#### examples:

- the axiom for **fail** can be replaced with  $\frac{1}{\{\text{true}\} \text{ fail } \{\text{false}\}}$  (as  $P \Rightarrow \text{true}$  and false  $\Rightarrow Q$  always hold)
- $\{X = 99 \land Y \in [1, 10]\}\ X \leftarrow Y + 10\ \{X = Y + 10 \land Y \in [1, 10]\}\$  (as  $\{Y \in [1, 10]\}\ X \leftarrow Y + 10\ \{X = Y + 10 \land Y \in [1, 10]\}\$  and  $X = 99 \land Y \in [1, 10] \Rightarrow Y \in [1, 10]$ )

## Hoare rules: tests

$$\frac{\{P \land e\} \ s \ \{Q\}}{\{P\} \ \text{if } e \ \text{then } s \ \text{else} \ t \ \{Q\}}$$

to prove that Q holds after the test we prove that it holds after each branch (s, t) under the assumption that it is executed  $(e, \neg e)$ 

#### example:

$$\frac{ \{X < 0\} \ X \leftarrow -X \ \{X > 0\}}{\{(X \neq 0) \land (X < 0)\} \ X \leftarrow -X \ \{X > 0\}} \frac{ \{X > 0\} \ \text{skip} \ \{X > 0\}}{\{(X \neq 0) \land (X \geq 0)\} \ \text{skip} \ \{X > 0\}} }{\{(X \neq 0) \land (X \geq 0)\} \ \text{skip} \ \{X > 0\}}$$

# Hoare rules: sequences

### **Sequences:**

$$\frac{\{P\} \ s \ \{R\} \ t \ \{Q\}}{\{P\} \ s; t \ \{Q\}}$$

```
to prove a sequence s; t
we must invent an intermediate assertion R
implied by P after s, and implying Q after t
(often denoted \{P\} s \{R\} t \{Q\})
```

#### example:

$$\{X = 1 \land Y = 1\} \ X \leftarrow X + 1 \ \{X = 2 \land Y = 1\} \ Y \leftarrow Y - 1 \ \{X = 2 \land Y = 0\}$$

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## Hoare rules: loops

$$\frac{\{P \land e\} \ s \ \{P\}}{\{P\} \ \text{while} \ e \ \text{do} \ s \ \{P \land \neg e\}}$$

#### P is a loop invariant

P holds before each loop iteration, before even testing e

#### Practical use:

we can derive the rule.

```
actually, we would rather prove the triple: \{P\} while e do s \{Q\} it is sufficient to invent an assertion I that:

holds when the loop start: P\Rightarrow I
is invariant by the body s: \{I \land e\} s \{I\}
implies the assertion when the loop stops: (I \land \neg e) \Rightarrow Q
\{I \land e\} \ s \ \{I\}
P \Rightarrow I \qquad I \land \neg e \Rightarrow Q \qquad \{I \land e\} \ s \ \{I\}
\{I\} \text{ while } e \text{ do } s \ \{I \land \neg e\}
```

 $\{P\}$  while e do s  $\{Q\}$ 

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# Hoare rules: logical part

Hoare logic is parameterized by the choice of logical theory of assertions the logical theory is used to:

- prove properties of the form  $P \Rightarrow Q$  (rule of consequence)
- simplify formulas
   (replace a formula with a simpler one, equivalent in a logical sens: ⇔)

#### Examples: (generally first order theories)

- booleans ( $\mathbb{B}, \neg, \wedge, \vee$ )
- bit-vectors  $(\mathbb{B}^n, \neg, \wedge, \vee)$
- Presburger arithmetic  $(\mathbb{N}, +)$
- Peano arithmetic  $(\mathbb{N},+,\times)$
- linear arithmetic on R
- Zermelo-Fraenkel set theory  $(\in, \{\})$
- theory of arrays (lookup, update)

theories have different expressiveness, decidability and complexity results this is an important factor when trying to automate program verification

# Hoare rules: summary

 $\frac{P \Rightarrow P' \qquad Q' \Rightarrow Q \qquad \{P'\} \ c \ \{Q'\}}{\{P\} \ c \ \{Q\}}$ 

# Proof tree example

$$s \stackrel{\text{def}}{=} \text{ while } I < N \text{ do } (X \leftarrow 2X; \ I \leftarrow I + 1)$$

$$\frac{C \quad \overline{\{P_3\} \ X \leftarrow 2X \ \{P_2\}} \quad \overline{\{P_2\} \ I \leftarrow I + 1 \ \{P_1\}}}{\{P_1 \land I < N\} \ X \leftarrow 2X; \ I \leftarrow I + 1 \ \{P_1\}}$$

$$\frac{A \quad B \quad \overline{\{P_1\} \ s \ \{P_1 \land I \ge N\}}}{\{X = 1 \land I = 0 \land N > 0\} \ s \ \{X = 2^N \land N = I \land N > 0\}}$$

$$P_{1} \stackrel{\text{def}}{=} X = 2^{I} \land I \leq N \land N \geq 0$$

$$P_{2} \stackrel{\text{def}}{=} X = 2^{I+1} \land I + 1 \leq N \land N \geq 0$$

$$P_{3} \stackrel{\text{def}}{=} 2X = 2^{I+1} \land I + 1 \leq N \land N \geq 0 \quad \equiv X = 2^{I} \land I < N \land N \geq 0$$

$$A: (X = 1 \land I = 0 \land N \geq 0) \Rightarrow P_{1}$$

$$B: (P_{1} \land I \geq N) \Rightarrow (X = 2^{N} \land N = I \land N \geq 0)$$

$$C: P_{3} \iff (P_{1} \land I < N)$$

# Proof tree example

$$s \stackrel{\mathsf{def}}{=} \mathsf{while} \ I \neq 0 \ \mathsf{do} \ I \leftarrow I - 1$$

- in some cases, the program does not terminate
   (if the program starts with I < 0)</li>
- the same proof holds for:  $\{\text{true}\}\$ while  $I \neq 0\$ do  $J \leftarrow J 1\ \{I = 0\}$
- anything can be proven of a program that never terminates:

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### Invariants and inductive invariants

#### Example: we wish to prove:

$${X = Y = 0}$$
 while  $X < 10$  do  $(X \leftarrow X + 1; Y \leftarrow Y + 1)$   ${X = Y = 10}$ 

we need to find an invariant assertion P for the while rule

## **Incorrect invariant:** $P \stackrel{\text{def}}{=} X, Y \in [0, 10]$

- P indeed holds at each loop iteration (P is an invariant)
- but {P ∧ (X < 10)} X ← X + 1; Y ← Y + 1 {P} does not hold

$$P \wedge X < 10$$
 does not prevent  $Y = 10$  after  $Y \leftarrow Y + 1$ ,  $P$  does not hold anymore

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### Invariants and inductive invariants

#### Example: we wish to prove:

$${X = Y = 0}$$
 while  $X < 10$  do  $(X \leftarrow X + 1; Y \leftarrow Y + 1)$   ${X = Y = 10}$ 

we need to find an invariant assertion P for the while rule

## **Correct invariant:** $P' \stackrel{\text{def}}{=} X \in [0, 10] \land X = Y$

- P' also holds at each loop iteration (P' is an invariant)
- $\{P' \land (X < 10)\}\ X \leftarrow X + 1;\ Y \leftarrow Y + 1\ \{P'\}\$ can be proven
- P' is an inductive invariant (passes to the induction, stable by a loop iteration)



to prove a loop invariant

it is often necessary to find a stronger inductive loop invariant

# Soundness and completeness

### Validity:

$$\begin{array}{c} \{P\} \ c \ \{Q\} \ \text{is valid} & \stackrel{\mathsf{def}}{\Longleftrightarrow} \\ & \text{executions starting in a state satisfying } P \\ & \text{and terminating} \\ & \text{end in a state satisfying } Q \end{array}$$

(it is an operational notion)

- soundness a proof tree exists for  $\{P\}$  c  $\{Q\}$   $\Longrightarrow$   $\{P\}$  c  $\{Q\}$  is valid
  - completeness

$$\{P\}\ c\ \{Q\}\$$
is valid  $\implies$  a proof tree exists for  $\{P\}\ c\ \{Q\}\$ 

(technically, by Gödel's incompleteness theorem,  $P\Rightarrow Q$  is not always provable for strong theories; hence, Hoare logic is incomplete; we consider relative completeness by adding all valid properties  $P\Rightarrow Q$  on assertions as axioms)

### Theorem (Cook 1974)

Hoare logic is sound (and relatively complete)

Completeness no longer holds for more complex languages (Clarke 1976)

## Link with denotational semantics

```
S[stat]: \mathcal{P}(\mathcal{E}) \to \mathcal{P}(\mathcal{E}) \text{ where } \mathcal{E} \stackrel{\mathsf{def}}{=} V \mapsto \mathbb{I}
Reminder:
S[skip]R \stackrel{\text{def}}{=} R
S[fail]R \stackrel{\mathsf{def}}{=} \emptyset
S[s_1; s_2] \stackrel{\text{def}}{=} S[s_2] \circ S[s_1]
S[X \leftarrow e]R \stackrel{\text{def}}{=} {\rho[X \mapsto v] | \rho \in R, v \in E[e] \rho}
S[ if e then s_1 else s_2 | R \stackrel{\text{def}}{=} S[ s_1 ] \{ \rho \in R \mid \text{true} \in E[ e ] \rho \} \cup
                                                                S[s_2] \{ \rho \in R \mid \text{false} \in E[e] \mid \rho \}
S | while e do s | R \stackrel{\text{def}}{=} \{ \rho \in \text{Ifp } F \mid \text{false} \in E | e | \rho \}
          where F(X) \stackrel{\text{def}}{=} R \cup S[s] \{ \rho \in X \mid \text{true} \in E[e] \mid \rho \}
```

#### Theorem

$$\{P\} \ c \ \{Q\} \iff \forall R \subseteq \mathcal{E}: R \models P \implies S \llbracket c \rrbracket R \models Q$$

 $(A \models P \text{ means } \forall \rho \in A, \text{ the formula } P \text{ is true on the variable assignment } \rho)$ 

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### Link with denotational semantics

- Hoare logic reasons on formulas
- denotational semantics reasons on state sets

we can assimilate assertion formulas and state sets (logical abuse: we assimilate formulas and models)

let [R] be any formula representing the set R, then:

- $\{[R]\}\ c\ \{[S[c]R]\}\$ is always valid
- $\{[R]\}\ c\ \{[R']\} \Rightarrow S[c]R \subseteq R'$ 
  - $\implies$  [S|| c || R| provides the best valid postcondition

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### Link with denotational semantics

### **Loop invariants**

#### Hoare:

to prove  $\{P\}$  while e do s  $\{P \land \neg e\}$  we must prove  $\{P \land e\}$  s  $\{P\}$  i.e., P is an inductive invariant

#### Denotational semantics:

we must find Ifp F where  $F(X) \stackrel{\text{def}}{=} R \cup S[s] \{ \rho \in X \mid \rho \models e \}$ 

• Ifp 
$$F = \cap \{ X | F(X) \subseteq X \}$$

(Tarski's theorem)

• 
$$F(X) \subseteq X \iff ([R] \Rightarrow [X]) \land \{[X \land e]\} \ S \{[X]\}$$
  
 $R \subseteq X \text{ means } [R] \Rightarrow [X],$   
 $S[s] \{ \rho \in X \mid \rho \models e \} \subseteq X \text{ means } \{[X \land e]\} \ S \{[X]\}$ 

#### As a consequence:

- any X such that  $F(X) \subseteq X$  gives an inductive invariant [X]
- Ifp F gives the best inductive invariant
- any X such that Ifp F ⊆ X gives an invariant (not necessarily inductive)

(see [Cousot02])

## **Predicate transformers**

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# Dijkstra's weakest liberal preconditions

### Principle:

- calculus to derive preconditions from postconditions
- order and mechanize the search for intermediate assertions

(easier to go backwards, mainly due to assignments)

```
Weakest liberal precondition \textit{wlp}: (\textit{prog} \times \textit{Prop}) \rightarrow \textit{Prop}
```

wlp(c, P) is the weakest, i.e. most general, precondition ensuring that  $\{wlp(c, P)\}\ c\ \{P\}$  is a Hoare triple

(greatest state set that ensures that the computation ends up in P)

formally: 
$$\{P\} \ c \ \{Q\} \iff (P \Rightarrow wlp(c, Q))$$

"liberal" means that we do not care about termination and errors

#### Examples:

$$wlp(X \leftarrow X + 1, X = 1) =$$
  
 $wlp(\text{while } X < 0 \ X \leftarrow X + 1, X \ge 0) =$   
 $wlp(\text{while } X \ne 0 \ X \leftarrow X + 1, X \ge 0) =$ 

(introduced in [Dijkstra75])

# Dijkstra's weakest liberal preconditions

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"liberal" means that we do not care about termination and errors

#### Examples:

$$wlp(X \leftarrow X+1, X=1) = (X=0)$$
  
 $wlp(\text{while } X < 0 \ X \leftarrow X+1, \ X \ge 0) = \text{true}$   
 $wlp(\text{while } X \ne 0 \ X \leftarrow X+1, \ X \ge 0) = \text{true}$ 

(introduced in [Dijkstra75])

# A calculus for wlp

 $\mathit{wlp}$  is defined by induction on the syntax of programs:

```
wlp(\mathbf{skip}, P) \stackrel{\text{def}}{=} P
wlp(\mathbf{fail}, P) \stackrel{\text{def}}{=} \text{ true}
wlp(X \leftarrow e, P) \stackrel{\text{def}}{=} P[e/X]
wlp(s; t, P) \stackrel{\text{def}}{=} wlp(s, wlp(t, P))
wlp(\mathbf{if} e \mathbf{then} s \mathbf{else} t, P) \stackrel{\text{def}}{=} (e \Rightarrow wlp(s, P)) \land (\neg e \Rightarrow wlp(t, P))
wlp(\mathbf{while} e \mathbf{do} s, P) \stackrel{\text{def}}{=} I \land ((e \land I) \Rightarrow wlp(s, I)) \land ((\neg e \land I) \Rightarrow P)
```

- $e \Rightarrow Q$  is equivalent to  $Q \lor \neg e$ weakest property that matches Q when e holds but says nothing when e does not hold
- while loops require providing an invariant predicate /
  intuitively, wlp checks that I is an inductive invariant implying P
  if so, it returns I; otherwise, it returns false
  wlp is the weakest precondition only if I is well-chosen...

# Alternate form for loops

### **Unrolling** of the loop **while** *e* **do** *s*:

- $L_0 \stackrel{\text{def}}{=} \text{fail}$
- $L_{i+1} \stackrel{\text{def}}{=} \text{ if } e \text{ then } (s; L_i) \text{ else skip}$
- L<sub>i</sub> runs the loop and fails after i iterations

we have: 
$$\begin{cases} \textit{wlp}(L_0,P) = \mathsf{true} \\ \textit{wlp}(L_{i+1},P) = (e \Rightarrow \textit{wlp}(s,\textit{wlp}(L_i,P))) \land (\neg e \Rightarrow P) \end{cases}$$

### **Alternate** *wlp* **for loops**: $wlp(\textbf{while } e \textbf{ do } s, P) \stackrel{\text{def}}{=} \forall i: X_i$

where 
$$X_0 \stackrel{\text{def}}{=} \text{true}$$

$$X_{i+1} \stackrel{\mathsf{def}}{=} (e \Rightarrow \mathsf{wlp}(s, X_i)) \land (\neg e \Rightarrow P)$$

 $X_i \Leftarrow X_{i+1}$ : sequence of assertions of increasing strength  $(\forall i : X_i)$  is the limit, with an arbitrary number of iterations

 $(\forall i: X_i)$  is a closed form guaranteed to be the weakest precondition (no need for a user-specified invariant)

 $(\forall i: X_i)$  is the fixpoint of a second-order formula  $\implies$  very difficult to handle

# WIp computation example

*wlp*(if *X* < 0 then *Y* ← −*X* else *Y* ← *X*, *Y* ≥ 10) =   
(*X* < 0 ⇒ *wlp*(*Y* ← −*X*, *Y* ≥ 10)) 
$$\land$$
 (*X* ≥ 0 ⇒ *wlp*(*Y* ← *X*, *Y* ≥ 10))  
(*X* < 0 ⇒ −*X* ≥ 10)  $\land$  (*X* ≥ 0 ⇒ *X* ≥ 10) =  
(*X* ≥ 0  $\lor$  −*X* ≥ 10)  $\land$  (*X* < 0  $\lor$  *X* ≥ 10) =  
*X* ≥ 10  $\lor$  *X* ≤ −10

wlp generates complex formulas it is important to simplify them from time to time

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## Properties of wlp

•  $wlp(c, false) \equiv false$ 

- (excluded miracle)
- $\textit{wlp}(c, P) \land \textit{wlp}(d, Q) \equiv \textit{wlp}(c, P \land Q)$  (distributivity)
- $\textit{wlp}(c, P) \lor \textit{wlp}(d, Q) \equiv \textit{wlp}(c, P \lor Q)$  (distributivity) ( $\Rightarrow$  always true,  $\Leftarrow$  only true for deterministic, error-free programs)
- if  $P \Rightarrow Q$ , then  $\textit{wlp}(c, P) \Rightarrow \textit{wlp}(c, Q)$  (monotonicity)

 $A \equiv B$  means that the formulas A and B are equivalent i.e.,  $\forall \rho \colon \rho \models A \iff \rho \models B$  (stronger that syntactic equality)

# Strongest liberal postconditions

we can define  $slp:(Prop \times prog) \rightarrow Prop$ 

- $\{P\}$  C  $\{Slp(P,C)\}$  (postcondition)
- $\{P\}$  C  $\{Q\}$   $\iff$   $(slp(P,C) \Rightarrow Q)$  (strongest postcondition) (corresponds to the smallest state set)
- SIp(P, c) does not care about non-termination (liberal)
- allows forward reasoning

we have a duality:

$$(P \Rightarrow wlp(c, Q)) \iff (slp(P, c) \Rightarrow Q)$$

proof: 
$$(P \Rightarrow wlp(c, Q)) \iff \{P\} \ c \ \{Q\} \iff (slp(P, c) \Rightarrow Q)$$

# Calculus for slp

```
slp(P, \mathbf{skip}) \stackrel{\text{def}}{=} P
slp(P, \mathbf{fail}) \stackrel{\text{def}}{=} \text{false}
slp(P, X \leftarrow e) \stackrel{\text{def}}{=} \exists v : P[v/X] \land X = e[v/X]
slp(P, s; t) \stackrel{\text{def}}{=} slp(slp(P, s), t)
slp(P, \mathbf{if} e \mathbf{then} s \mathbf{else} t) \stackrel{\text{def}}{=} slp(P \land e, s) \lor slp(P \land \neg e, t)
slp(P, \mathbf{while} e \mathbf{do} s) \stackrel{\text{def}}{=} (P \Rightarrow I) \land (slp(I \land e, s) \Rightarrow I) \land (\neg e \land I)
```

(the rule for  $X \leftarrow e$  makes slp much less attractive than wlp)

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### **Verification conditions**

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## Verification condition approch to program verification

#### How can we automate program verification using logic?

- Hoare logic: deductive system can only automate the checking of proofs
- predicate transformers: Wlp, Slp calculus construct (big) formulas mechanically invention is still needed for loops
- verification condition generation
   take as input a program with annotations
   (at least contracts and loop invariants)
   generate mechanically logic formulas ensuring the correctness
   (reduction to a mathematical problem, no longer any reference to a program)
   use an automatic SAT/SMT solver to prove (discharge) the formulas
   or an interactive theorem prover

(the idea of logic-based automated verification appears as early as [King69])

### Language

```
stat ::= X ← expr

| skip

| stat; stat

| if expr then stat else stat

| while {Prop} expr do stat

| assert expr

prog ::= {Prop} stat {Prop}
```

- loops are annotated with loop invariants
- optional assertions at any point
- programs are annotated with a contract (precondition and postcondition)

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## Verification condition generation algorithm

### by induction on the syntax of statements

```
\mathsf{vcg}_p : \mathsf{prog} \to \mathcal{P}(\mathsf{Prop})
vcg_n(P) c(Q) \stackrel{\text{def}}{=}
         let (R, C) = vcg_s(c, Q) in C \cup \{P \Rightarrow R\}
\mathsf{vcg}_s : (\mathsf{stat} \times \mathsf{Prop}) \to (\mathsf{Prop} \times \mathcal{P}(\mathsf{Prop}))
vcg_s(skip, Q) \stackrel{\text{def}}{=} (Q, \emptyset)
\operatorname{vcg}_{\mathfrak{s}}(X \leftarrow e, Q) \stackrel{\mathsf{def}}{=} (Q[e/X], \emptyset)
vcg_s(s; t, Q) \stackrel{\text{def}}{=}
         let (R,C) = vcg_s(t, Q) in let (P,D) = vcg_s(s, R) in (P,C \cup D)
vcg_c(if \ e \ then \ s \ else \ t, \ Q) \stackrel{def}{=}
         let (S, C) = \text{vcg}_s(s, Q) in let (T, D) = \text{vcg}_s(t, Q) in ((e \Rightarrow S) \land (\neg e \Rightarrow T), C \cup D)
vcg_s(while \{I\} e do s, Q) \stackrel{def}{=}
         let (R, C) = \text{vcg}_s(s, I) in (I, C \cup \{(I \land e) \Rightarrow R, (I \land \neg e) \Rightarrow Q\})
vcg_e(assert\ e,\ Q) \stackrel{\mathsf{def}}{=} (e \Rightarrow Q, \emptyset)
```

- we use wlp to infer assertions automatically when possible
- vcg<sub>s</sub>(c, P) = (P', C) propagates postconditions backwards (P into P') and accumulates into C verification conditions (from loops)
- we could do the same using *slp* instead of *wlp* (symbolic execution)

## Verification condition generation example

#### Consider the program:

we get three verification conditions:

$$C_1 \stackrel{\text{def}}{=} (X = 2^I \land 0 \le I \le N) \land I \ge N \Rightarrow X = 2^N$$

$$C_2 \stackrel{\text{def}}{=} (X = 2^I \land 0 \le I \le N) \land I < N \Rightarrow 2X = 2^{I+1} \land 0 \le I + 1 \le N$$

$$(\text{from } (X = 2^I \land 0 \le I \le N)[I + 1/I, 2X/X])$$

$$C_3 \stackrel{\text{def}}{=} N \ge 0 \Rightarrow 1 = 2^0 \land 0 \le 0 \le N$$

$$(\text{from } (X = 2^I \land 0 \le I \le N)[0/I, 1/X])$$

which can be checked independently

# What about real languages?

In a real language such as C, the rules are not so simple

 $\underline{\mathsf{Example:}} \quad \mathsf{the \ assignment \ rule} \ \overline{\{P[e/X]\} \ X \leftarrow e \ \{P\}} \ \mathsf{requires \ that}$ 

- e has no effect
- there is no pointer aliasing
  e has no run-time error
- moreover, the operators in the program and in the logic may not match:
  - integers: logic models  $\mathbb{Z}$ , computers use  $\mathbb{Z}/2^n\mathbb{Z}$  (wrap-around)

(memory write, function calls)

- continuous: logic models  $\mathbb Q$  or  $\mathbb R$ , programs use floating-point numbers (rounding error)
- a logic for pointers and dynamic allocation is also required (separation logic)

(see for instance the tool Why, to see how some problems can be circumvented)

### **Conclusion**

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#### Conclusion

- logic allows us to reason about program correctness
- verification can be reduced to proofs of simple logic statements

#### **Issue: automation**

- annotations are required (loop invariants, contracts)
- verification conditions must be proven

to scale up to realistic programs, we need to automate as much as possible

#### Some solutions:

- automatic logic solvers to discharge proof obligations
   SAT / SMT solvers
- abstract interpretation to approximate the semantics
  - fully automatic
  - able to infer invariants

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### **Extensions**

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#### Total correctness

### **Hoare triple:** [P] prog [Q]

- if P holds before prog is executed
- then prog always terminates
- and Q holds after the execution of prog

Rules: we only need to change the rule for while

$$\frac{\forall t \in W : [P \land e \land u = t] \ s \ [P \land u \prec t]}{[P] \ \text{while } e \ \text{do} \ s \ [P \land \neg e]} \ ((W, \prec) \ \text{is well-founded})$$

- $(W, \prec)$  well-founded  $\stackrel{\mathsf{def}}{\Longleftrightarrow}$  every  $V \subseteq W, \ V \neq \emptyset$  has a minimal element for  $\prec$  ensures that we cannot decrease infinitely by  $\prec$  in W generally, we simply use  $(\mathbb{N}, <)$  (also useful: lexicographic orders, ordinals)
- in addition to the loop invariant P
   we invent an expression u that strictly decreases by S
   u is called a "ranking function"
   often ¬e ⇒ u = 0: u counts the number of steps until termination

#### Total correctness

To simplify, we can decompose a proof of total correctness into:

- a proof of partial correctness {P} c {Q} ignoring termination
- a proof of termination [P] C [true] ignoring the specification
   (we must still include the precondition P as the program may not terminate for all inputs)

indeed, we have:

$$\frac{\{P\}\ c\ \{Q\}\qquad [P]\ c\ [\mathsf{true}]}{[P]\ c\ [Q]}$$

## Total correctness example

We use a simpler rule for integer ranking functions  $((W, \prec) \stackrel{\mathsf{def}}{=} (\mathbb{N}, \leq))$  using an integer expression r over program variables:

$$\frac{\forall n: [P \land e \land (r = n)] \ s \ [P \land (r < n)] \qquad (P \land e) \Rightarrow (r \ge 0)}{[P] \ \text{while } e \ \text{do} \ s \ [P \land \neg e]}$$

Example: 
$$p \stackrel{\text{def}}{=} \text{ while } I < N \text{ do } I \leftarrow I+1; \ X \leftarrow 2X \text{ done}$$

we use  $r \stackrel{\text{def}}{=} N-I$  and  $P \stackrel{\text{def}}{=} \text{ true}$ 

$$\forall n: [I < N \land N-I = n] \ I \leftarrow I+1; \ X \leftarrow 2X \ [N-I = n-1]$$

$$\frac{I < N \Rightarrow N-I \ge 0}{[\text{true}] \ p \ [I > N]}$$

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### Weakest precondition

#### Weakest precondition wp(prog, Prop) : Prop

- similar to wp, but also additionally imposes termination
- $[P] c [Q] \iff (P \Rightarrow wp(c, Q))$

As before, only the definition for **while** needs to be modified:

the invariant predicate I is combined with a variant expression V V is positive (this is an invariant:  $I \Rightarrow v \geq 0$ ) V decreases at each loop iteration

(and similarly for strongest postconditions)