

The Complexity of Pure Nash Equilibria

Alex Fabrikant
Christos Papadimitriou
Kunal Talwar

CS Division, UC Berkeley

Definitions

- A **game**: a set of n players, a set of actions S_i for each player, and a payoff function u_i mapping **states** (combinations of actions) to integers for each player
- A **pure Nash equilibrium**: a state such that no player has an incentive to unilaterally change his action
- A **randomized (or mixed) Nash equilibrium**: for each player, a distribution over his states such that no player can improve his expected payoff by changing his action
- A **symmetric game**: a game with all S_i 's equal, and all u_i 's identical and symmetric as functions of the other $n-1$ players

Context

- Lots of work studying Nash equilibria:
 - Whether they exist
 - What are their properties
 - How they compare to other notions of equilibria
 - etc.
- **But how hard is it to actually find one?**

Complexity: Randomized NE

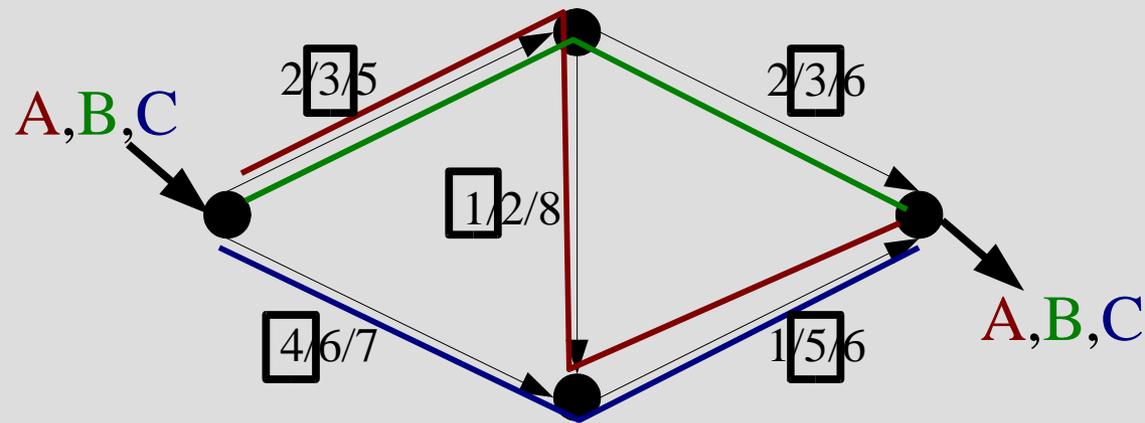
- Nash's theorem guarantees existence of randomized NE, so “find a randomized NE” is a total function, and NP-completeness is out of the question, but:
 - Various slight variations on the problem quickly become NP-Complete [[Conitzer&Sandholm '03](#)]
 - The two-person case has an interesting combinatorial construction, but with exponential counter-examples [[von Stengel '02](#); [Savani&von Stengel '03](#)]
 - It has an “inefficient proof of existence”, placing it in PPAD; other related problems are complete for PPAD, although NE is not known to be [[Papadimitriou '94](#)]

Complexity: Pure NE

- Natural question: what about pure equilibria?
 - When do they exist?
 - How hard are they to find?
- Immediate problem: with n players, explicit representations of the payoff functions are exponential in n ; brute-force search for pure NE is then linear (on the other hand, fixed #players \Rightarrow boring)
- **Our focus:** The complexity of finding a pure Nash equilibrium in broad *concisely-representable* classes of games

Congestion games

- Well-studied class of games with clear affinity to networks [Roughgarden&Tardos '02, inter alia]



Congestion games (cont)

- **General congestion game:**

- finite set E of resources

- non-decreasing delay function: $d : E \times \{1, \dots, n\} \rightarrow \mathbb{Z}$

- S_i 's are subsets of E

- Cost for a player:

$$\sum_{e \in S_i} d_e(f_s(e))$$

(number of players using resource e in state s)

(delay function for resource e)

- **Network congestion game:** each edge is a resource, and each player has a source and a sink, with paths forming allowed strategies

Congestion games & potential functions

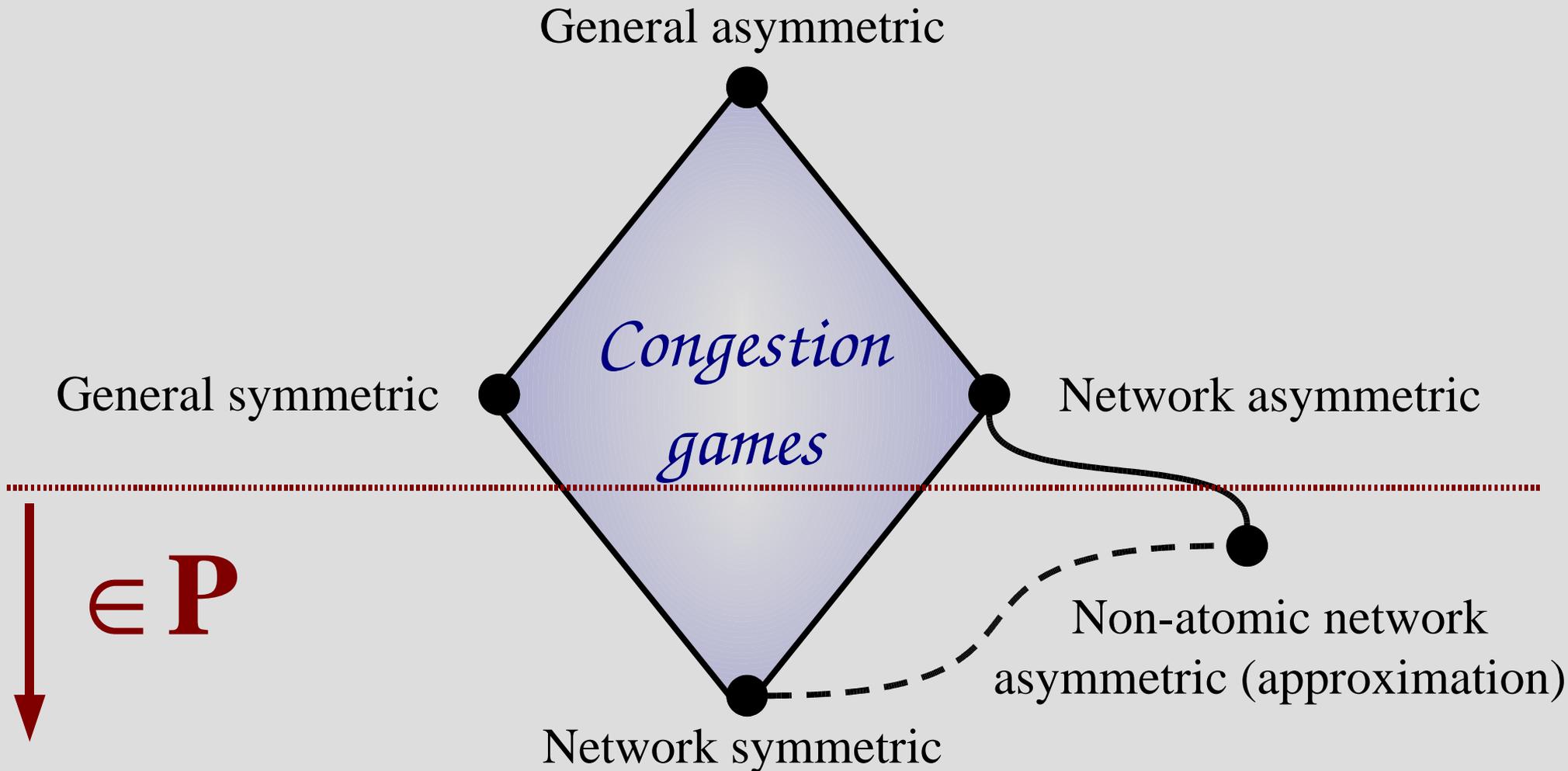
- Congestion games have a **potential function**:

$$\phi(s) = \sum_e \sum_{j=1}^{f_s(e)} d_e(j)$$

If a player changes his strategy, the change in the potential function is **equal** to the change in his payoff

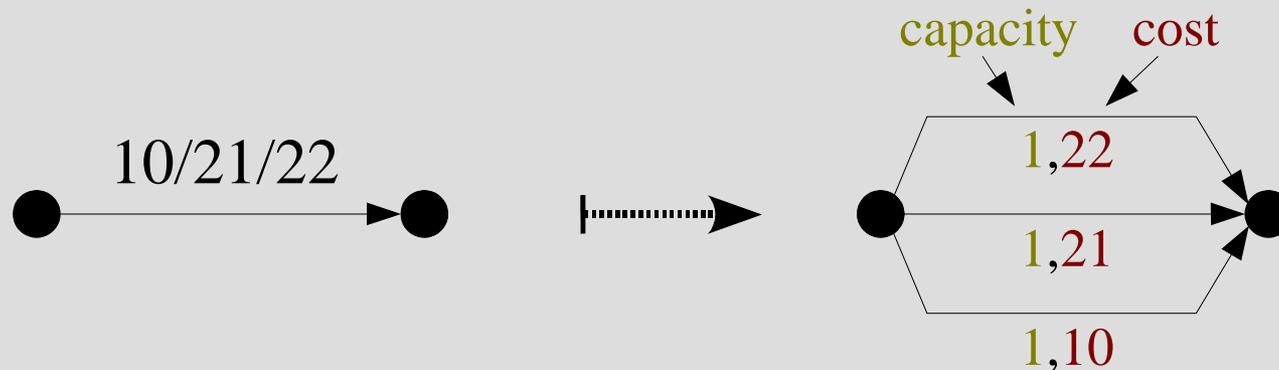
- Local search on potential function guaranteed to converge to a local optimum – an pure NE
[Rosenthal '73]
- Note: the potential is *not* the social cost

Our results: upper bounds



Algorithm: symmetric network games

- Reduction to min-cost-flow: transform each edge into n edges, with capacities 1, costs $d_e(1), \dots, d_e(n)$:

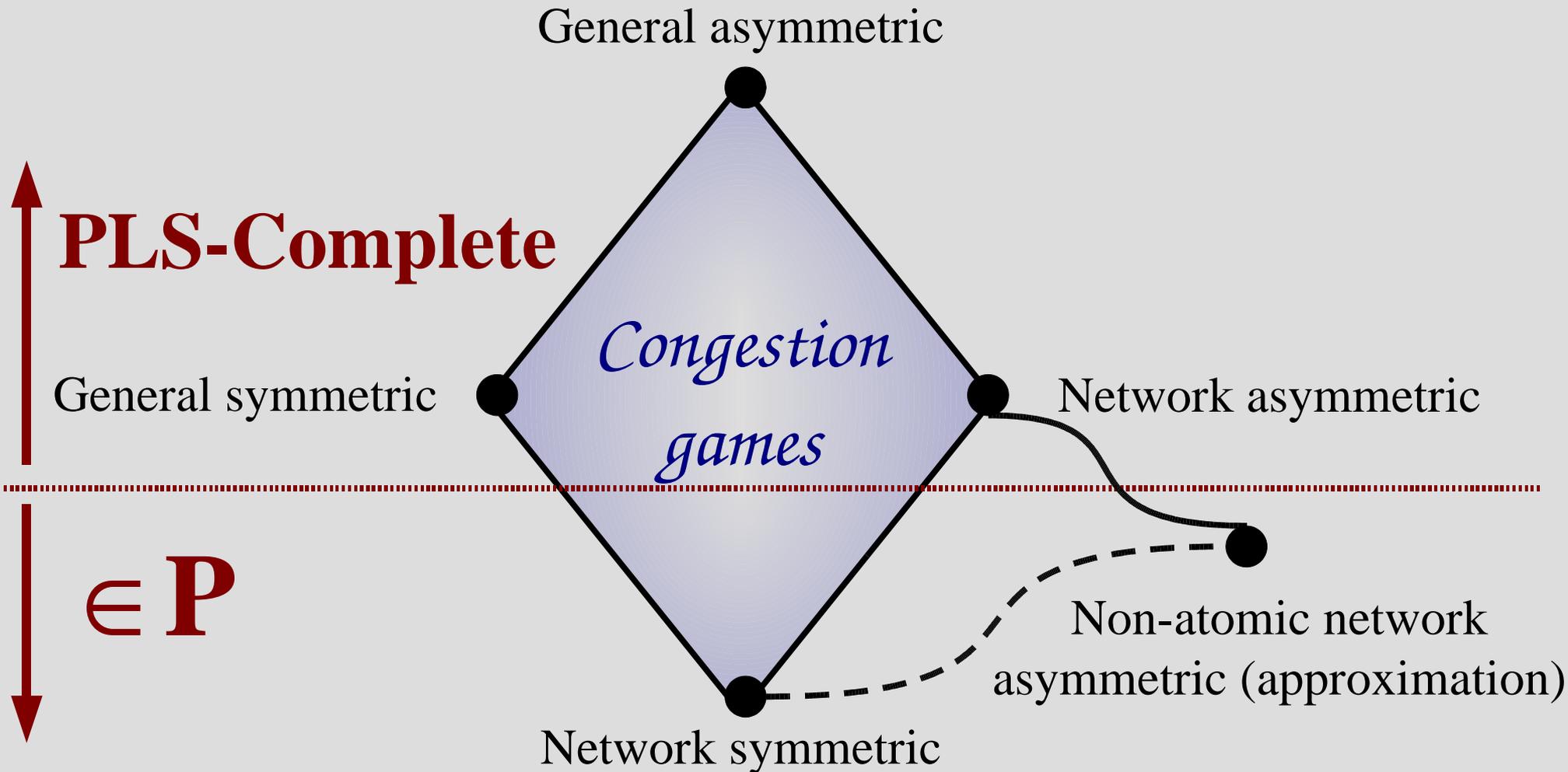


- Integral min-cost flow \Rightarrow local minimum of potential function

Algorithm: non-atomic games

- [Roughgarden&Tardos '02] studied *non-atomic* congestion games: what happens when $n \rightarrow \infty$ (with continuous delay functions)? Can cast as convex optimization, and thus approximate in polynomial time by the ellipsoid method.
- We modify the above to get, in *strongly* polynomial time, approximate pure Nash equilibria (no player can benefit by $>\epsilon$) in the *non-atomic asymmetric network case*
- N.B.: Another strongly-polynomial approximation scheme follows from the OR literature, but it is not clear that it produces approximate Nash equilibria

Our results: Lower bounds



P...what?

- **PLS** (polynomial local search [Johnson, et al '88]) – “find **some local minimum** in a reasonable search space”:
 - A **problem with a search space** (a set of feasible solutions which has a neighborhood structure)
 - A poly-time cost function $c(x,s)$ on the search space
 - A poly-time function that $g(x,s)$, given an instance x and a feasible solution s , either returns another one in its neighborhood with lower cost or “none” if there are none
- E.g.: “Find a local optimum of a congestion game's potential function under single-player strategy changes”
- Membership in PLS is an inefficient proof of existence

PLS-Completeness

- PLS reduction:
(instance_A, search space_A) \mapsto (instance_B, search space_B)
Local optima of A must map to local optima of B
- Basic PLS-Complete problem: weighted CIRCUIT-SAT under input bitflips; since [JPY'88], local-optimum relatives of TSP, MAXCUT, SAT shown PLS-Complete
- We mostly use POS-NAE-3SAT (under input bitflips):
NAE-3SAT with positive literals only; very complex PLS reduction from CIRCUIT-SAT due to [Schaeffer&Yannakakis '91]

PLS-Completeness: general asymmetric

- $\text{POS-NAE-3SAT} \leq_{\text{PLS}} \text{General Asymmetric CG}$:

variable $x \rightsquigarrow$ player x

clause $c \rightsquigarrow$ resources e_c, e_c'

$$S_x = \left\{ \left\{ e_c \mid c \ni x \right\}, \left\{ e_c' \mid c \ni x \right\} \right\}$$
$$d_{e_c}(1) = d_{e_c}(2) = 0 \quad ; \quad d_{e_c}(3) = w(c)$$

- Input bitflip maps to a single-player strategy change, with the same change in cost, so search space structure preserved
- $\text{General Asymmetric CG} \leq_{\text{PLS}} \text{General Symmetric CG}$:
 - “Anonymous” players arbitrarily take on the roles of “non-anonymous” players in the asymmetric game

PLS-Completeness: general symmetric

- General Asymmetric CG \leq_{PLS} General Symmetric CG:
 - Introduce an extra resource r_x for each player x
 - $d_r(1)=0, d_r(n>1)=\infty$
 - $S = \bigcup_x \{s \cup \{r_x\} \mid s \in S_x\}$
- Same number of players, so any solution that uses an r_x twice has an unused r_x , so can't be a local minimum
- Otherwise, players arbitrarily take on the “roles” of players in the original game

PLS-Completeness: network asymmetric

- First guess: make a network following the idea of the general asymmetric reduction – each POS-NAE-3SAT clause becomes two edges, add extra edges so each variable-player traverses either all e_c edges, or all the e'_c edges
- Problem: How do we prevent a player from taking a path that doesn't correspond to a consistent assignment?
- For a dense instance of POS-NAE-3SAT, this appears unavoidable

PLS-Completeness: network asymmetric

(cont.)

- But: the Schaeffer-Yannakakis reduction produces a very structured, sparse instance of POS-NAE-3SAT
- Our approach:
 - tweak formulae produced by the S-Y reduction
 - carefully arrange the network so “non-canonical” paths are never a good choice
- Details:
 - 39 variable types
 - 124 clause types
 - 3 more talks today
 - full reduction and a sketch of the proof are in the paper

More on PLS-completeness

- “Clean” PLS reductions: an edge in the original search space corresponds to a short path in the new search space (holds for ours)
- A clean PLS reduction preserves interesting complexity properties (shared by CIRCUIT-SAT, POS-NAE-3SAT, etc):
 - Finding the local optimum reachable from a specific state is PSPACE-complete
 - There are instances with states exponentially far from *any* local optimum

More on potential functions

- Potential functions clearly relevant to equilibria, so:
How applicable is this method?
- [Monderer&Shapley '96] If *any* game has a potential function, it's equivalent to a (slightly generalized) congestion game
- Party affiliation game: n players, actions: $\{-1, 1\}$, “friendliness” matrix $\{w_{ij}\}$. Payoff: $p(i) = \text{sgn} \sum_j s_i \cdot s_j \cdot w_{ij}$
- Follow the gradient of $\Phi(s) = \sum_{i,j} s_i \cdot s_j \cdot w_{ij}$ – terminates at a pure NE; but agrees with payoff changes only in sign (and is not a congestion game)

General potential functions

- Define a *general potential function* as one that agrees just in sign with payoff changes under single-player strategy changes (if one exists, there is a pure NE)
- The problem of finding a pure NE in the presence of such a function is clearly in PLS
- **Theorem:** *Any* problem in PLS corresponds to a family of general potential games with polynomially many players; the set of pure Nash equilibria corresponds exactly to the set of local optima

Conclusions

- We have:
 1. Given an efficient algorithm for symmetric network congestion games (and an approximation scheme for the non-atomic asymmetric case)
 2. Shown PLS-completeness of both extensions (asymmetry and general congestion game form); “clean” reductions imply other complexity results
 3. Characterized a link between PLS and general potential games
- Congestion games are thus as hard as any other game with pure NEs guaranteed by a general potential function

Open problems

- Other classes of games where the Nash dynamics converges:
 - Via general potential functions:
 - Basic utility games in [Vetta '02]
 - Congestion games with player-specific delays [Fotakis, et al '02]
 - An algebraic argument shows that the union of 2 games with pure NE's, under some conditions, retains pure NE's
- Acyclic Nash dynamics guarantees *some* potential function (toposort the solution space), but is there always a *tractable* one?
- Pointed out yesterday [Wigderson, yesterday]: complexity classification of games?