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*Наведено умови на модель Фрідрікса, які дозволяють записати формулу для стрибка резольвенти на неперервному спектрі*

*Ключові слова: модель Фрідрікса, неперервний спектр, факторизація, резольвента, стрибок*

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*Приведены условия на модель Фридрикса, которые позволяют записать формулу для скачка резольвенты на непрерывном спектре*

*Ключевые слова: модель Фридрикса, непрерывный спектр, факторизация, резольвента, скачок*

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*The conditions on the Friedrich's model, which permit to write the formula for the jump of the resolvent on continuous spectrum are indicated*

*Keywords: Friedrich's model, continuous spectrum, factorization, resolvent, jump*

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# A REMARK ABOUT CALCULATION OF THE JUMP OF THE RESOLVENT IN FRIEDRICHS' MODEL

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**Introduction**

The presentation of spectral projection by the resolvent  $R_\zeta$  of selfadjoint operator

$$E(\Delta) = \lim_{\epsilon \rightarrow +0} \frac{1}{2\pi i} \int_{\Delta+i\epsilon} (\mathcal{R}_\zeta - \mathcal{R}_{\bar{\zeta}}) d\zeta, \Delta \subset (-\infty, \infty)$$

is well-known for a long time (see for example Bereznanski Yu.M. [1], p.425). Obviously the jump of the resolvent  $\lim_{\epsilon \rightarrow +0} ((\mathcal{R}_\zeta - \mathcal{R}_{\bar{\zeta}})\phi, \psi)$ ,  $\zeta = \sigma + i\epsilon$ ,  $\sigma \in (-\infty, \infty)$  is important in the theory of nonselfadjoint perturbation of continuous spectrum too. In the work Ljance V.E. [2] concerning non-selfadjoint Friedrichs' model the author uses an extension of the operator in more wide space. In the work Cheremnikh E.V. [3] an auxiliary operator (like maximal differential operator) was used. In presented article we precise the calculus of the jump of resolvent.

**Preliminary and main theorem**

Let  $H = L^2(R, H_1)$ ,  $R = (-\infty, \infty)$ , where  $H_1$  is some Hilbert space with scalar product  $(\bullet, \bullet)_{H_1}$ . We consider Friedrichs' model

$$T = S + V, V = A^*B, D(T) = D(S), A, B: H \rightarrow G, \tag{1}$$

where  $S$  is the operator of multiplication by independent variable (i.e.  $(S\phi)(\tau) = \tau\phi(\tau)$ ,  $\tau \in R$ ) with maximal domain of definition  $D(S)$  and  $A, B$  are bounded operators from  $H$  in  $G$ . The space  $G$  is auxiliary Hilbert space. We use notation  $\phi, \psi, f, g \in H, c, d \in G$  for the elements and  $(\bullet, \bullet), (\bullet, \bullet)_G$  for scalar product respectively. We denote  $S_\zeta = (S - \zeta)^{-1}$ ,  $T_\zeta = (T - \zeta)^{-1}$ . The relation  $(T - \zeta)\psi = \phi$  or  $(S - \zeta)\psi + A^*B\psi = \phi$  (see1) gives

$$\psi + S_\zeta A^*B\psi = S_\zeta \phi, \text{Im} \zeta \neq 0 \tag{2}$$

Now we apply the operator  $B$  to both sides of the relation (2) and denote  $c = B\psi$ . Then  $c + BS_\zeta A^* c = BS_\zeta \phi$  or  $K(\zeta)c = BS_\zeta \phi$ , where

$$K(\zeta) = 1 + BS_\zeta A^*, \quad \text{Im}\zeta \neq 0 \tag{3}$$

Substituting  $c = K(\zeta)^{-1}BS_\zeta \phi$  in (2), we obtain  $\psi = T_\zeta \phi$ , where

$$T_\zeta \phi = S_\zeta \phi - S_\zeta A^* K(\zeta)^{-1}BS_\zeta \phi, \quad \text{Im}\zeta \neq 0 \tag{4}$$

for every value  $\zeta$  such that there exists bounded inverse operator  $K(\zeta)^{-1}$ .

We denote by  $K_+(\zeta), \text{Im}\zeta > -\varepsilon$  and  $K_-(\zeta), \text{Im}\zeta < \varepsilon$  the extensions of the operator function (3) over axis  $\text{Im}\zeta = 0, \zeta \neq 0$  from the domains  $\text{Im}\zeta > 0$  and  $\text{Im}\zeta < 0$  respectively for some  $\varepsilon > 0$ .

We suppose that:

- $C_1$ ) there exist the extensions  $K_\pm(\zeta)$  and  $\|K_\pm(\zeta) - 1\| \rightarrow 0, \zeta \rightarrow \infty$  uniformly in the domain  $|\text{Im}\zeta| < \varepsilon$ ;
- $C_2$ ) the operators  $K_\pm(\zeta)^{-1}$  exist and are holomorph in the domain  $|\text{Im}\zeta| < \varepsilon, \text{Re}\zeta \neq 0$  except may be finite set of points.

Denote

$$B(\zeta)\phi = \phi - A^*K(\zeta)^{-1}BS_\zeta \phi, \quad A(\zeta)\psi = \psi - B^*K(\zeta)^{-1}AS_\zeta \psi. \tag{5}$$

Let

$$h(\tau, \zeta) = ((B(\zeta)\phi)(\tau), (A(\zeta)\psi)(\tau)), \quad \tau \in \mathbb{R}, \text{Im}\zeta > 0. \tag{6}$$

We need strong limits in the space  $G$

$$(AS_\sigma)_\pm \phi = \lim_{\nu \rightarrow +0} AS_\zeta \phi, \quad (BS_\sigma)_\pm \phi = \lim_{\nu \rightarrow +0} BS_\zeta \phi, \quad \zeta = \sigma + i\nu \tag{7}$$

and corresponding strong limits in  $H$

$$B_+(\sigma)\phi = \phi - A^*K_+(\sigma)^{-1}(BS_\sigma)_+ \phi,$$

$$A_-(\sigma)\phi = \phi - B^*K_-(\sigma)^{-1}(AS_\sigma)_+ \phi, \phi \in H^0$$

for the elements  $\phi$  from some subspace  $H^0 \subset H$  dense in  $H, H^0 = H$ .

We suppose that

- $C_3$ ) strong limits (7) exist except may be finite set  $D \subset \mathbb{R}$  of values of  $\sigma$  for the elements  $\phi \in H^0$  and the function  $h(\tau, \zeta)$  (see(6)) for  $0 \leq \text{Im}\zeta < \varepsilon_0$ , for some  $\varepsilon_0 > 0$  is differentiable on  $\tau$  in  $\mathbb{R}$  and

$$\int_{\mathbb{R}} |h(\tau, \zeta)| d\tau \leq M, 0 \leq \text{Im}\zeta < \varepsilon_0, \tag{8}$$

where  $M = \text{const}$ ;

- $C_4$ ) for every finite interval  $(a, b)$  we have

$$|h(\tau, \zeta) - h(\tau, \sigma)| \leq C|\zeta - \sigma|, |\tau - \sigma| < \delta, \tau \in (a, b), \zeta = \sigma + i\nu, \tag{9}$$

where  $\sigma \in \mathbb{R} \setminus D$  (see  $C_3$ ) and  $C = \text{const}$  does not depend on  $\delta_0$ .

The main result of the article is given by following theorem. Denote (see  $C_3$ )

$$(T_\sigma \phi, \psi)_\pm = \lim_{\nu \rightarrow +0} (T_{\sigma+i\nu} \phi, \psi), \quad \phi, \psi \in H^0, \sigma \in \mathbb{R} \setminus D.$$

**Theorem 1.** There exists subspace  $H^1 \subset H^0$  dense in  $H, H^1 = H$  such that

- 1) limit values  $(T_\sigma \phi, \psi)_\pm$  exist if  $\sigma \in \mathbb{R} \setminus D, \phi, \psi \in H^1$ ;
- 2) jump of the resolvent in the point  $\sigma \in \mathbb{R} \setminus D$  is

$$(T_\sigma \phi, \psi)_+ - (T_\sigma \phi, \psi)_- = 2\pi i ((B_+(\sigma)\phi)(\sigma), (A_-(\sigma)\psi)(\sigma))_{H_1}, \tag{10}$$

where

$$B_+(\sigma)\phi = \phi - A^*K_+(\sigma)^{-1}(BS_\sigma)_+ \phi, \quad A_-(\sigma)\phi = \phi - B^*K_-(\sigma)^{-1}(AS_\sigma)_+ \phi, \phi \in H^1 \tag{11}$$

- 3) if  $\phi, \psi \in D(T) \cap H^1$  then

$$(A_-(\sigma)(T^* - \sigma)\psi)(\sigma) = 0, \quad (B_+(\sigma)(T - \sigma)\phi)(\sigma) = 0 \tag{12}$$

and if  $\{e_k\} \subset H_1$  is arbitrary orthonormal base in  $H_1$  then the functionals

$$\begin{aligned} (a_{\sigma,k}, \psi) &= (e_k, (A_-(\sigma)\psi)(\sigma))_{H_1}, \\ (\phi, b_{\sigma,k}) &= ((B_+(\sigma)\phi)(\sigma), e_k)_{H_1}, \end{aligned} \tag{13}$$

$k = 1, 2, \dots$

are eigenfunctionals of the operators  $T$  and  $T^*$  respectively.

Choice of the factorization.

Note that the operators  $B(\zeta), A(\zeta): H \rightarrow H$  (see(5)) do not depend on the choice of the factorization  $V = A^*B$ , really comparison (5) with (4) gives

$$(S - \zeta)T_\zeta \phi = B(\zeta)\phi, \quad (S - \zeta)T_\zeta^* \psi = A(\zeta)\psi, \tag{14}$$

where  $T_\zeta^*$  is the resolvent of adjoint operator  $T^*$  in the point  $\zeta$ . In the case

$$\overline{R(A^*)} = \overline{R(B^*)} = H, \tag{15}$$

the calculation of the jump of the resolvent is more simple. Otherwise we will replace given factorization  $V = A^*B$  by some special factorization which satisfies the condition (15). So, suppose now that  $R(A^*) \neq H$  or  $R(B^*) \neq H$ . We denote  $Z(A) = \{f \in H: Af = 0\}$ . It is known that if  $A, B: H \rightarrow G$  are bounded operators then

$$\overline{R(A^*)} \oplus Z(A) = H, \quad \overline{R(B^*)} \oplus Z(B) = H. \tag{16}$$

Definition. Let  $\tilde{G} = G \oplus Z(A) \oplus Z(B)$ .

The space  $\tilde{G}$  is Hilbert space and scalar product for the elements

$$\tilde{c} = \{c, g_\alpha, g_\beta\}, \tilde{d} = \{d, h_\alpha, h_\beta\} \in \tilde{G}$$

with arbitrary elements  $g_\alpha, h_\alpha \in Z(A), g_\beta, h_\beta \in Z(B)$  is defined by the expression

$$(\tilde{c}, \tilde{d})_{\tilde{G}} = (c, d)_G + (g_\alpha, h_\alpha) + (g_\beta, h_\beta). \tag{17}$$

Let  $P_\alpha: H \rightarrow Z(A), P_\beta: H \rightarrow Z(B)$  are orthogonal projection.

Definition. The operators  $\tilde{A}, \tilde{B}: H \rightarrow \tilde{G}$  are defined by the relation

$$\tilde{A}f = \{Af, P_\alpha f, 0\}, \tilde{B}f = \{Bf, 0, P_\beta f\}. \quad (18)$$

As  $\tilde{G}$  is Hilbert space then  $\tilde{A}^*, \tilde{B}^*: \tilde{G} \rightarrow H$ .

**Lemma 1.** Following relations hold:

$$1) \tilde{A}^* \tilde{B} = A^* B$$

$$2) \overline{R(\tilde{A}^*)} = \overline{R(\tilde{B}^*)} = H$$

Proof. 1) Let  $f \in H$  be arbitrary element, according to (17)-(18) we have

$$(\tilde{A}f, \tilde{c})_{\tilde{G}} = (Af, c)_G + (P_\alpha f, g_\alpha) = (f, A^*c) + (f, g_\alpha) = (f, A^*c + g_\alpha).$$

Therefore, if  $\tilde{c} = \{c, g_\alpha, g_\beta\}$  then

$$\tilde{A}^* \tilde{c} = A^*c + g_\alpha. \quad (19)$$

Substituting (see(18))  $\tilde{c} = \tilde{B}f = \{Bf, 0, P_\beta f\} \equiv \{c, g_\alpha, g_\beta\}$  in (19)- we obtain the statement 1).

2) As element  $g_\alpha \in Z(A)$  in the relation is arbitrary then  $\overline{R(\tilde{A}^*)} = H$  (see(16)). The operator  $B$  is considered by analogy what proves the statement 2).

Lemma 1 is proved.

Note that new factorization  $V = \tilde{A}^* \tilde{B}$  satisfies the condition (15).

Lemma about the difference  $T_\zeta - T_{\bar{\zeta}}$ .

Let us consider the case of arbitrary factorization  $V = A^* B$ .

**Lemma 2.**

Let  $\phi = A^*c, \psi = B^*d, c, d \in G$  then (see(2))

$$\left( (T_\zeta - T_{\bar{\zeta}})\phi, \psi \right) = \left( (S_\zeta - S_{\bar{\zeta}})B(\zeta)\phi, A(\zeta)\psi \right) \quad (20)$$

and

$$|I_1(v)| \leq \int_{|\tau-\sigma|<\delta} \left( \frac{1}{|\tau-\zeta|} + \frac{1}{|\tau-\bar{\zeta}|} \right) |h(\tau, \zeta) - h(\tau, \sigma)| d\tau \leq \frac{2}{|\zeta-\sigma|} \int_{|\tau-\sigma|<\delta} |h(\tau, \zeta) - h(\tau, \sigma)| d\tau \leq 4C\delta$$

$$B(\zeta)(T - \zeta)\phi = (S - \zeta)\phi, \quad A(\zeta)(T^* - \bar{\zeta})\psi = (S - \bar{\zeta})\psi. \quad (21)$$

Proof. According to (3)-(4)

$$BT_\zeta A^* = BS_\zeta A^* - BS_\zeta A^* K(\zeta)^{-1} BS_\zeta A^* = K(\zeta) - 1 - (K(\zeta) - 1)K(\zeta)^{-1}(K(\zeta) - 1) = 1 - K(\zeta)^{-1}$$

and in view of presentation  $\phi = A^*c, \psi = B^*d$  we have

$$(T_\zeta \phi, \psi) = (BT_\zeta A^* c, d)_G = (c, d)_G - (K(\zeta)^{-1} c, d)_G.$$

Therefore

$$\begin{aligned} \left( (T_\zeta - T_{\bar{\zeta}})\phi, \psi \right) &= - \left( (K(\zeta)^{-1} - K(\bar{\zeta})^{-1})c, d \right)_G = \\ &= \left( K(\bar{\zeta})^{-1} [K(\zeta) - K(\bar{\zeta})] K(\zeta)^{-1} c, d \right)_G = \\ &= \left( (BS_\zeta A^* - BS_{\bar{\zeta}} A^*) K(\zeta)^{-1} c, K(\bar{\zeta})^{-1} d \right)_G = \\ &= \left( (S_\zeta - S_{\bar{\zeta}}) A^* K(\zeta)^{-1} c, B^* K(\bar{\zeta})^{-1} d \right)_G. \end{aligned} \quad (22)$$

Multiplying  $K(\zeta) = 1 + BS_\zeta A^*$  by  $A^* K(\zeta)^{-1}$  we obtain

$$A^*c = A^* K(\zeta)^{-1} c + A^* K(\zeta)^{-1} BS_\zeta A^* c$$

As  $\phi = A^*c$  then  $A^* K(\zeta)^{-1} c = \phi - A^* K(\zeta)^{-1} BS_\zeta \phi = B(\zeta)\phi$  (see(5)). By analogy  $B^* K(\bar{\zeta})^{-1} d = A(\bar{\zeta})\psi$  then (20) results from (22). The change  $T_\zeta \phi \rightarrow \phi$  and  $T_{\bar{\zeta}} \psi \rightarrow \psi$  transforms (14) into (21).

Lemma 2 is proved.

To study right side of the relation (20) we need next Lemma.

**Lemma 3.** If the function  $h(\tau, \zeta)$  satisfies the conditions  $C_3) - C_4)$  then

$$\lim_{v \rightarrow +0} \int_{\mathbb{R}} \left( \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right) h(\tau, \zeta) d\tau = 2\pi i h(\sigma, \sigma), \zeta = \sigma + iv. \quad (23)$$

Proof. We have

$$\begin{aligned} &\int_{\mathbb{R}} \left( \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right) h(\tau, \zeta) d\tau = \\ &= \int_{\mathbb{R}} \left( \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right) (h(\tau, \zeta) - h(\tau, \sigma)) d\tau + \\ &+ \int_{\mathbb{R}} \left( \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right) h(\tau, \sigma) d\tau. \end{aligned}$$

So, to prove the relation (23) it is sufficient to prove that

$$I(v) \equiv \int_{\mathbb{R}} \left( \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right) (h(\tau, \zeta) - h(\tau, \sigma)) d\tau \rightarrow 0, v \rightarrow +0, \quad (24)$$

where  $\text{Re} \zeta = \sigma = \text{const}$ . Let  $\delta > 0$  and

$$I(v) = \int_{|\tau-\sigma|<\delta} + \int_{|\tau-\sigma|>\delta} \equiv I_1(v) + I_2(v)$$

1) As  $|\tau - \zeta| = |\tau - \bar{\zeta}| \geq |\zeta - \sigma|$  then (see(9))

2) If  $|\tau - \sigma| > \delta$  then  $|\zeta - \tau| > \delta$  and

$$\left| \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right| = \left| \frac{2iv}{(\tau - \zeta)(\tau - \bar{\zeta})} \right| \leq \frac{2v}{\delta^2}$$

Therefore (see(8))

$$|I_2(v)| \leq \int_{|\tau-\sigma|>\delta} \left| \frac{1}{\tau - \zeta} - \frac{1}{\tau - \bar{\zeta}} \right| (|h(\tau, \zeta)| + |h(\tau, \sigma)|) d\tau \leq 4M \frac{v}{\delta^2}.$$

If we choose  $\delta = \sqrt[3]{v}$  then  $I_1(v), I_2(v) \rightarrow 0, v \rightarrow +0$ , what proves the relation (24).

Lemma is proved.

Proof of Theorem 1. 1) In view of (14) and the condition  $C_3)$  limit values  $(T_\sigma \phi, \psi)_\pm$  exist if we choose  $H^1 \subset H^0$  as subspace of differentiable functions.

2) According to (14) the expressions  $B(\zeta)\phi, A(\zeta)\psi$  does not depend on the choice of the factorization. We pose  $V = \tilde{A}^* \tilde{B}$  (see Lemma 1) and obtain the relation (20) for some subspace dense in  $H$ . All operators in the relation (20) are bounded, therefore (20) holds for all elements

$\phi, \psi \in H$ . Using Lemma 3 we obtain the relation (10) from the relation (20).

3) Let us consider the relation (21), where  $\text{Im} \zeta \rightarrow +0$  and  $\text{Re} \zeta = \sigma = \text{const}$ . The right side  $(S - \sigma)\phi$  is vector function with values in the space  $H_1$ . Obviously  $\lim_{\tau \rightarrow \sigma} [(\tau - \sigma)\phi(\tau)]_{\tau - \sigma} = 0$ . So, relations (12)-(13) result from (21).

Theorem 1 is proved.

As conclusion note that one obtain formula of jump of the resolvent (see (10))

$$(T_\sigma \phi, \psi)_+ - (T_\sigma \phi, \psi)_- = 2\pi i ((B_+(\sigma)\phi)(\sigma), (A_-(\sigma)\psi)(\sigma))_{H_1}$$

if 1) condition on the elements  $\phi, \psi$  which give  $C_3) - C_4)$  are indicated;

2) condition on  $\phi, \psi$  which permit to prolongate continuously both side of (10) in more wide subspace are given.

Note that sign  $\pm$  in the notation  $B_\pm(\sigma), A_\pm(\sigma)$  correspond to sign of limit values  $K_+(\sigma)^{-1}, K_-(\sigma)^{-1}$  in the expression of  $B_\pm(\sigma), A_\pm(\sigma)$ .

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*Запропоновано технологію розрахунку аналітичного опису нечітких чисел, що визначає ймовірності стану об'єктів на момент прогнозу, що формуються нечіткою експертною системою. Описано процедуру дефазифікації результатів прогнозування*

*Ключові слова: прогнозування, експертна система*

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*Предложена технология расчета аналитических описаний нечетких чисел, определяющих вероятности состояний объекта на момент прогноза, формируемых нечеткой экспертной системой. Описана процедура дефазификации результатов прогнозирования*

*Ключевые слова: прогнозирование, экспертная система*

□ □

*The calculation technology of analytical descriptions of fuzzy numbers which determining probabilities of the object's states in the moment of prognosis in the fuzzy expert system is offered. The defuzzification procedure of the prognostication results is described*

*Keywords: prediction, expert system*

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УДК 681.3

# ПРОГНОЗИРОВАНИЕ СОСТОЯНИЯ ОБЪЕКТА ПО РЕЗУЛЬТАТАМ ОЦЕНИВАНИЯ НЕЧЕТКОЙ ЭКСПЕРТНОЙ СИСТЕМОЙ

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### 1. Введение

При решении многих практических задач в технике, экономике, медицине и др. возникает необходимость прогнозирования состояния объекта, характеризуемого набором контролируемых, часто зависимых параметров [1,2]. Такие задачи традиционно решаются с использованием экспертных систем (ЭС) [3-5]. При этом обычно предполагается, что механизм логического вывода этих систем (продукционный или бай-

есов) оперирует с четко заданными базами данных и знаний. Вместе с тем, в последнее время все более ясно осознается понимание необходимости учета реальной неопределенности исходных данных задачи. При этом поскольку законы распределения соответствующих случайных величин, как правило, неизвестны, для их описания используют технологию нечеткой математики, что приводит к применению экспертных систем с нечетким механизмом логического вывода. В силу специфического характера функционирования нечет-