Practical experience shows that the coefficients of Kernel-based interpolants in terms of the basis of translates of the kernel are unstable due to the bad condition of the kernel matrix. However, due to results of S. De Marchi and R. Schaback, the resulting interpolant is stable in function space. This implies that there must be better bases than the standard one. This poster provides a variety of different bases based on factorizations of the kernel matrix. These bases differ in their stability, orthogonality, adaptivity, duality, and computational efficiency properties. Special emphasis is given to the “Newton” basis arising from a pivoted Cholesky factorization. It turns out to be stable and computationally cheap while being orthonormal in the “native” Hilbert space of the kernel. There are efficient adaptive algorithms for calculating the Newton basis along the lines of Orthogonal Matching Pursuit.