

# **NATURAL PROOFS FOR STRUCTURE, DATA, AND SEPARATION**

**XIAOKANG QIU**

**PRANAV GARG**

**ANDREI STEFANESCU**

**P. MADHUSUDAN**

*UNIVERSITY OF ILLINOIS AT URBANA-CHAMPAIGN*

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# MOTIVATION

## Automatic Software Verification

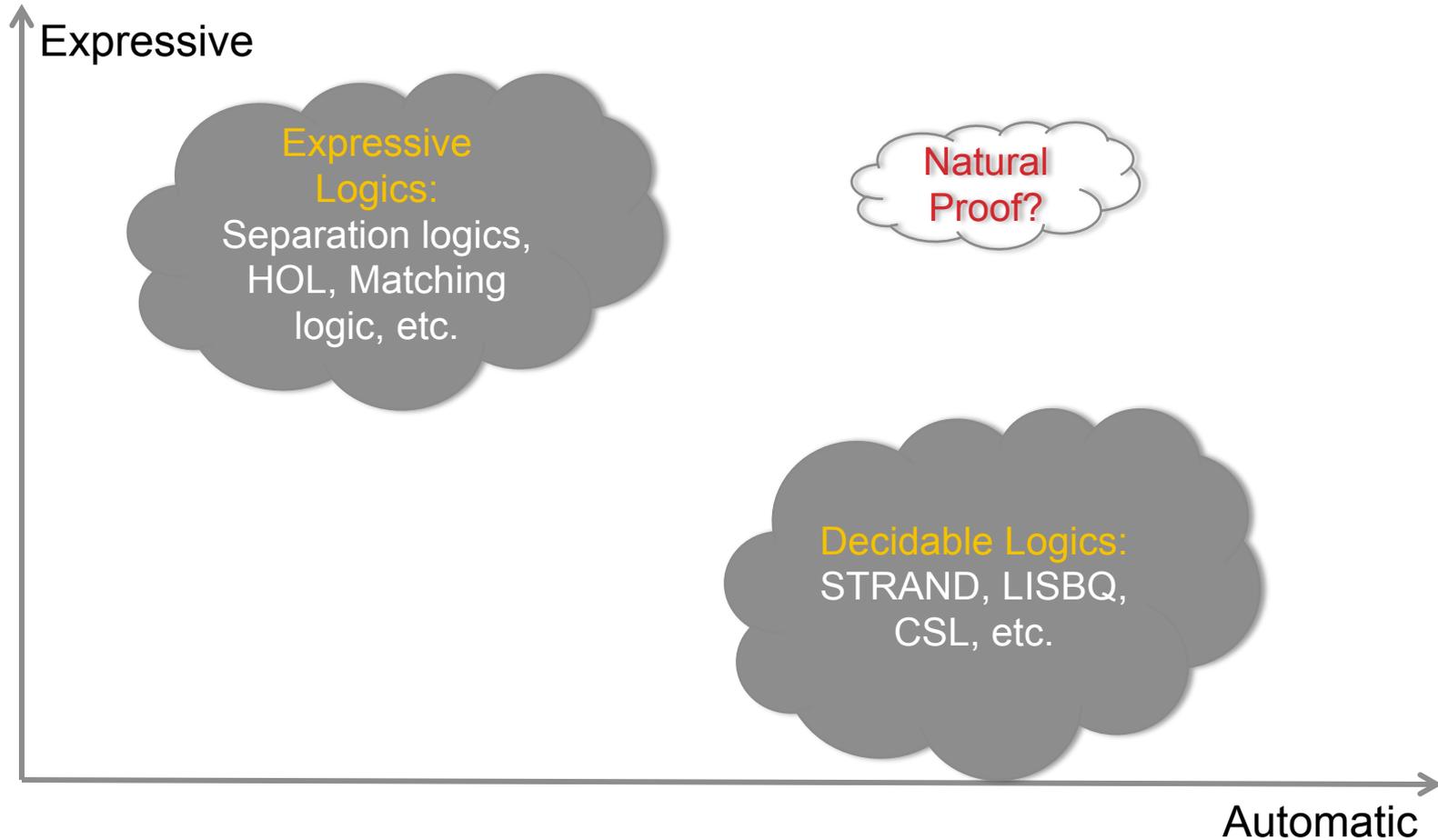
- Modular annotations + VC-Generation + SMT solvers
- Success stories (Boogie, VCC, Verifast, etc.)

## How about dynamically modified heap?

- Structure (e.g., “ $p$  points to the root of a tree”)
- Data (e.g., “the integers stored in a list is sorted”)
- Separation (e.g., “the procedure modifies only elements reachable using the *next* field”)

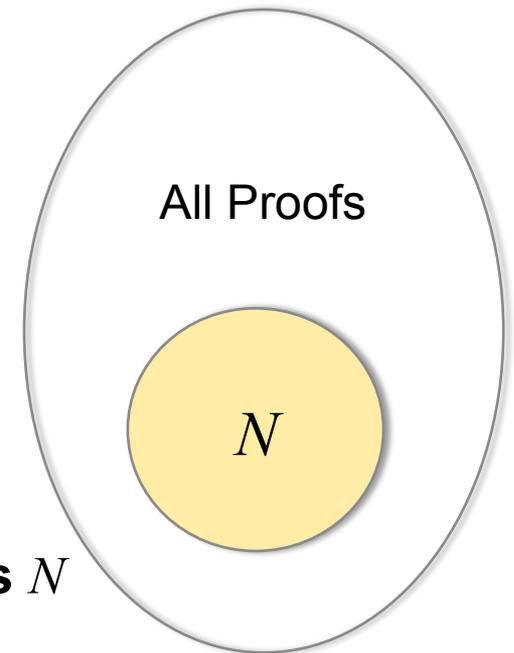
**Key Challenge:** Expressive Power vs. Automated Reasoning

# EXPRESSIVENESS VS. AUTOMATICITY



# NATURAL PROOFS: IN A NUTSHELL

- **Handle a logic that is very expressive**  
(inevitably undecidable)
- **Retain automaticity at the same level as decidable logics**
- **Identify a class of simple and natural proofs  $N$  such that**
  - Many correct programs can be proved using a proof in class  $N$
  - The class  $N$  is effectively searchable  
(searching thoroughly for a proof in  $N$  is efficiently decidable)
  - “Unfold recursive defs + formula abstraction”



# CONTRIBUTION

- **DRYAD<sub>tree</sub>** [POPL'12]: **Natural proofs for trees**
  - only for trees (can't say “ $x$  points to a tree and  $y$  points into the tree”)
  - only functional recursion (no while-loops, too weak for loop invariants)
  - only classical logic (no frame reasoning)
- **Aim**
  - To provide a single logical framework that supports natural proofs for general properties of **structure, data, and separation**
- **Contribution**
  - **DRYAD**: A dialect of separation logic
    - no explicit quantification, but supports recursive definitions
    - admits a **deterministic** translation to classical logic
  - Develop natural proofs for this logic using decision procedures (powered by SMT solvers)
  - A much wider variety of programs verified automatically and efficiently

# BINARY SEARCH TREE: AN EXAMPLE OF DRYAD

$$bst^*(x) \stackrel{def}{=} (x = nil \wedge emp) \vee$$

$$(x \mapsto xl, xr, xk) * \left( bst^*(xl) \wedge keys^*(xl) < \{xk\} \right) * \left( bst^*(xr) \wedge \{xk\} < keys^*(xr) \right)$$

$$keys^*(x) \stackrel{def}{=} (x = nil : \emptyset ;$$

$$(x \mapsto xl, xr, xk) * true : \{xk\} \cup keys^*(xl) \cup keys^*(xr) ;$$

default:  $\emptyset$

Recursive predicate

Recursive function

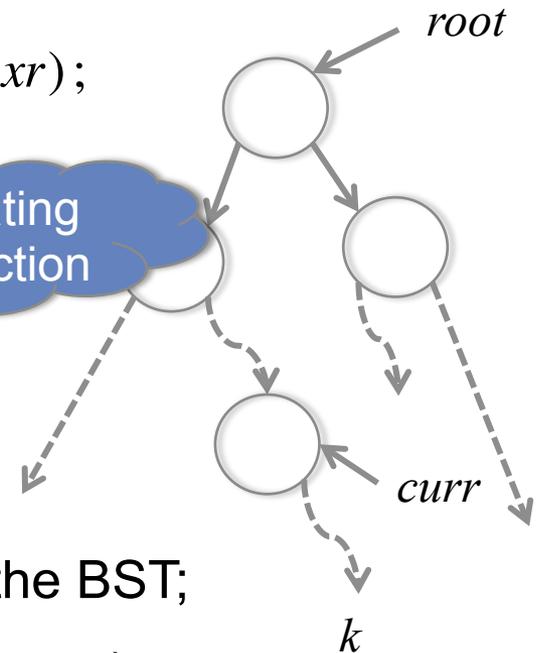
Separating Conjunction

$$\psi \equiv bst^*(root) \wedge (bst^*(curr) * true) \wedge (k \in keys^*(root) \leftrightarrow k \in keys^*(curr) * true)$$

(loop invariant for “*bst-search*”:

*root* points to a BST **and** *curr* points into the BST;

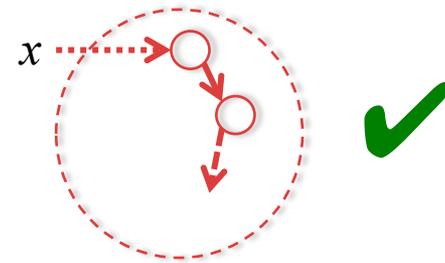
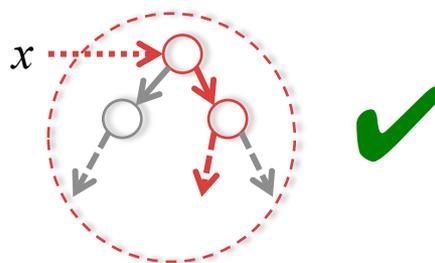
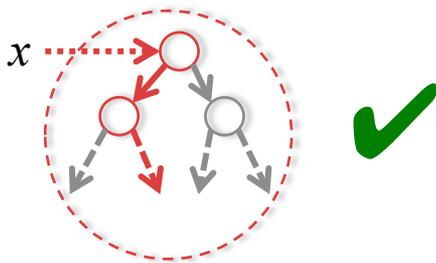
*k* is stored in the BST **iff** *k* is stored under *curr*)



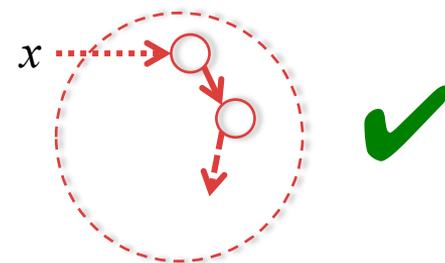
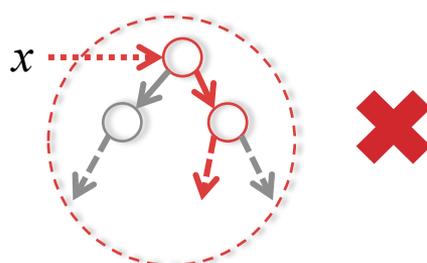
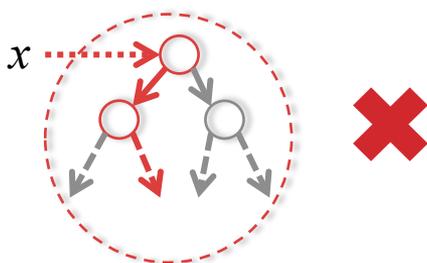
# DRYAD VS. SEPARATION LOGIC

$$U^*(x) \stackrel{def}{=} (x = \text{nil} \wedge \text{emp}) \vee (x \mapsto^{l,r} xl, xr * U^*(xl)) \vee (x \mapsto^{l,r} xl, xr * U^*(xr))$$

Separation Logic: **any** tree and **any** path



DRYAD: the heaplet is **exactly** the reachable locations from  $x$



# TRANSLATE DRYAD TO A CLASSICAL LOGIC

The **scope** (heaplet required) of a formula can be **syntactically determined**

- *singleton heap*  $x \mapsto y : \{x\}$
- *recursive definitions*  $U^*(x) : \text{reach}(x)$
- *Connective*  $t \sim t' : \text{scope}(t) \cup \text{scope}(t')$

the domain of a heaplet can be modeled as a **set of locations**, and the heaplet semantics can be expressed using free set variables

**Example:**  $tree^*(x) * tree^*(y)$

can be translated to

$$\begin{aligned} & tree(x) \wedge tree(y) \wedge \\ & \text{reach}(x) \cap \text{reach}(y) = \emptyset \wedge \\ & \text{reach}(x) \cup \text{reach}(y) = G \end{aligned} \quad \text{(still quantifier-free)}$$

# NATURAL PROOFS FOR DRYAD

We consider a toy programming language that explicitly manages the heap

We consider **programs with modular annotations**

(pre/post, loop invariant in DRYAD)

## Natural Proofs in 4 steps

1. Translate DRYAD to classical logic
2. Generate the verification condition (compute strongest-post)
3. Unfold recursive definitions across the footprint (still precise)
4. Formula Abstraction and solve in SMT  
(recursive definitions uninterpreted, becomes sound but incomplete)

# EXPERIMENTAL EVALUATION

## A prototype verifier with Z3 as the backend solver

(more details at <http://web.engr.illinois.edu/~qiu2/dryad/>)

- 10+ data structures  
singly-linked list, sorted list, doubly-linked list, cyclic list, max-heap, BST, Treap, AVL tree, red-black tree, binomial heap...
- 100+ DRYAD-annotated programs  
textbook algorithms, Glib library, OpenBSD library, Linux kernel, an ongoing OS-Browser verification project...
- **All** these VCs were **proved** by Z3!
- Few routines exceed 1 sec, even fewer exceed 100 secs  
*“RBT-delete\_iter”* spent 225 secs, *“binomial-heap-merge\_rec”* spent 153 secs

(To the best of our knowledge)

**First terminating automatic** mechanism that can prove such a wide variety of programs **full-functionally correct**

# CONCLUSION

**DRYAD is an expressive, tractable dialect of separation logic**

**A deterministic translation to classical logic**

**Extended the natural proof scheme to let the user**

- specify structural properties of the heap
- reason with multiple structures
- reason with separation (frame reasoning)

**A tool that handles Hoare-triples automatically using SMT solvers**

(more details at <http://web.engr.illinois.edu/~qiu2/dryad/>)

**Ongoing: Natural Proofs for C**

(encode the natural proof scheme in ghost code for VCC)

**THANK YOU!**