

Counting minimum (s,t) -cuts
in weighted planar graphs
in polynomial time

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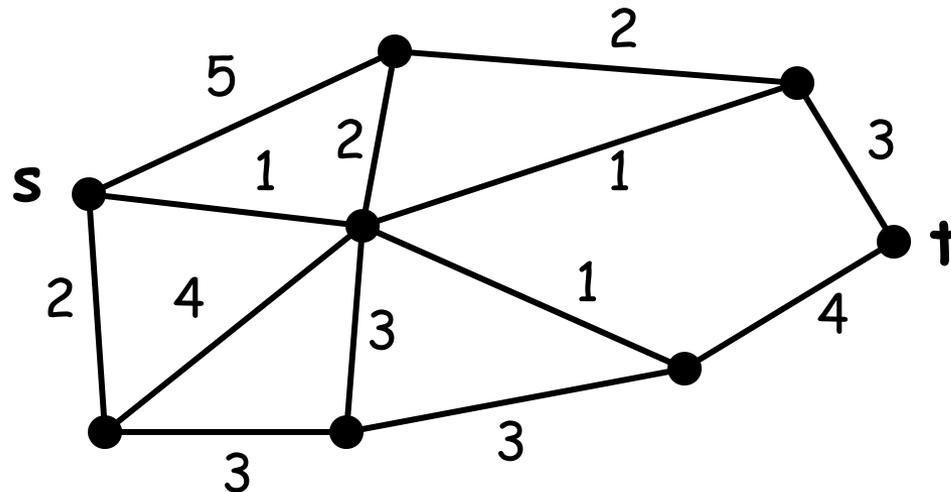
(before: B.S./M.S. RIT, now: IBM, Poughkeepsie, NY)

The problem: Counting minimum (s,t) -cuts

Input: a positively weighted (directed) planar graph $G=(V,E)$ and two vertices s,t

Output: the number of minimum (s,t) -cuts of G

Example:



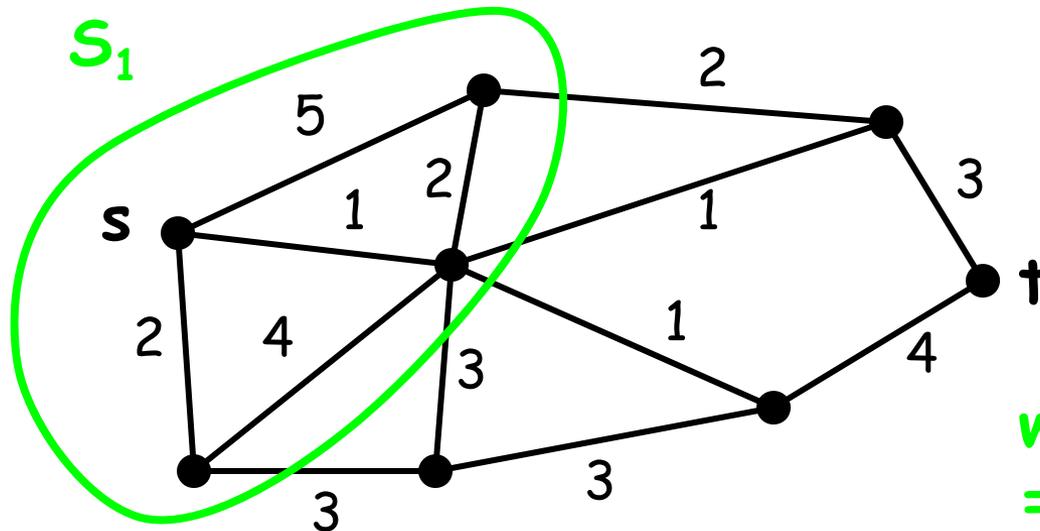
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Example:



$$\begin{aligned} \text{weight}(S_1) &= 2+1+1+3+3 \\ &= 10 \end{aligned}$$

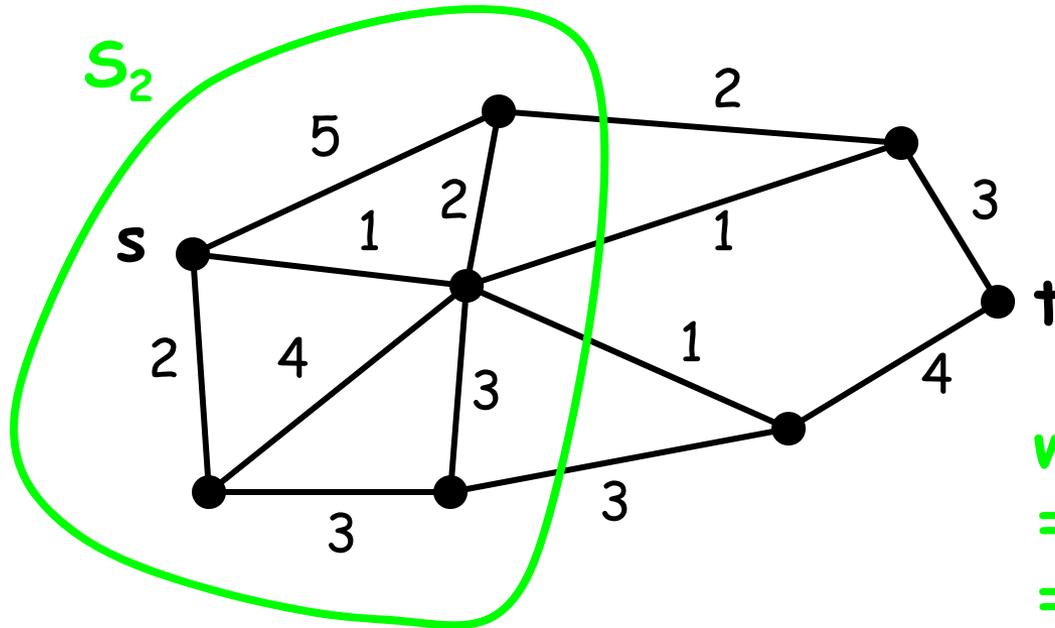
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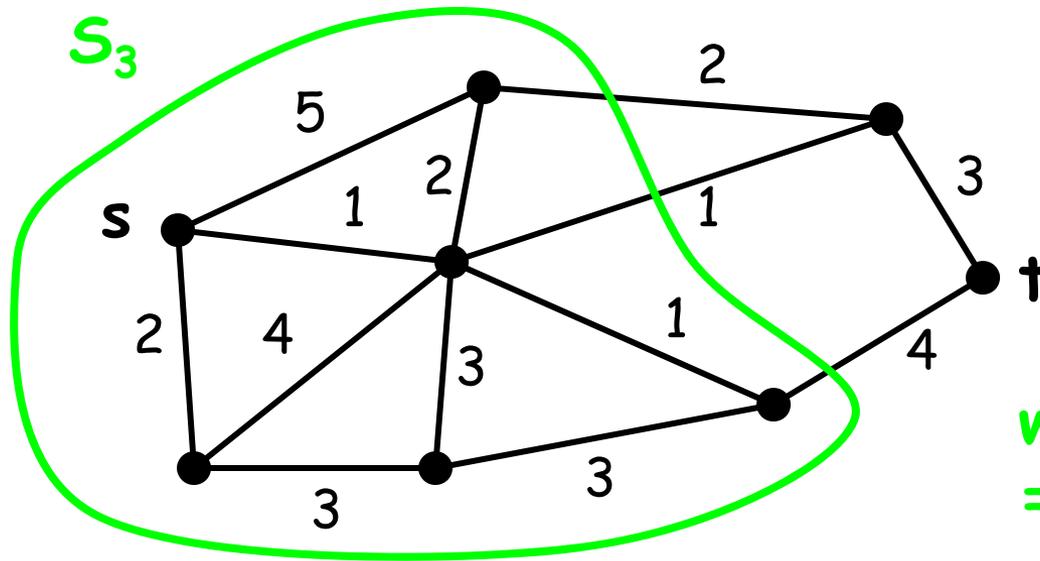
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Example:



$$\begin{aligned} \text{weight}(S_3) &= 2+1+4 \\ &= 7 \end{aligned}$$

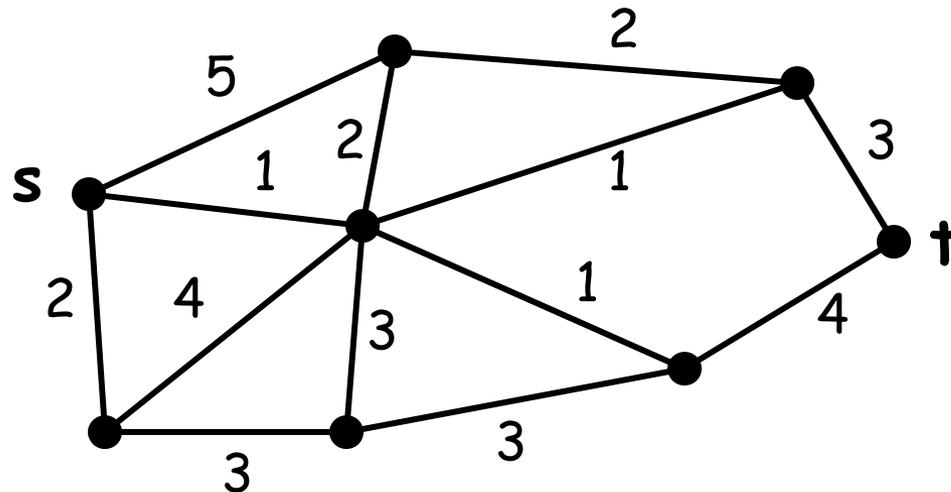
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Example:



Min (s,t) -cut weight: 7

Number of min (s,t) -cuts: 5

Motivation & related work

Initial motivation: **network reliability problems**

- number of min (s,t) -cuts useful in estimating the probability of disconnecting the network, e.g., [Colbourn '05]
- most related: Ball and Provan '82-'84
- [Ball and Provan '83]: efficient poly-time counting in (unweighted) planar (multi-) graphs when s,t on the same face
- [Nagamochi, Sun, Ibaraki '91]: unweighted multi-graphs, running time dependent on the number of cuts - not poly-time (improving Ball & Provan's run.time for non-planar graphs)

Other, recent, motivation: **computer vision**

- influential works, e.g.: [Boykov, Veksler & Zabih '01], [Boykov & Kolmogorov '04], [Geman & Geman '84]

Motivation & related work

Other, recent, motivation: **computer vision**

- the simplest case: image segmentation where image represented by a planar graph
- user selects two points, the graph cut represents the segmentation
- currently in use only min-cut algorithms (optimization version), using an arbitrary min-cut
- many advantages of counting (and the related sampling) versions, e.g.:
 - user can choose from several cuts
 - can be used to compute the partition function that can be used to estimate model parameters

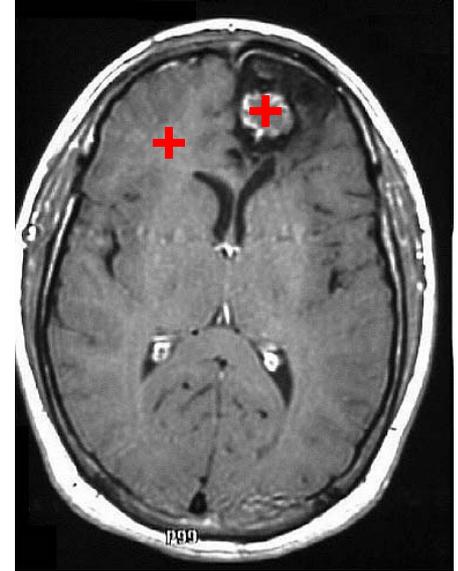


<http://path.upmc.edu/cases/case123.html>

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Our contributions

Thm: An $O(nd + n \log n)$ algorithm computing the number of minimum (s,t) -cuts in weighted planar graphs, where:

- $n = \#$ vertices
- $d =$ length of the shortest s - t path
- for directed graphs, assume all vertices are reachable from s and lead to t .

Comparison with earlier works:

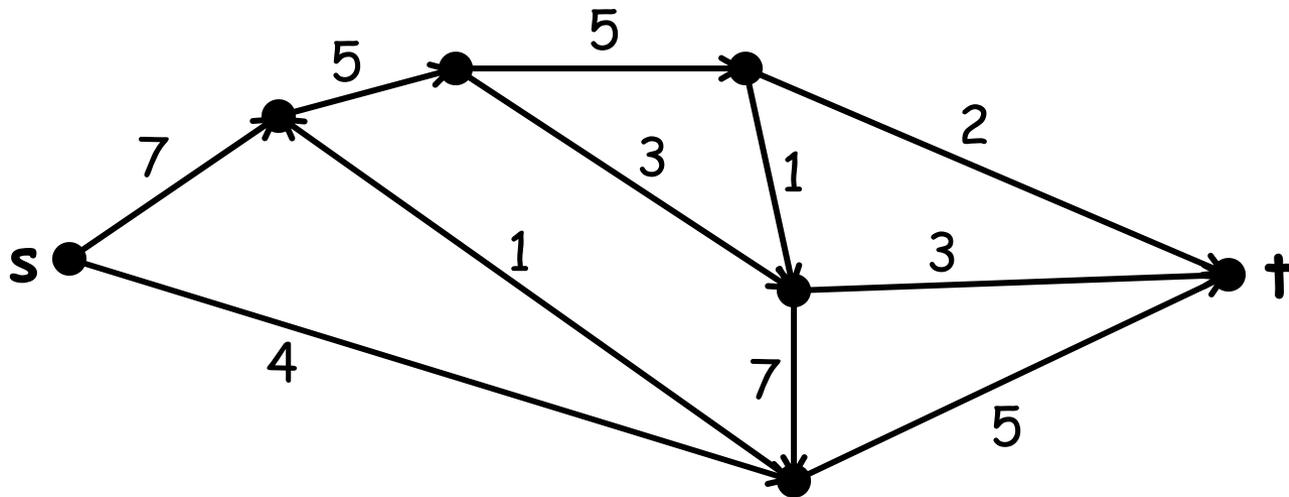
here no assumptions on the relative position of s and t
(and weighted)

-> important for computer vision applications

Review of network flows

Flow network:

- a directed graph with positive capacities on the edges, and
- two vertices s (the source) and t (the sink)



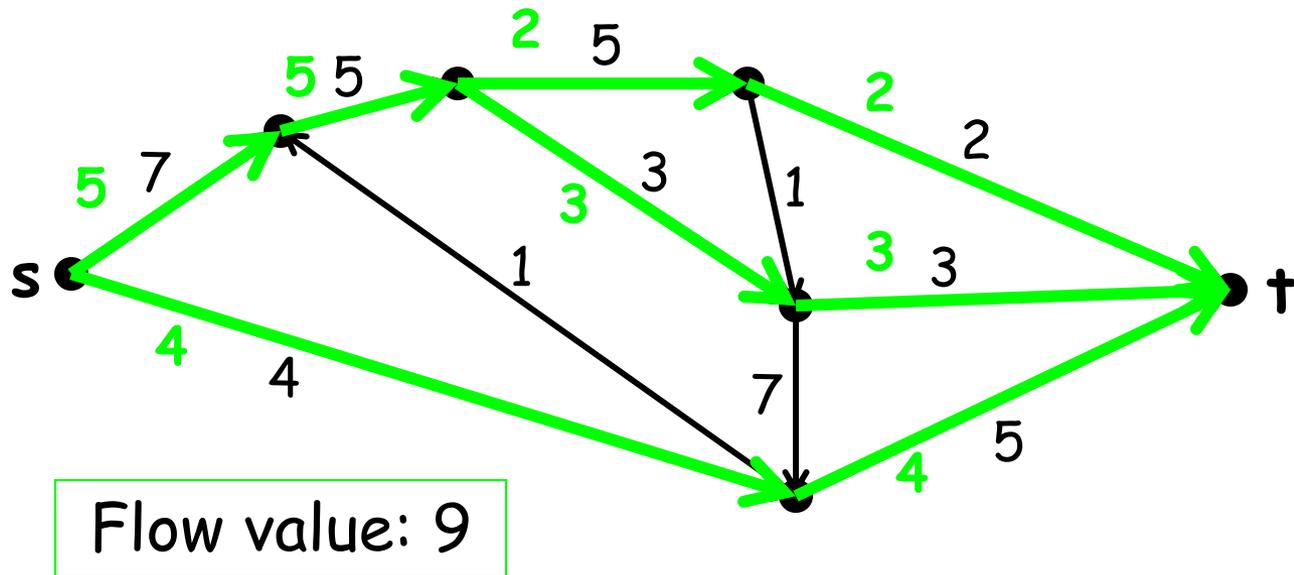
Review of network flows

Flow f : flow amount on every edge satisfying:

- for every edge e : flow amount $f(e) \leq$ capacity $c(e)$, and
- for every vertex v (except s, t):

flow amount into v = flow amount out of v

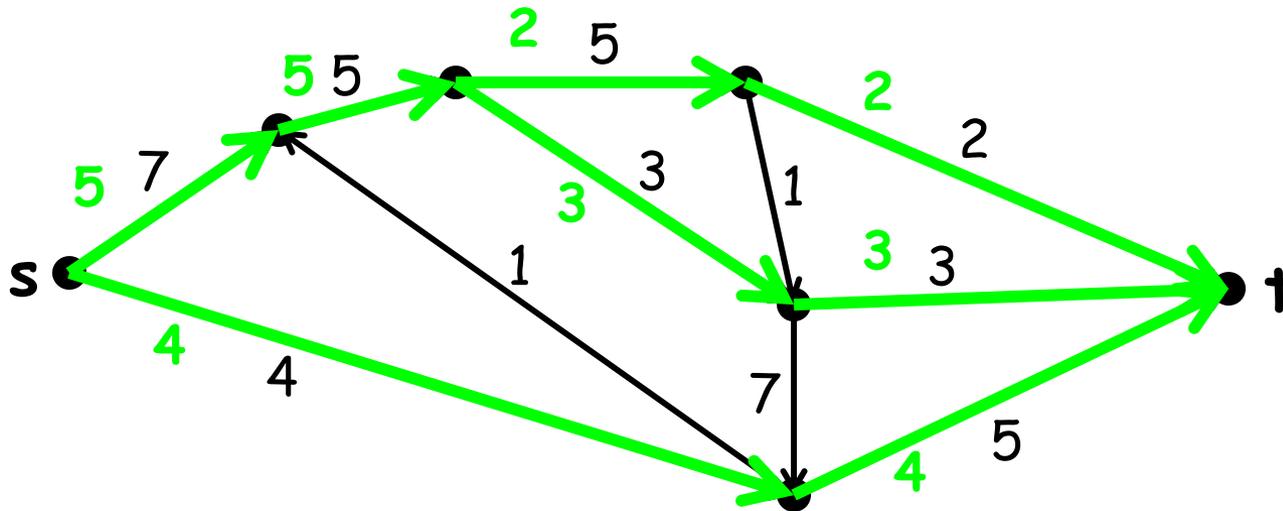
- flow value: amount out of s minus amount into s



Review of network flows

Residual graph of a flow f :

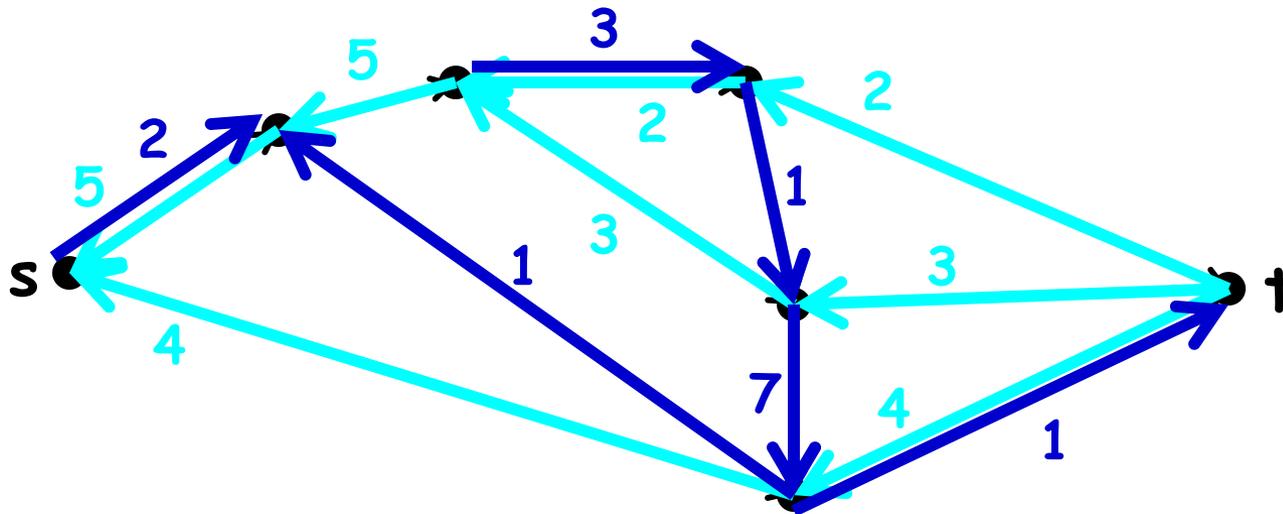
- **forward edges**: weight = capacity - flow
- **backward edges**: weight = flow



Review of network flows

Residual graph of a flow f :

- **forward edges**: weight = capacity - flow
 - **backward edges**: weight = flow
- (only edges with positive weight)

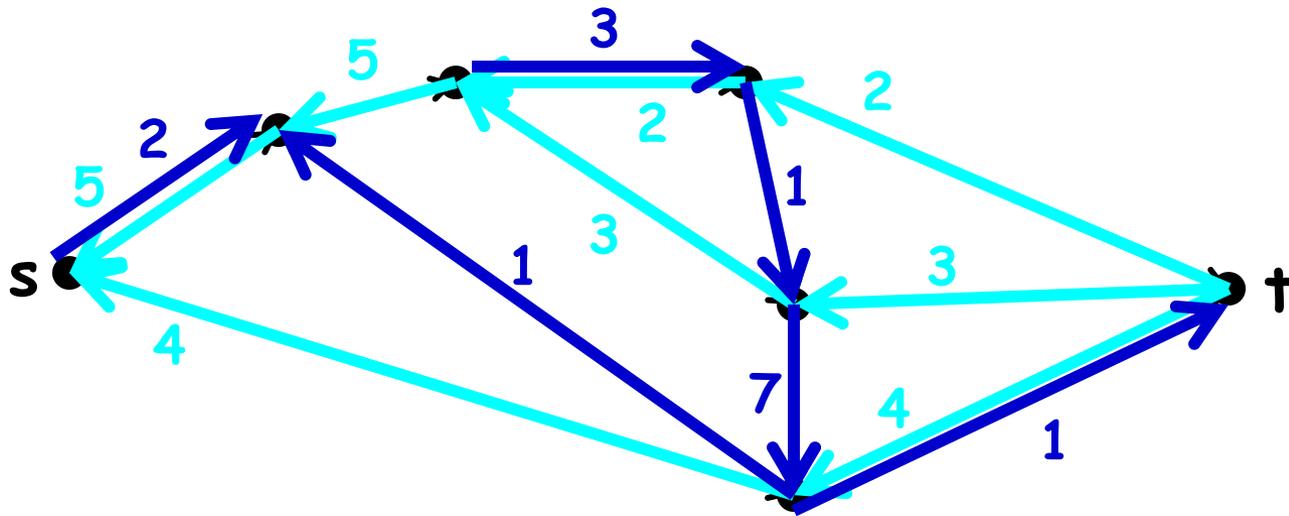


Review of network flows

Ford-Fulkerson Thm:

value of max s - t flow = value of min s - t cut

Note: flow is max iff no s - t path in the residual graph

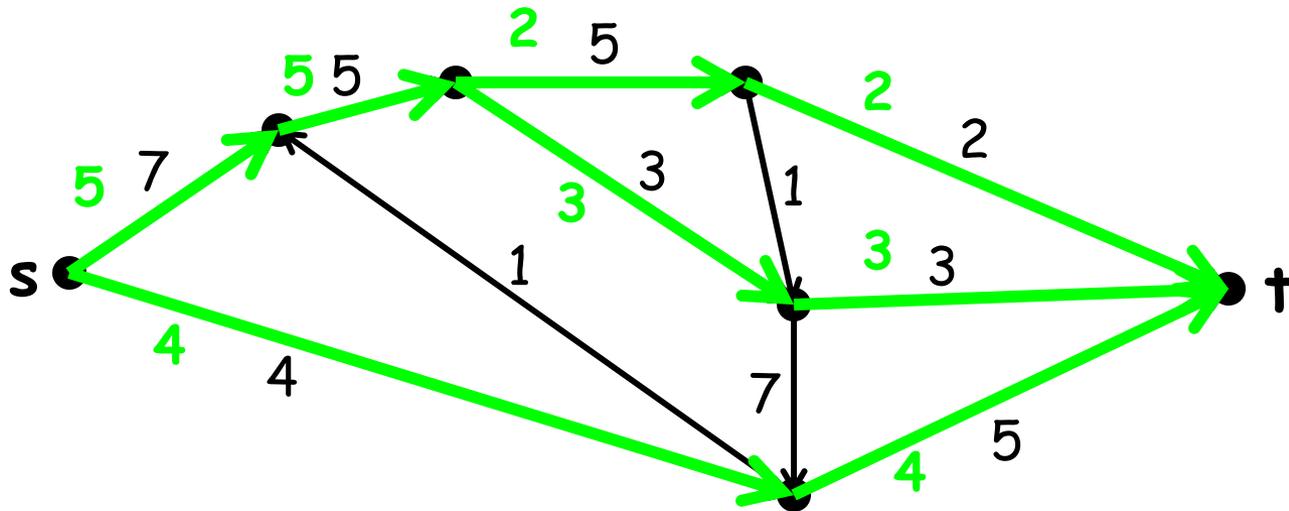


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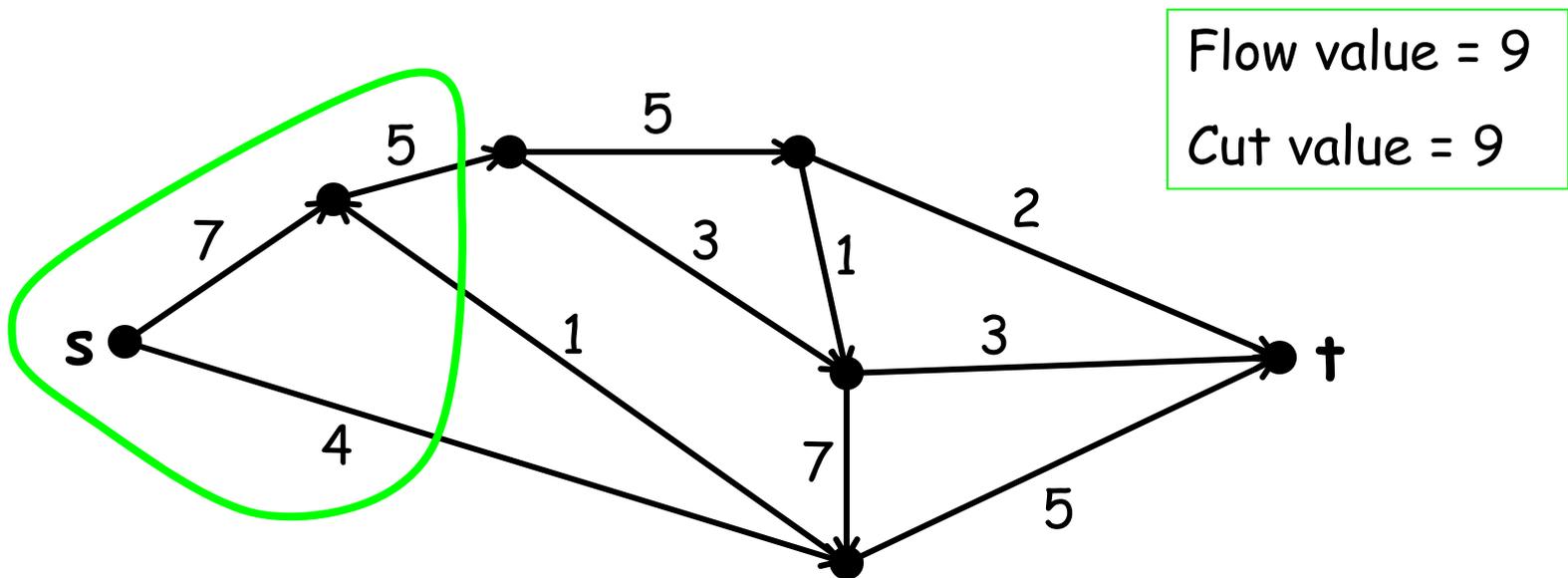


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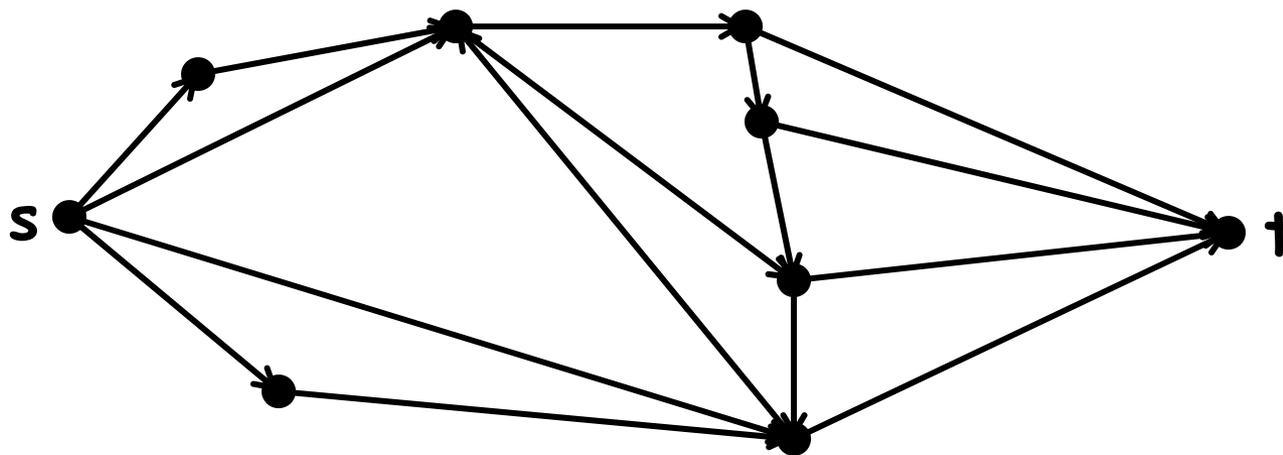


Ball & Provan's counting approach

Given an unweighted (multi-)graph:

1. Find a max flow and construct the residual graph
2. Contract strongly connected components
3. Compute # "forward-cuts" in the DAG

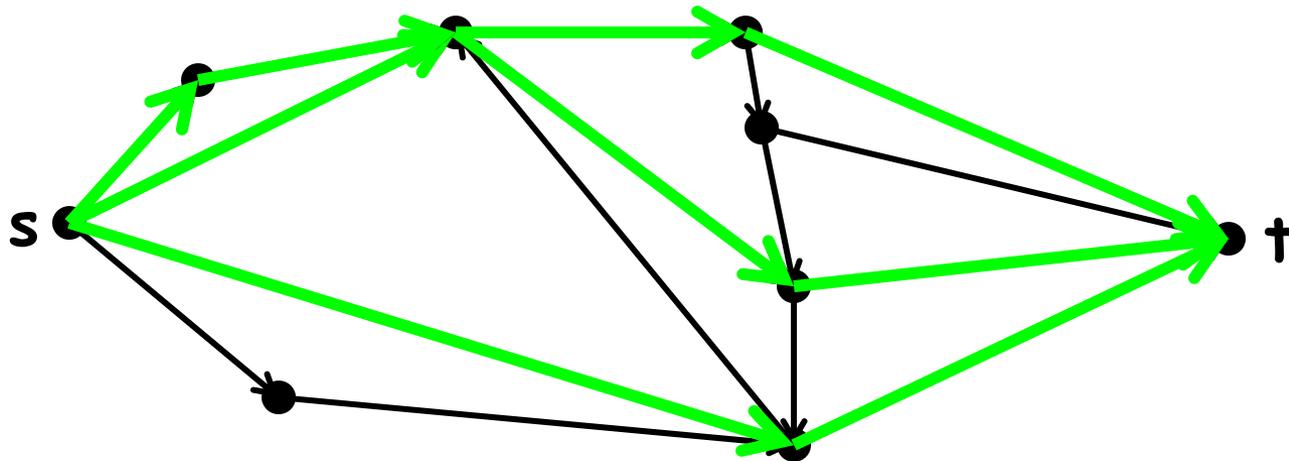
(forward-cuts = maximal antichains in the poset)



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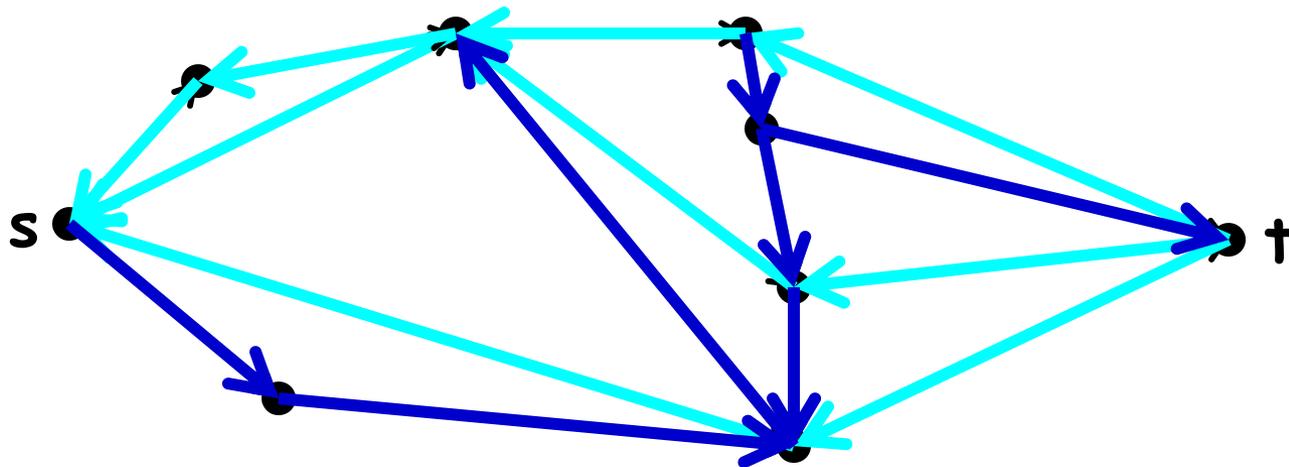
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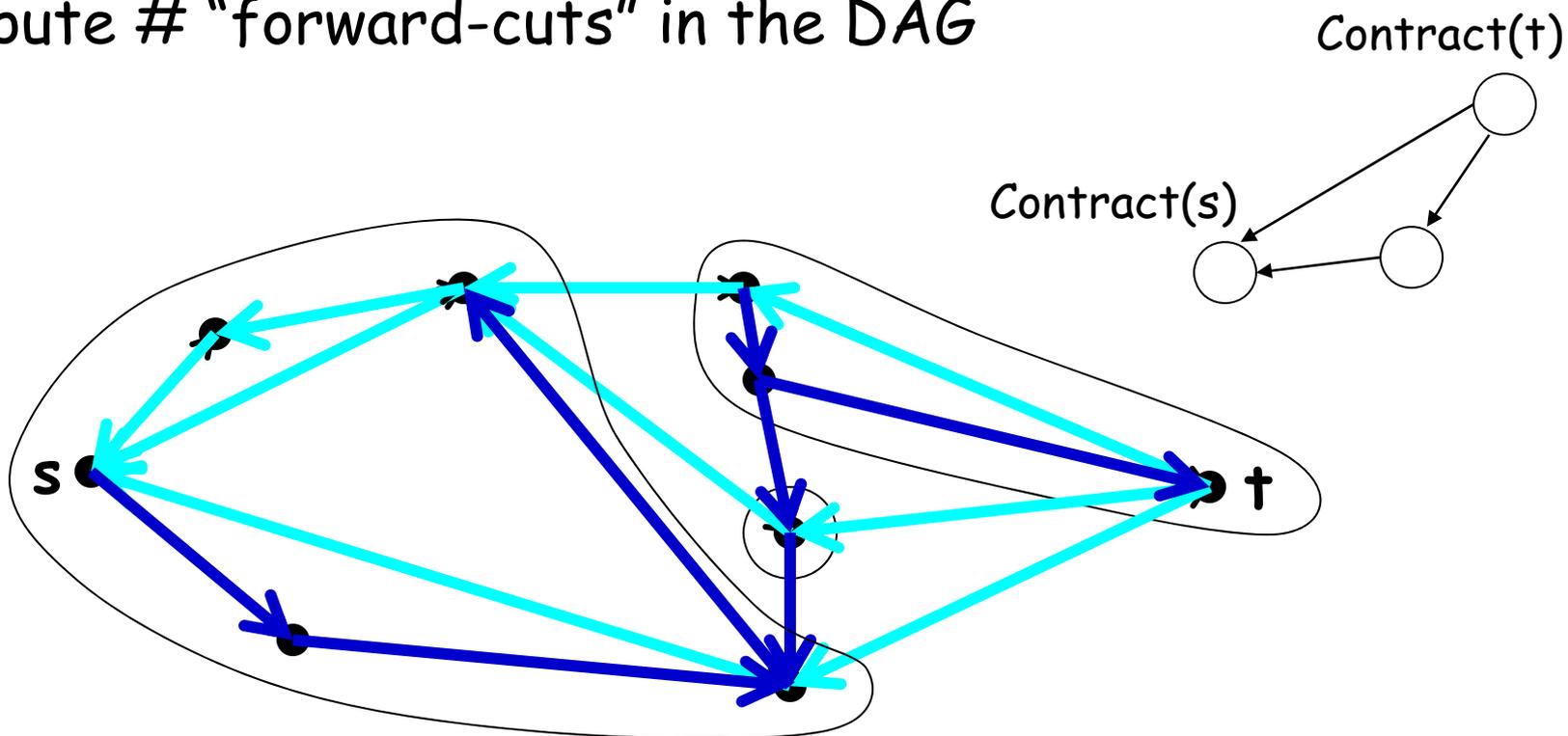
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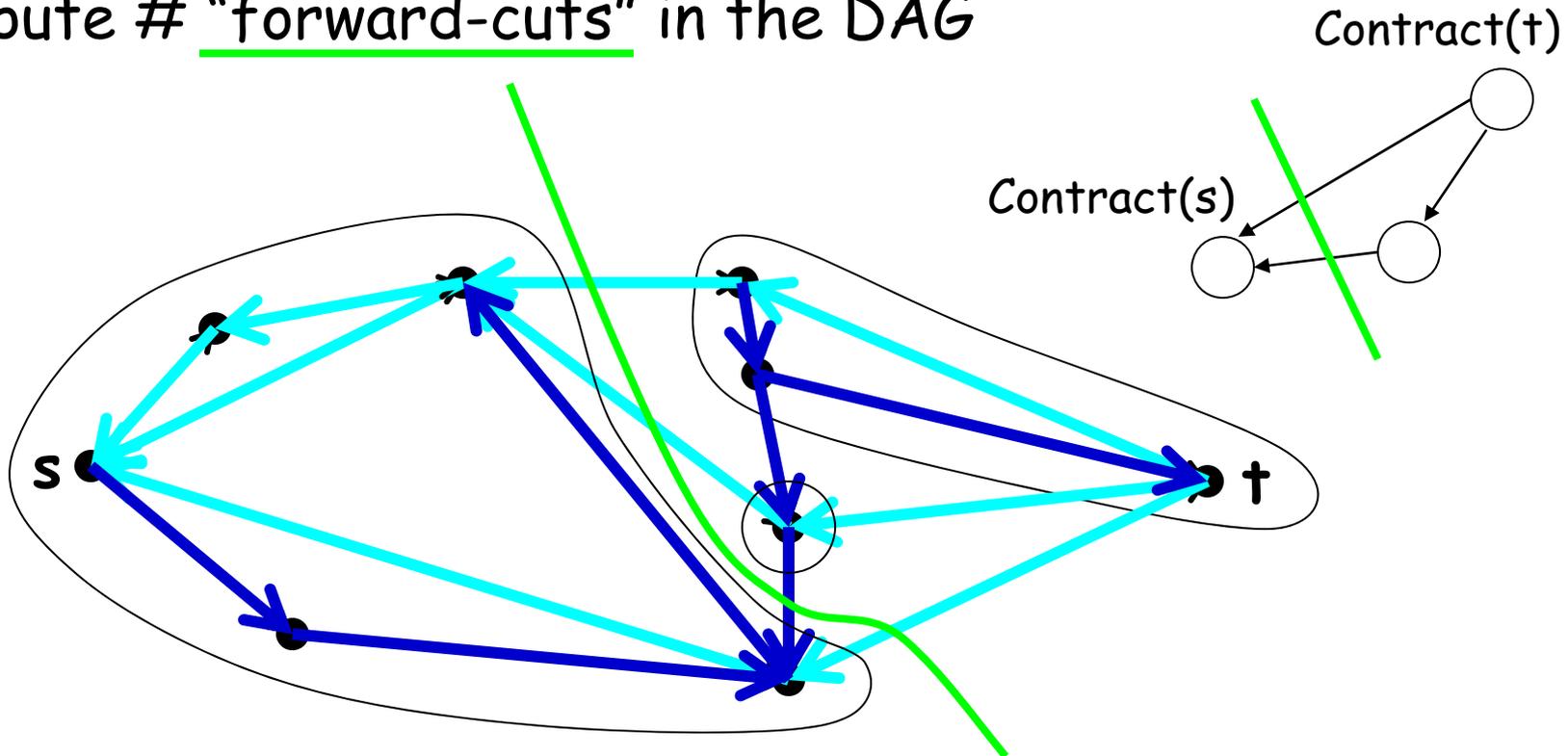
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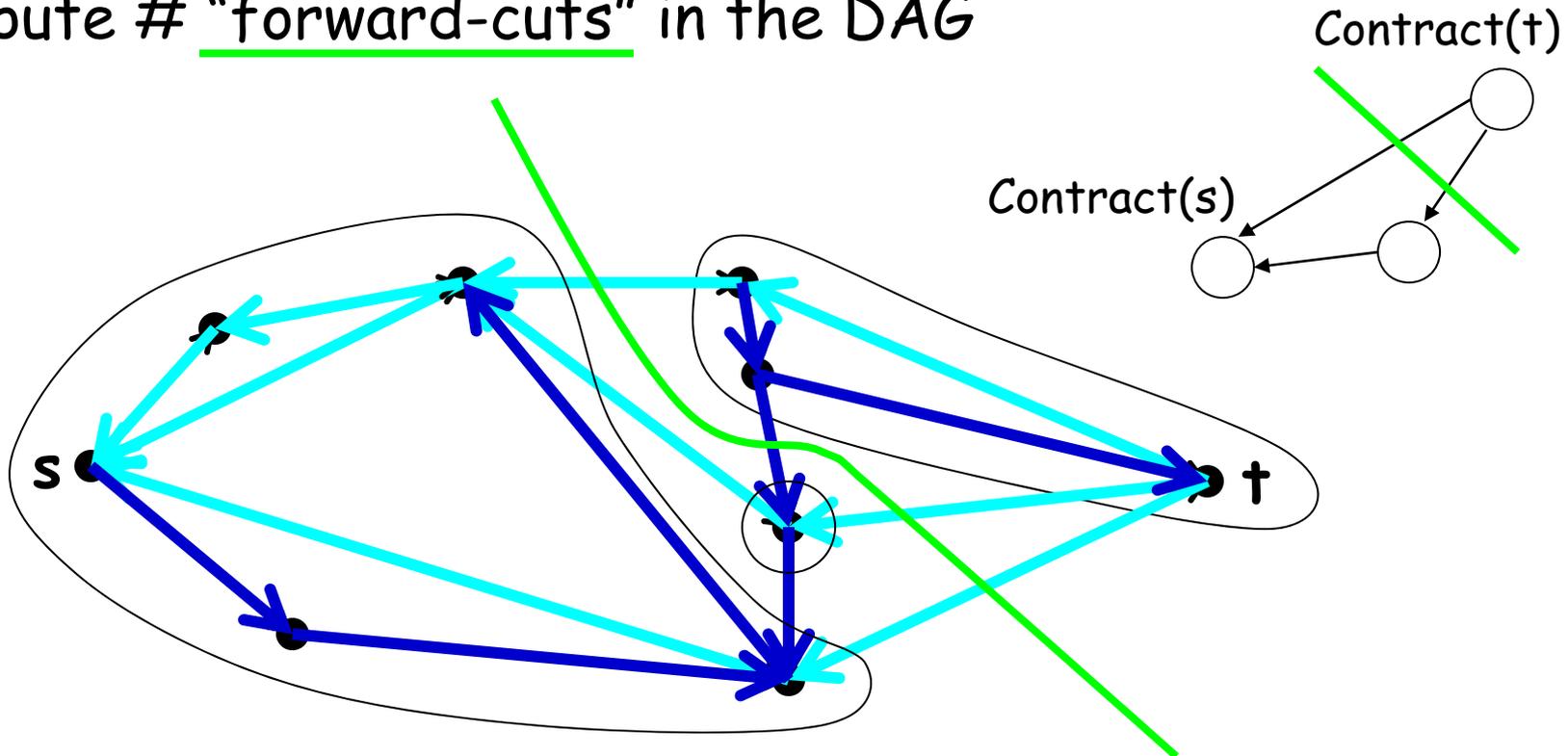
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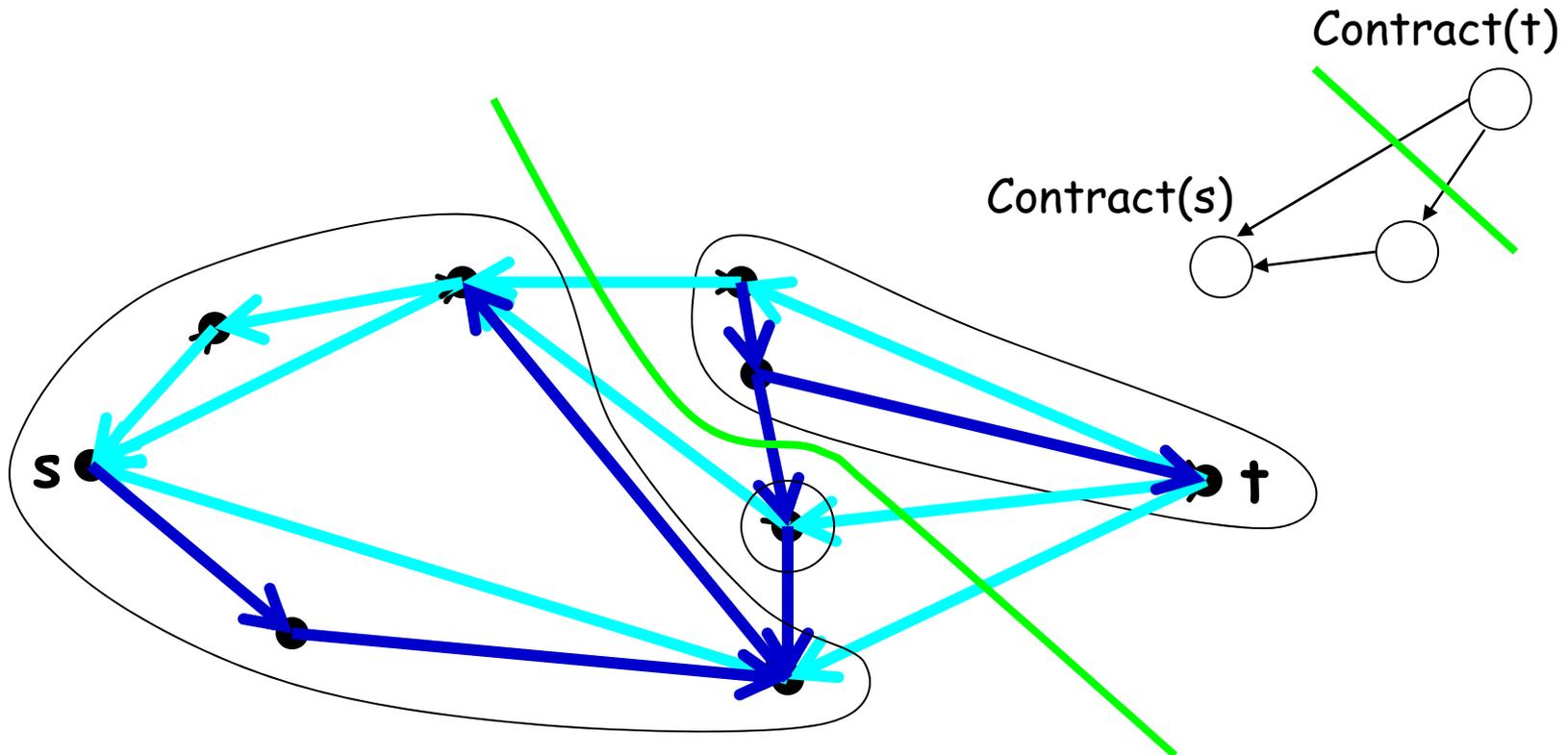
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"Forward-cut:" a set of vertices S such that:

- contains $\text{Contract}(s)$ and not $\text{Contract}(t)$, and
- for every vertex in S , all successors also in S

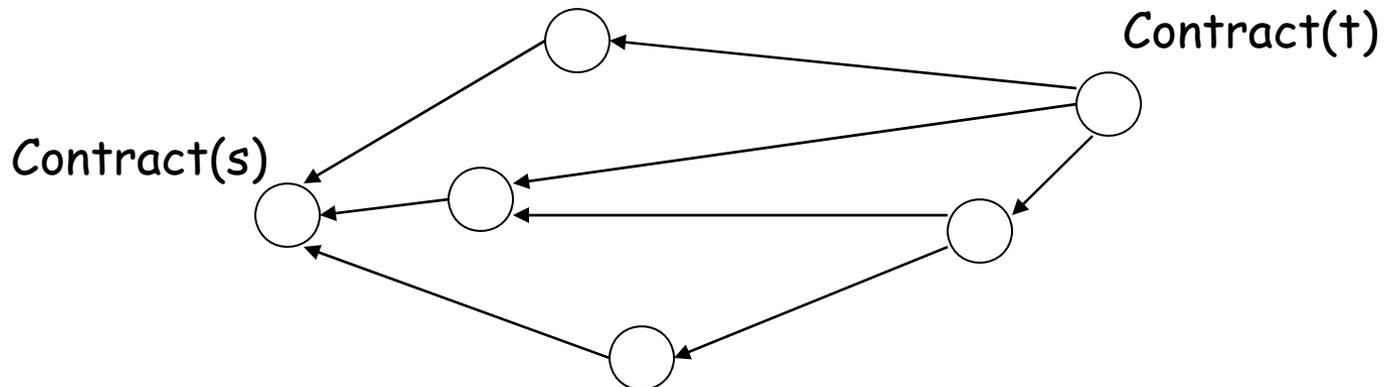


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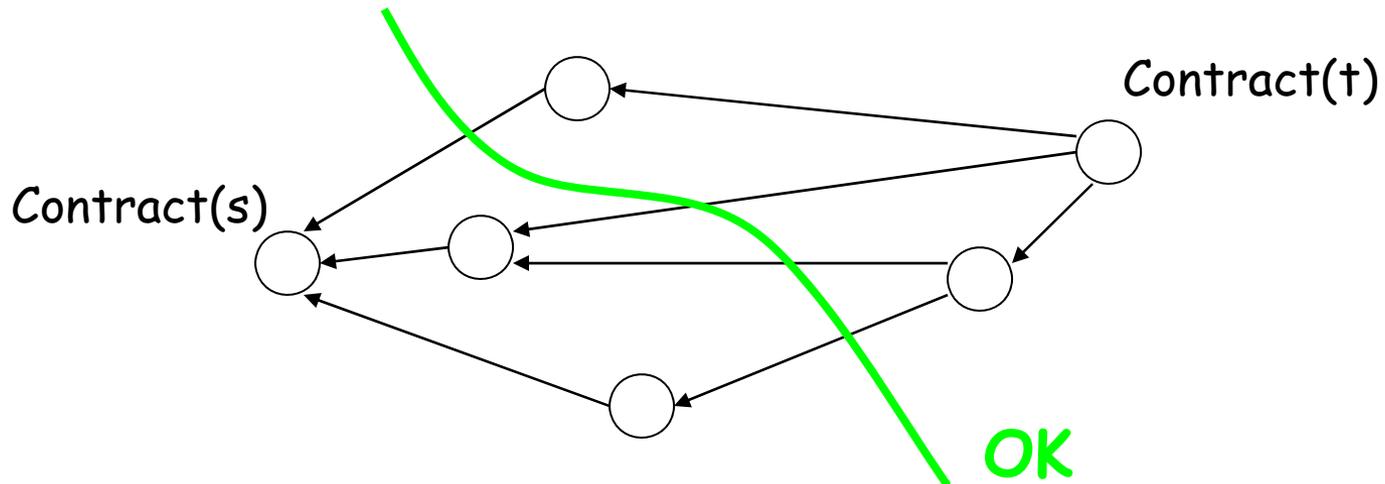


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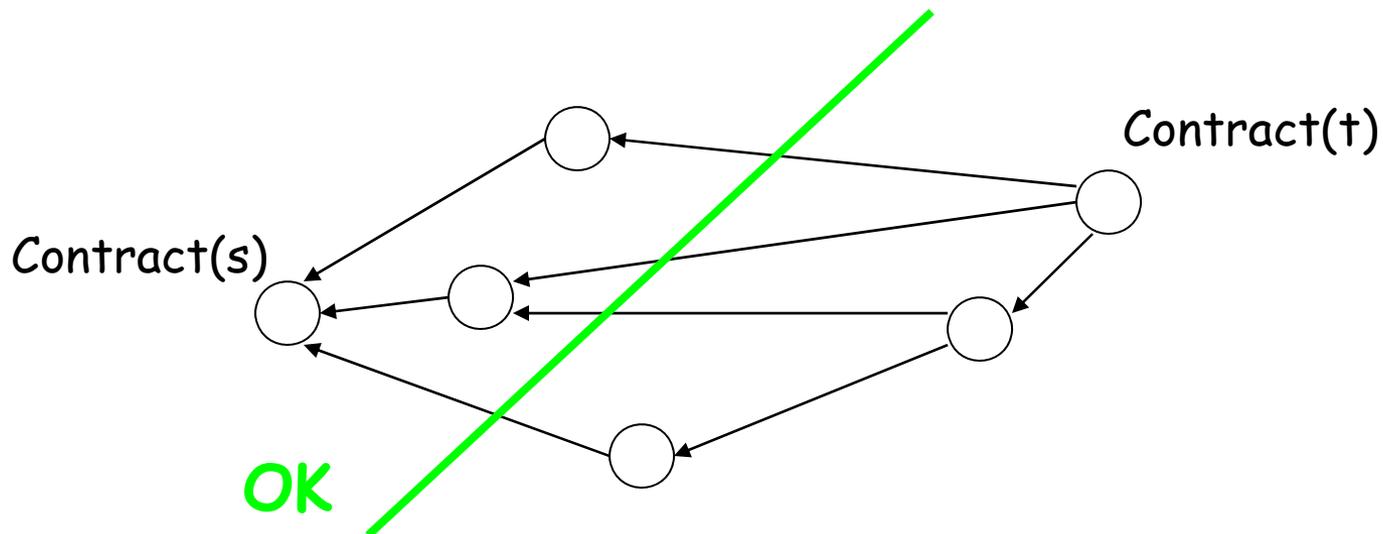


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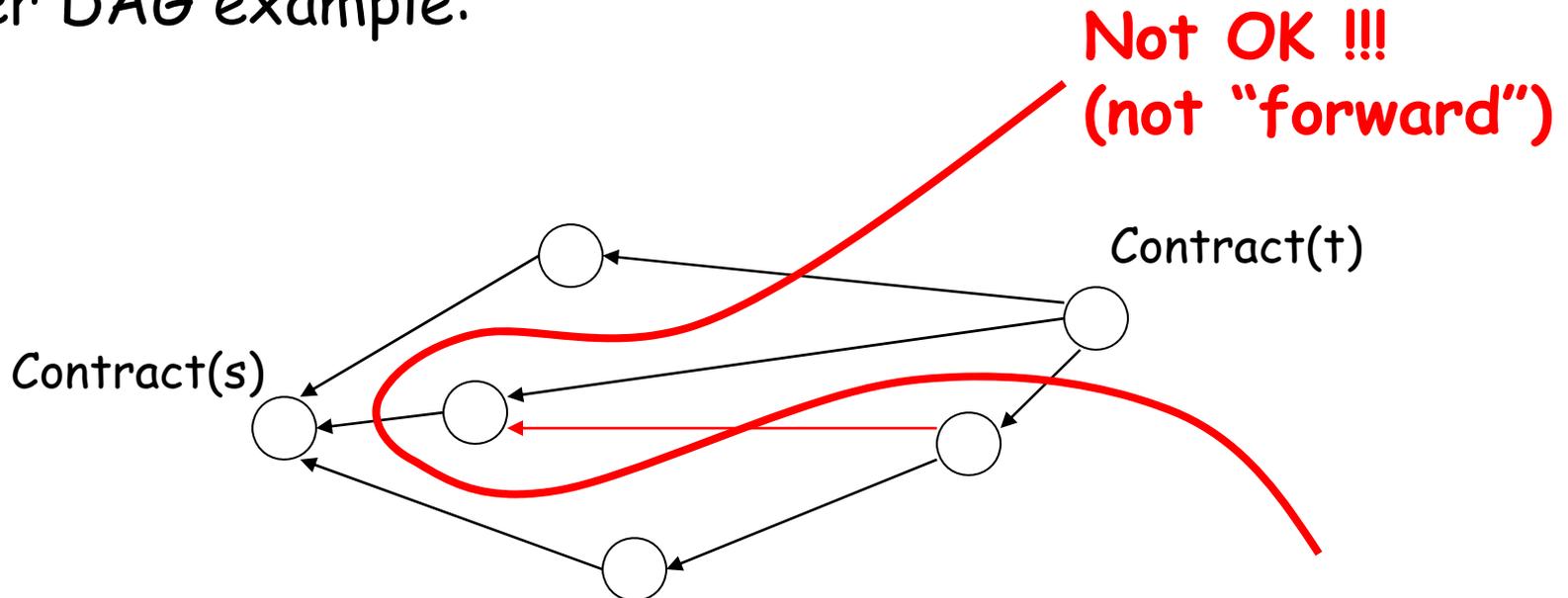


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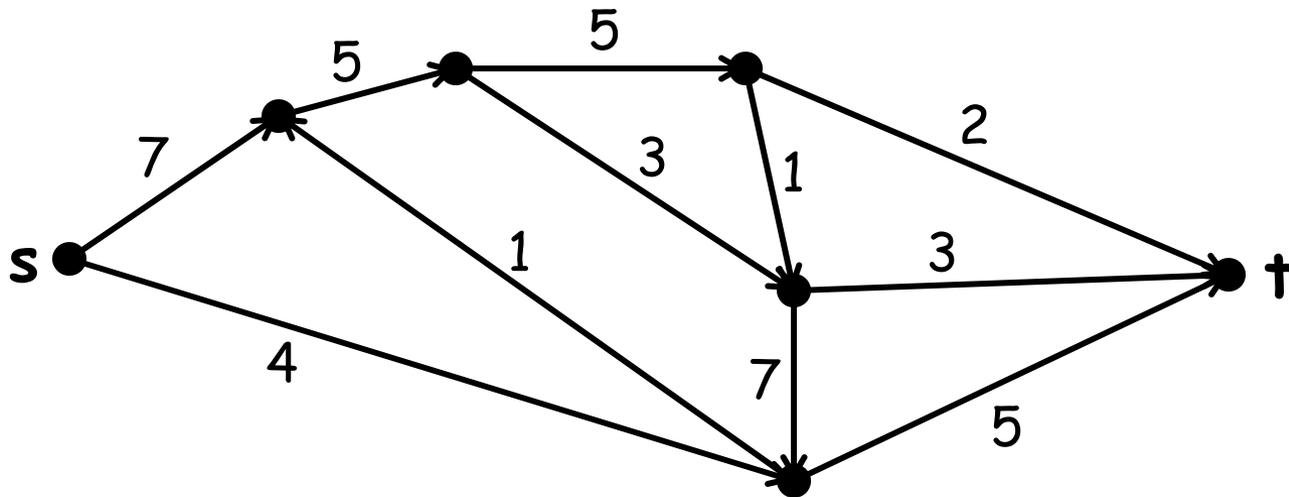
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The weighted case

What if the graph is (positively) weighted ?

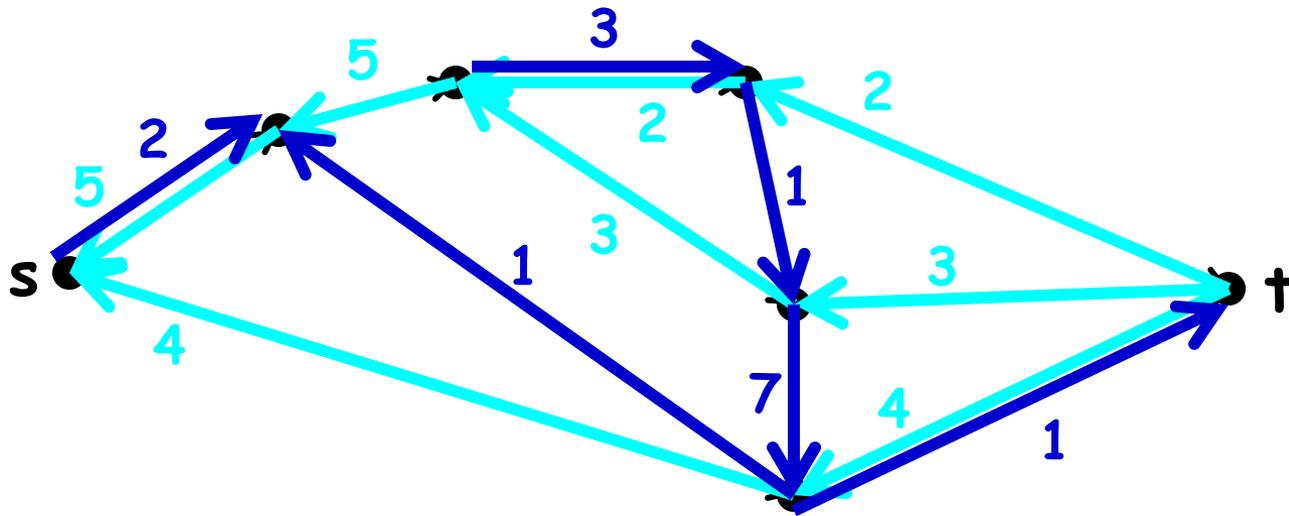
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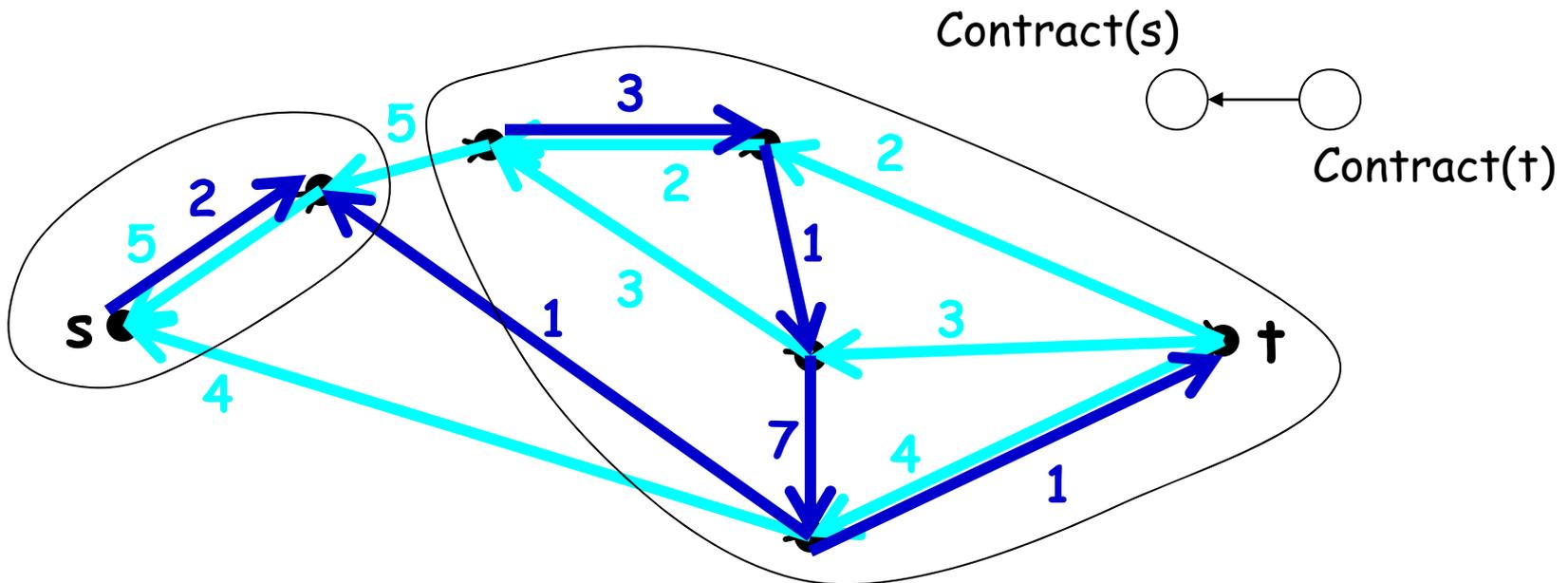
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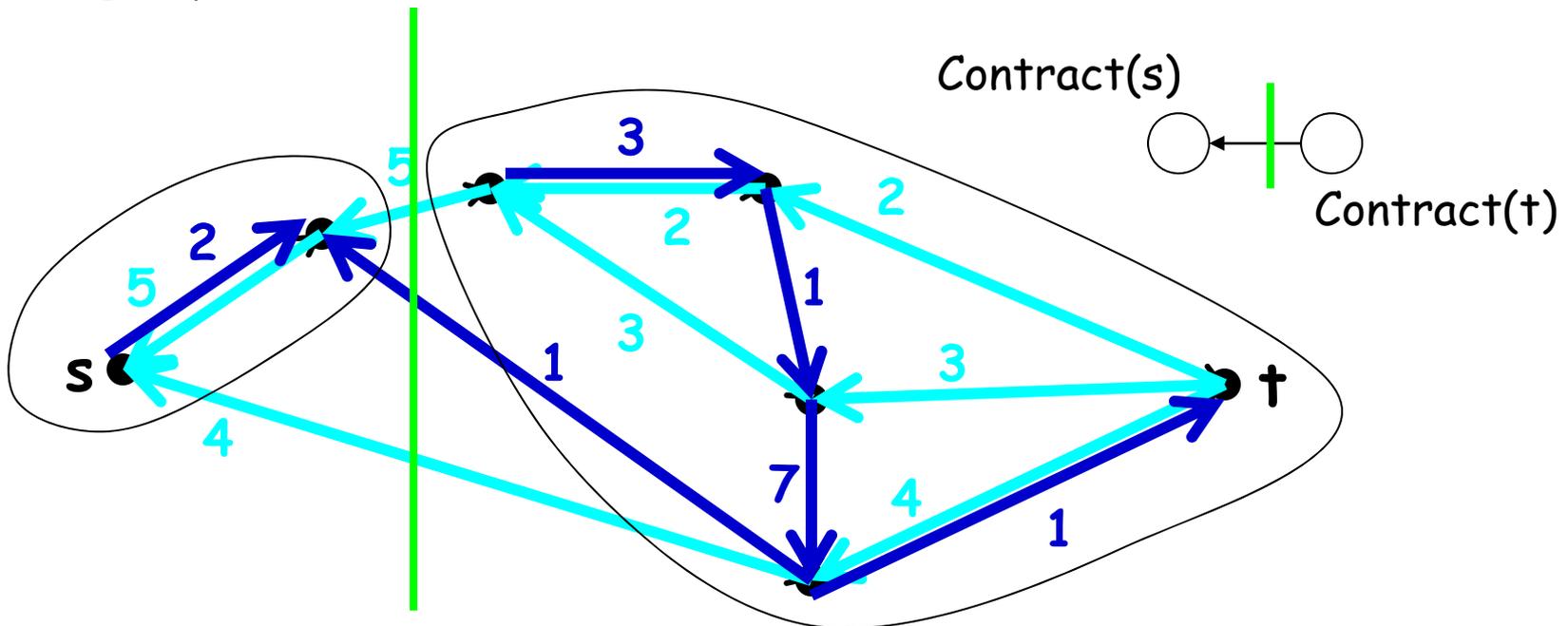
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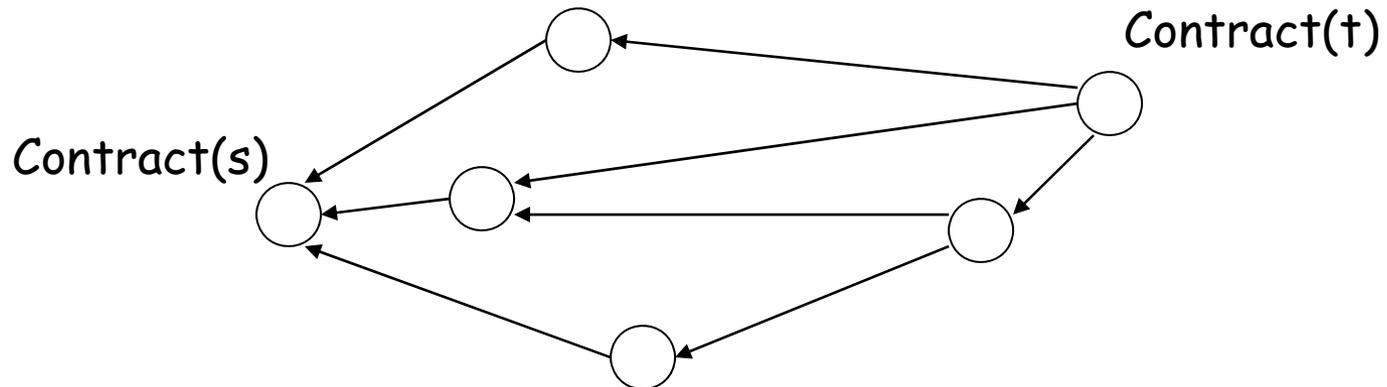
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"Forward-cuts" in planar DAGs

Observe: Planar input graph \rightarrow planar DAG

Goal: count "forward-cuts" (or maximal antichains)



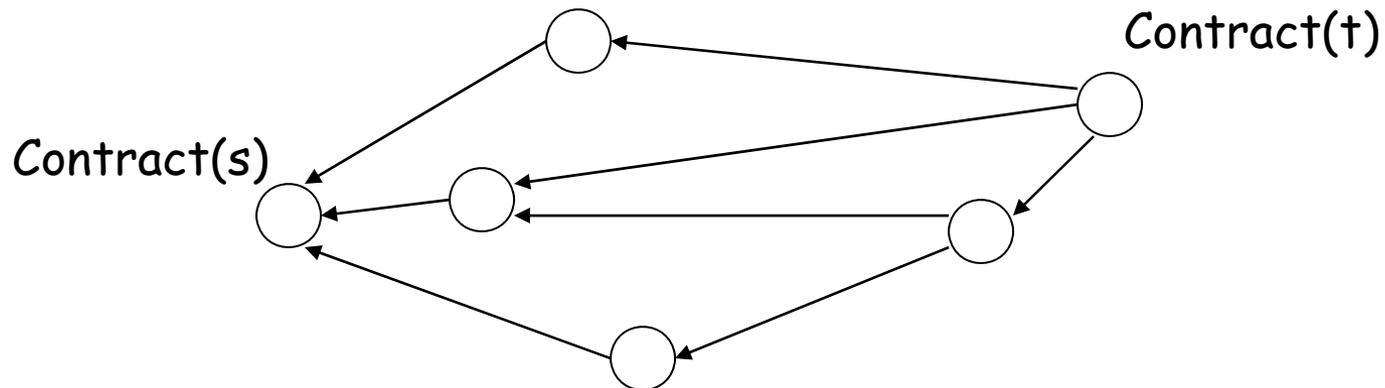
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- split the outer face into the “top” and the “bottom” face
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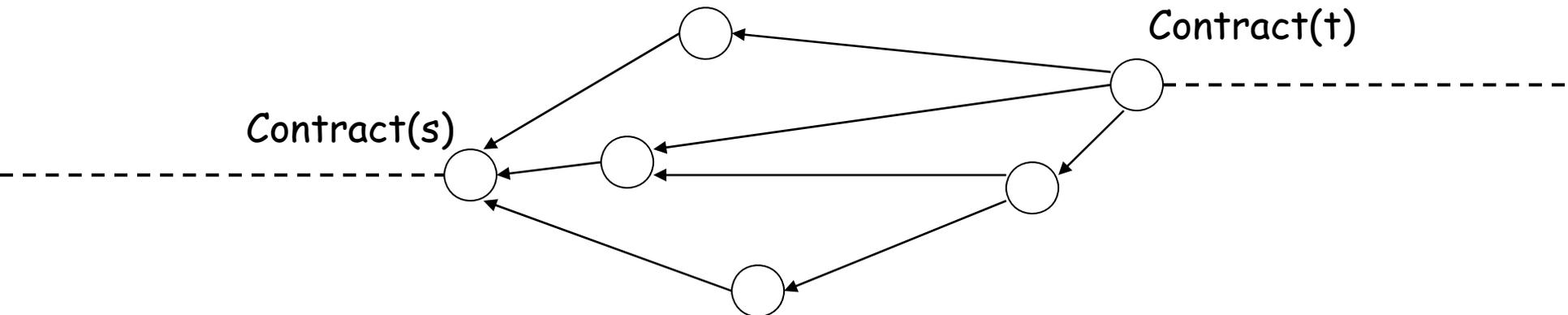
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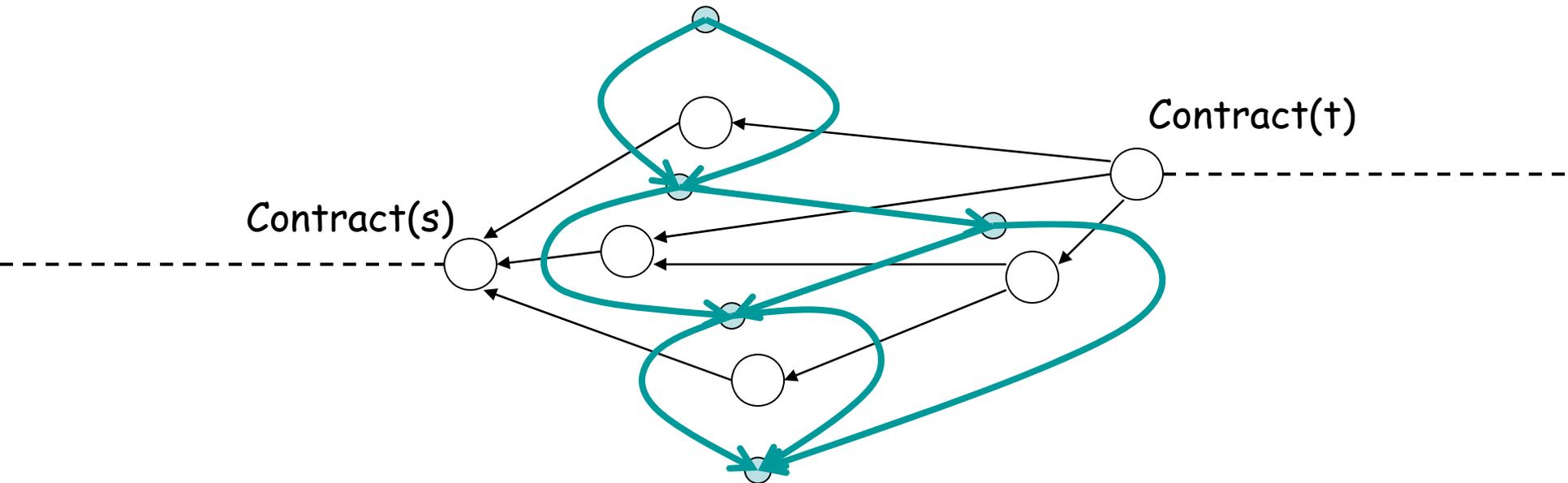
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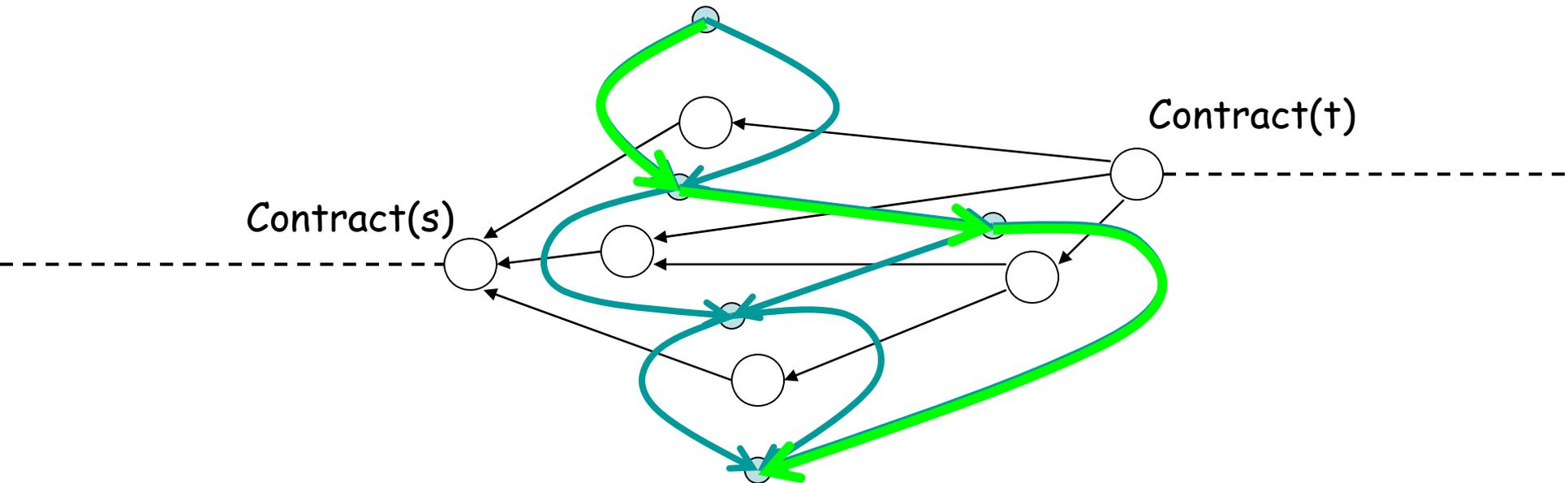
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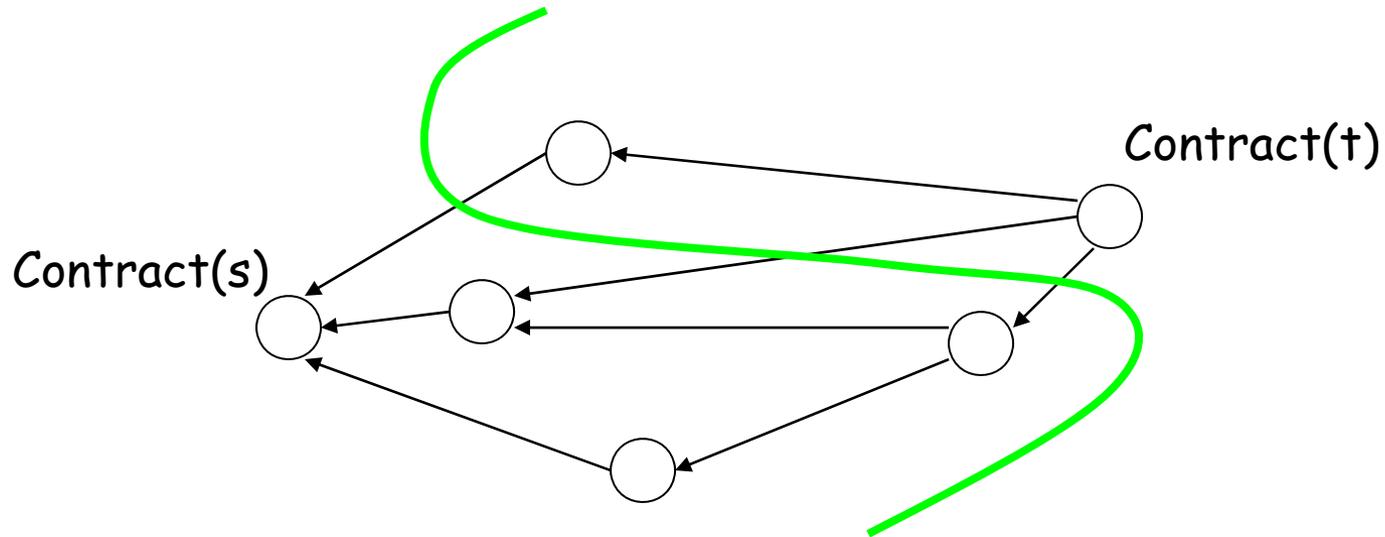
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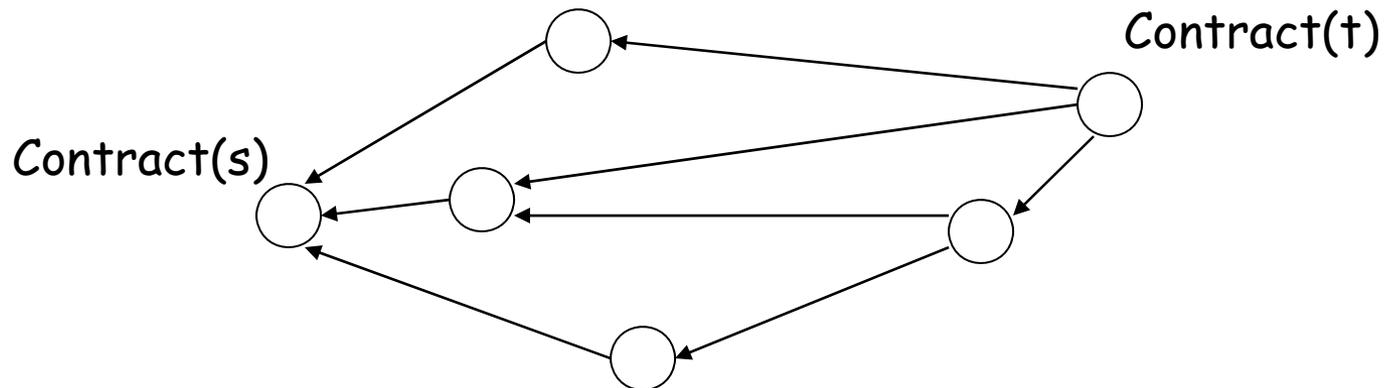
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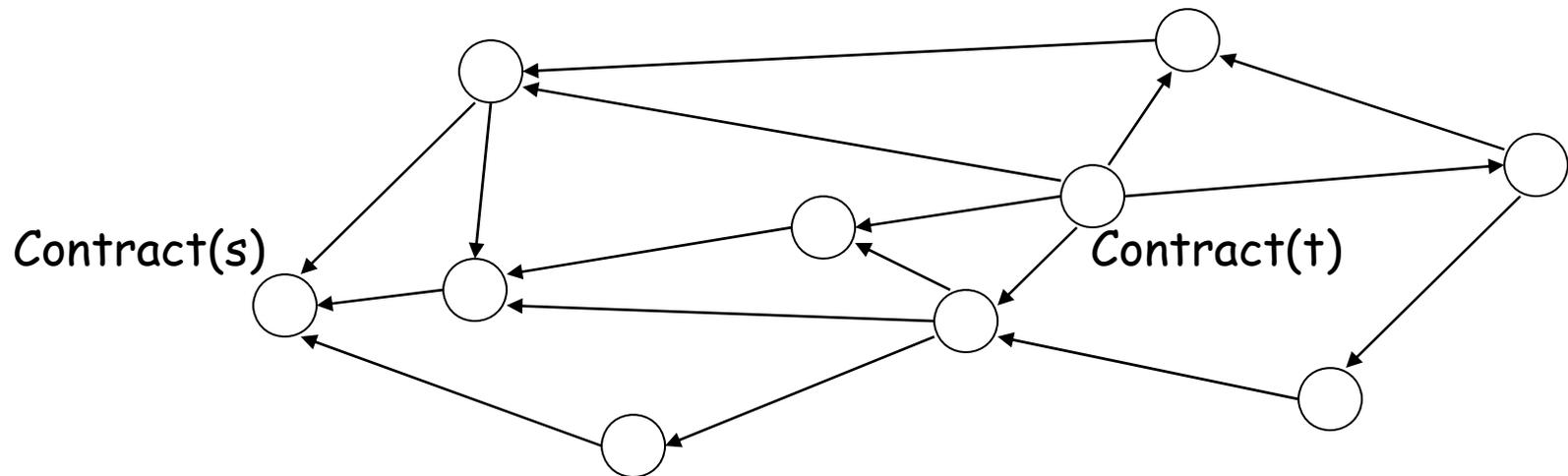
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Note: poly-time because the dual is a DAG



“Forward-cuts” and different faces

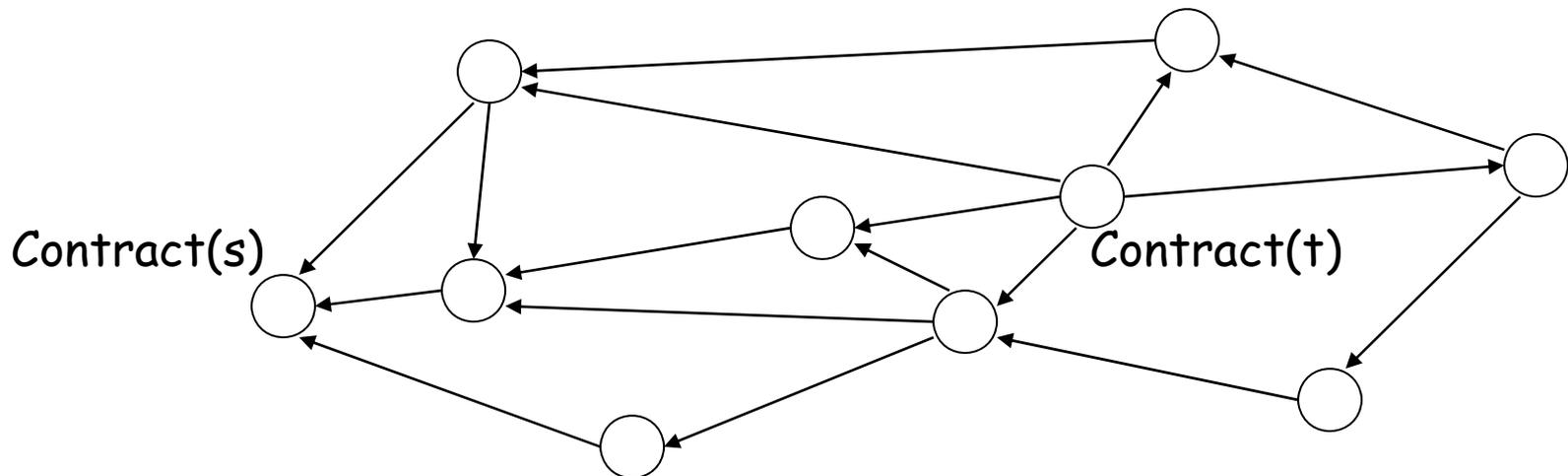
What if s, t are on different faces? [\[this paper\]](#)



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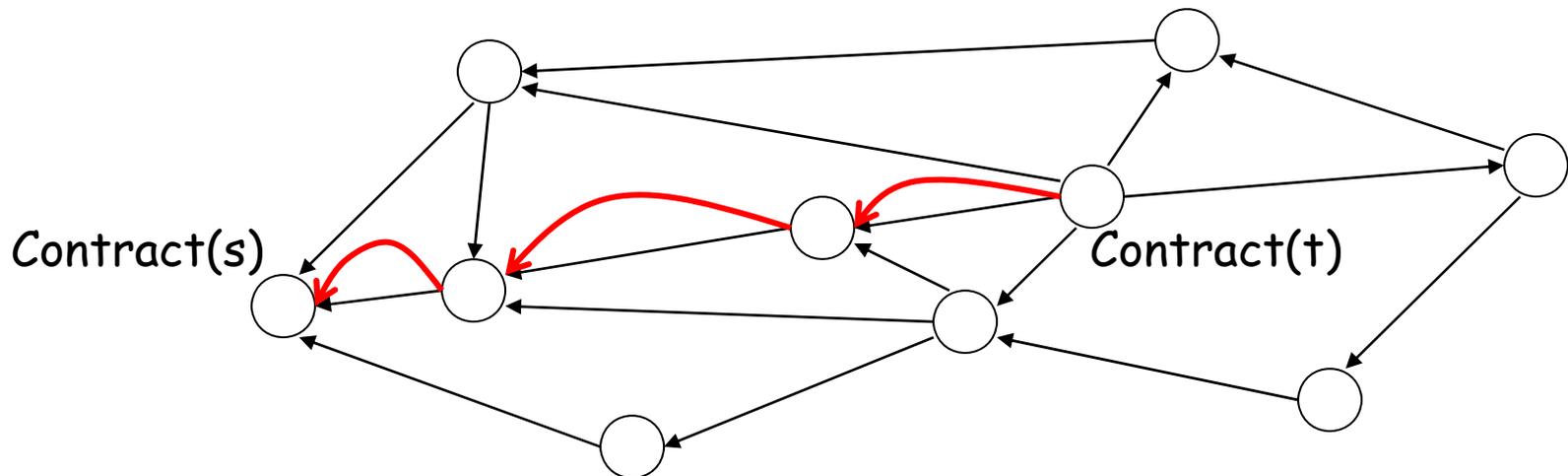
- find $\text{contract}(t)$ - $\text{contract}(s)$ path, duplicate edges, “merge” edges within the same face
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- sum # paths between faces sharing a new edge



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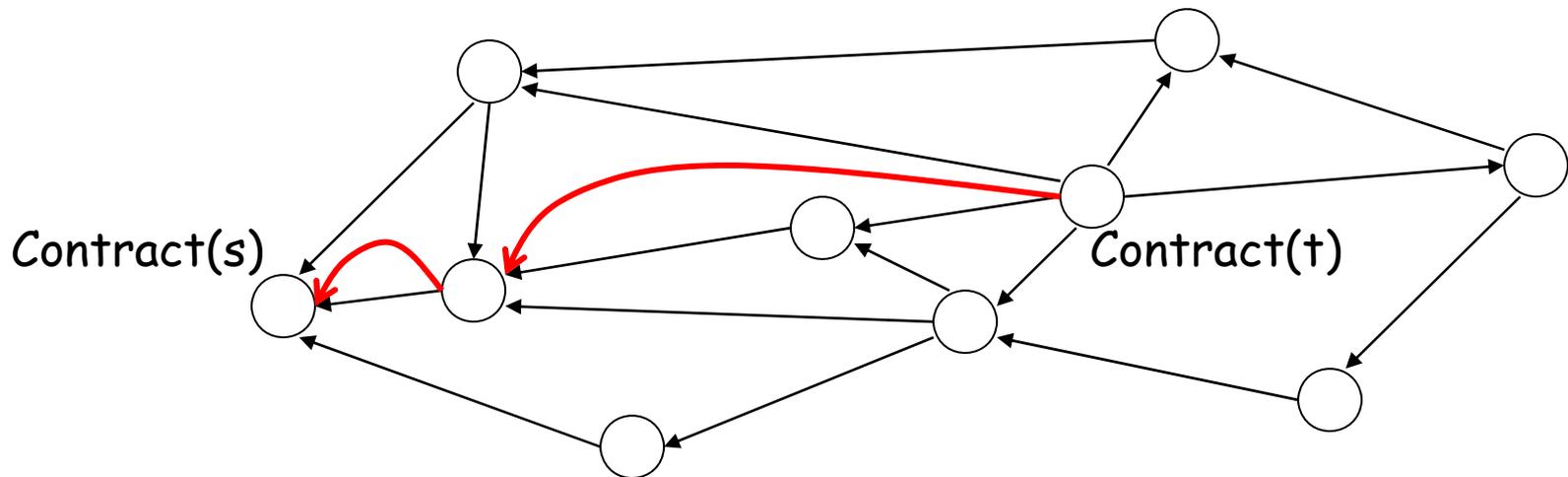
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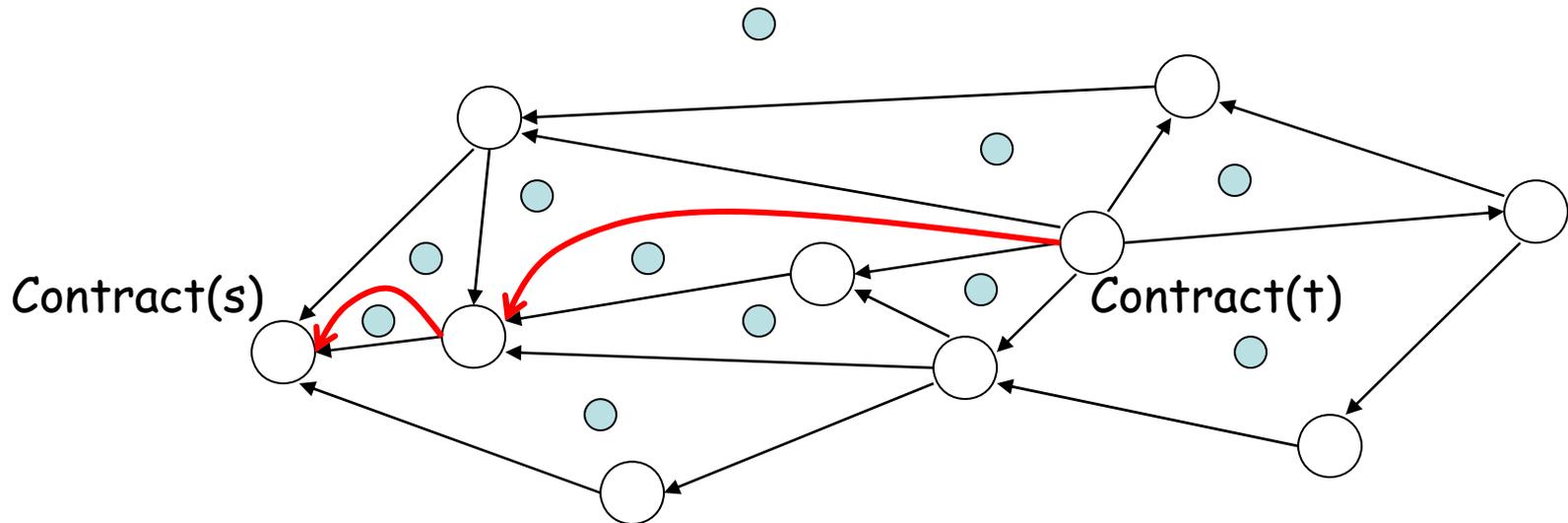
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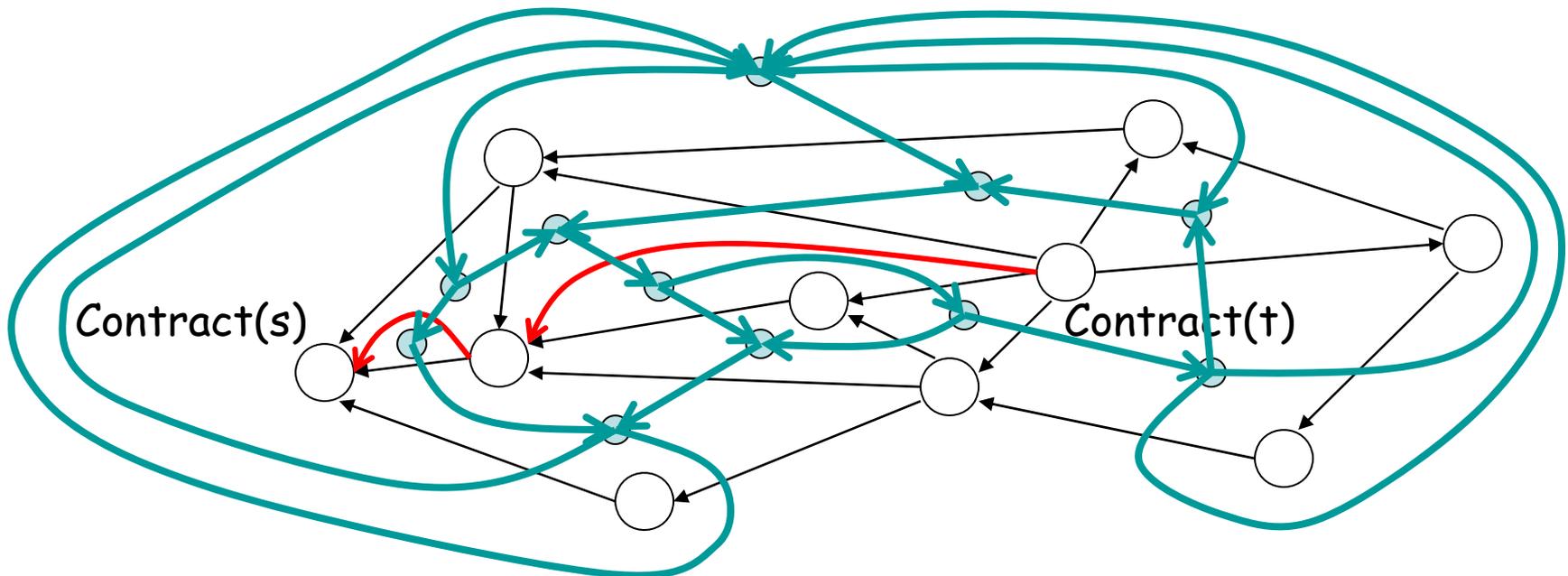
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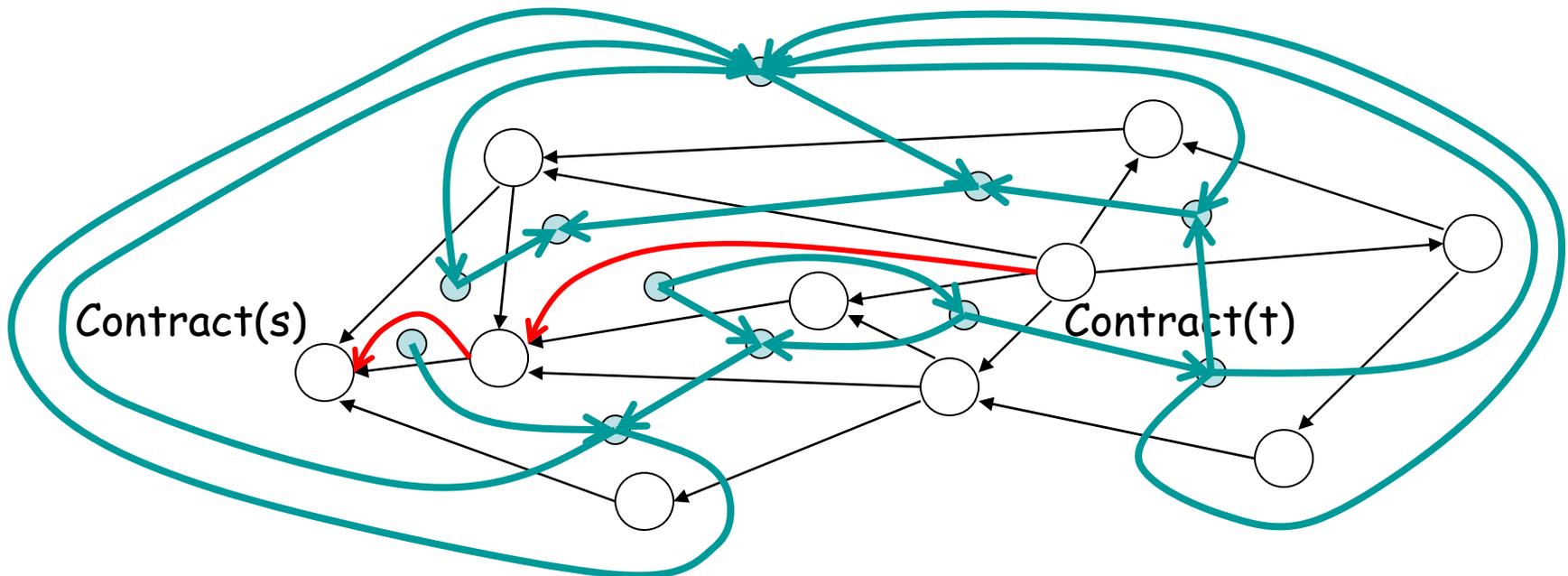
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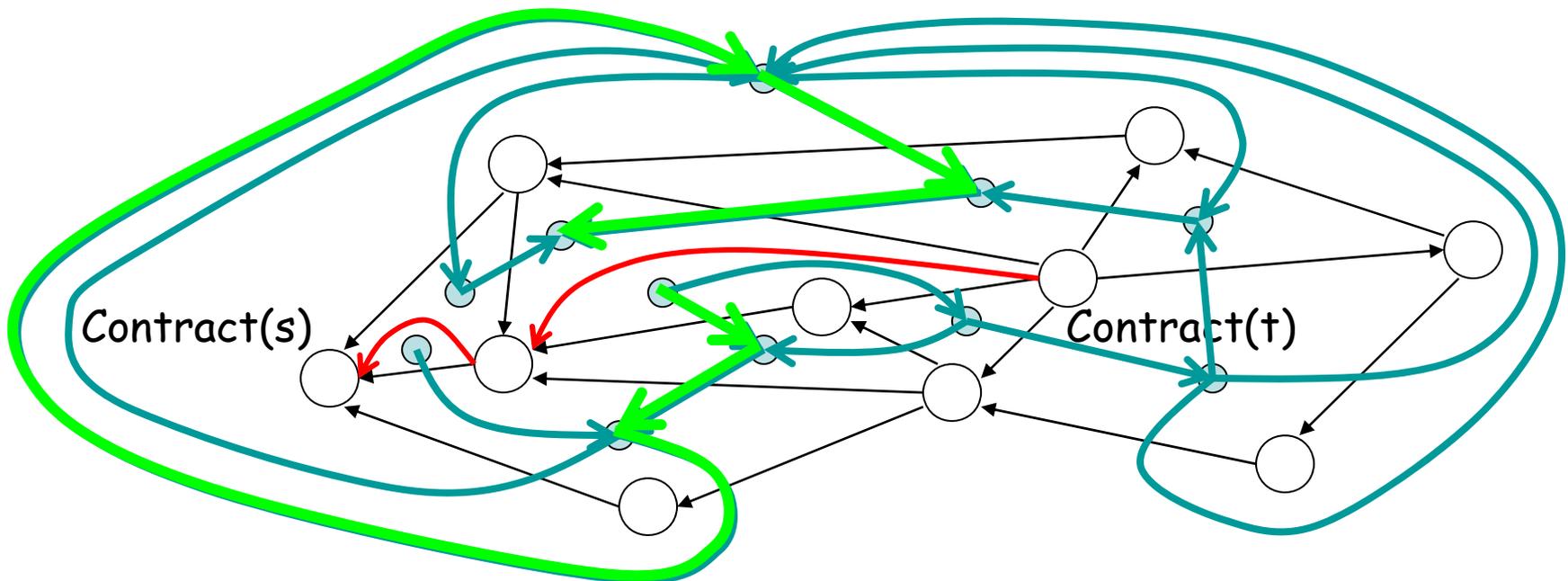
- find $\text{contract}(t)$ - $\text{contract}(s)$ path, duplicate edges, “merge” edges within the same face
- construct the dual, except no edges cross the new path \rightarrow a **DAG**
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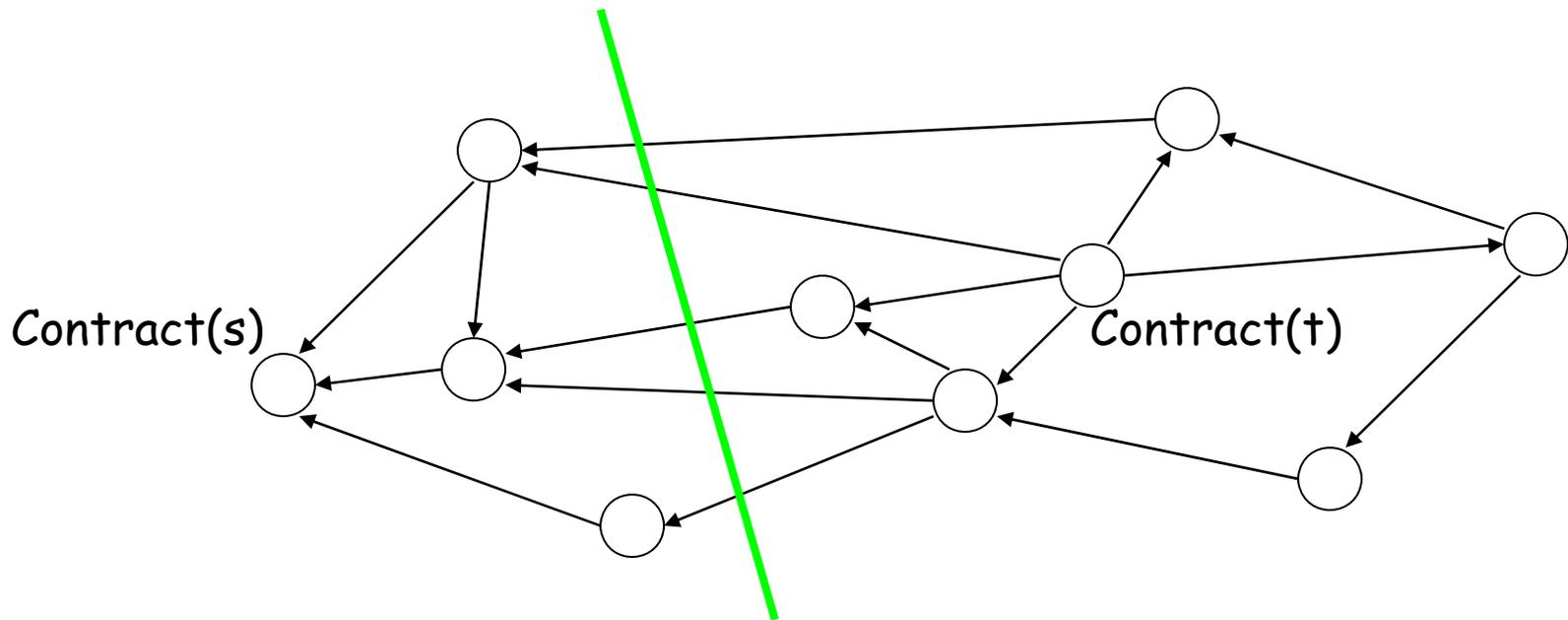
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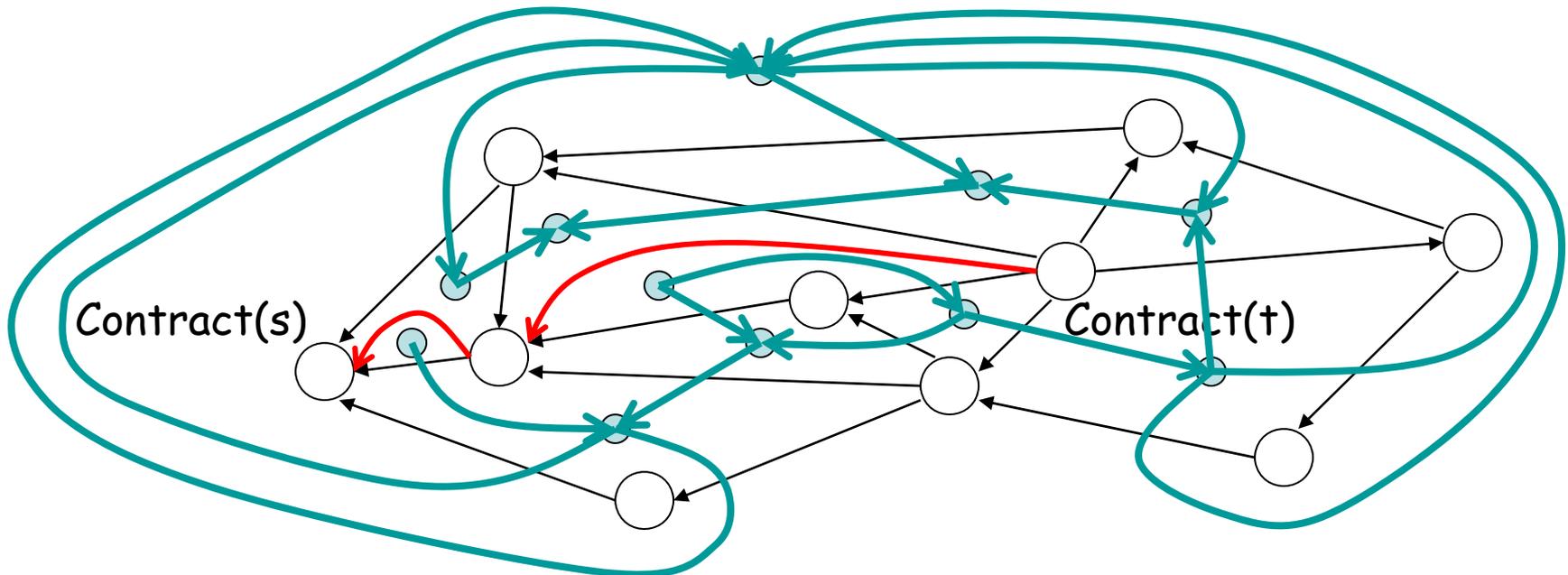
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“Forward-cuts” and different faces

Why does it work ?

- the dual (without the cross edges) is a DAG [whenever all vertices lie on an s-t path - a standard assumption]
- a simple dynamic programming counts all paths between two end-points in a DAG



Running time

Reduction to forward cuts:

- $O(n \log n)$ to find a (acyclic) max-flow in planar graphs
[Borradaile-Klein '09]
- $O(n)$ to find and contract the strongly connected components

Counting forward cuts:

- $O(n)$ find the path, construct the dual graph
- $O(n)$ compute #paths between two end-points in the dual
- $O(dn)$ overall computation of paths, at most d end-point pairs where d = length of the s - t path

TOTAL: $O(dn + n \log n)$

Open Problems

Many open problems:

- non-planar graphs ? (unweighted or weighted)
- graph arising in computer vision (high-dimensional grids, with extra source/sink vertices)
- computing the sum of all (s,t) -cut weights (i.e., weighted counting = the partition function) \rightarrow important for parameter estimation, e.g., in the Markov Random Field model in vision

