



Stochastic Rasterization using Time-Continuous Triangles

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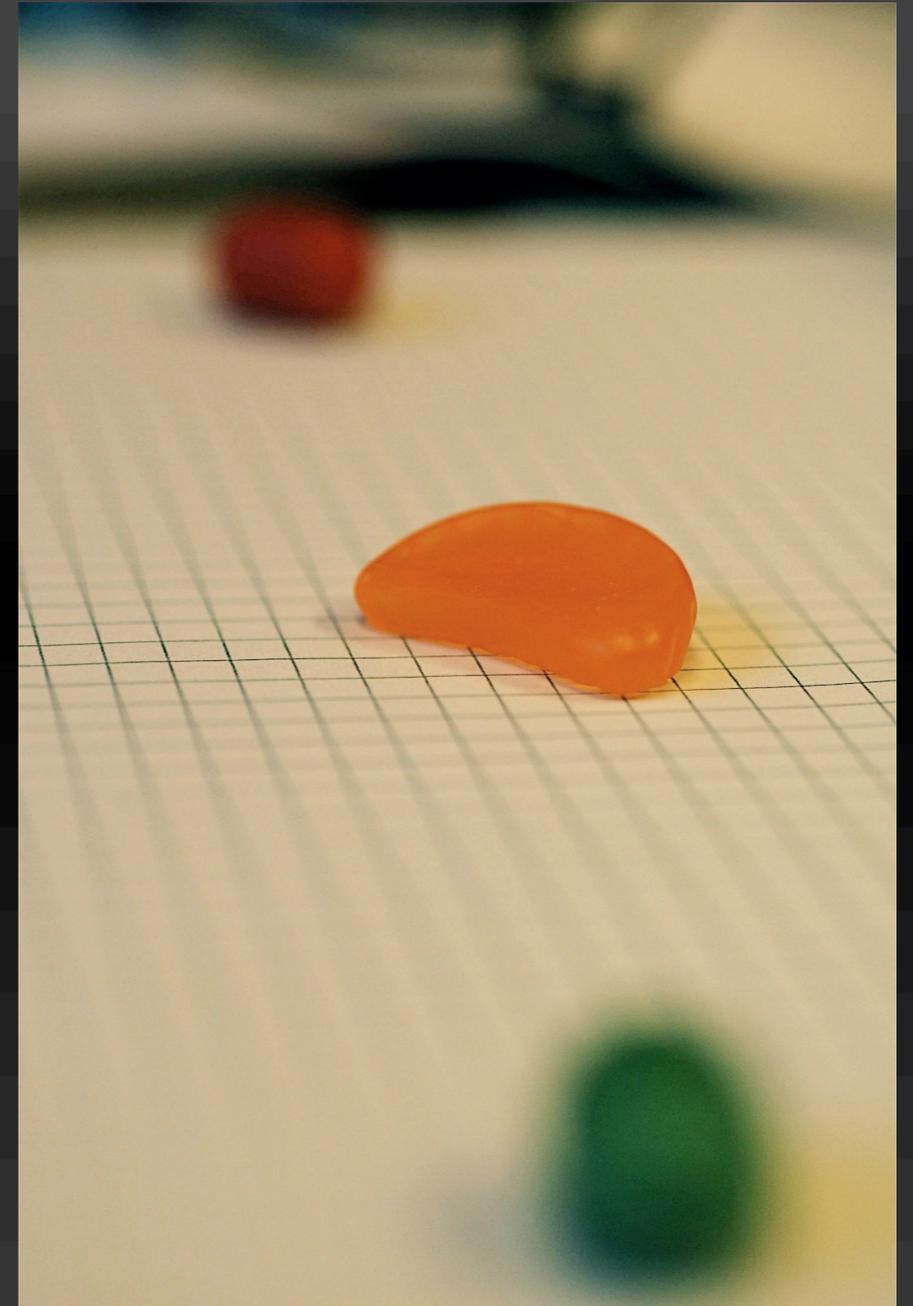
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Motivation

- We want:
 - Motion blur
 - Depth of field
 - Glossy reflections
- Stochastic Sampling!
- Seldom or never used for Real-Time rasterization
- We present :
A new framework for
Stochastic Rasterization (SR)



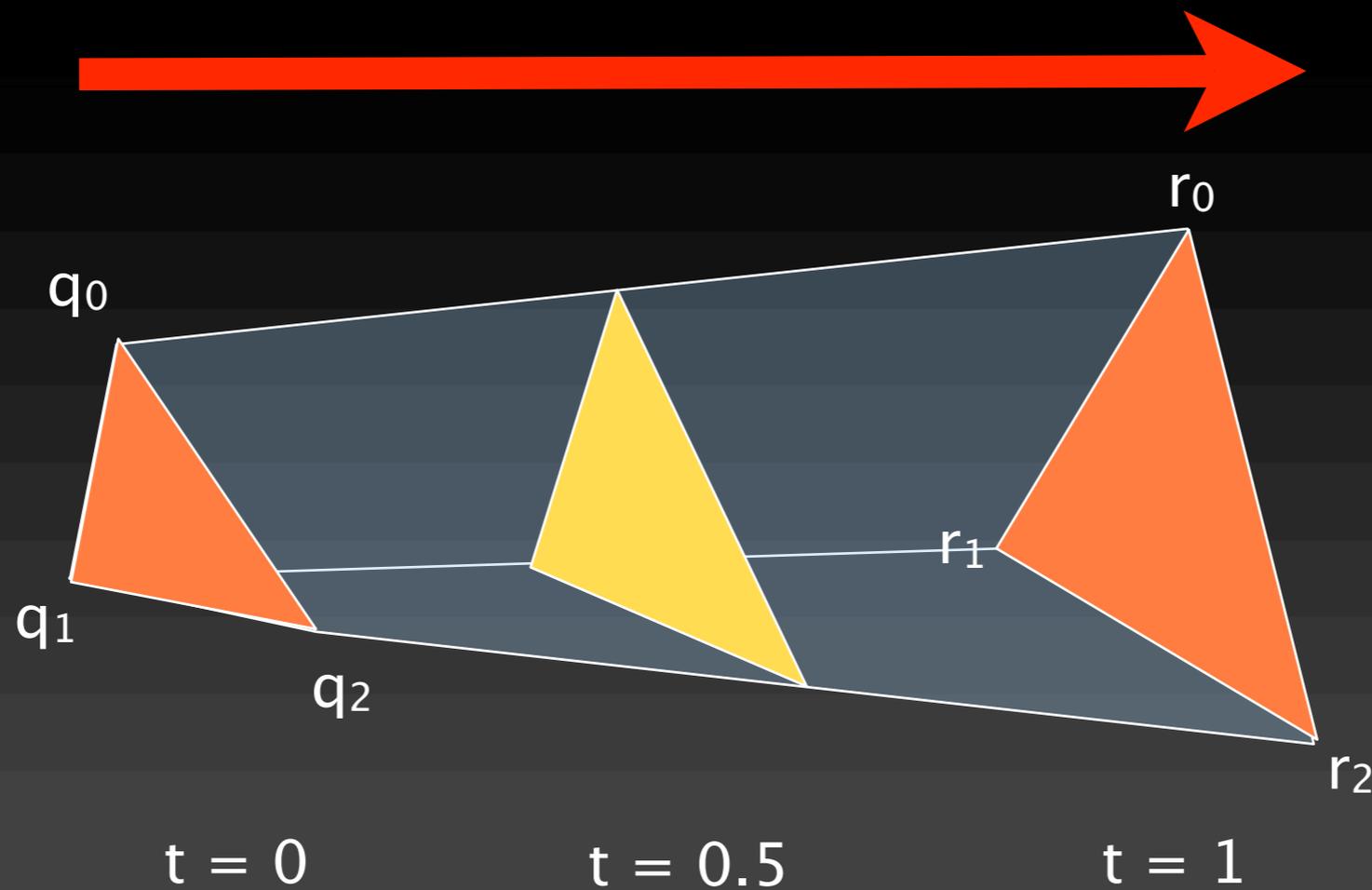
Current HW methods for Motion Blur

- Accumulation Buffering Techniques (**ABT**)
 - Rendering n buffers at different points in time [Deering et al. 88 , Haeberli et al. 90]
- Motion vectors [Shimizu et al. 03]
- Texture space blur only [Loviscash 05]
- Silhouette-based methods [Jones 01, Wloka 96]
- Too slow or too inaccurate

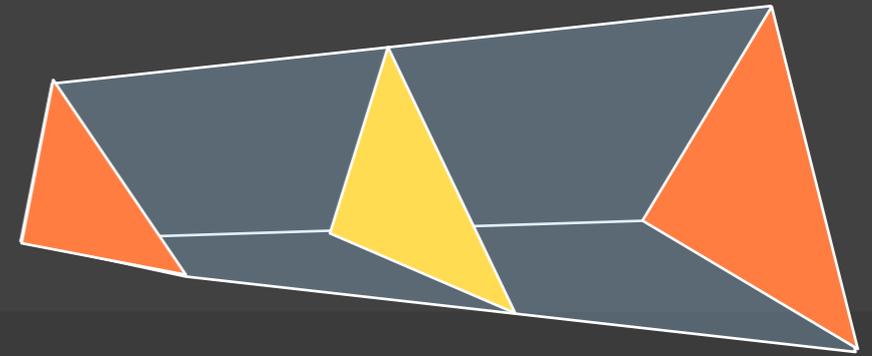


Our approach

- Stochastic rasterization of “moving triangles”
 - We call them “time-continuous triangles” (TCT)



Interpolation of TCTs

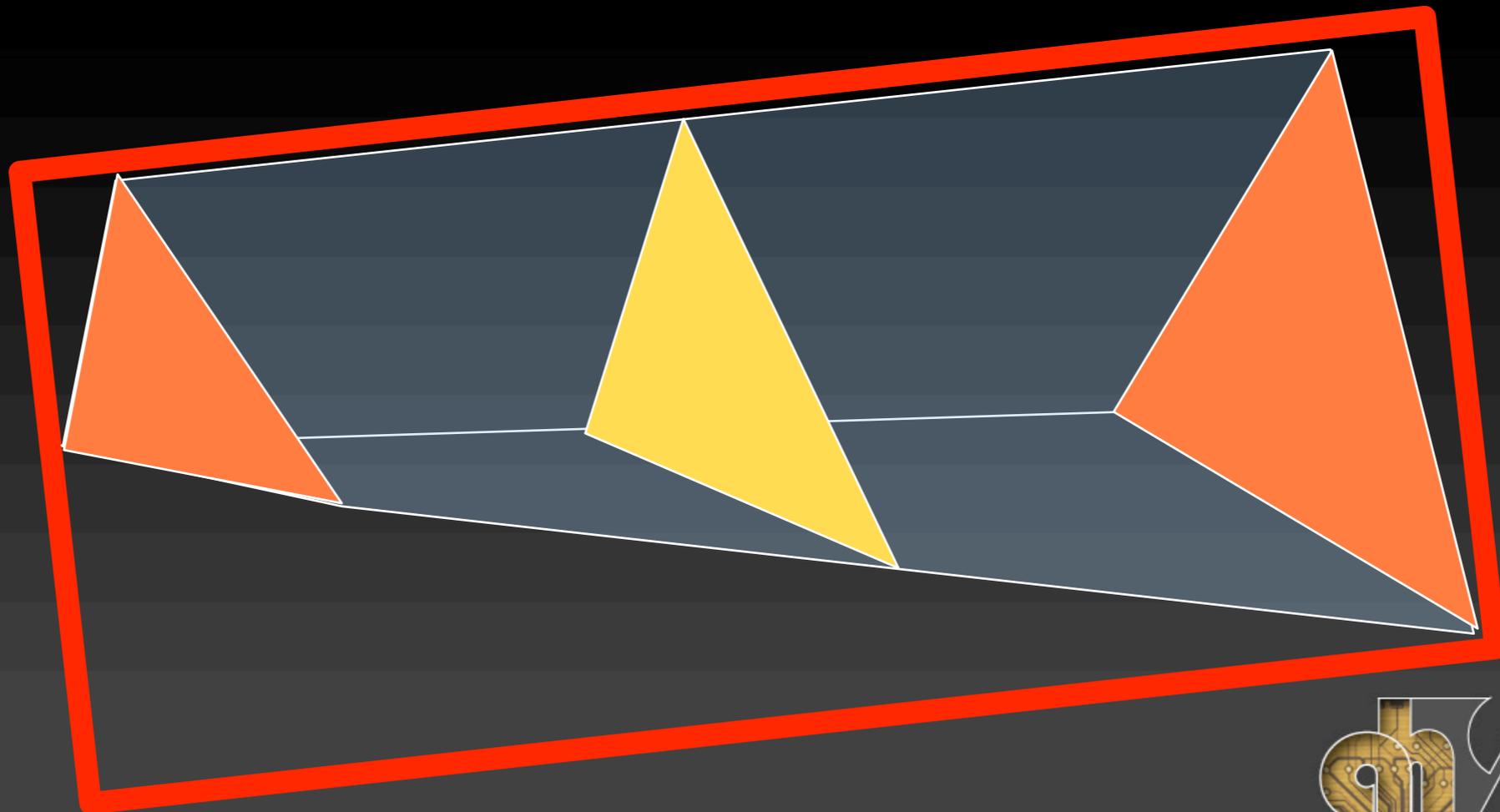


- For simplicity, we use linear interpolation
 - Simple to extend to, e.g., quadratic Bézier curves
- Interpolation is done in homogeneous coordinates
 - **After** application of projection matrix, but **before** division by w
- Important: same result as interpolating in world space!



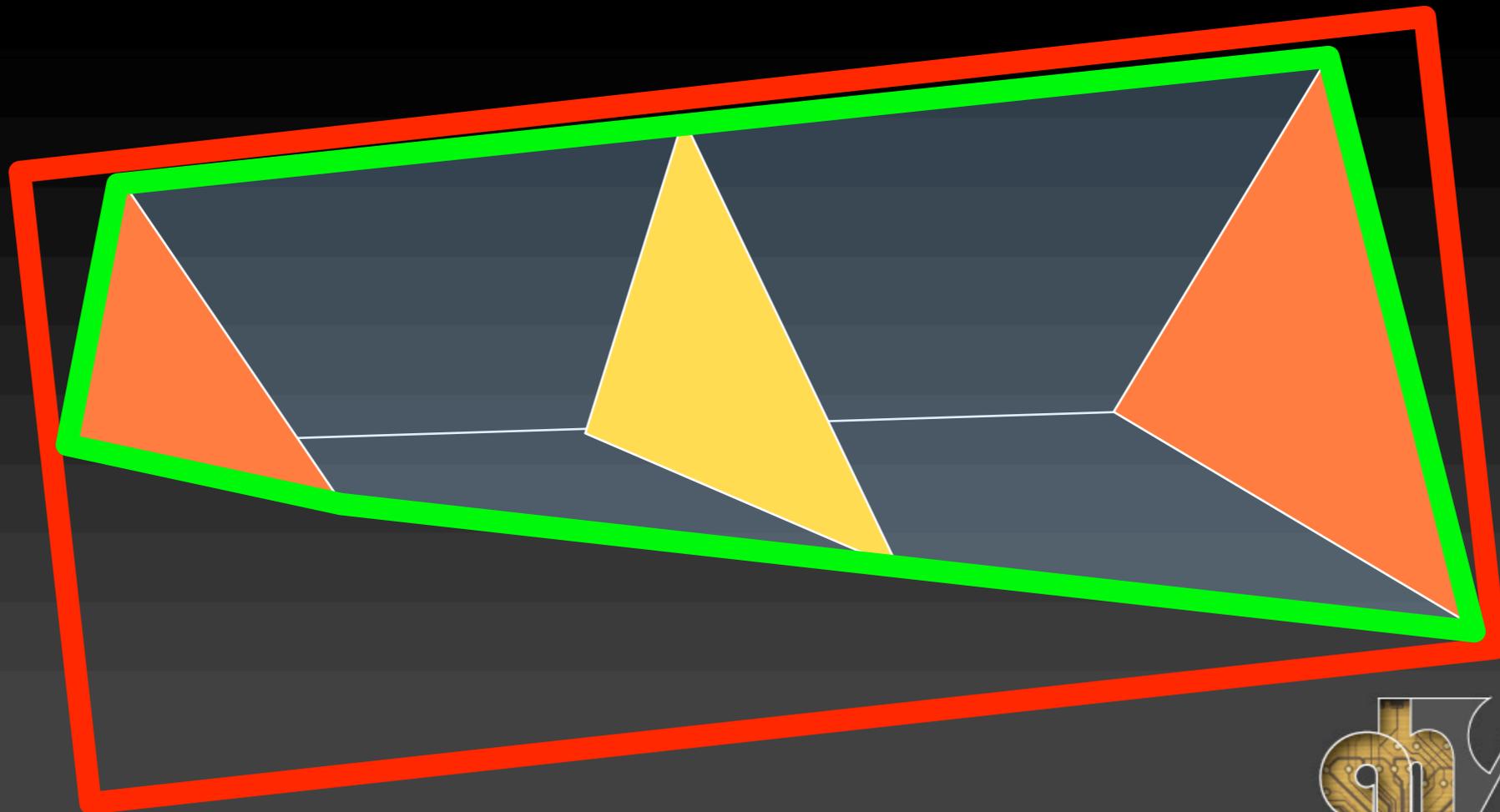
High-level overview (1)

- For each TCT:
 1. Find tight bounding volume (BV) around TCT



High-level overview (2)

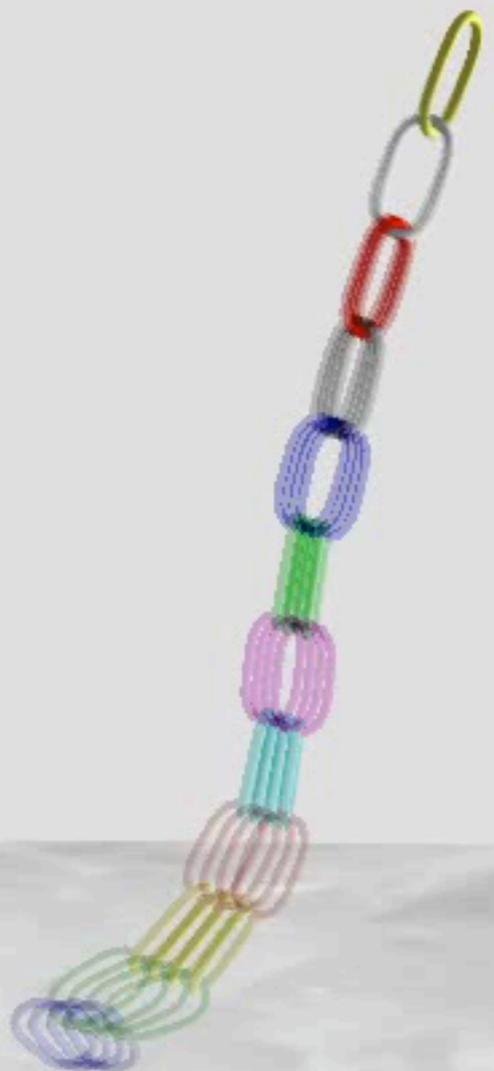
- For each TCT:
 2. Compute **time-dependent** edge functions



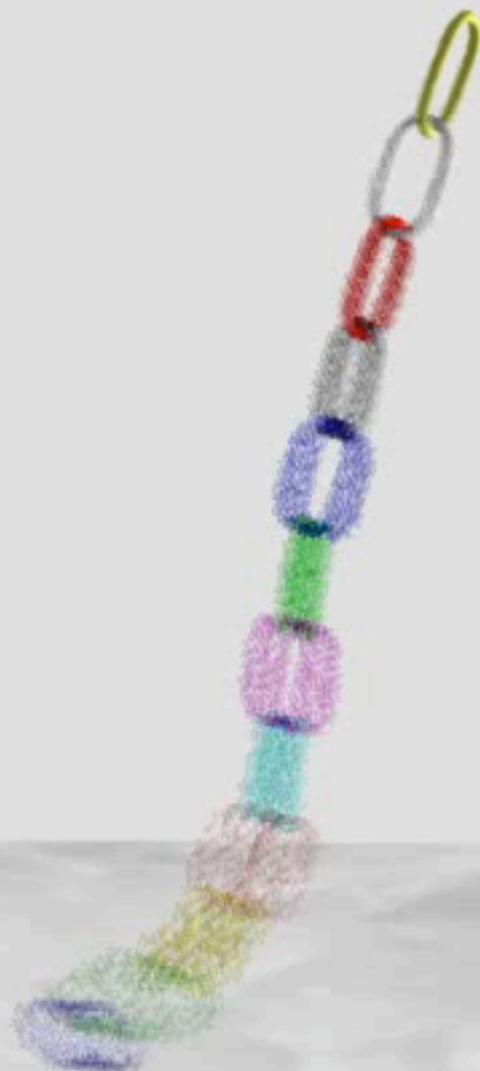
Example - Chain Link

- Accumulation Buffer Techniques (**ABT**) using N images, render a complete scene N times
- Our approach renders N samples in a **single** pass, saving geometry processing and memory bandwidth





ABT (4)



Our (4)

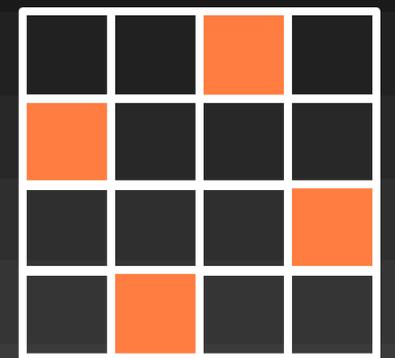


ABT (8)



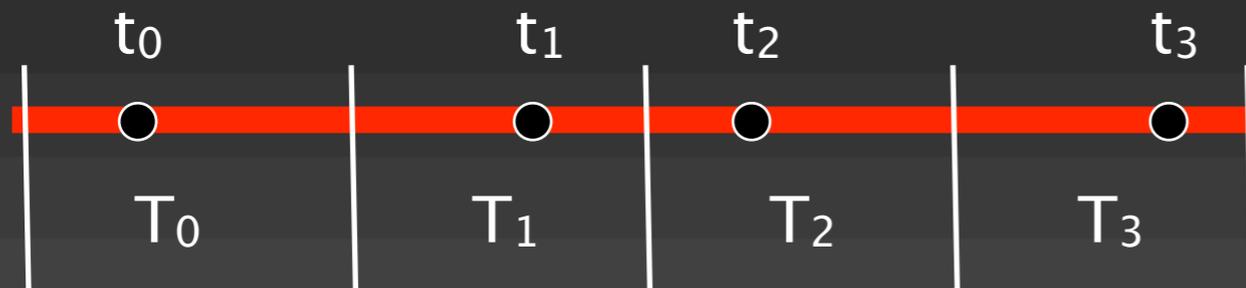
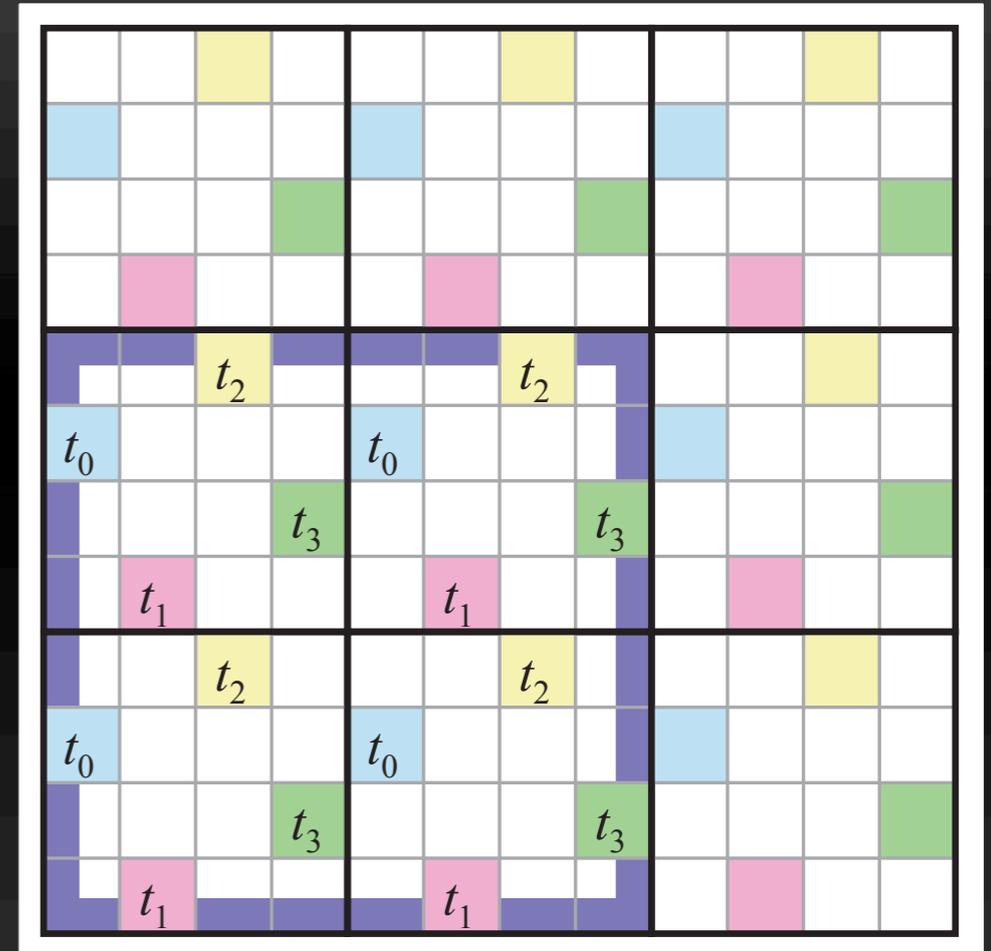
Sampling strategy

- Target:
 - few samples (4-8)
 - piggyback on much of already existing HW
 - comply with **quad requirement** (for derivatives)
 - Evenly distributed samples in space and time
- We describe our strategy using RGSS
 - Used in most GPU:s
 - However, any spatial sampling pattern can be used



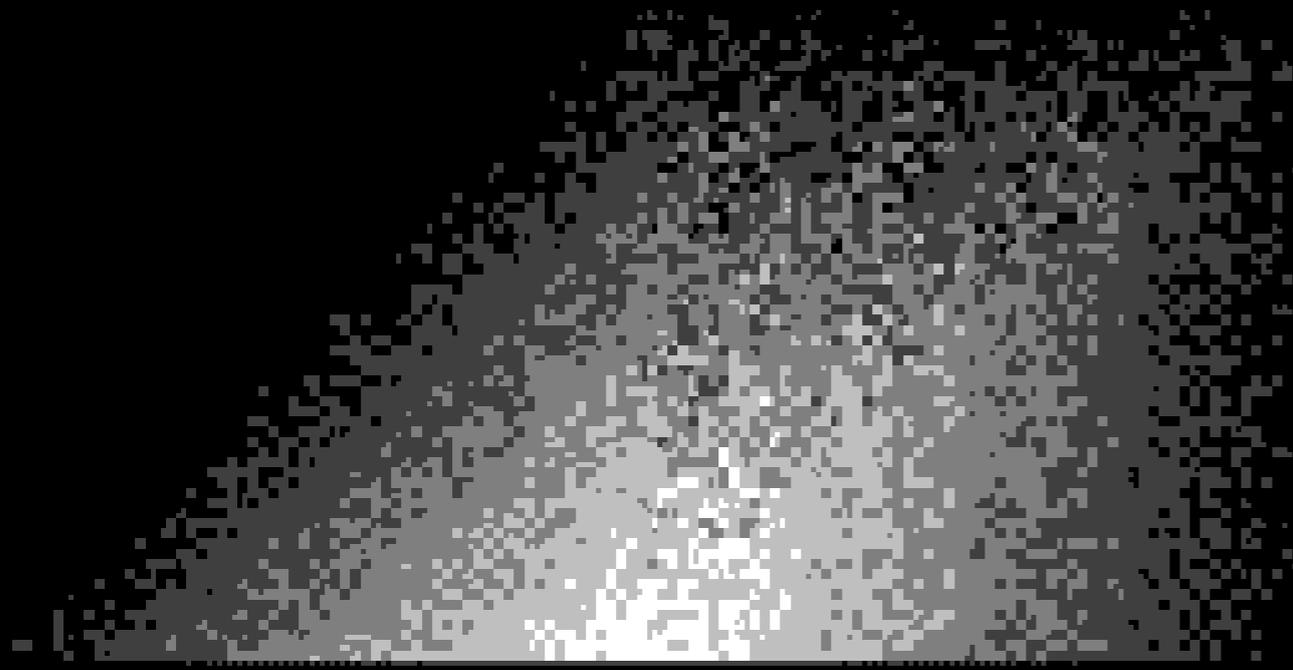
Sampling strategy

- Each sample time, t_i , must exist once per pixel in each quad
- Each pixel has n samples
 $S_i = \{x_i, y_i, t_i\}$
- Jittering

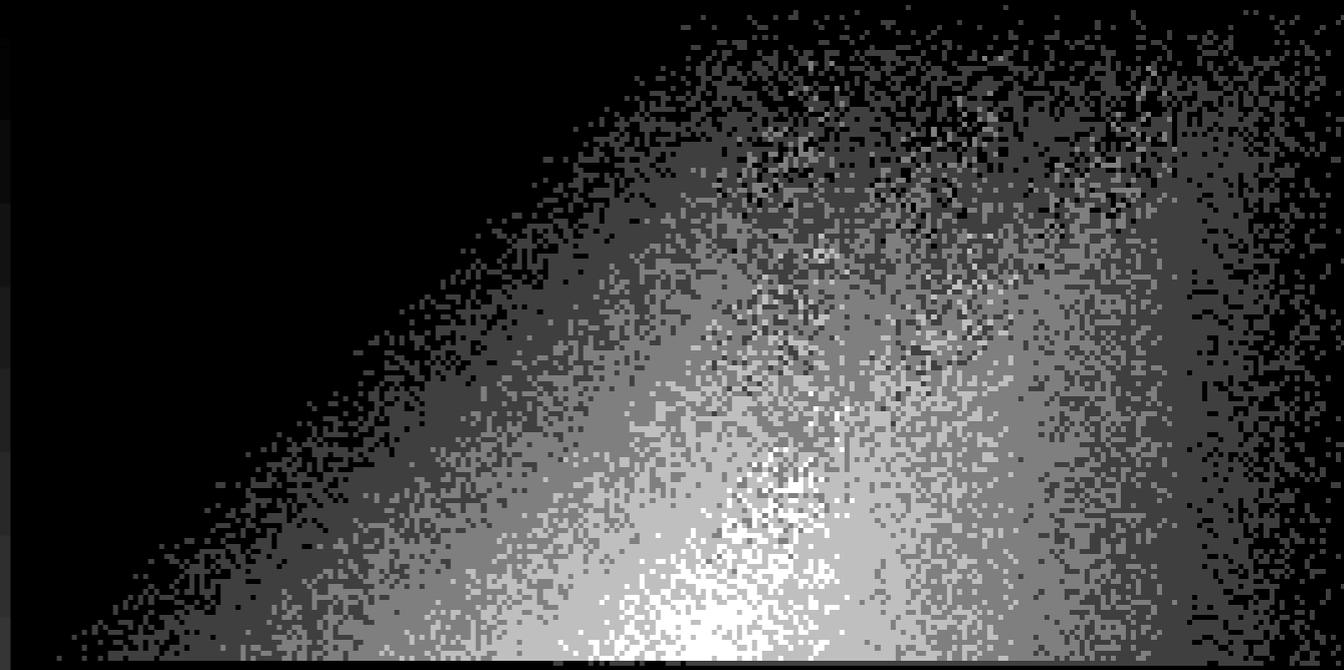


Results

- Bad pixelation due to stamp out “pixels in time” with size of 2x2, instead of optimal 1x1



Our first approach

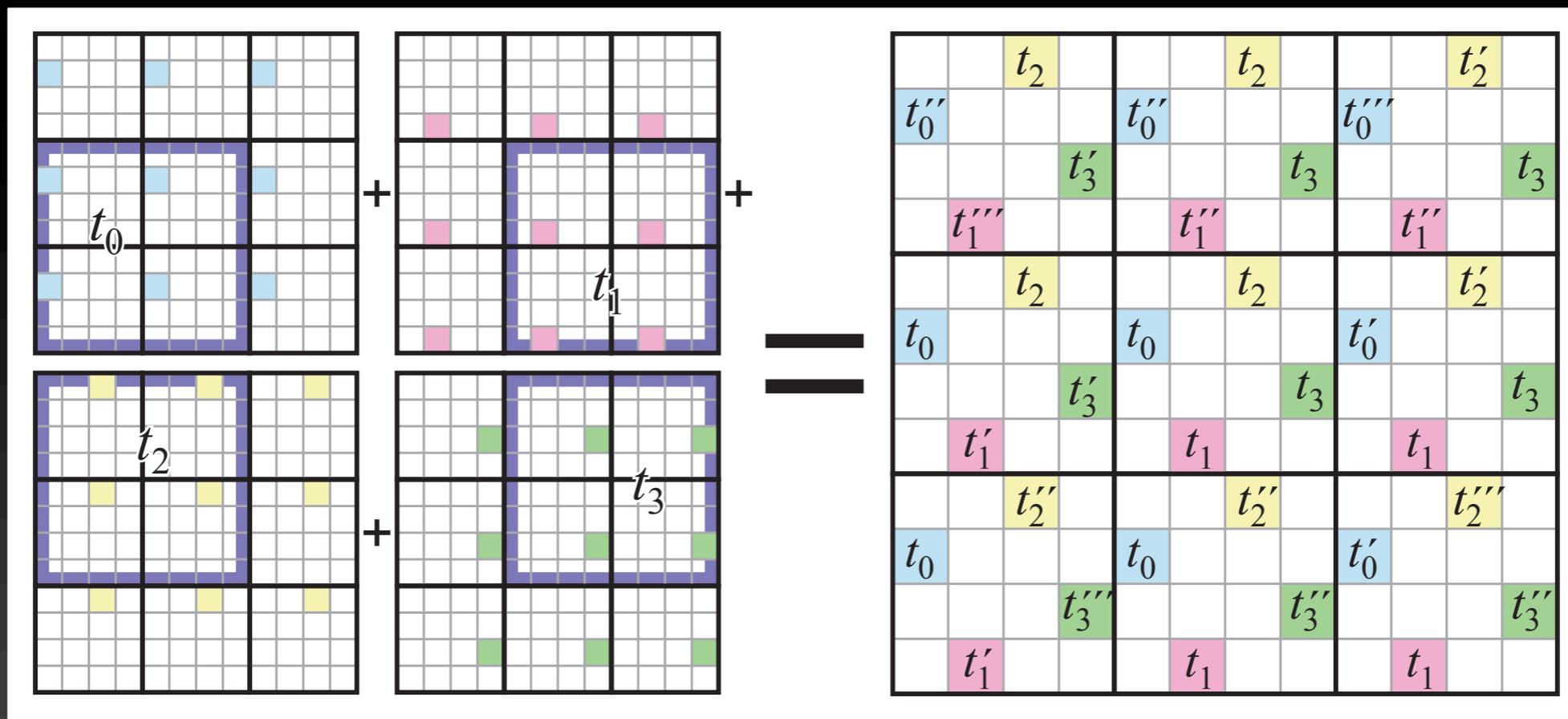


Ideal (four random times per pixel)



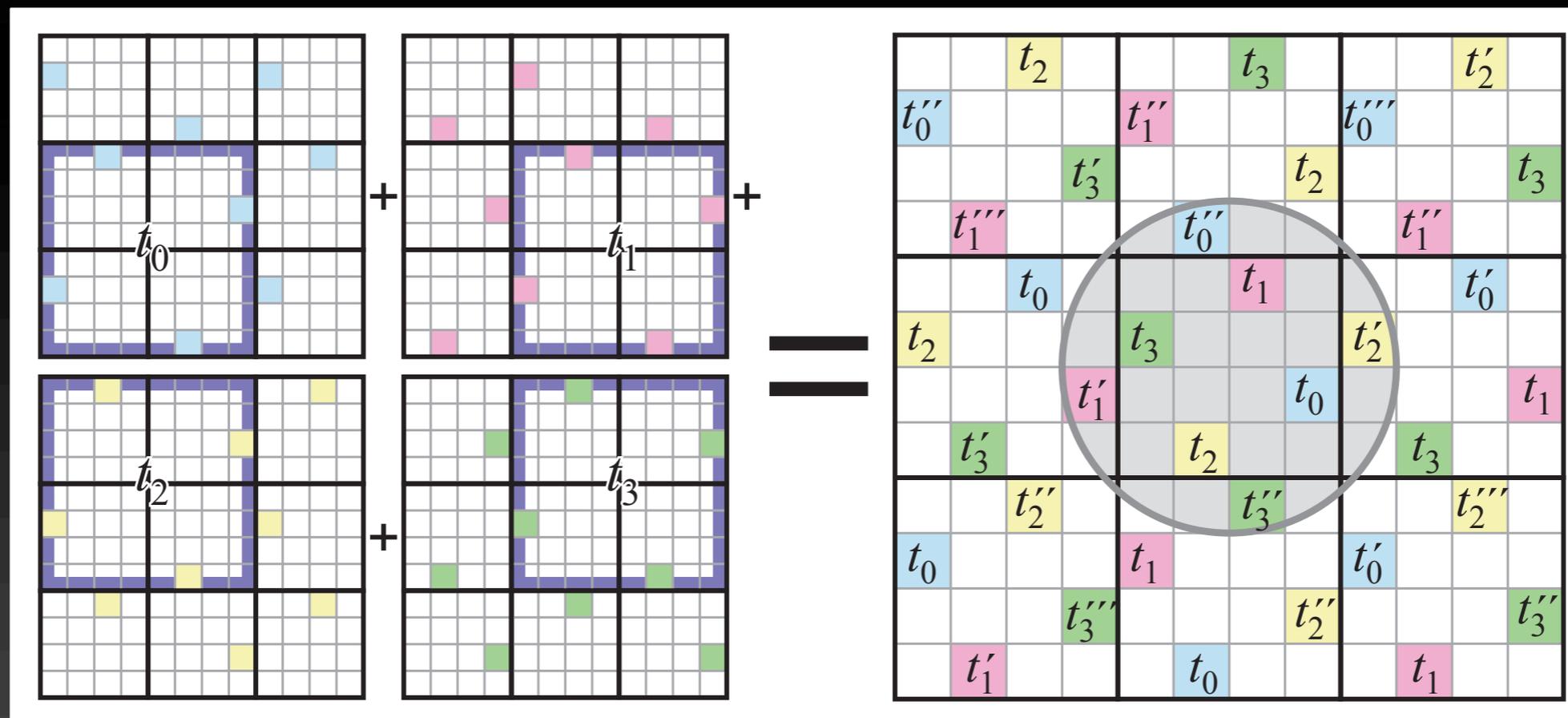
Improved sampling (1)

- Solution: offset the quads depending on which time-interval, T_i , they belong to



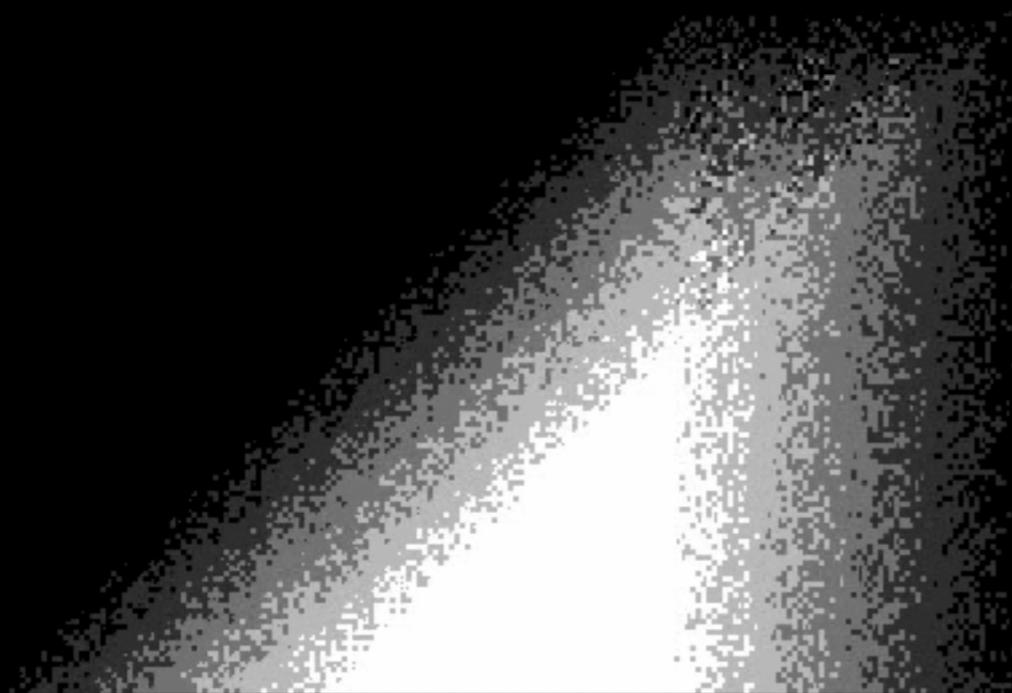
Improved sampling (2)

- Increase size of filter kernel
 - 4 more samples from immediate pixel neighbors

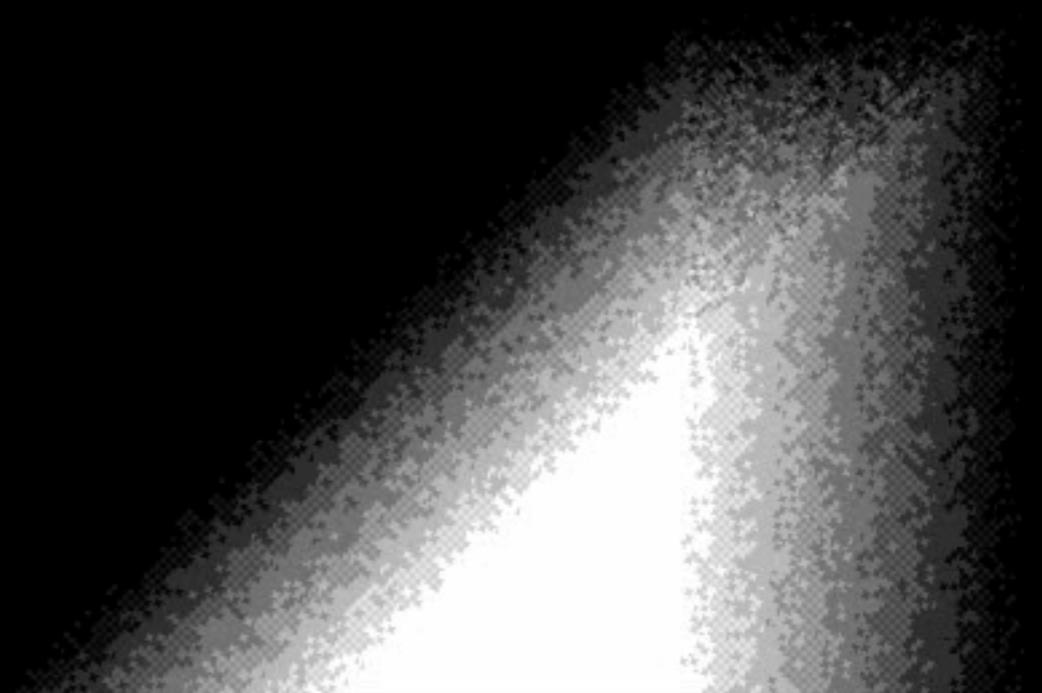


Comparison

- Sampling quality (4 samples per pixel)



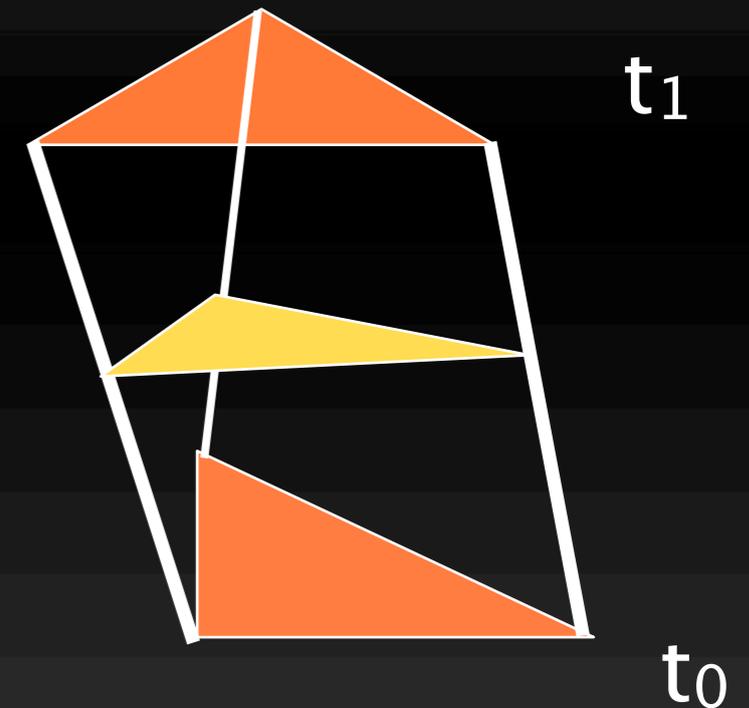
standard filter kernel



increased filter kernel

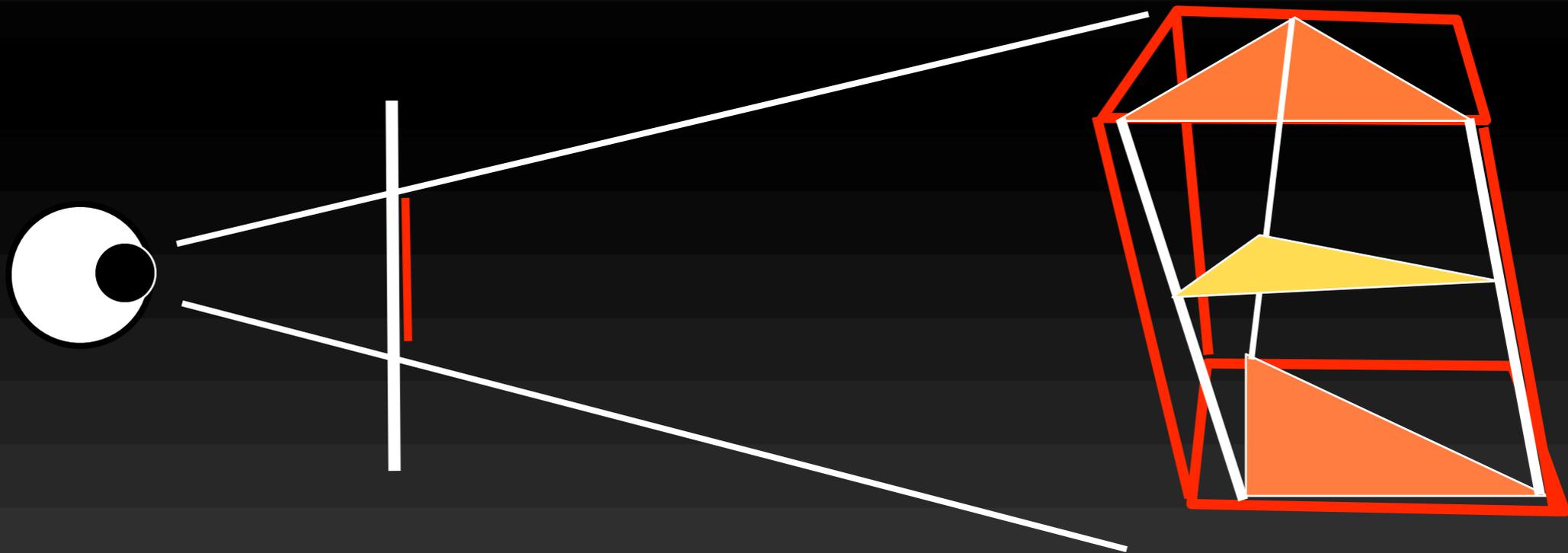
Rasterization of TCTs

- Bad options:
 - Rasterize in screen space
 - TCT: quad surfaces are bilinear patches (not planar)
 - Clipping → headache
 - TCTs can move through the near plane
 - 2D BBox in screen space may be too large [Wexler05]
- We propose a two-level algorithm...



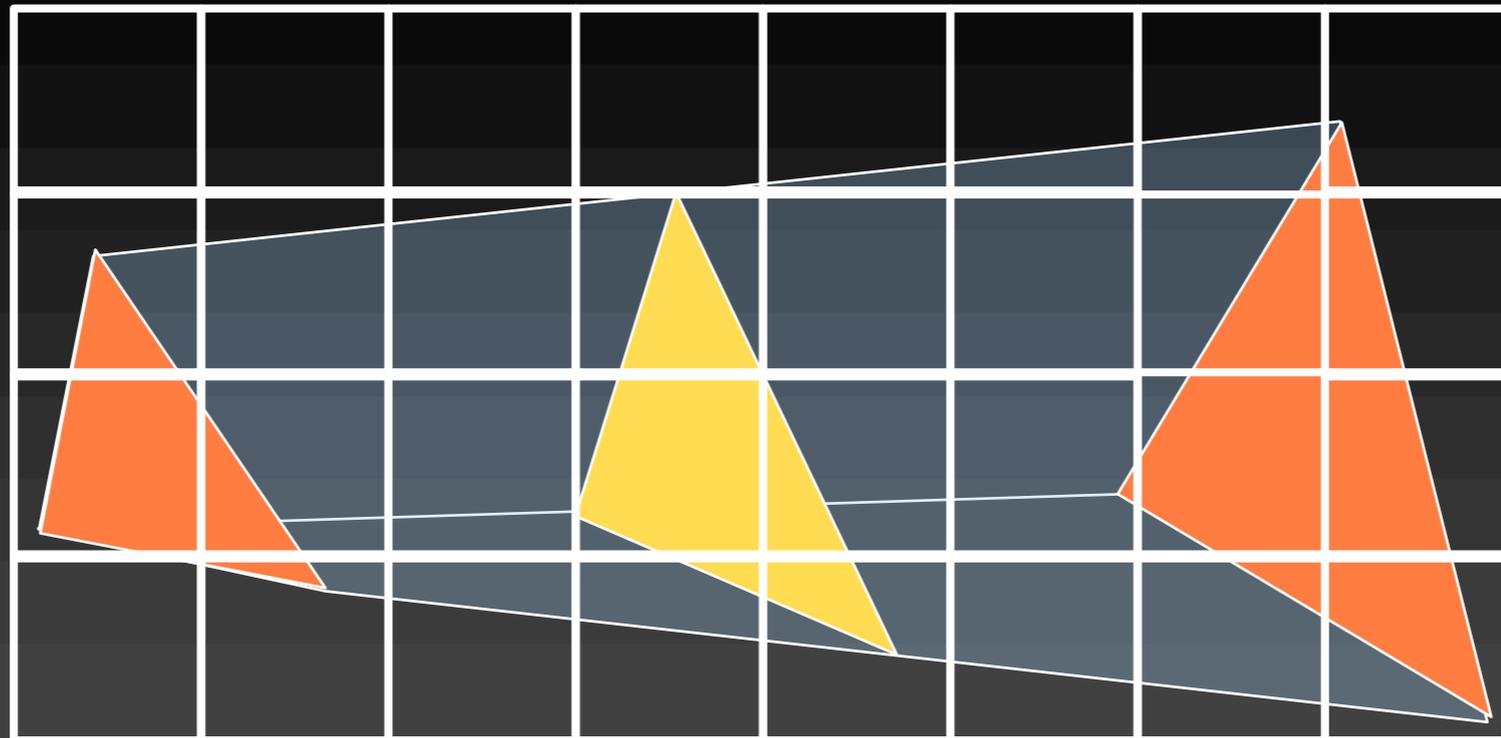
Two-level rasterization of TCT

- Rasterize backfaces of OBB using z-fail (similar to robust shadow volume rendering)



Two-level rasterization of TCT

- For fragments inside OBB, check whether samples are inside using **time-dependent edge functions**



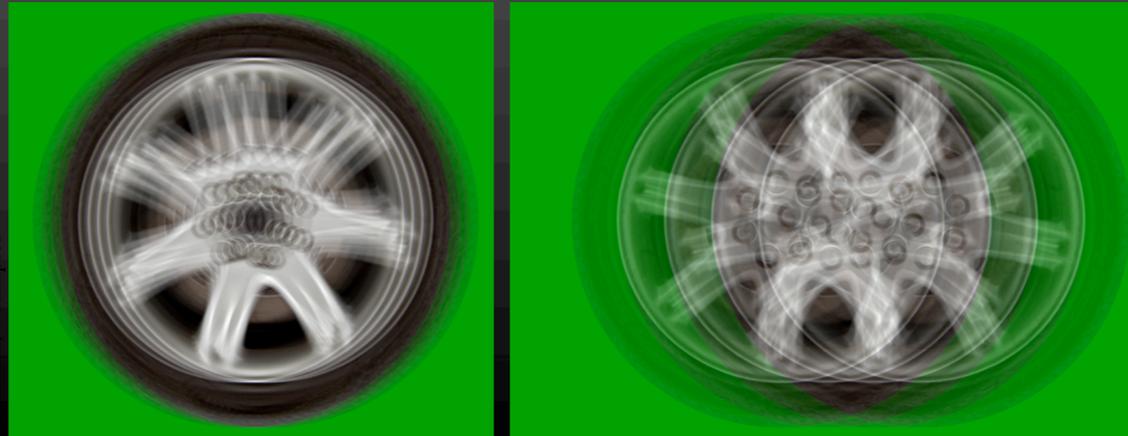
Time-dependent edge functions

- Simple to derive:
 - $e(x_i, y_i, t_i) = a(t_i) * x_i + b(t_i) * y_i + c(t_i)$
 - where, for example, $a(t_i) = f * t_i^2 + g * t_i + h$
- f, g, h only depends on TCT vertices
 - Can be computed during triangle setup
- The **standard** edge functions of a triangle for a particular time, t_i , are obtained from the time-dependent edge functions

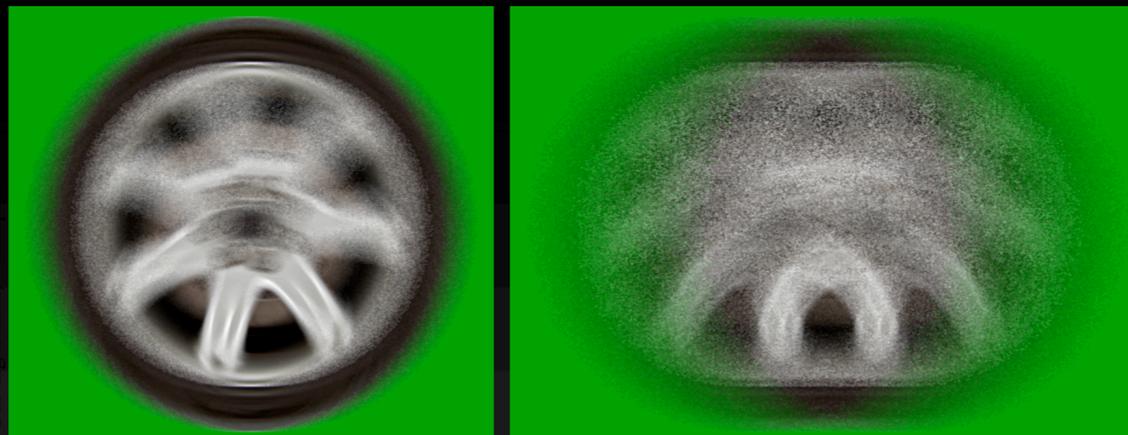


Example - Textured Wheel

ABT, 4 samples



SR, 4 samples



Jittered, 64 samples
(reference)



No blur

Our (4)

ABT (4)



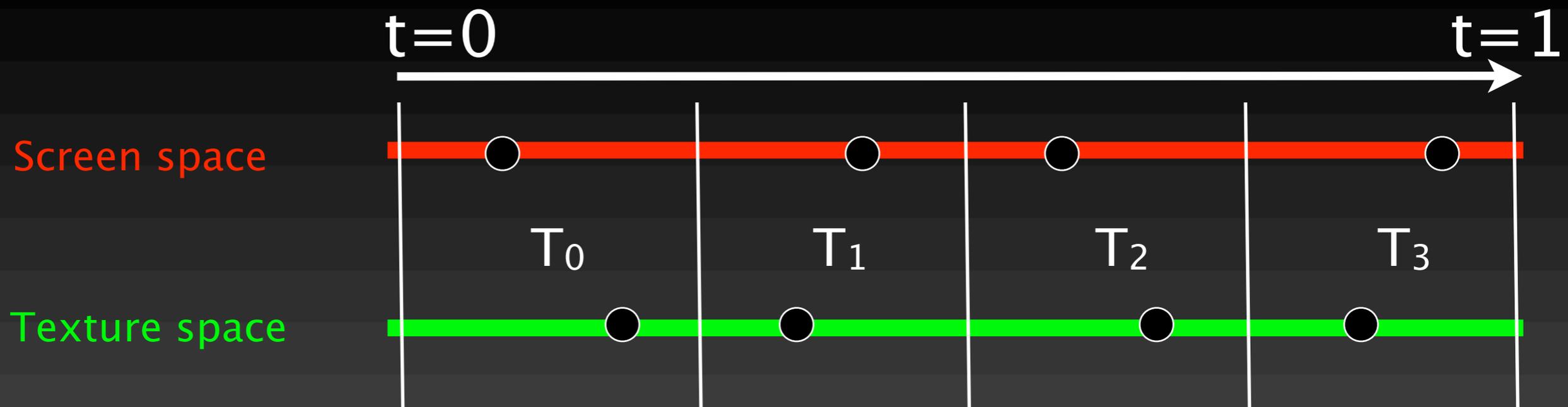
Time-dependent textures

- Motivation: motion blurred geometry without motion blurred shadows.... looks bad!
- Deep shadow maps [Lokovic and Veach 00]
 - Correct only for static shadow receivers, as seen from the light source
- Our approach: let each shadow map pixel have n time-samples
- Support time-dependent reads...



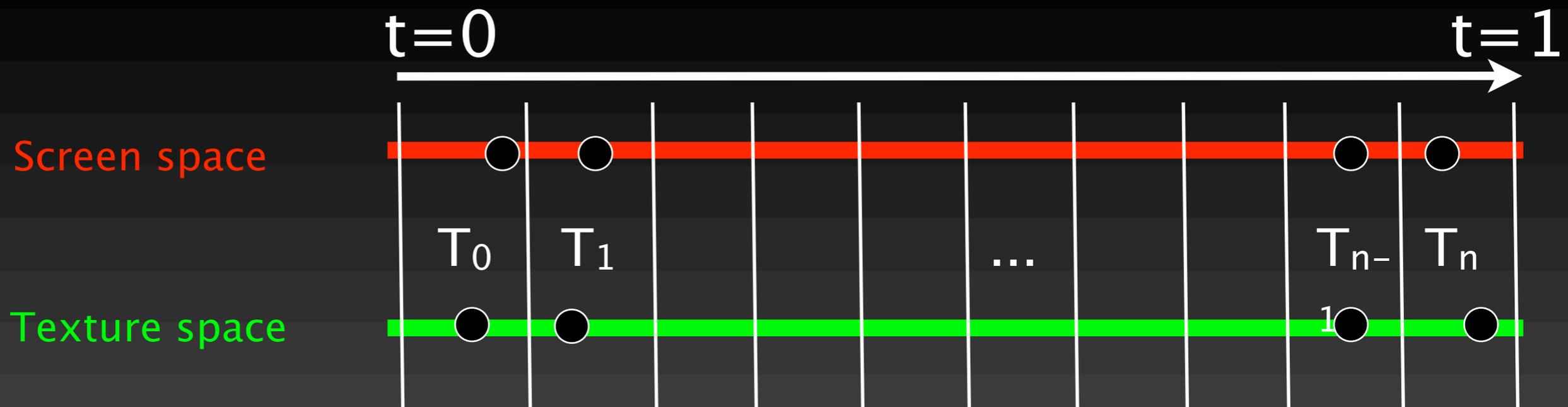
Time-dependent texture reads

- Strategy : Pick sample from same interval in time

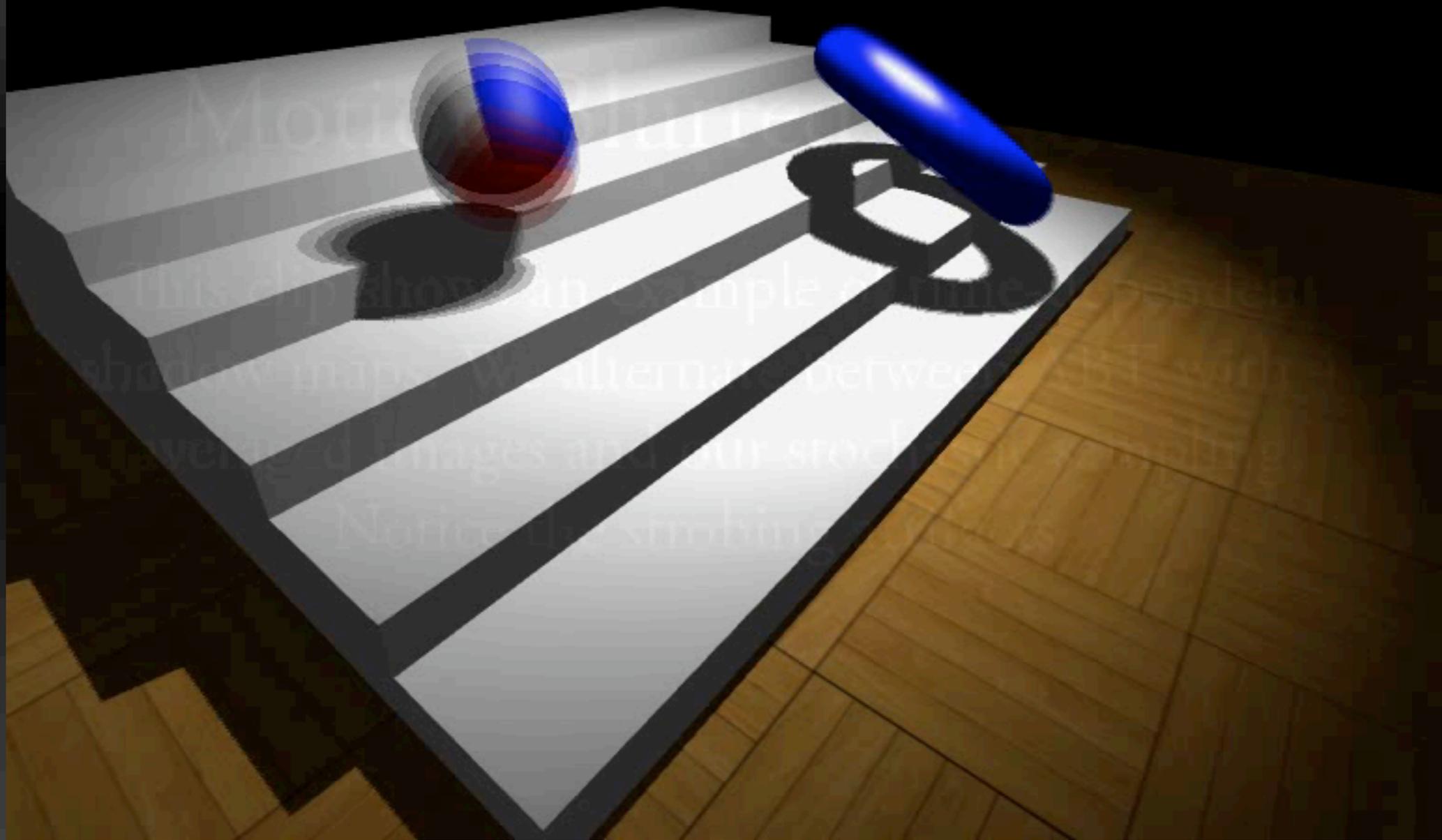


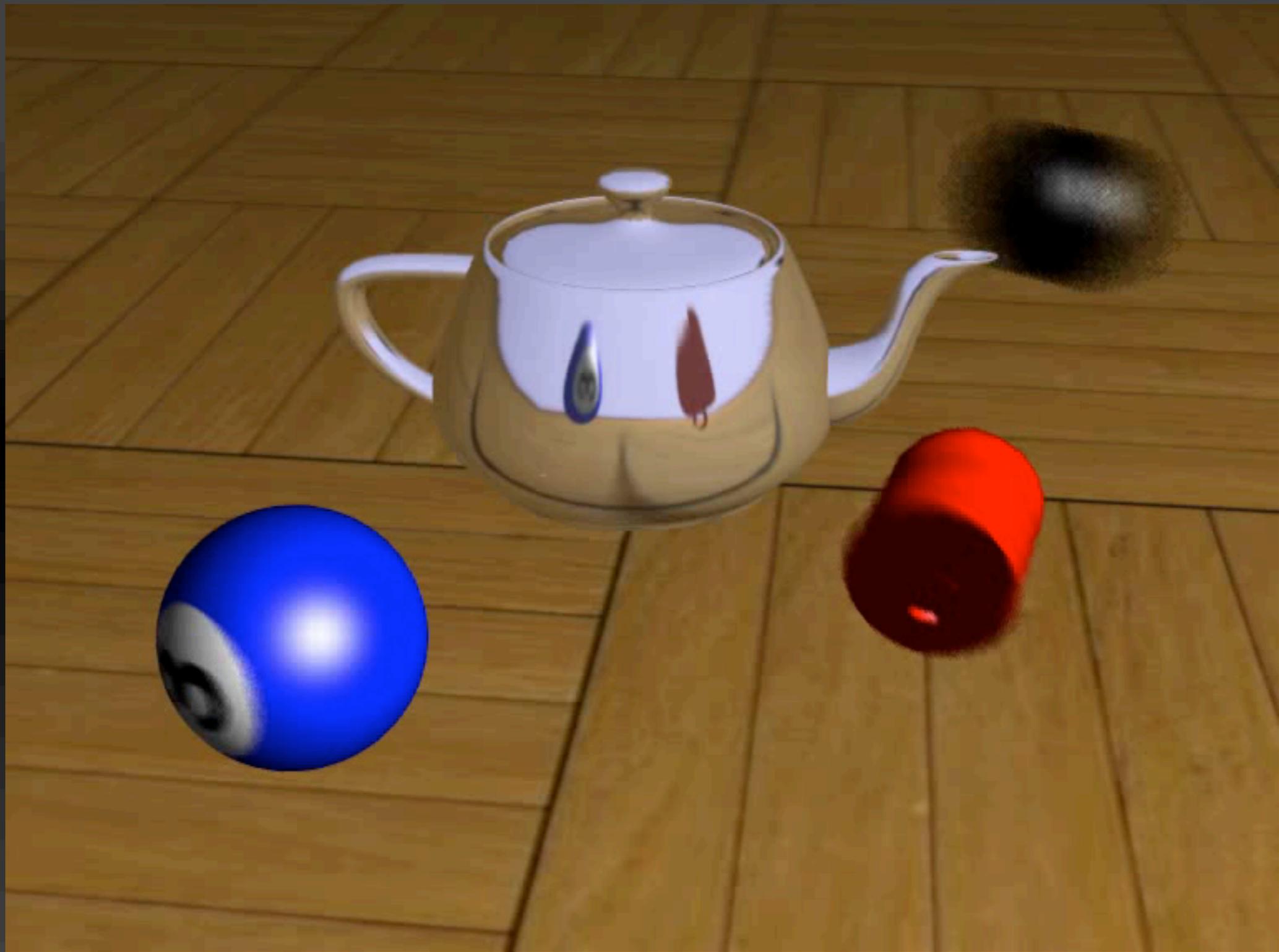
Time-dependent texture reads

- The more time-samples per pixel, the more accurate the result
- We use it for motion blurred shadows and reflections



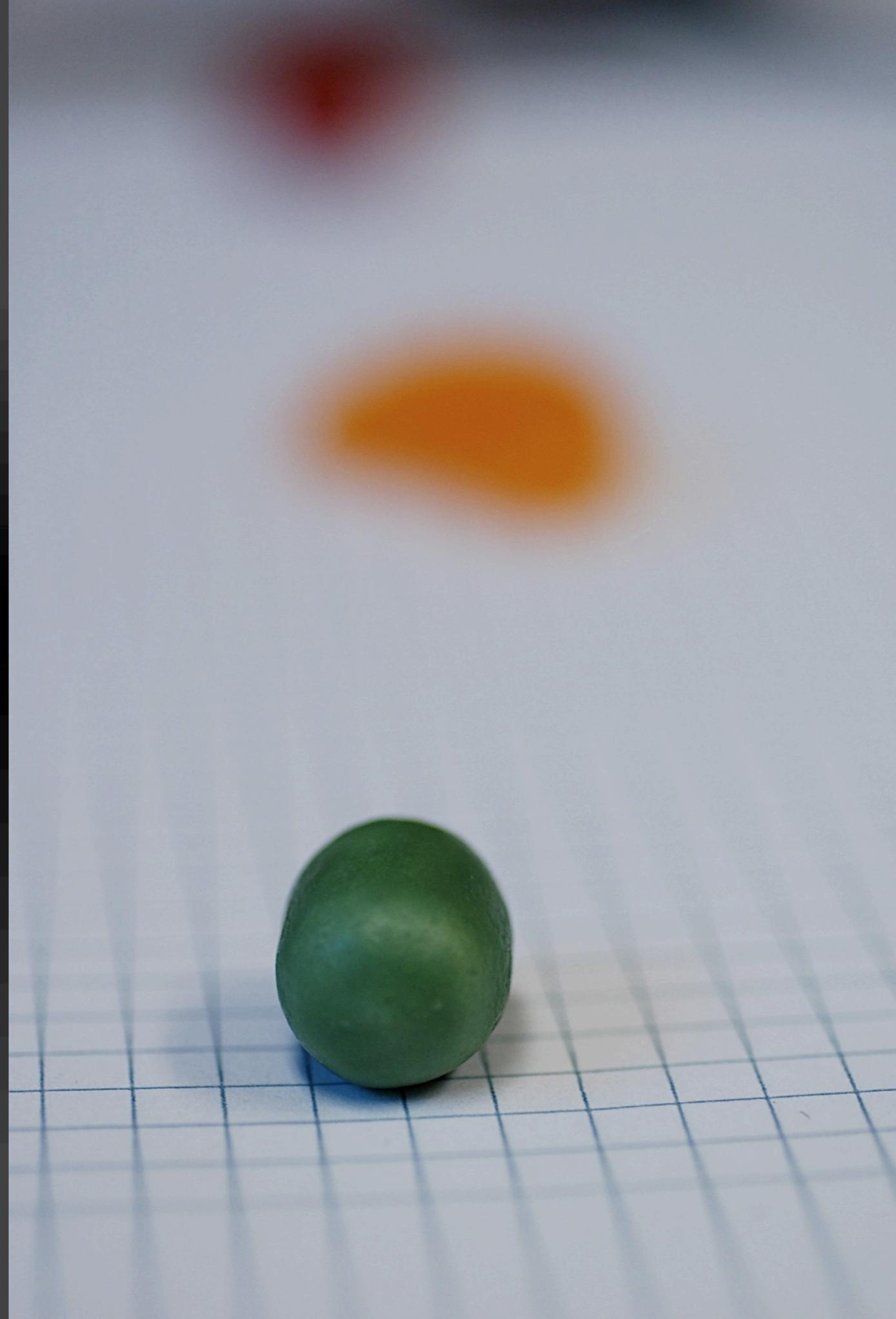
ABT (4)





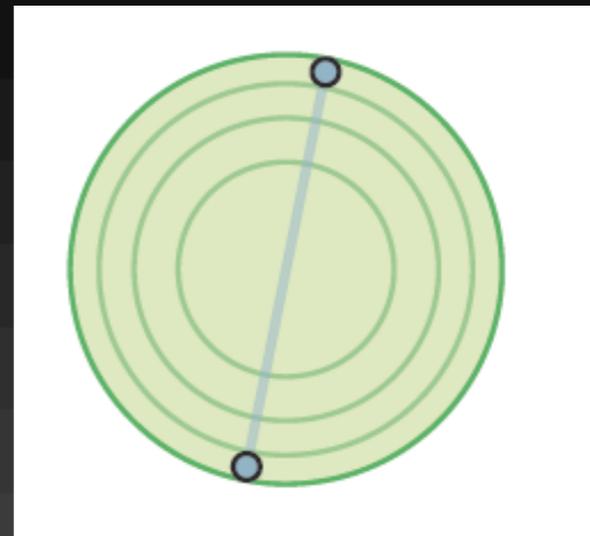
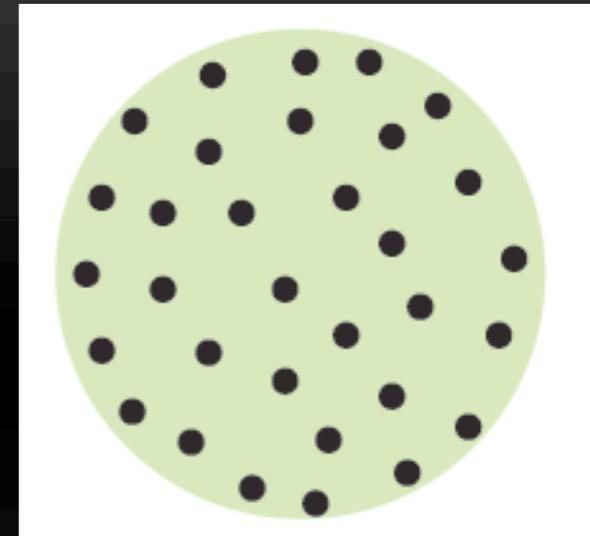
Depth of Field

- A highly desired photorealistic effect
- Great for directing the focus of the viewer
- Usually expensive, or poorly approximated



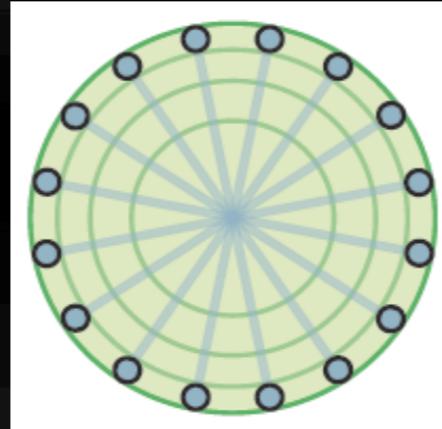
Depth of field

- Standard technique: Many point samples over the lens
- New idea: Use stochastic rasterization in one direction at a time
 - We get “**line** samples”



Render the scene in n passes

- Best strategy: long lines, uniform coverage

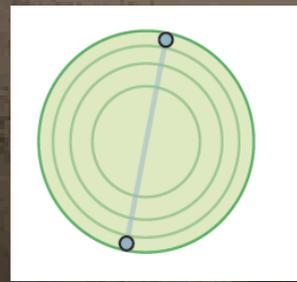


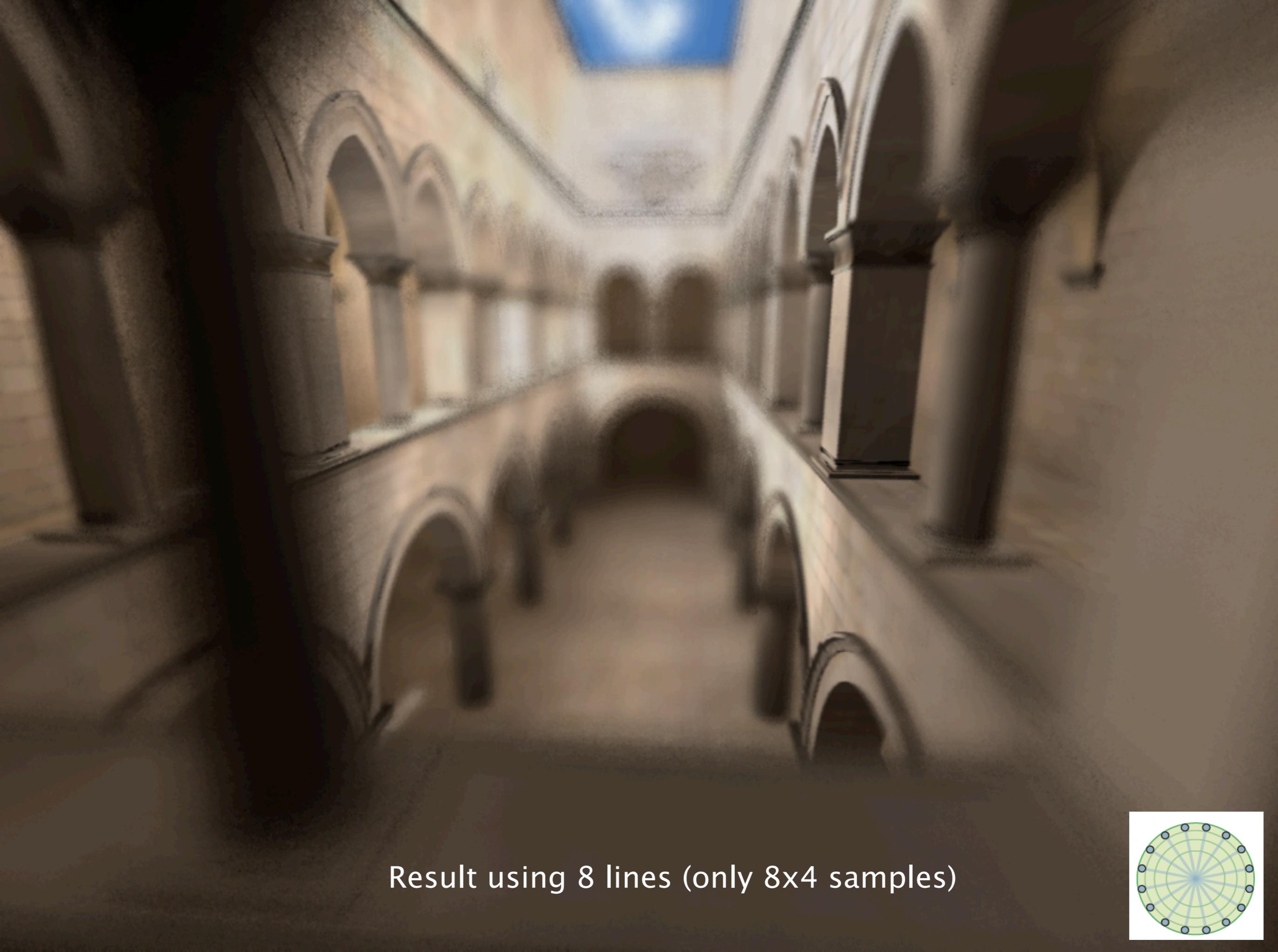
- We correct for oversampling in the center



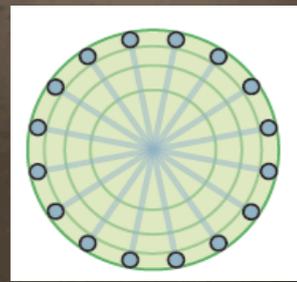


Result using one line (4 samples)



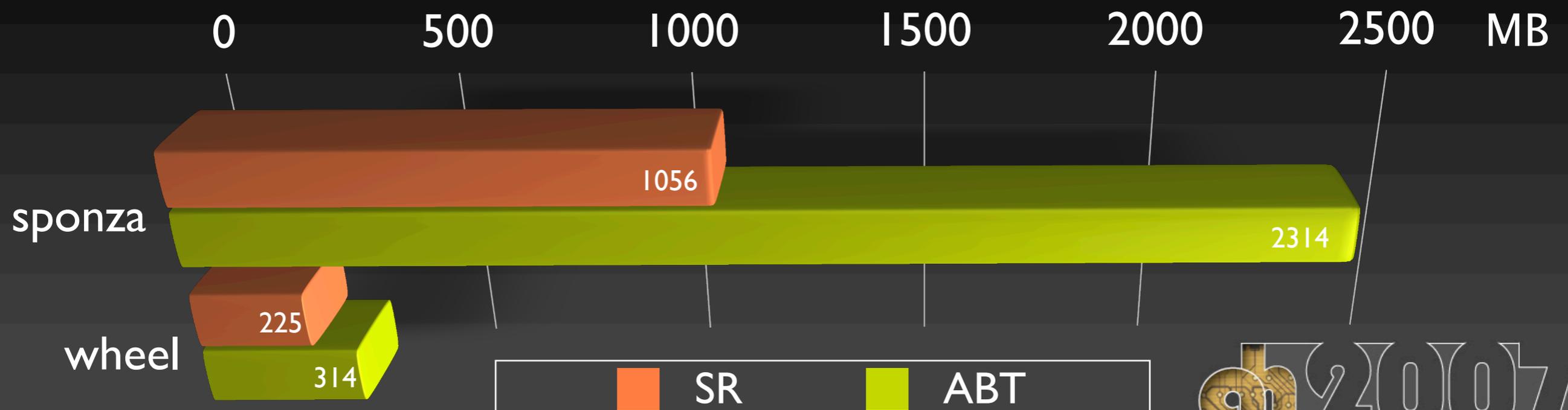


Result using 8 lines (only 8x4 samples)



Bandwidth analysis

- Random sampling could potentially reduce performance in a modern GPU
 - Texturing, depth compression, ...
- Texture bandwidth (6kB cache):



Implementation aspects

- We have a partial implementation of the “inner loop” of our algorithm in fragment prog:
 - nvshaderperf: 11 clock cycles on GeForce 7800 with expected fillrate: 873 Mpixels/s
- Too slow for practical use (e.g Bump, Tex,...)
- Conclusion: need hardware support for time-dependent edge functions and interpolation



Summary

- New algorithm for pseudo-random sampling of dynamic triangles
 - Need minor hardware modifications
- Enables motion blur, depth-of-field, and planar glossy reflections
 - Substantial geometry bandwidth savings compared to Accumulation Buffering Techniques
 - Efficient alternative compared to ray tracing



Thanks for listening!

<http://graphics.cs.lth.se>

