Molecular Dynamics Simulations of the Adenosine A2a Receptor: Structural Stability, Sampling, and Convergence

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ABSTRACT: Molecular dynamics (MD) simulations of membrane-embedded G-protein coupled receptors (GPCRs) have rapidly gained popularity among the molecular simulation community in recent years, a trend which has an obvious link to the tremendous pharmaceutical importance of this group of receptors and the increasing availability of crystal structures. In view of the widespread use of this technique, it is of fundamental importance to ensure the reliability and robustness of the methodologies so they yield valid results and enable sufficiently accurate predictions to be made. In this work, 200 ns simulations of the A2a adenosine receptor (A2a AR) have been produced and evaluated in the light of these requirements. The conformational dynamics of the target protein, as obtained from replicate simulations in both the presence and absence of an inverse agonist ligand (ZM241385), have been investigated and compared using principal component analysis (PCA). Results show that, on this time scale, convergence of the replicates is not readily evident and dependent on the types of the protein motions considered. Thus rates of inter- as opposed to intrahelical relaxation and sampling can be different. When studied individually, we find that helices III and IV have noticeably greater stability than helices I, II, V, VI, and VII in the apo form. The addition of the inverse agonist ligand greatly improves the stability of all helices.

INTRODUCTION

The G-protein coupled receptors (GPCRs) are a versatile group of receptors due to their ability to respond to a vast array of neurotransmitters, hormones, and metabolites and trigger a complex cascade of cellular signaling processes. In addition, these receptors are also important targets for numerous biological products and small molecule drugs that have therapeutic values in a diverse range of diseases.1–5 Close to half of all currently marketed drugs are GPCR-targeting;6,7 approximately 24% of the new drugs that reached the market between 2000 and 2009 are GPCR ligands;8 yet only an estimated 10% of all GPCRs are currently targeted.8

The adenosine A2a receptor (A2a AR) belongs to the family of adenosine receptors that also includes the adenosine A1, A2b, and A3 subtypes. These receptors are widely distributed and have therapeutic potential in some of the major disease areas involving the central nervous, respiratory, endocrine, inflammatory, renal, and cardiovascular systems.9 For instance, ligands that target these receptors have been developed to treat Parkinson’s disease (A2a AR antagonists),10–12 diabetes (A1AR agonists),13 and arthritis (A3AR agonists).14

Technological breakthroughs in recent years have seen the emergence of an increasing number of new GPCR crystal structures. To date, the GPCRs whose structures have successfully been elucidated are bovine rhodopsin (2000),15 human β2 adrenergic receptor (2007),16 turkey β1 adrenergic receptor (2008),17 human A2a adenosine receptor (2008),18 human CXCR4 chemokine (2010),19 human dopamine D3 receptor (2010),20 human histamine H1 receptor (2011),21 human M2 muscarinic acetylcholine receptor (2012),22 rat M3 muscarinic acetylcholine receptor (2012),23 human sphingosine 1-phosphate (S1P1) receptor (2012),24 mouse μ-opioid receptor (2012),25 human κ-opioid receptor (2012),26 mouse δ-opioid receptor (2012),27 human nociceptin/orphanin FQ receptor (2012),28 human CXCR1 chemokine receptor (2012),29 NSRT1 neurotensin receptor (2012),30 and PAR1 human protease-activated receptor (2012).31

The availability of GPCR crystal structures has not only led to a greater understanding of these important proteins but also propelled in silico studies of GPCRs to a new height. MD simulations have been performed on numerous GPCRs for various purposes over the years. Among these, studies have been carried out to investigate the molecular properties of GPCRs,32–34 improve the understanding of GPCR–ligand binding and the associated ligand-induced structural changes on the protein,35–37 as well as to provide clues to the receptor activation process.38,39 In addition, in the structure-based design of GPCR ligands, MD has been used to generate conformational ensembles which are used in virtual screening and docking studies.40–43

The robustness and reliability of MD simulations performed on GPCRs are of critical importance due to the widespread use of this technique. Users need to be assured of the reproducibility of the results and the relevance of the data generated before any meaningful conclusions can be drawn. In

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this study, we have sought to apply robust, sensitive, and quantitative metrics to investigate this and also to attempt to answer some of the common technical questions that may arise while performing these simulations: How good are my models/systems? How long should the equilibration process be? Are my results sufficiently reliable and reproducible such that meaningful observations can be made and conclusions drawn? A detailed understanding of the inherent limitations of the technique and the errors that may arise will help the users to be judicious in interpreting their results.

For this study, 200 ns simulations of the A2a adenosine receptor (A2a AR) in its apo form as well as in complex with an inverse agonist ligand (ZM241385) were carried out. The simulations were performed in triplicate, replicates differing only in their initially assigned velocity distributions. Using principal component analysis (PCA), we have systematically compared the replicate simulations and assessed the convergence and reproducibility of the results. PCA was used to study the molecular motions of the A2a AR at different levels: (1) the whole protein, (2) the transmembrane (TM) regions, (3) within helices I–VII individually, and (4) between the TM helices (i.e., looking at the interhelical dynamics of the TM region after removing all intrahelical motions). PCA is an ideal tool to study molecular behavior because of its ability to reduce the dimensionality of complex molecular motions to a small number of large-scale, often functionally important modes. It is also a powerful tool that provides quantitative metrics to test whether two different simulations are exploring the same conformational space and the level of sampling that occurs in a simulation.

PCA has been used in a number of studies to investigate the molecular motions of proteins including GPCRs. The issues of sampling time length, simulation convergence, and the difficulties in assessing and achieving a fully converged sampling have been recurrent themes in these works. In the earlier studies, time scales ranging from subnanoseconds to 10 ns have highlighted the problem of insufficient simulation time. The difficulties in identifying reliable modes have become apparent in these studies. While Amadei et al. have concluded that the determination of essential and near constant subspaces could be achieved in simulations of a few hundred picoseconds, later studies with up to the hundred nanosecond time scale have shown that convergence and undersampling are still a problem. In a recent study, Romo et al. have conducted microsecond scale simulations on proteins of varying sizes and measured the extent of convergence with the age-old problem of sampling and convergence in MD, have also revealed interesting dynamic behaviors associated with the helices which change upon ligand binding.

**METHODS**

**Model Construction.** The crystal structure of engineered A2a AR at 2.6 Å resolution (3EML) was obtained from the Protein Data Bank. The 160 residue long T4-lysosome portion (N1002–N1161), SO42− ions, and stearic acid molecules were deleted. The ligand ZM241385 was in left place for the liganded model and (ii) removed to create the apo form. Crystallographic waters were preserved. The missing residues in the crystal structure were added using the **loop** search tool in SYBYL 6.5. These were M1-13 (N-terminus), P149–H1155 (extracellular loop 2, EL2), and K209–A221 (intracellular loop 3, IL3). The final structures lacked the C terminus and contained only residues 1–310. A brief round of steepest descent energy minimization was performed using the GROMOS96 53A6 force field in GROMACS 4.5.3 to remove any steric clashes in the models arising from the loop building. The quality and integrity of the final A2a AR models were checked using PROCHECK and WHATIF. For both models, the validation programs did not report any critical problems and more than 99% of the residues were found in the allowed region of the Ramachandran plot. Therefore, they were considered fit for production simulations.

**ZM241385 Parameterization.** PRODRG beta was used to generate the topology of ZM241385 and to assign atom types and bonded parameters. To deal with the potential lack of accuracy of PRODRG generated charges and charge groups, these values were reassigned following the strategy suggested by Lemkul et al. This task was achieved by deriving charges and charge groups from known functional groups found in the amino acid residues topologies defined in the GROMOS 53A6 force field. (The topology can be found in Supporting Information Figure 1.)

**System Setup and Simulation Protocols.** The energy minimized A2a AR models (apo and liganded) were inserted into a pre-equilibrated and fully hydrated POPC lipid bilayer of 340 molecules. The bilayer was constructed and tailored to the intended size using the original “Berger lipids” (obtained from http://moose.bio.ucalgary.ca/). The embedding process was achieved using the _g_membed_ tool which was available as part of GROMACS 4.5.3. The water model used was the single point charge (SPC) model. To remove the net charge of the system, 11 chloride ions were added as counterions. The equilibration process started with a 100 ps simulation under NVT conditions at 310 K. The simulation parameters were as follows: electrostatic interactions were treated with the smooth particle mesh Ewald (PME) method with a short-range cutoff of 1.2 nm, van der Waals interactions were also given a short-range cutoff of 1.2 nm, all bonds were constrained with LINCS to enable a 2 fs time step to be applied, and temperature was coupled to the v-rescale thermostat with a time constant of 0.1 ps. Coordinates were written to the output trajectory file every 100 ps. Position restraints were applied to the heavy atoms of the A2a AR model along the x, y, and z axes as well as the phosphorus atom of POPC along the z axis only, where x–y is the membrane plane. Under these restraints, the water molecules were allowed to move in all directions while the lipids were able to do so only in the x–y plane. After NVT, three separate rounds of NPT were carried out to allow the position restraints to be gradually released. Maintaining the
restraints from the NVT stage, the first round of NPT was carried out for 10 ns, with semi-isotropic pressure coupling to the Parinello-Rahman barostat and a time constant of 1 ps. The second round was performed for 20 ns with position restraints applied only to the protein. All the position restraints were removed in the third round, and the systems were allowed to equilibrate for 40 ns. Finally, production simulations of 200 ns were performed in triplicate under the same NPT conditions. The only difference between replicates was in the initial velocity assignments at the start of the dynamics. Typically, ca. 20 ns of simulations could be achieved per day using ten Quad-Core 3.00 GHz Harpertown CPUs and 8 Gb of RAM.

**Analysis.** Principal component analysis was performed using our in-house toolkit pcazip (http://holmes.canres.nottingham.ac.uk/pcazip). The GROMACS generated trajectories which contained 2000 snapshots (coordinates were saved every 100 ps) of the system were compressed and processed using these tools. In all cases, the data for the three replicates for each of the apo and ligand-bound systems was combined into a common subspace. Focusing on the backbone of the protein, the analysis was divided into four parts. First, the protein was considered as a whole. This was followed by the analysis just of the TM region (i.e., excluding all loop residues). Next the pure interhelical motions of the TM region were studied. To achieve this, for each snapshot in each trajectory, copies of each individual helix, in the crystal structure conformation, were least-squares fitted to the respective sections of the snapshot structure and used to generate a pseudotrajectory in which the seven helices appear to move relative to each other as rigid bodies. This was then used for the PC analysis. Finally helices I–VII were analyzed individually (see Supporting Information Table 1 for residues found in each helix). To visualize the major relaxation processes, we looked at the trajectories when projected onto the two-dimensional subspace defined by the top two principal components (PC1 and PC2). In this study, PC1 and PC2 alone typically account for about half of the overall motions (importance of the remaining PCs decrease dramatically thereafter). Therefore they are deemed an adequate, albeit rough, representation of the overall dynamics of the system. However, PC3 was also taken into account to generate additional PC1/PC3 and PC3/PC2 projections to further verify the results of the intrahelical motions obtained (see the Results section for rationale). For the top n PCs that capture 90% of the variance, the dot products and subspace overlaps between the replicate simulations were also calculated using pcazip. The backbone root-mean-square fluctuations (RMSF) and root-mean-square deviations (RMSD) were calculated using GROMACS 4.5.3. The PCA, RMSF, and RMSD plots were generated using gnuplot. The residues interacting with ZM241385 in the 3EML crystal structure were identified using Ligplot together with visual inspection. The porcupine plots were generated using a perl script and VMD. The PC1/PC3 plots, PC3/
PC2 plots, RMSD, and porcupine plots are presented in the Supporting Information.

**RESULTS**

**Overall Protein Behavior: Apo A2a AR and A2a AR-ZMA Systems.** The projections of the apo A2a AR and A2a AR-ZMA trajectories onto the common subspace defined by the top two PCs are shown in Figure 1 in two ways: (1) when the two systems are considered separately (top) and (2) when both systems are considered together (bottom).

In 1, three things are immediately obvious from these projections. First, all simulations show a more or less continuous drift away from the conformation at the start of the production phase. Second, replicate simulations drift away along distinct paths. Third, the simulations of the apo protein are more divergent than those of the ligand-bound form.

From 2, we see that if we attempt to use a common subspace to analyze both apo and ligand-bound simulation systems, the analysis is dominated by the structural adjustment that accompanies ligand binding. This is clearly of greater magnitude than any structural perturbation that goes on during an individual MD simulation. Since it is perfectly reasonable that ligand binding has this effect, but that for our purposes here this structural variation is not of direct interest and “swamps” the more subtle conformational adjustments observed within and between replicates of each system, for the rest of the analyses we always perform the PCA analysis on the two systems independently.

Animations of the structures along the principal components reveal that they represent complex collective motions (results not shown). However it is clear that much of the dynamics is concentrated in the extra- and intracellular loop regions, as might be expected. This is evident from the calculation of root-mean-square fluctuations of each amino acid (Figure 2). We see that IL3 is the most dynamic feature in all replicate simulations and that, in agreement with the PC subspace plots in Figure 1, overall dynamics is somewhat suppressed by ligand binding.

Interestingly, the crystal structure reveals no direct contact between ZM241385 and IL3 (Figure 3); extracellular loops 2 and 3 are much more involved, yet the effect of ligand binding on their dynamics is much more subtle. The fact that the rigidification of IL3 on ligand binding is a consistent feature in all replicates of the simulation increases our confidence in its authenticity; however, at present the mechanism by which the allostery comes about is unclear. We must also bear in mind that since the evidence here is that the simulations are not well converged, the biological significance of this observation cannot be assured.
The TM helical bundle is a portion of the protein that is most structured. Confined in a lipid environment, these helices have less freedom to move compared to the intra- and extracellular loops. However, we know from the crystal structure that they contribute to the majority of the binding site cavity and, so, may be expected to have dynamics that is sensitive to ligand binding.\(^{15\text{-}18,74\text{-}79}\) Performing the PCA on the helical portions of the structure alone (Figure 4), we note a number of features. First it is clear by comparison with Figure 1 that the dynamics of this region is indeed reduced in comparison to the loops. However all observations made for the protein as a whole still hold true; the conformations of the helical region drift away from the conformation at the start of the production phase over the course of the MD simulations, the individual replicates drift away along (fairly) distinct paths, and the drift for the ligand-bound replicates is less marked than for the replicates of the apo protein.

Visualization of the motions corresponding to the principal components again reveals that they are capturing complex collective motions (result not shown). To simplify the interpretation of the dynamics of the system, we have therefore dissected this dynamics into inter- and intrahelical components.

**Interhelical Behavior: Apo A2a AR and A2a AR-ZMA Systems.** Figure 5 shows the projection of the simulations onto the common subspace defined by the PC1/PC2 plane for the interhelical motions of the TM backbone. These plots are almost perfectly identical with Figure 4.

**Intrahelical Behavior: Apo A2a AR and A2a AR-ZMA Systems.** While it is clear from the above that interhelical dynamics dominates the conformational flexibility of this system, intrahelical motions cannot be neglected. In particular it seems clear that the degree of divergence observed in the dynamics of individual replicates could be manifested at the intrahelical level. Performing PCA on the TM helices individually, we see that this is indeed the case. We see that different helices show quite different degrees of flexibility and quite different degrees of dynamical reproducibility. For the apo simulations (Figure 6) the most rigid helix is helix IV. Helices I, III, and V are more dynamic but in a consistent way across the replicates. Helices II, VI, and VII are the most dynamic and the most variable in their behavior between replicate simulations.
Looking now at the behavior of the helices in the presence of bound ligand (Figure 6b), we see that the result is a marked increase in the reproducibility of the dynamics in helix II, though it remains quite dynamic; that helix VII becomes...
somewhat more rigid and somewhat more consistent in its motion, but that the behavior of helix VI is largely unchanged. It is interesting to note that few of these observations are easily predictable on the basis of the crystal structure data (Figure 3). Thus there are no direct interactions between helix II and ZM241385, yet its dynamic is clearly sensitive to the presence of the ligand. Conversely, there are direct interactions between the ligand and helix VI, yet it seems to remain insensitive to the occupation or otherwise of the binding site. The clear response of helix VII to ligand binding is however as one might expect from the interactions visible in the crystal structure.

Conscious of the pitfalls of viewing these results from only one perspective i.e. the two-dimensional PC1/PC2 subspace, additional plots of PC1/PC3 and PC3/PC2 have been generated (see Supporting Information Figures 3 and 4). These provide further verification that the overlaps observed between the replicates are indeed real and not an artifact of our analysis protocol. Apart from that, as a means to demonstrate and quantify the changes in the extent of replicate simulations overlap observed throughout the study, the dot products and subspace overlaps between the replicate simulations have also been calculated (see Supporting Information Figures S—9). All in all, consistent with our findings, a clear increase in subspace overlap was observed from the overall protein (ca. 0.500—0.600) to the intrahelical (ca. 0.800 and above) analyses. A similar scenario was also found in the dot products whereby a rise in the conservation of the individual PCs between the simulations were noted as the study progressed.

**DISCUSSION**

One of the first lessons learned from the whole protein and TM region analyses is that the protein is still experiencing an ongoing relaxation process which takes place in a random and protracted manner throughout the 200 ns simulation. The finding leads to a number of conclusions: (1) the progression toward an equilibrated state for our target protein does not occur in a single prescribed route; (2) the protein drifts away from the conformation at the start of the production phase over the course of simulation; (3) the simulation time scale is not long enough to ensure convergence. It has also become apparent from this study that even by using the g_membed method for protein insertion, one that is believed to minimally perturb the properties and hydration of a pre-equilibrated lipid bilayer, long equilibration time is still necessary for certain proteins to fully relax within a lipid environment. Our analysis of the simulations—particularly the divergent behavior of replicates—leads us to conclude that the problem is not so much with the system setup process as with the inherent slow dynamics and complex energy landscape. These conclusions would not have been nearly so apparent from other metrics commonly used to measure the convergence of simulations such as the RMSD (see Supporting Information Figure 10 for the RMSDs calculated for these simulations).

The issue of convergence in computational simulations has long been a topic of interest. Lyman et al. have described a converged system as one that has sampled all possible states at the correct intervals and probabilities according to Boltzmann factor. They have also pointed out the challenges of assessing the quality of a simulation and determining true convergence due to inherent statistical errors. At the outset, true convergence is enormously difficult to achieve. In fact instead of absolute convergence, the concept of relative convergence has been raised previously by other groups. We are in agreement with Grossfield and co-workers that a simulation is considered valid and sufficiently converged if it is performed long enough for a reliable prediction to be made in order to answer a specific question. However, an excellent example demonstrated in another piece of work also by Grossfield et al. had shown that even this was not straightforward: the 50, 150, and 1600 ns simulations of dark state rhodopsin gave significantly different conclusions when analyses were performed on the torsion of the ionone ring (found as part of the covalently bound retinal) ligand. In that study, the torsional state of retinal which was considered as a local degree of freedom was expected to relax in a reasonably short time. The 1600 ns simulation had revealed an increase in the trans state population as a result of the slow relaxation of the internal degrees of freedom of the whole protein. This outcome was unforeseen in the two shorter durations and aptly highlighted the risk of not performing a long enough simulation.

Our results have shown an increase in the degree of convergence of the simulations after the elimination of the loop regions from the analyses. This points toward the fact that the loop regions were the most under-sampled—an observation which is consistent with the findings from other groups. The RMSF analysis has also revealed an interesting observation whereby the mobility of the IL3 was most affected by ligand binding compared to the other loops despite the fact that it had no direct contact with the ligand. While the reason for this is unclear to us, the role of IL3 in ligand-induced coupling to the G-proteins is, however, a well-known fact.

A higher degree of convergence is expected in the TM region analyses (particularly in the bound form) because this region is more well-structured compared to the rest of the protein. However, dissimilarities between the replicates are still obvious in both the bound and unbound form although more pronounced in the latter. We have found that this was largely attributed to the differences in the interhelical motions. This finding coincides with the observations made by Deupi et al. in their study of β2 adrenergic receptor using atomic force microscopy whereby their results showed that the binding of ligands (agonists, antagonists, and inverse agonists) has little effects in stabilizing interhelical interactions. They had also suggested that an inverse agonist (carazolol in Deupi’s case) promotes the receptor to sample a different conformational space that prevents the receptor from being activated, much as an agonist promotes the opposite.

The PCA of the interhelical motions have shown a large increase in convergence. Comparing the bound and unbound forms, the latter had shown more random behaviors than the former. This is in accord with the currently held view that, in the unbound form, the GPCRs sample a wide conformational space and exist in multiple states (e.g., inactive R, activated R*, etc.). The binding of a ligand shifts this equilibrium toward a specific state; in this case, the inactive state considering the inverse agonistic role of ZM241385. We have managed to associate distinctive dynamical behaviors with the individual helices. Helix IV is predicted to be the most stable helix, demonstrating the least movement with regards to the intra- and interhelical motions and in both apo and ligand-bound systems. This helix has not been found to interact with any of the agonists, antagonists, and inverse agonists currently cocryrstallized with A2a AR. When in the unbound form, we found that helices I, III, and V were more dynamic in a consistent manner while helices II, VI, and VII were more dynamic in a variable way. These dynamics are slightly different...
from those reported by Deupi et al.\textsuperscript{85} on the apo form of β2 adrenergic receptor whereby helices III, IV, and V were found to have a relatively high flexibility. While Deupi et al.\textsuperscript{85} reported that the binding of carazolol to β2 adrenergic receptor led to increased conformational changes in helices I, III, IV, V, VI, VII, and VIII, the binding of ZM241385 has caused the variation of the helices between the replicate simulations to reduce significantly with the exception of helix VI.

Experimentally, the rearrangement of the individual helices in the 7-TM bundle has been found to be central to the activation process; the movement of helices III, V, VI, and VII have been reported to play an important part in A2a AR activation.\textsuperscript{76,79} Helices V–VII have been reported to experience larger movements during the activation process compared to helices I–IV which were described as the more stable helical bundle “core.”\textsuperscript{78} The dramatic movement of helix VI in receptor activation\textsuperscript{4,79} has made it particularly noteworthy: This helix contains part of the “ionic lock” (E6.30 with R3.50 of the E/DRY motif) that seems to stabilize receptors in an inactive conformation and is where the “toggle switch” (W6.48) resides.\textsuperscript{90,91} Apart from that, it also contains a kink at the conserved P6.50 which is believed to be involved in maintaining receptors at an inactivate state.\textsuperscript{92} Although our results do not cover the dynamics of an agonists bound A2a AR, they have shown a considerable degree of flexibility in helix VI in both the absence and presence of a ligand, which highlights its propensity to remain highly mobile. Visualization of trajectories shows that, in our apo A2a AR simulations, the P6.50 kink “strengthened” significantly while W6.48 was perceived to fluctuate between the states where it was parallel (toward active state) and perpendicular (starting/toward inactive state) to the membrane plane.\textsuperscript{93} While the starting structure contained a broken “ionic lock”, it was found that two residues of this lock had moved closer to each other causing the lock to be repeatedly reformed and broken during the course of the simulations. On the other hand, for the A2a AR-ZMA simulations, the P6.50 kink as well as W6.48 were found to remain relatively unchanged from the starting states. The two residues of the “ionic lock” were again found to be constantly formed and broken during the simulations. On the basis of our observations, it was tempting to suggest that the motions shown in the apo A2a AR simulations were those of the activation process while the motions in the A2a AR-ZMA simulations represented the inactive state. However, more caution needs to be exercised as it appears longer simulation time scales are required to verify this and a study by Dror et al.\textsuperscript{94} had suggested the low likelihood of the former.

\section*{CONCLUSIONS}

The behavior and conformational dynamics of the apo and liganded A2a adenosine receptors in MD simulations have been explored and analyzed in a detailed, quantitative, and unbiased way using PCA. The two main outcomes of this study are: (1) the convergence of protein dynamics for this system is not achievable in 200 ns, a time scale of the order of magnitude often used by current researchers in this and related fields; however, (2) by restricting ourselves to a very localized definition of convergence (intrahelical dynamics), we can fairly confidently conclude that interesting and variable dynamical behaviors are associated with the individual helices that are not directly predictable from crystal structure analysis. This study illustrates the power of replicate simulation strategies to identify the reliability of observations of dynamical behavior and of structurally sensitive techniques such as PCA to produce a more robust assessment of convergence and sampling than conventionally used parameters such as area per lipid, RMSDs, and energy terms. This said, it is unlikely that PCA-type analysis will directly correlate with an experimental observable, so it should be regarded as a surrogate, rather than direct, measure of adequate sampling or equilibration.

\section*{ASSOCIATED CONTENT}

\section*{Supporting Information}

Topology of ZM241385, porcupine plots, PC1/PC3 and PC2/PC2 plots, dot product matrices, RMSD plots, and table containing residues that constitute the 7-TM α-helices are provided. This material is available free of charge via the Internet at http://pubs.acs.org.

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\textbf{Author Contributions}\n
S.W.D and C.A.L conceived the ideas in this work, and C.A.L provided expertise in PCA. H.W.N performed the computational work and simulations. H.W.N, C.A.L, and S.W.D contributed to the analysis. H.W.N and C.A.L prepared the manuscript.

\textbf{Notes}\n
The authors declare no competing financial interest.

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\textbf{ABBREVIATIONS}\n
MD, molecular dynamics; GPCR, G-protein coupled receptors; AR, adenosine receptor; PCA, principal component analysis; EL, extracellular loop; IL, intracellular loop; POPC, palmitoyloleoyl-phosphatidylcholine; SPC, simple point charge; NVT, canonical ensemble; PME, smooth particle mesh Ewald; NPT, isothermal–isobaric ensemble; TM, transmembrane; PC, principal component; RMSD, root-mean-square deviation; RMSF, root-mean-square fluctuations

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