

CS 4204 Computer Graphics

Curves and Surfaces (Continue)

*Yong Cao
Virginia Tech*

Reference: Ed Angle, Interactive Computer Graphics, University of New Mexico, class notes

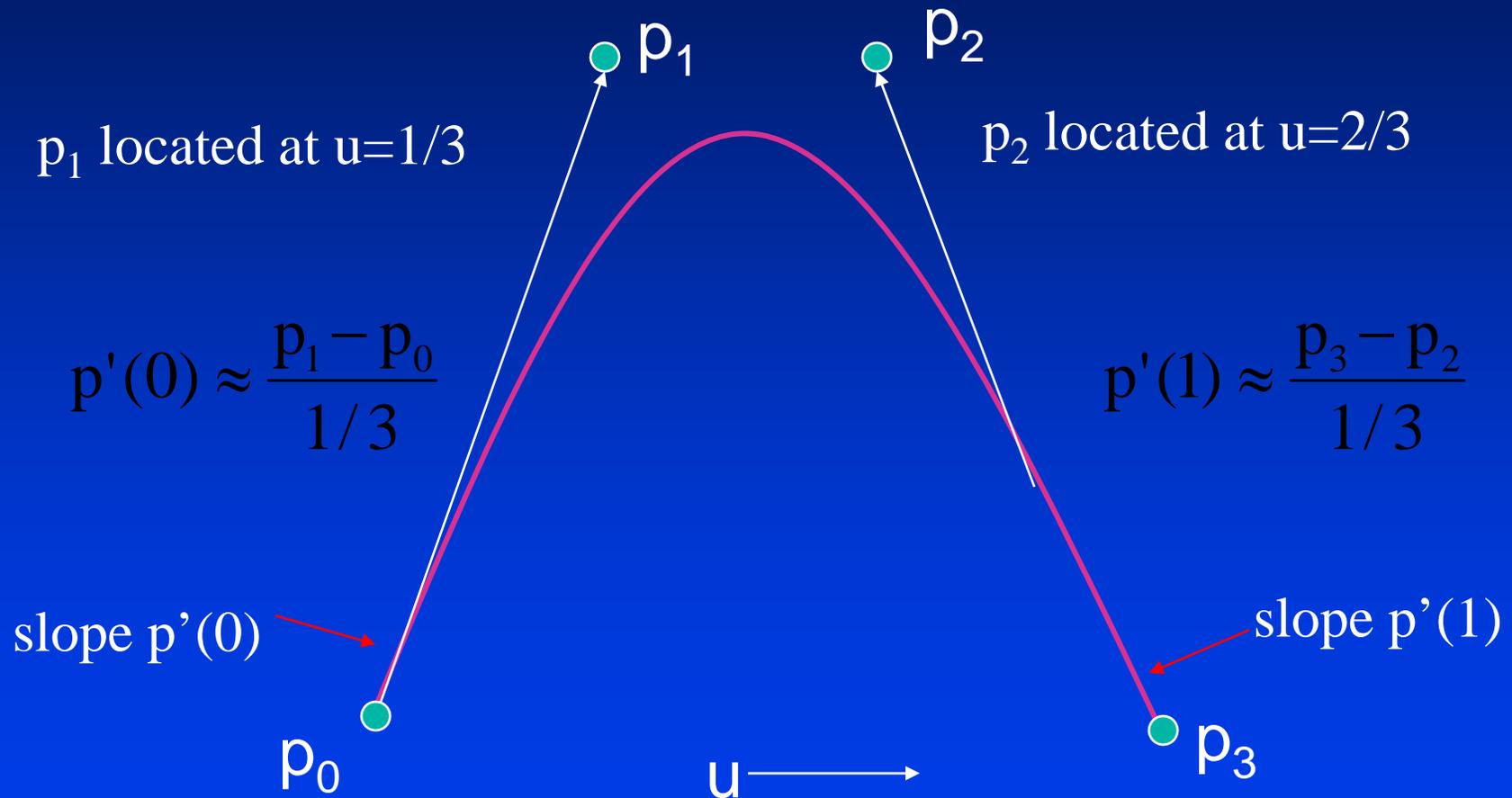
Objectives

- *Bezier curves and surfaces*
- *B-spline and compare it to the standard cubic Bezier*
- *Introduce OpenGL evaluators*
- *Learn to render polynomial curves and surfaces*

Bezier's Idea

- *In graphics and CAD, we do not usually have derivative data*
- *Bezier suggested using the same 4 data points as with the cubic interpolating curve to approximate the derivatives in the Hermite form*

Approximating Derivatives



Equations

Interpolating conditions are the same

$$p(0) = p_0 = c_0$$

$$p(1) = p_3 = c_0 + c_1 + c_2 + c_3$$

Approximating derivative conditions

$$p'(0) = 3(p_1 - p_0) = c_0$$

$$p'(1) = 3(p_3 - p_2) = c_1 + 2c_2 + 3c_3$$

Solve four linear equations for $\mathbf{c} = \mathbf{M}_B \mathbf{p}$

Bezier Matrix

$$\mathbf{M}_B = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 3 & 0 & 0 \\ 3 & -6 & 3 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}$$

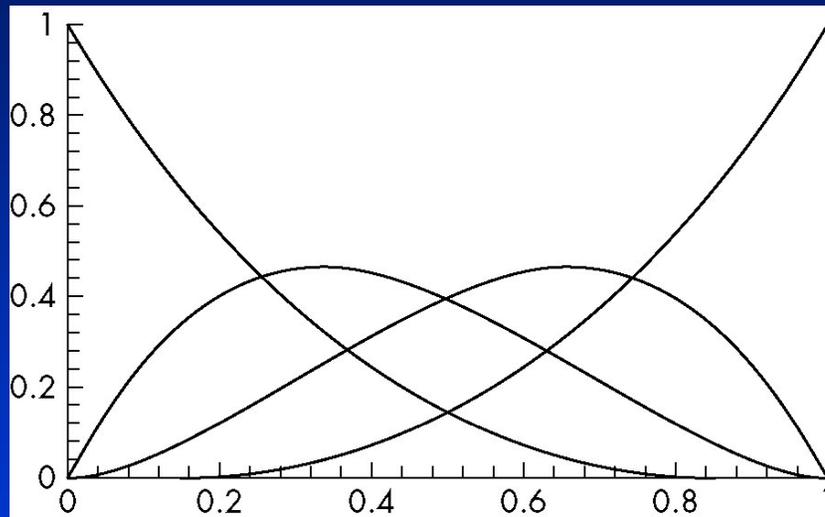
$$\mathbf{p}(u) = \mathbf{u}^T \mathbf{M}_B \mathbf{p} = \mathbf{b}(u)^T \mathbf{p}$$

blending functions



Blending Functions

$$\mathbf{b}(u) = \begin{bmatrix} (1-u)^3 \\ 3u(1-u)^2 \\ 2u^2(1-u) \\ u^3 \end{bmatrix}$$



Note that all zeros are at 0 and 1 which forces the functions to be smooth over $(0,1)$

Bernstein Polynomials

- *The blending functions are a special case of the Bernstein polynomials*

$$b_{kd}(u) = \frac{d!}{k!(d-k)!} u^k (1-u)^{d-k}$$

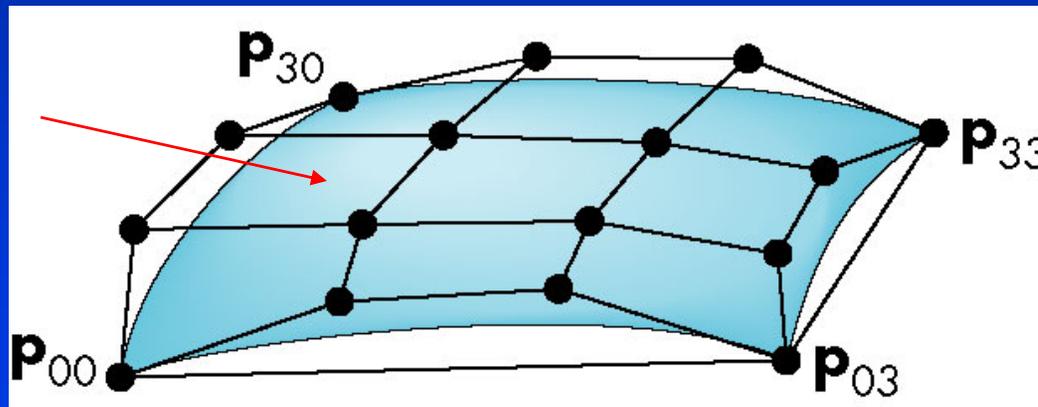
- *These polynomials give the blending polynomials for any degree Bezier form*
 - All zeros at 0 and 1
 - For any degree they all sum to 1
 - They are all between 0 and 1 inside (0,1)

Bezier Patches

Using same data array $\mathbf{P}=[p_{ij}]$ as with interpolating form

$$p(u, v) = \sum_{i=0}^3 \sum_{j=0}^3 b_i(u) b_j(v) p_{ij} = \mathbf{u}^T \mathbf{M}_B \mathbf{P} \mathbf{M}_B^T \mathbf{v}$$

Patch lies in
convex hull



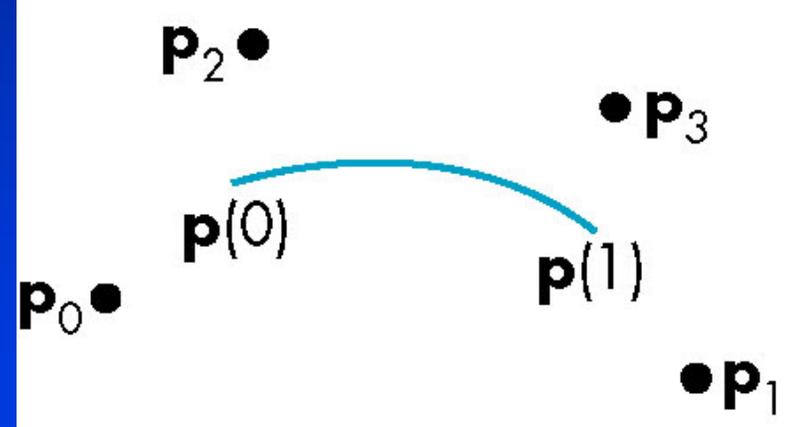
B-Splines

- ***Basis splines: use the data at $p=[p_{i-2} p_{i-1} p_i p_{i-1}]^T$ to define curve only between p_{i-1} and p_i***
- ***Allows us to apply more continuity conditions to each segment***
- ***For cubics, we can have continuity of function, first and second derivatives at join points***
- ***Cost is 3 times as much work for curves***
 - Add one new point each time rather than three
- ***For surfaces, we do 9 times as much work***

Cubic B-spline

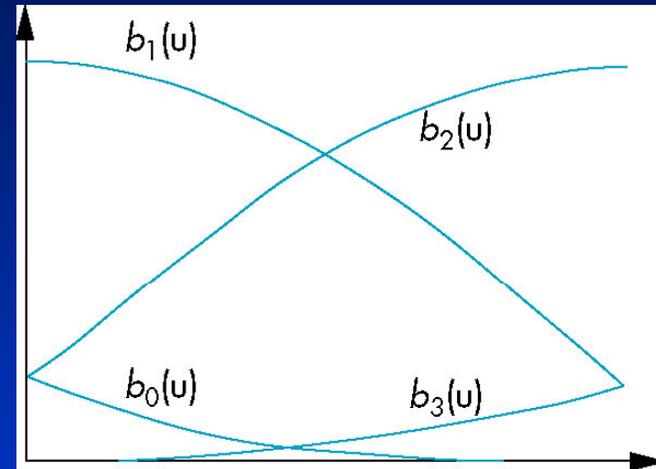
$$p(u) = \mathbf{u}^T \mathbf{M}_s \mathbf{p} = \mathbf{b}(u)^T \mathbf{p}$$

$$\mathbf{M}_s = \begin{bmatrix} 1 & 4 & 1 & 0 \\ -3 & 0 & 3 & 0 \\ 3 & -6 & 3 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}$$

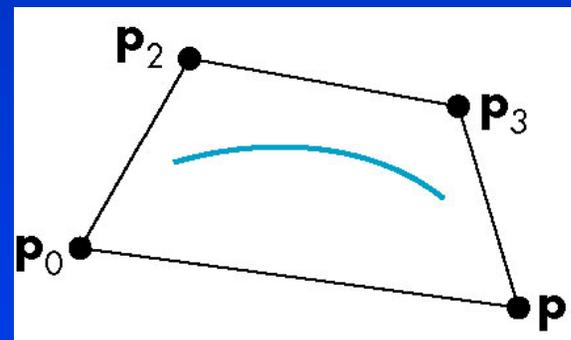


Blending Functions

$$\mathbf{b}(u) = \frac{1}{6} \begin{bmatrix} (1-u)^3 \\ 4-6u^2+3u^3 \\ 1+3u+3u^2-3u^2 \\ u^3 \end{bmatrix}$$



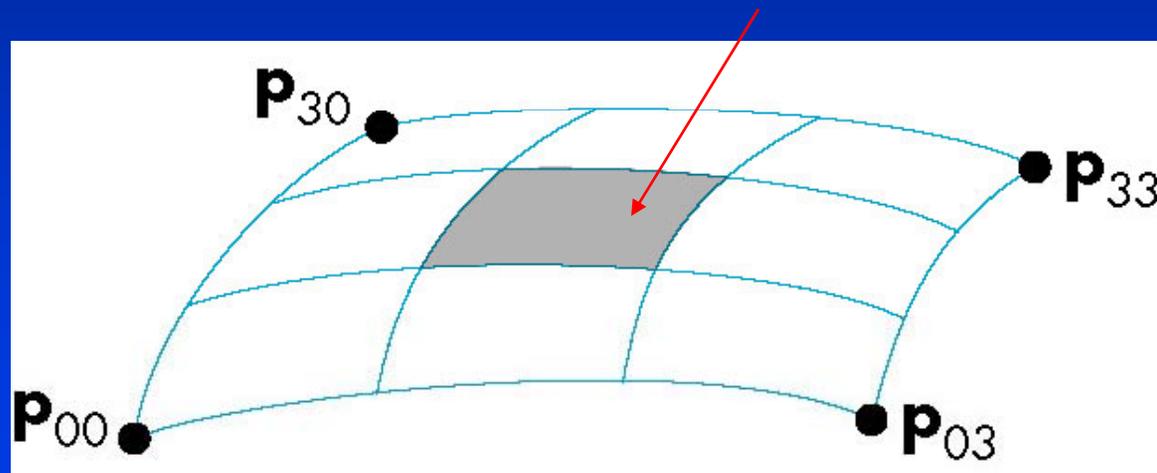
convex hull property



B-Spline Patches

$$p(u, v) = \sum_{i=0}^3 \sum_{j=0}^3 b_i(u) b_j(v) p_{ij} = u^T \mathbf{M}_S \mathbf{P} \mathbf{M}_S^T v$$

defined over only 1/9 of region



Splines and Basis

- *If we examine the cubic B-spline from the perspective of each control (data) point, each interior point contributes (through the blending functions) to four segments*
- *We can rewrite $p(u)$ in terms of the data points as*

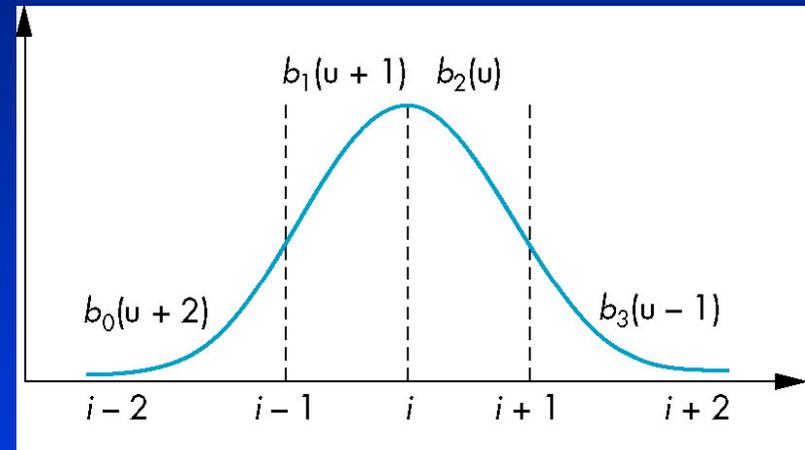
$$p(u) = \sum B_i(u) p_i$$

defining the basis functions $\{B_i(u)\}$

Basis Functions

In terms of the blending polynomials

$$B_i(u) = \begin{cases} 0 & u < i-2 \\ b_0(u+2) & i-2 \leq u < i-1 \\ b_1(u+1) & i-1 \leq u < i \\ b_2(u) & i \leq u < i+1 \\ b_3(u-1) & i+1 \leq u < i+2 \\ 0 & u \geq i+2 \end{cases}$$



NURBS

- ***Nonuniform Rational B-Spline curves and surfaces add a fourth variable w to x,y,z***
 - Can interpret as weight to give more importance to some control data
 - Can also interpret as moving to homogeneous coordinate
- ***Requires a perspective division***
 - NURBS act correctly for perspective viewing
- ***Quadratics are a special case of NURBS***

What Does OpenGL Support?

- ***Evaluators: a general mechanism for working with the Bernstein polynomials***
 - Can use any degree polynomials
 - Can use in 1-4 dimensions
 - Automatic generation of normals and texture coordinates
 - NURBS supported in GLU
- ***Quadrics***
 - GLU and GLUT contain polynomial approximations of quadrics

One-Dimensional Evaluators

- *Evaluate a Bernstein polynomial of any degree at a set of specified values*
- *Can evaluate a variety of variables*
 - Points along a 2, 3 or 4 dimensional curve
 - Colors
 - Normals
 - Texture Coordinates
- *We can set up multiple evaluators that are all evaluated for the same value*

Setting Up an Evaluator

what we want to evaluate

max and min of u

```
glMap1f(type, u_min, u_max, stride,  
order, pointer_to_array)
```

1+degree of polynomial

separation between
data points

pointer to control data

Each type must be enabled by `glEnable(type)`

Example

Consider an evaluator for a cubic Bezier curve over (0,1)

```
point data[ ]={.....}; * /3d data /*  
glMap1f(GL_MAP1_VERTEX_3,0.0,1.0,3,4,data);
```

data are 3D vertices

data are arranged as x,y,z,x,y,z.....
three floats between data points in array

cubic

```
glEnable(GL_MAP1_VERTEX_3);
```

Evaluating

- *The function `glEvalCoord1f(u)` causes all enabled evaluators to be evaluated for the specified `u`*
- Can replace `glVertex`, `glNormal`, `glTexCoord`
- *The values of `u` need not be equally spaced*

Example

- Consider the previous evaluator that was set up for a cubic Bezier over (0,1)
- Suppose that we want to approximate the curve with a 100 point polyline

```
glBegin(GL_LINE_STRIP)
    for(i=0; i<100; i++)
        glEvalCoord1f( (float) i/100.0);
glEnd();
```

Equally Spaced Points

Rather than use a loop, we can set up an equally spaced mesh (grid) and then evaluate it with one function call

```
glMapGrid(100, 0.0, 1.0);
```

sets up 100 equally-spaced points on (0,1)

```
glEvalMesh1(GL_LINE, 0, 99);
```

renders lines between adjacent evaluated points from point 0 to point 99

Bezier Surfaces

- *Similar procedure to 1D but use 2D evaluators in u and v*
- *Set up with*

```
glMap2f(type, u_min, umax, u_stride, u_order, v_min,  
v_max, v_stride, v_order, pointer_to_data)
```

- *Evaluate with `glEvalCoord2f(u,v)`*

Example

bicubic over $(0,1) \times (0,1)$

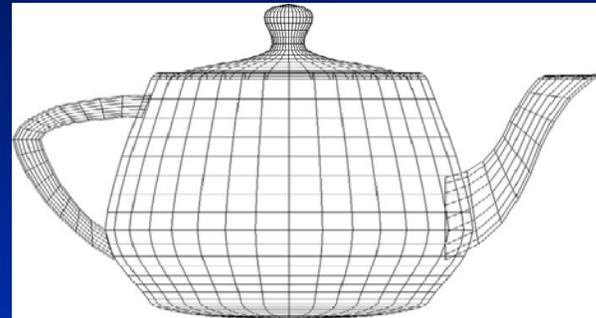
```
point data[4][4]={.....};  
glMap2f(GL_MAP1_VERTEX_3, 0.0, 1.0, 3, 4,  
        0.0, 1.0, 12, 4, data);
```

Note that in v direction data points
are separated by 12 floats since array
`data` is stored by rows

Rendering with Lines

must draw in both directions

```
for(j=0;j<100;j++) {  
    glBegin(GL_LINE_STRIP);  
        for(i=0;i<100;i++)  
            glVertex2f((float) i/100.0, (float) j/100.0);  
    glEnd();  
    glBegin(GL_LINE_STRIP);  
        for(i=0;i<100;i++)  
            glVertex2f((float) j/100.0, (float) i/100.0);  
    glEnd();  
}
```



Uniform Meshes

- *We can form a 2D mesh (grid) in a similar manner to 1D for uniform spacing*

```
glMapGrid2(u_num, u_min, u_max, v_num, v_min, v_max)
```

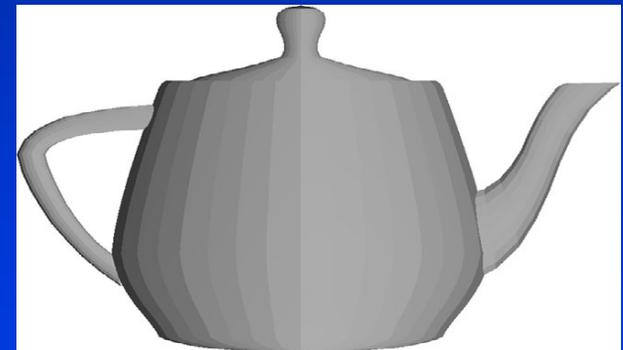
- *Can evaluate as before with lines or if want filled polygons*

```
glEvalMesh2( GL_FILL, u_start, u_num, v_start, v_num)
```

Rendering with Lighting

- *If we use filled polygons, we have to shade or we will see solid color uniform rendering*
- *Can specify lights and materials but we need normals*
 - Let OpenGL find them

```
glEnable(GL_AUTO_NORMAL);
```



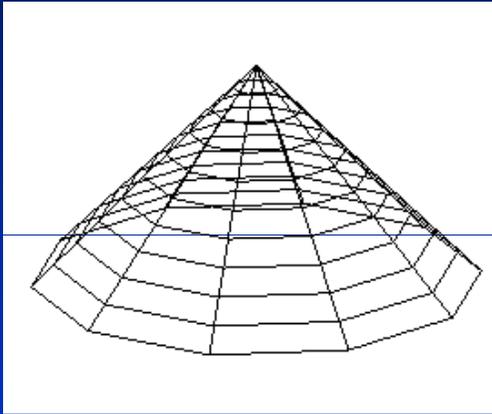
NURBS

- *OpenGL supports NURBS surfaces through the GLU library*
- *Why GLU?*
 - Can use evaluators in 4D with standard OpenGL library
 - However, there are many complexities with NURBS that need a lot of code
 - There are five NURBS surface functions plus functions for trimming curves that can remove pieces of a NURBS surface

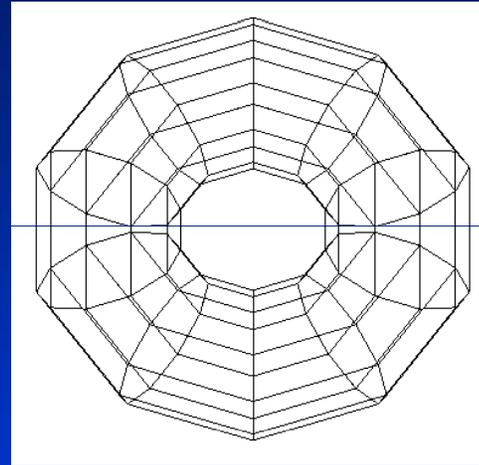
Quadrics

- ***Quadrics are in both the GLU and GLUT libraries***
 - Both use polygonal approximations where the application specifies the resolution
 - Sphere: lines of longitude and latitude
- ***GLU: disks, cylinders, spheres***
 - Can apply transformations to scale, orient, and position
- ***GLUT: Platonic solids, torus, Utah teapot, cone***

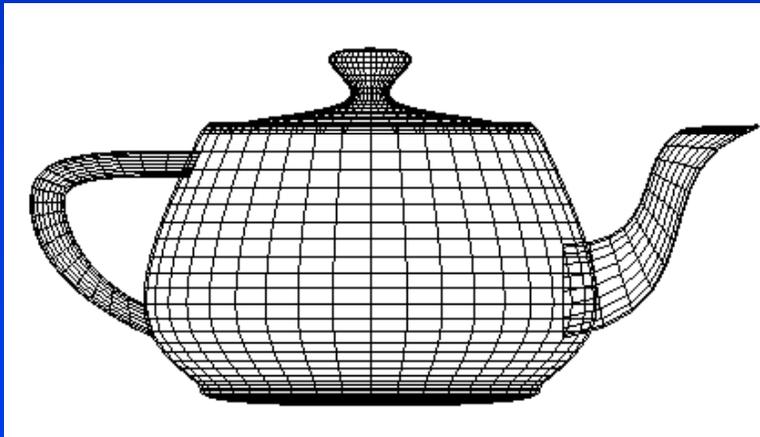
GLUT Objects



`glutWireCone()`

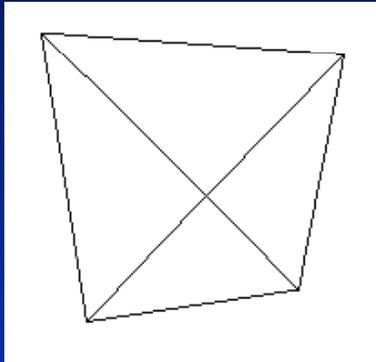


`glutWireTorus()`

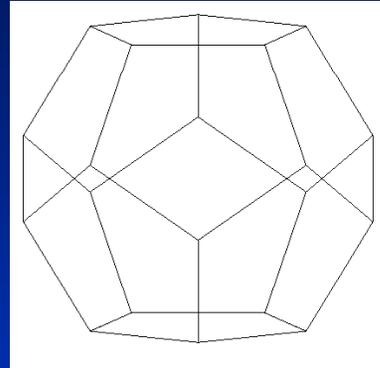


`glutWireTeapot()`

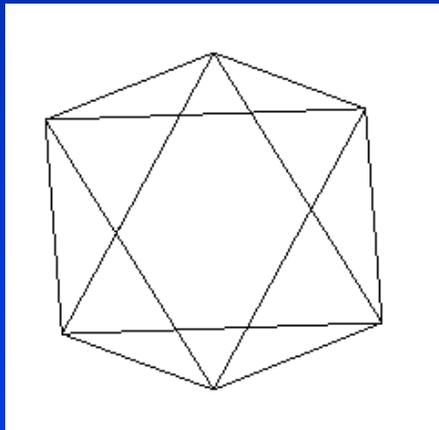
GLUT Platonic Solids



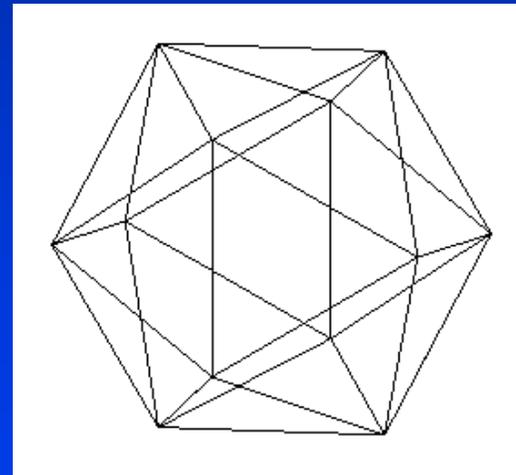
`glutWireTetrahedron()`



`glutWireDodecahedron()`



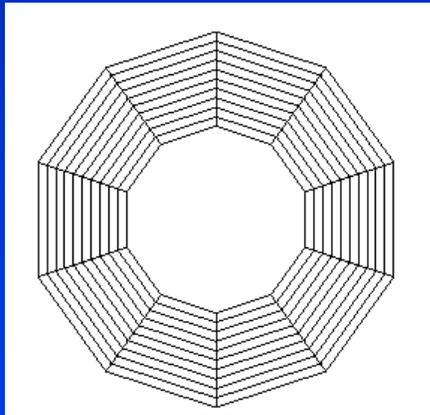
`glutWireOctahedron()`



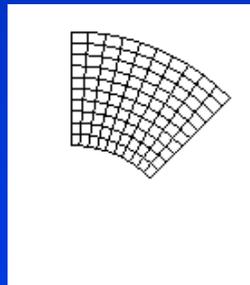
`glutWireIcosahedron()`

Quadric Objects in GLU

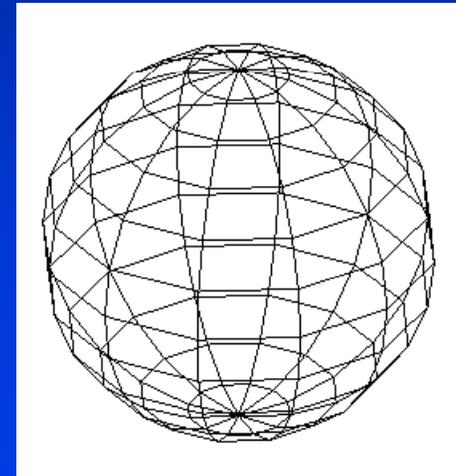
- *GLU can automatically generate normals and texture coordinates*
- *Quadrics are objects that include properties such as how we would like the object to be rendered*



disk



partial disk



sphere

Defining a Cylinder

```
GLUquadricOBJ *p;  
P = gluNewQuadric(); /*set up object */  
gluQuadricDrawStyle(GLU_LINE);/*render style*/  
gluCylinder(p, BASE_RADIUS, TOP_RADIUS,  
            BASE_HEIGHT, sections, slices);
```

