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# An Evaluation of OpenMP on Current and Emerging Multithreaded/Multicore Processors

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Matthew Curtis-Maury, Xiaoning Ding,  
Christos D. Antonopoulos, and  
Dimitrios S. Nikolopoulos

The College of William & Mary



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# Content

Motivation of this Evaluation

Overview of Multithreaded/Multicore Processors

Experimental Methodology

OpenMP Evaluation

Adaptive Multithreading Degree Selection

Implications for OpenMP

Conclusions



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# Motivation

CMPs and SMTs are gaining popularity

SMTs in high-end and mainstream computers

Intel Xeon HT

CMPs beginning to see same trend

Intel Pentium-D

Combined approach showing promise

IBM Power5 and Intel Pentium-D Extreme Edition

Given this popularity, evaluation of codes parallelized with OpenMP timely and necessary



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# Three Goals

Compare Multiprocessors of CMPs and SMTs

Low-level comparison (hardware counters)

High-level comparison (execution time)

Locate architectural bottlenecks on each

Find ways to improve OpenMP for these architectures without modifying interface

Awareness of underlying architecture



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Motivation of this Evaluation

## **Overview of Multithreaded/Multicore Processors**

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# Multithreaded and Multicore Processors

Execute multiple threads on single chip

Resource replication within processor

Improved cost/performance ratio

Minimal increases in architectural complexity provide significant increases in performance

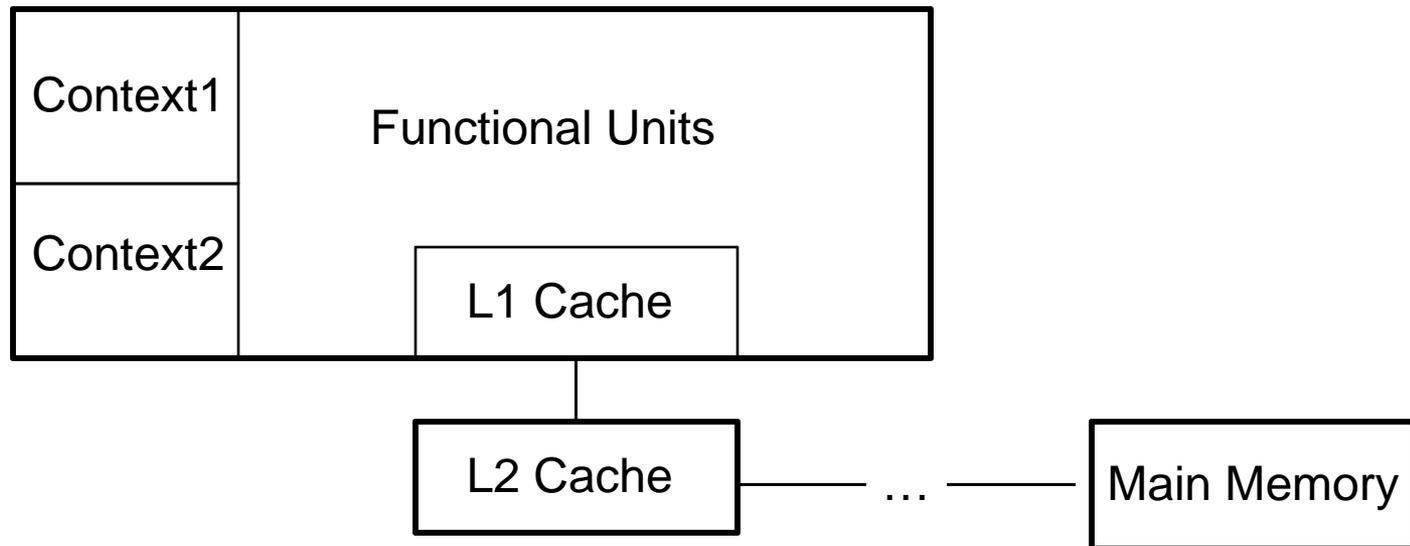


# Simultaneous Multithreading

Minimal resource replication

Provides instructions to overlap memory latency

Separate threads exploit idle resources



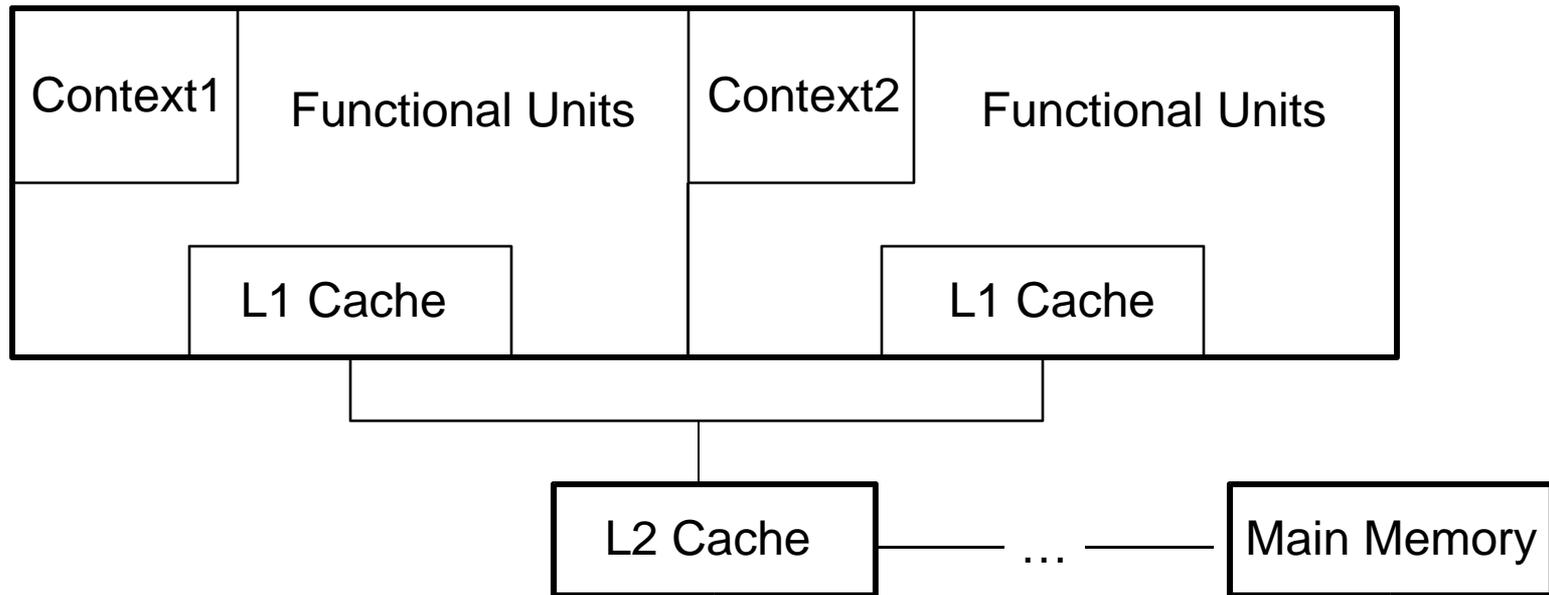
# Chip Multiprocessing

Much larger degree of resource replication

Two complete processing cores on each chip

Outer levels of cache and external interface are shared

Greatly reduced resource contention compared to SMT



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# Experimental Methodology

Real 4-way server based on Intel's HT processors

Representative of SMT class of architectures

2 execution contexts per chip

Shared execution units, cache hierarchy, and DTLB

Simulated 4-way CMP-based multiprocessor

Used the Simics simulation environment (full system)

2 execution cores per chip

Configured to be similar to SMT machine (cache configuration)

8K data L1, 256K L2, 512K L2, 64 entry TLB, 1GB main memory

Private L1 and DTLB per core doubles effective space

Shared L2 and L3 caches



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# Benchmarks

We used the NAS Parallel Benchmark Suite

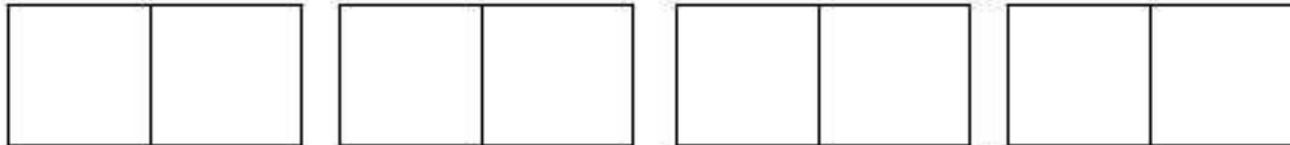
OpenMP version

Class A

Ran 1, 2, 4, and 8 threads

Bound to 1, 2, and 4 processors

1 and 2 contexts per processor



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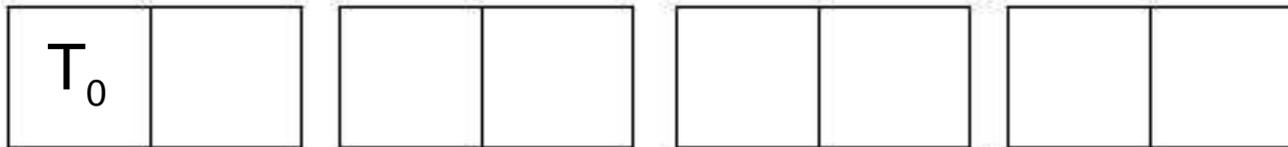
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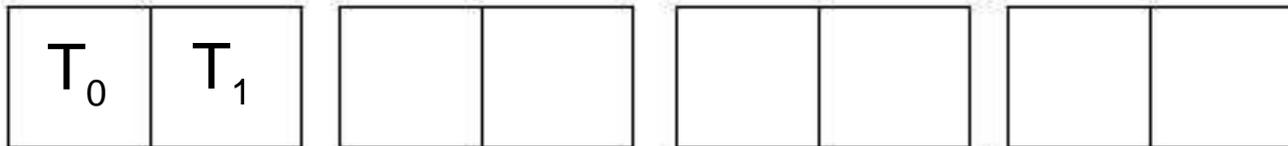
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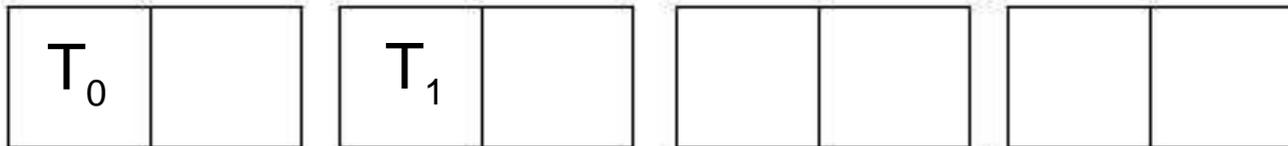
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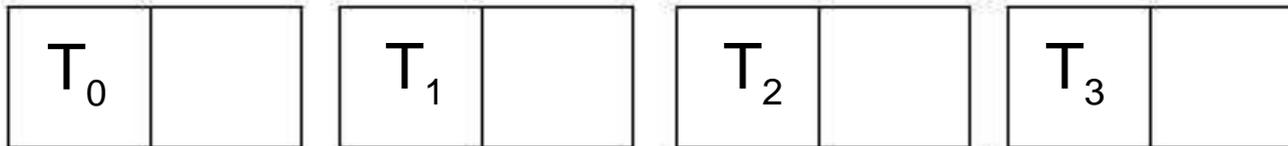
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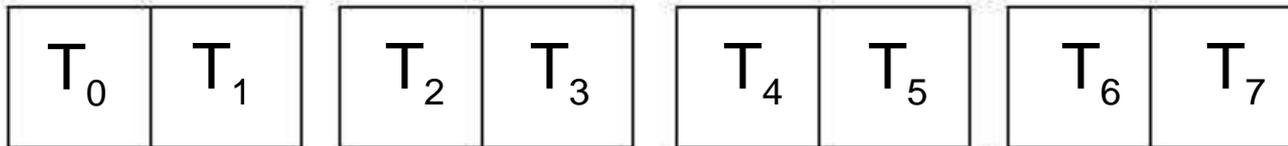
OpenMP version

Class A

Ran 1, 2, 4, and 8 threads

Bound to 1, 2, and 4 processors

1 and 2 contexts per processor



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# Benchmarks, cont.

On SMT machine, ran benchmarks to completion  
Collected HW statistics with VTune

Simulator introduces average of 7000-fold  
slowdown on execution for CMP

Ran same data set as on SMT

Ran only 3 iterations of outermost loop, discarding first  
for cache warm-up

Simics simulator directly provides HW statistics



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# Hardware Statistics Collected

Monitored direct metrics...

Wall clock time, number of instructions, number of L2 and L3 references and misses, number of stall cycles, number of data TLB misses, and number of bus transactions

...and derived metrics

Cycles per instruction and L2 and L3 miss rates

Due to time and space limitations, we present:

L2 references, L2 miss rates, DTLB misses, stall cycles, and execution time

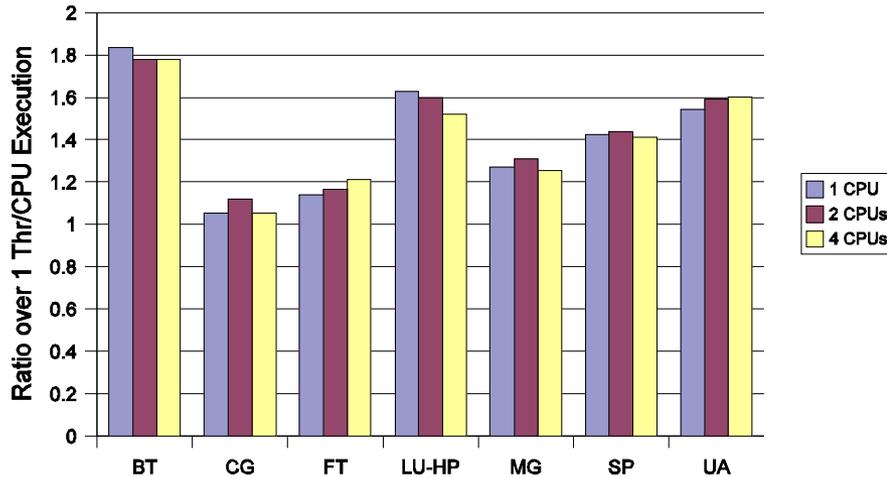
Most impact on performance

Provide insight into performance

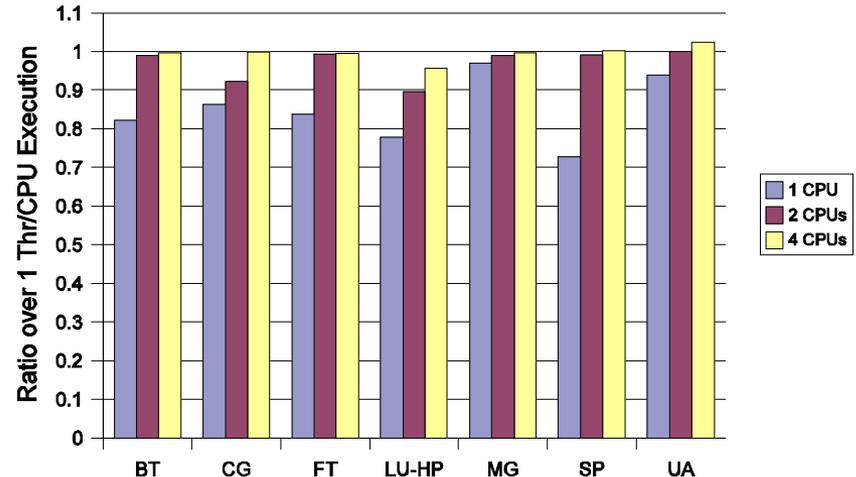


# L2 References

L2 Accesses (SMT)



L2 Accesses (CMP)

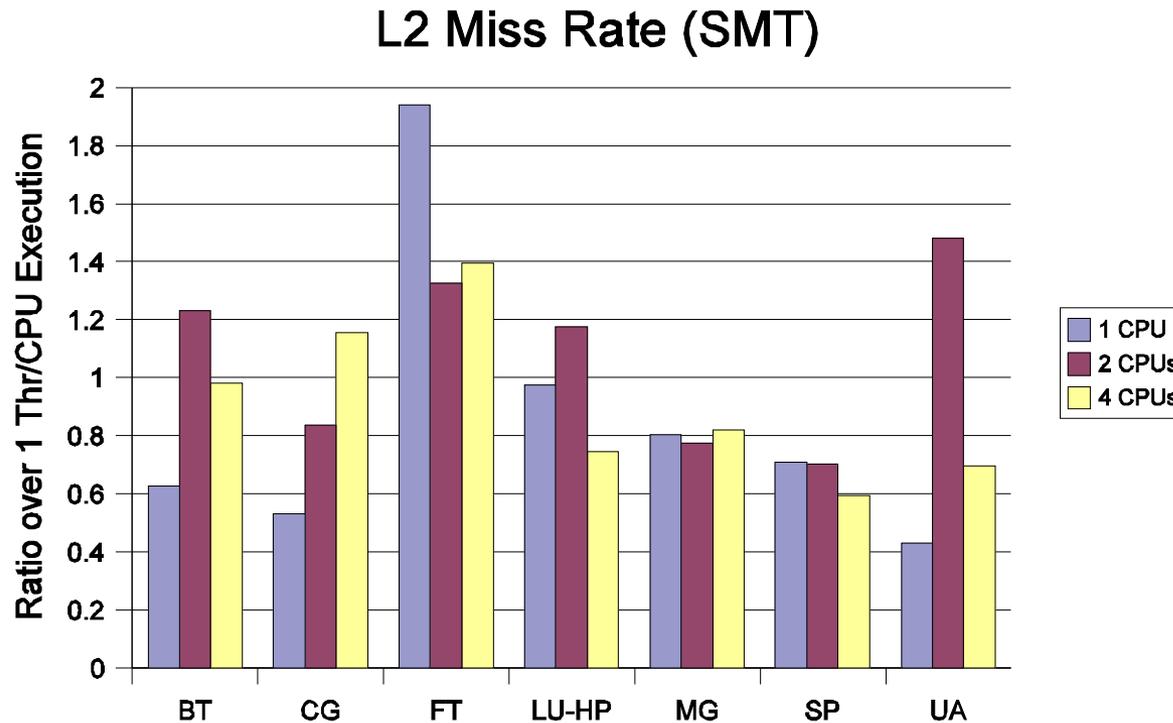


On SMT, two threads executing causes L2 references to go up by 42%

On CMP, running two threads causes L2 references to go down by 37%



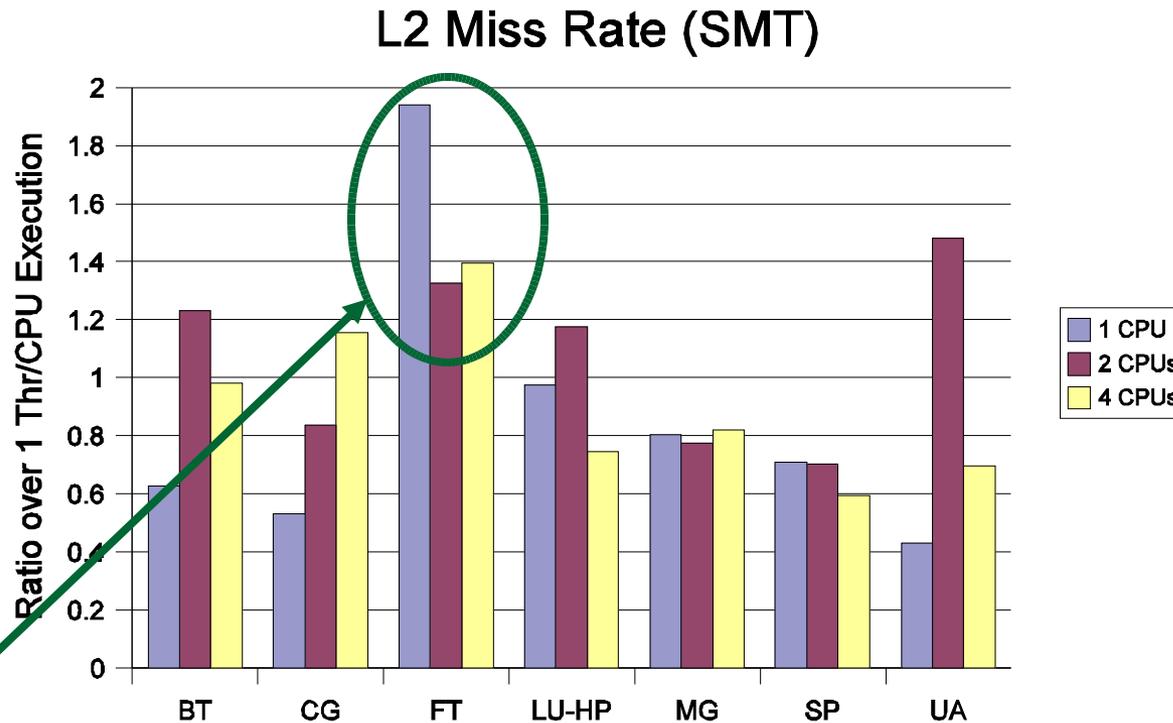
# L2 Miss Rate SMT



L2 miss rate highly dependent upon application characteristics



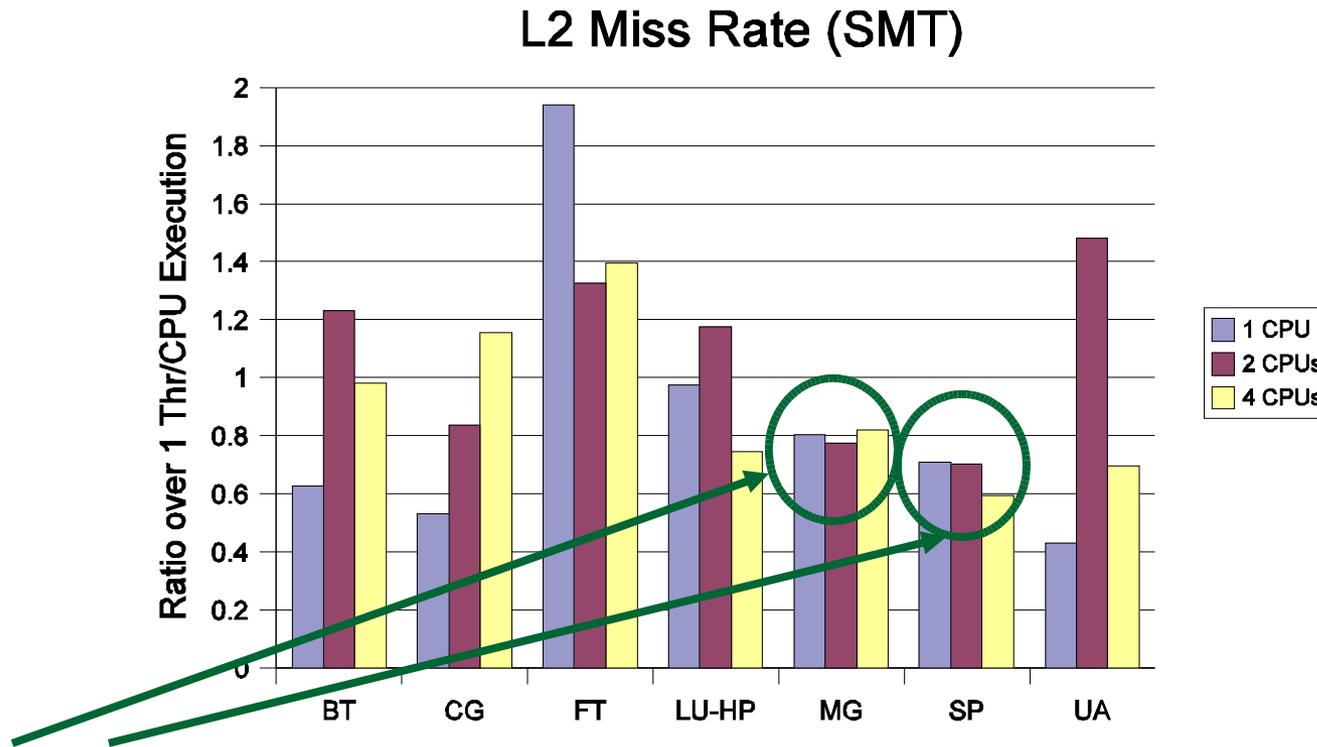
# L2 Miss Rate SMT



If working sets of both threads do not fit into shared cache, L2 miss rate increases



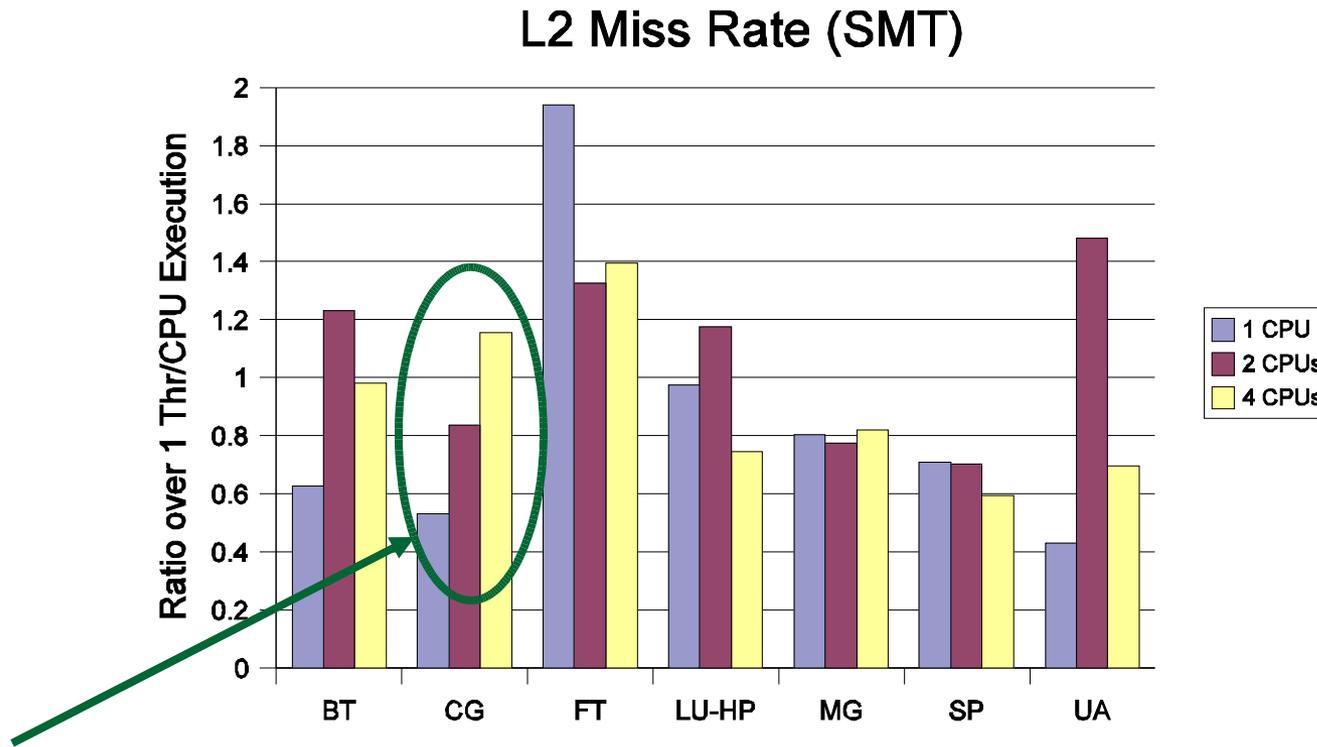
# L2 Miss Rate SMT



On the other hand, applications can benefit from data sharing in the shared cache



# L2 Miss Rate SMT

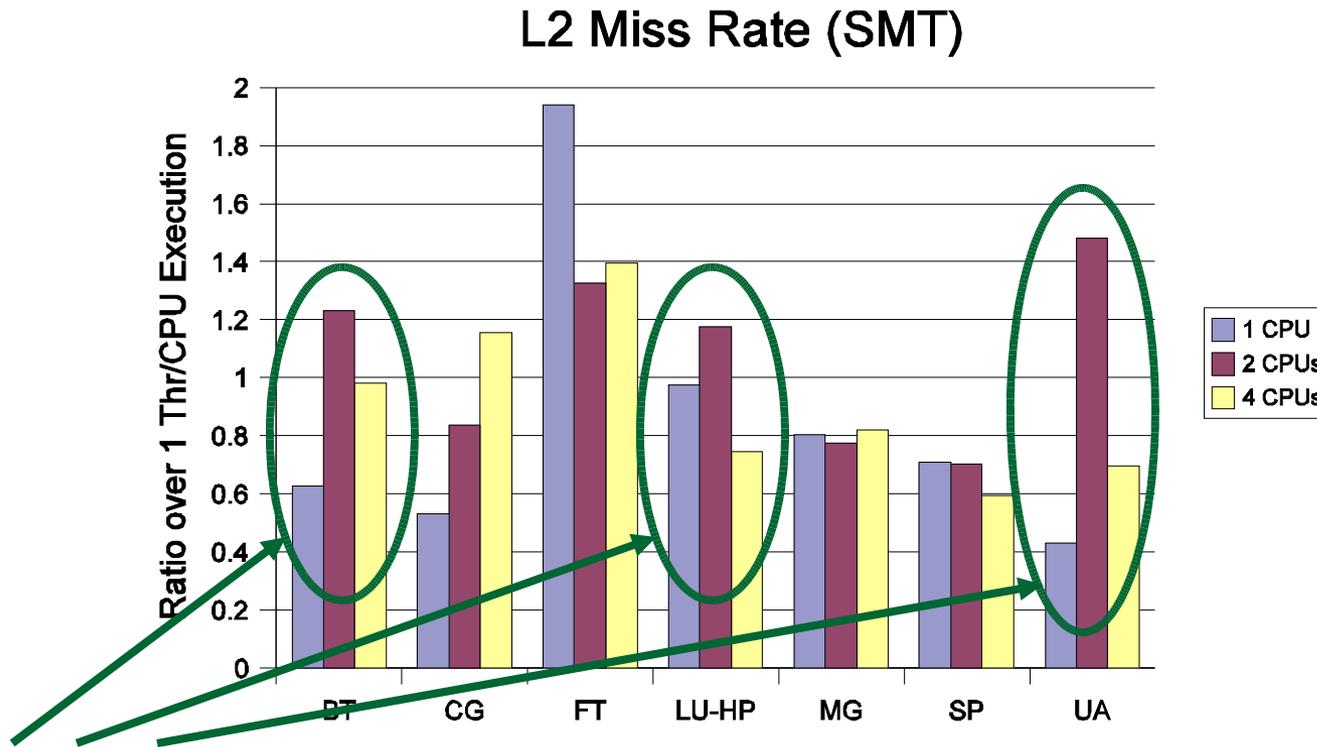


CG has a high degree of data sharing which is good with one processor but has negative consequences with more processors

- Inter-processor data sharing results in cache line invalidations



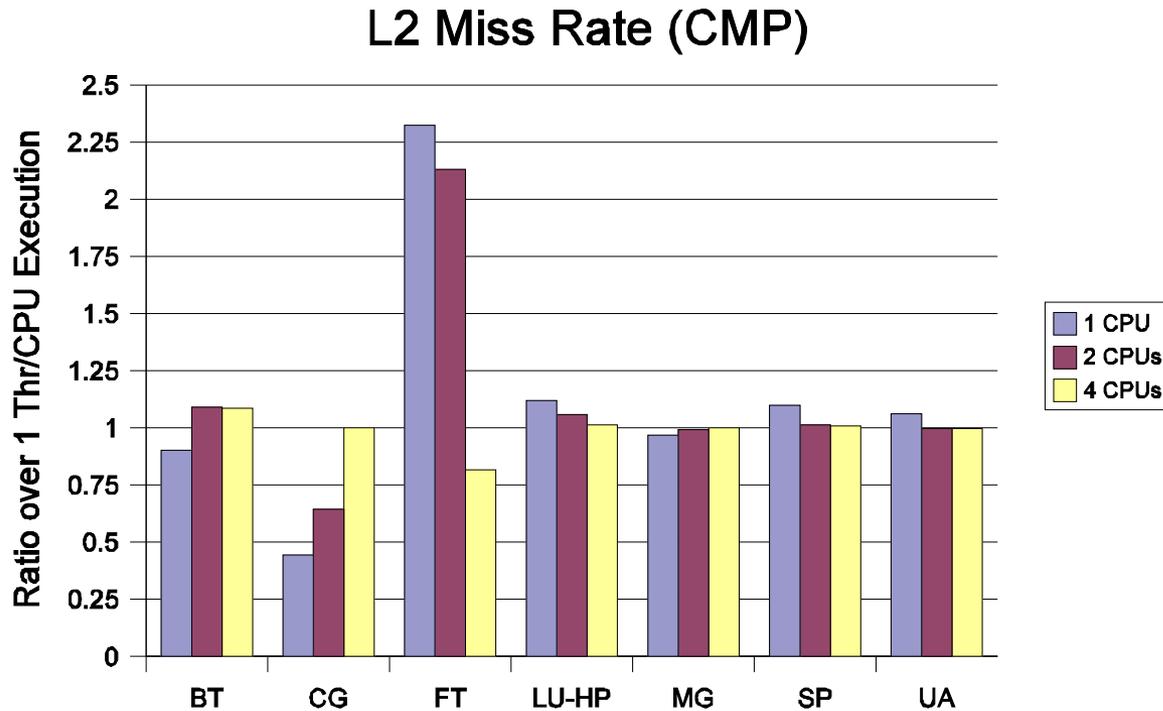
# L2 Miss Rate SMT



Tradeoffs between sharing in the L2 of one processor and increased cumulative L2 space from multiple processors



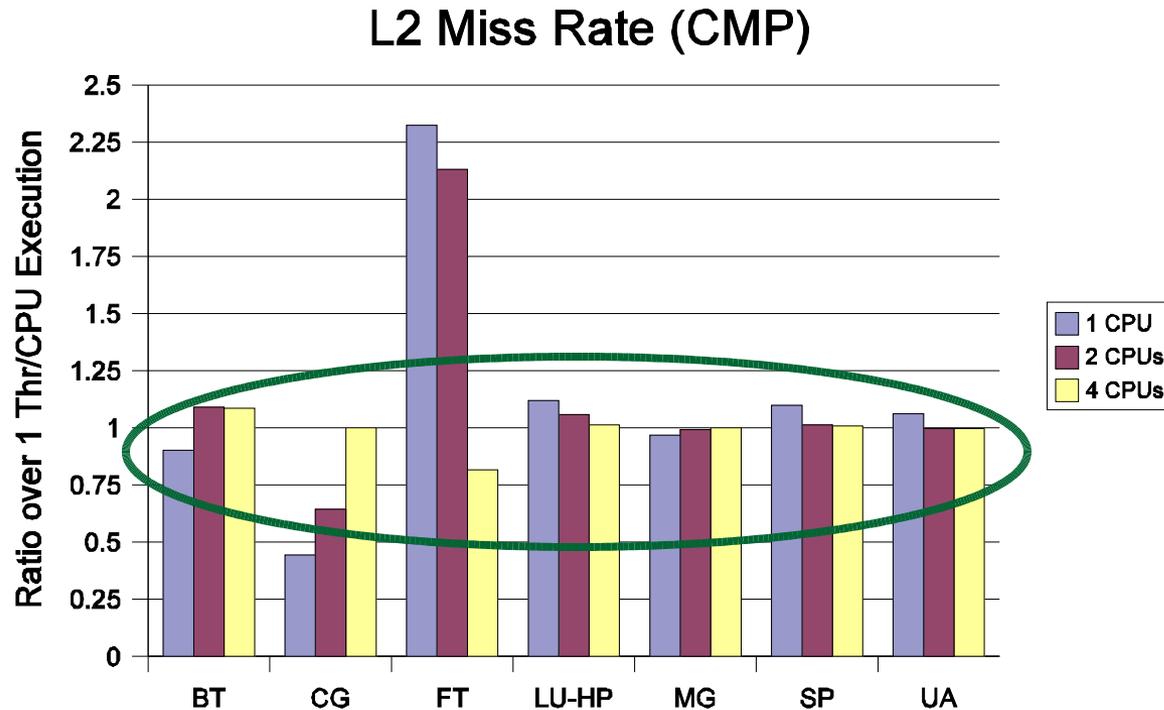
# L2 Miss Rate CMP



L2 miss rate much more stable on the CMP processors



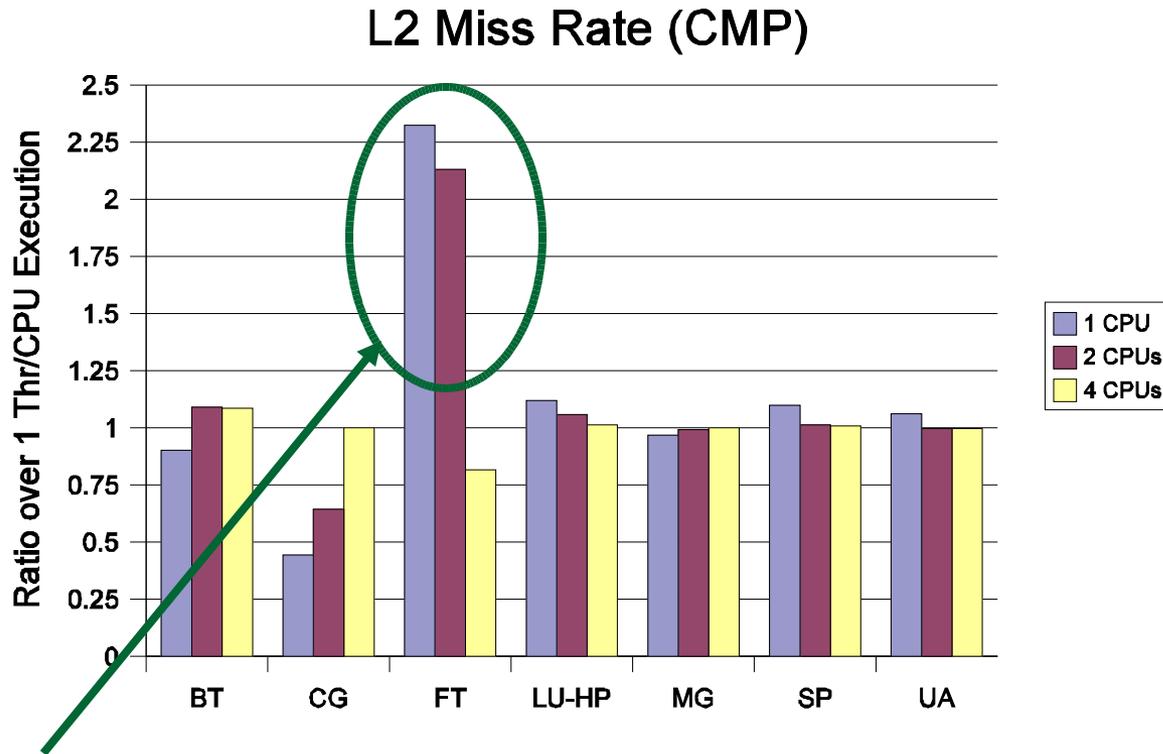
# L2 Miss Rate CMP



L2 miss rate generally uncorrelated to number of threads per processor



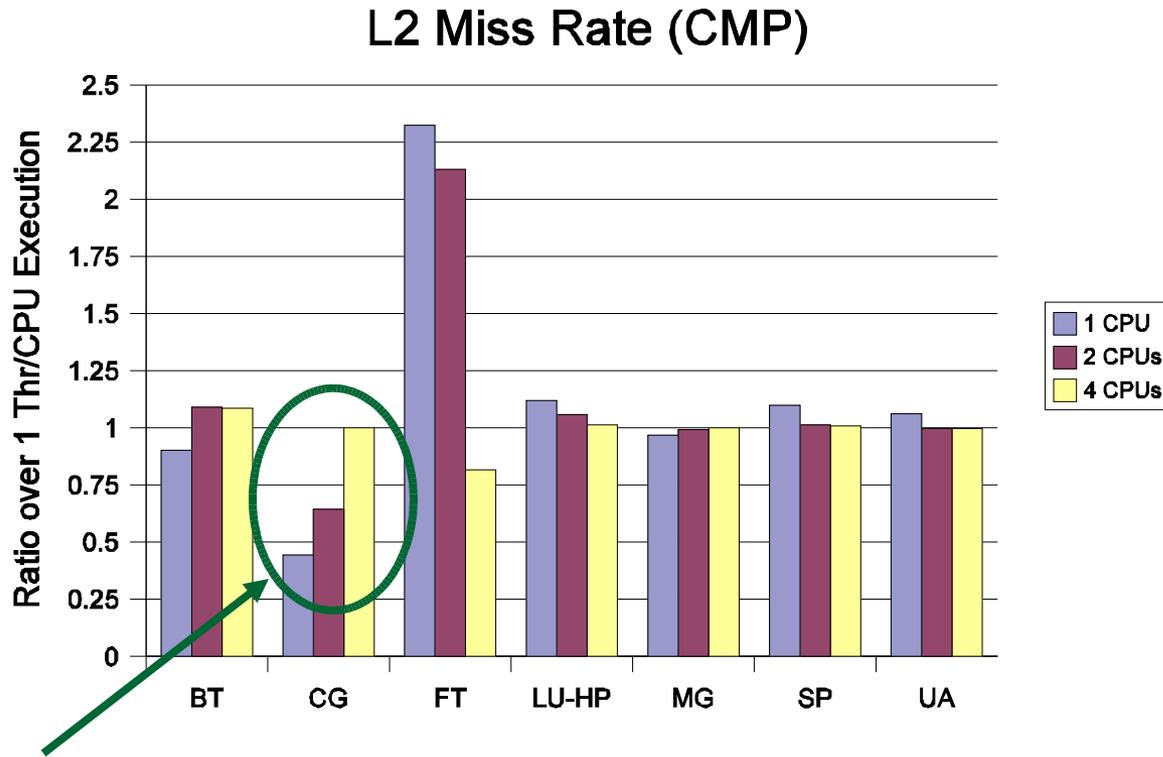
# L2 Miss Rate CMP



The large working set of FT is still a problem for 1 and 2 processors



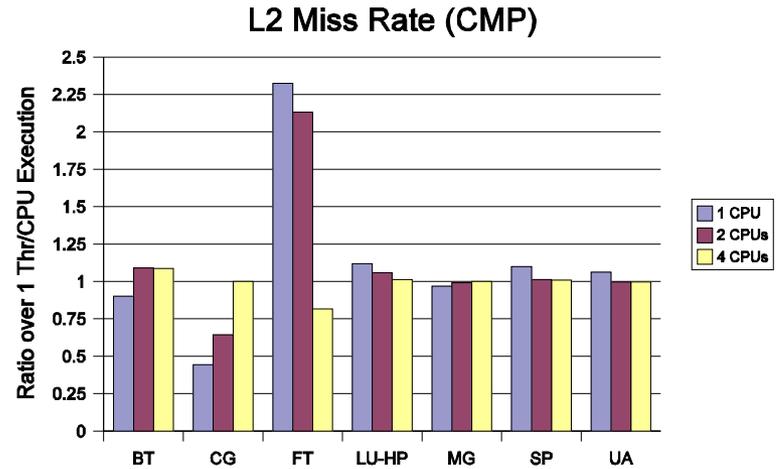
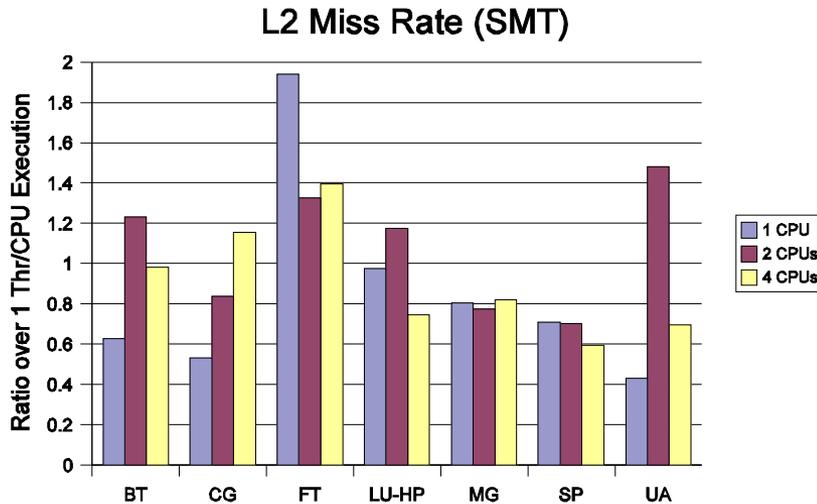
# L2 Miss Rate CMP



CG retains the property observed on SMT as well



# L2 Miss Rate Comparison



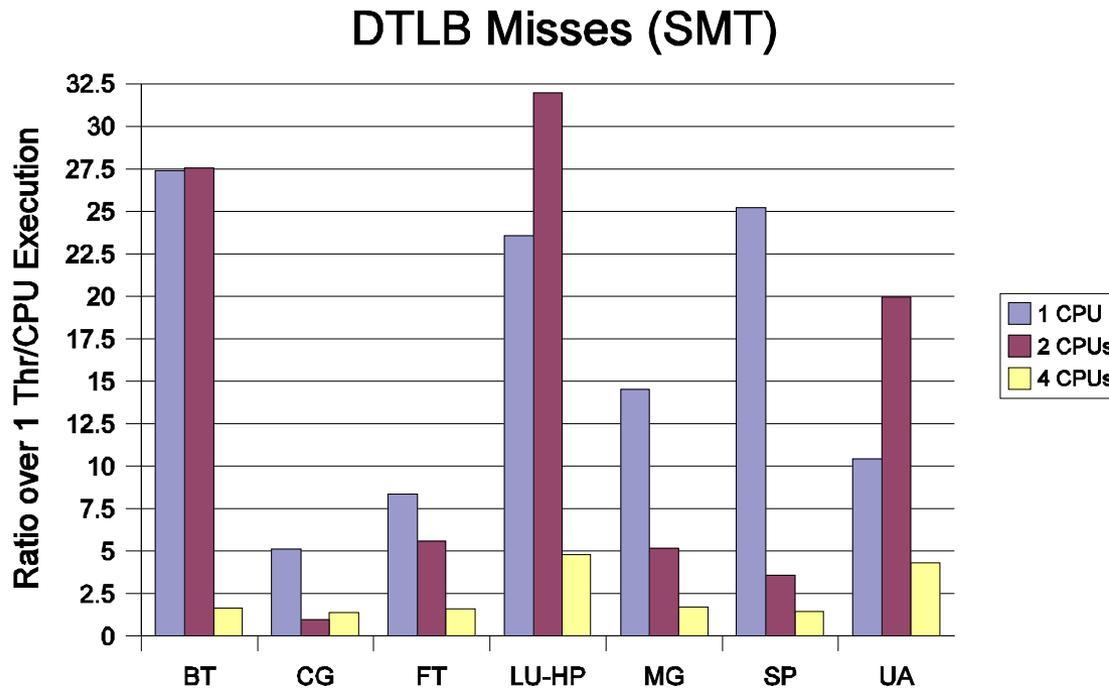
More potential for L2 data sharing on SMT, with shared L1

Private L1s can reduce L2 sharing, less L2 accesses

On CMP, L2 not as affected by executing two threads per processor



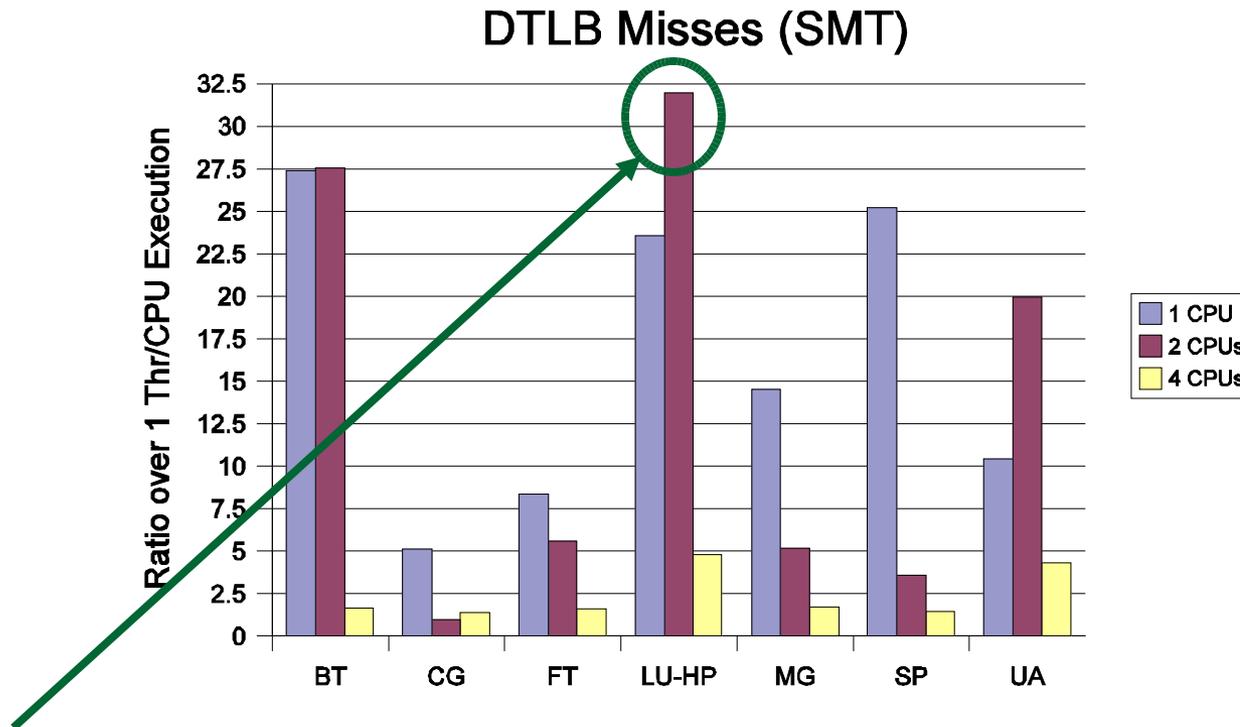
# Data TLB Misses SMT



The number of DTLB misses increases dramatically with use of second execution context



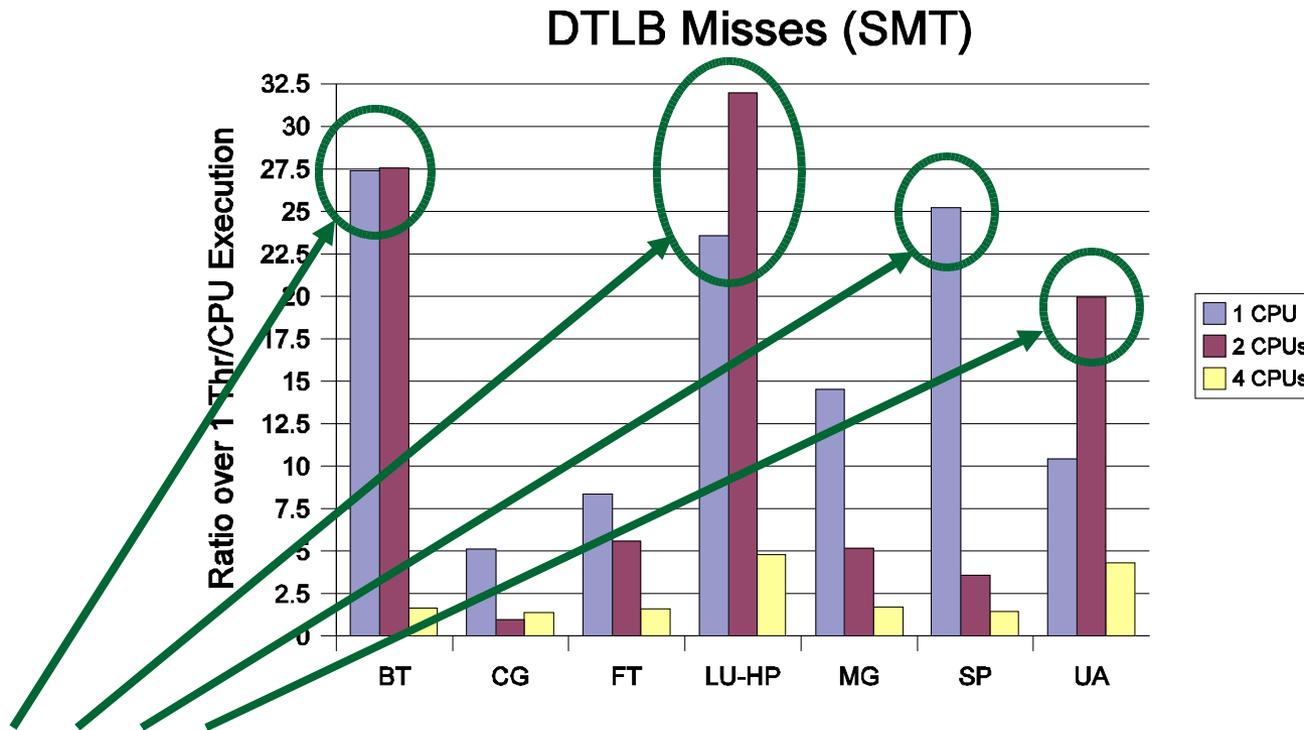
# Data TLB Misses SMT



DTLB misses suffer up to a 32-fold increase



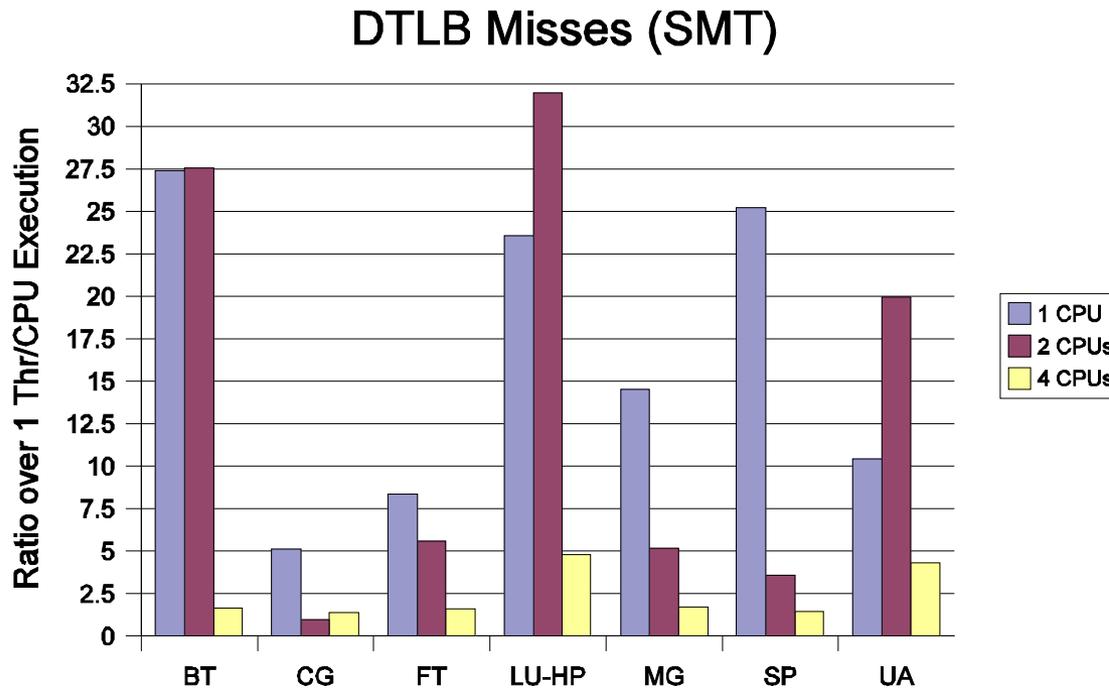
# Data TLB Misses SMT



6 executions suffer a 20 or more fold increase



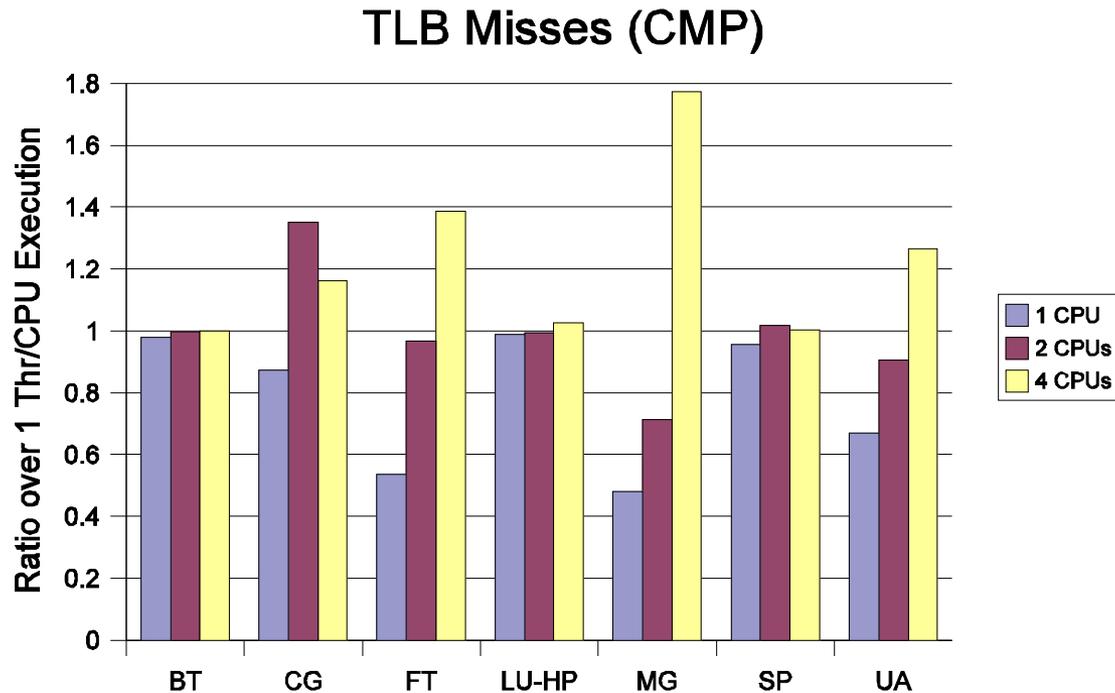
# Data TLB Misses SMT



Intel's HT processor has surprisingly small DTLB -> poor coverage of the virtual address space



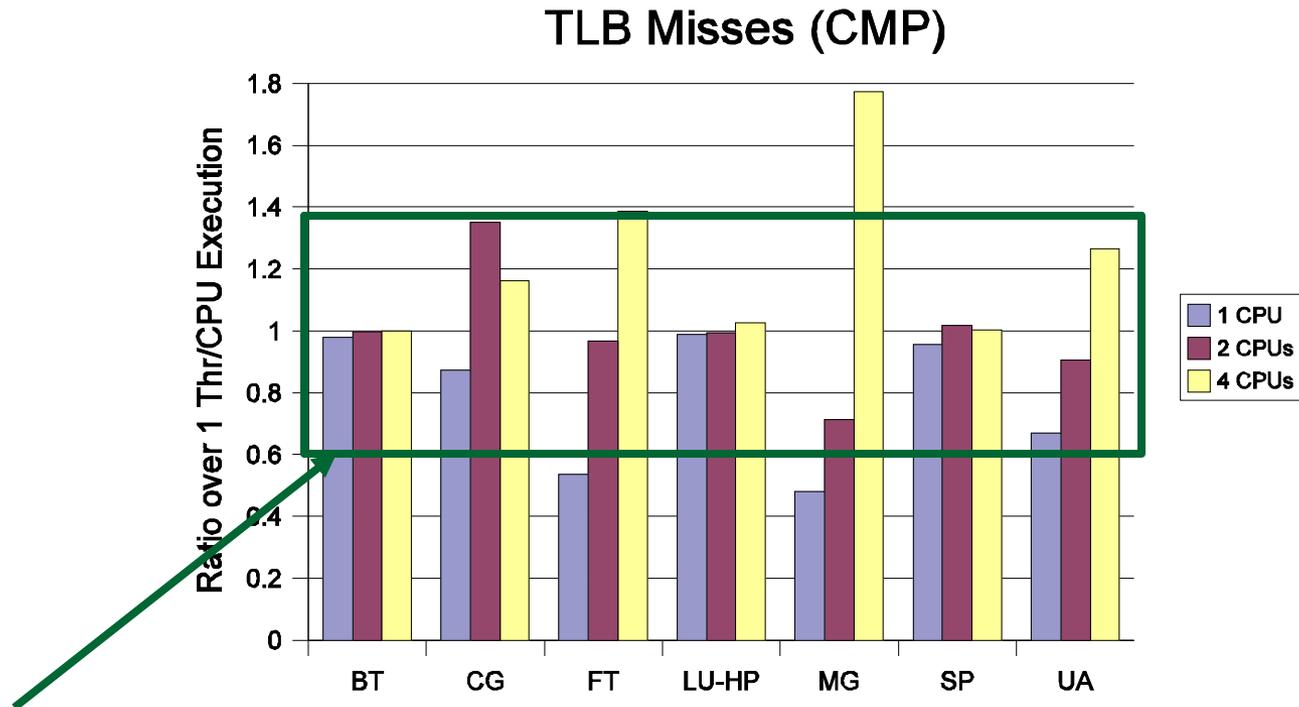
# Data TLB Misses CMP



CMP provides private DTLB to each core, which results in much more stable DTLB performance



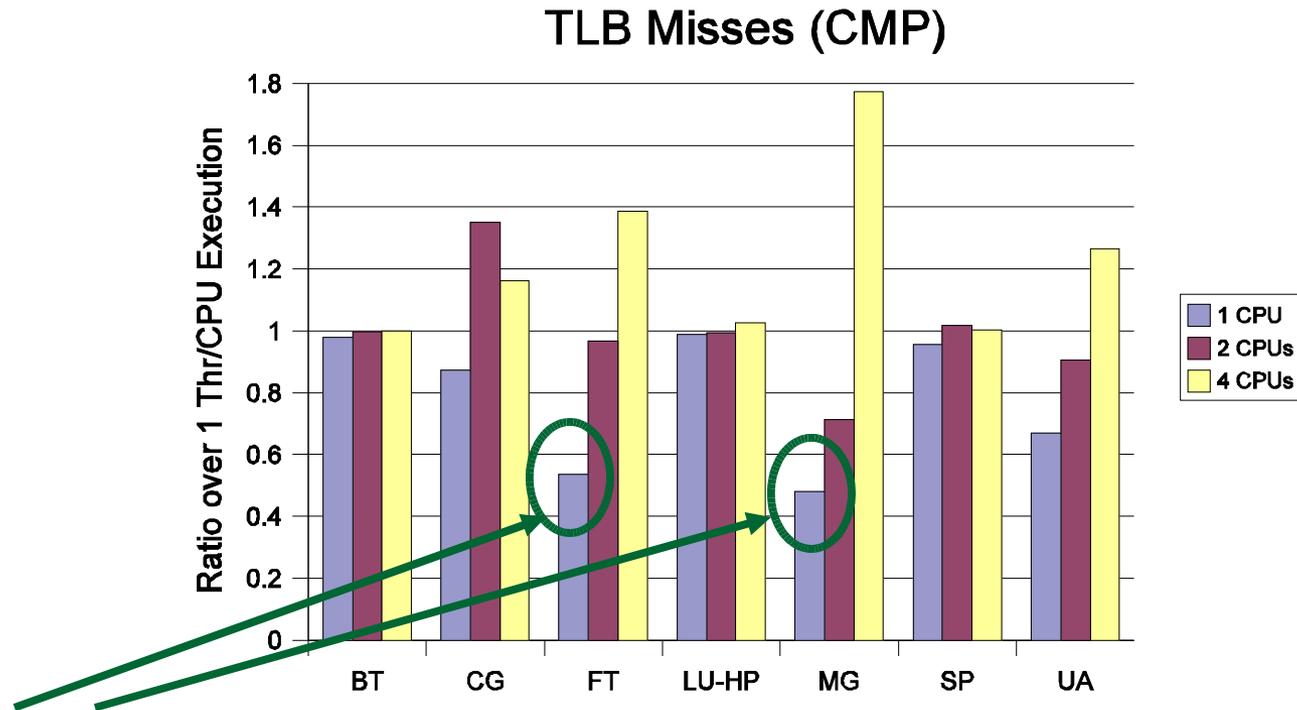
# Data TLB Misses CMP



The majority of the executions experience normalized DTLB misses quite close to 1



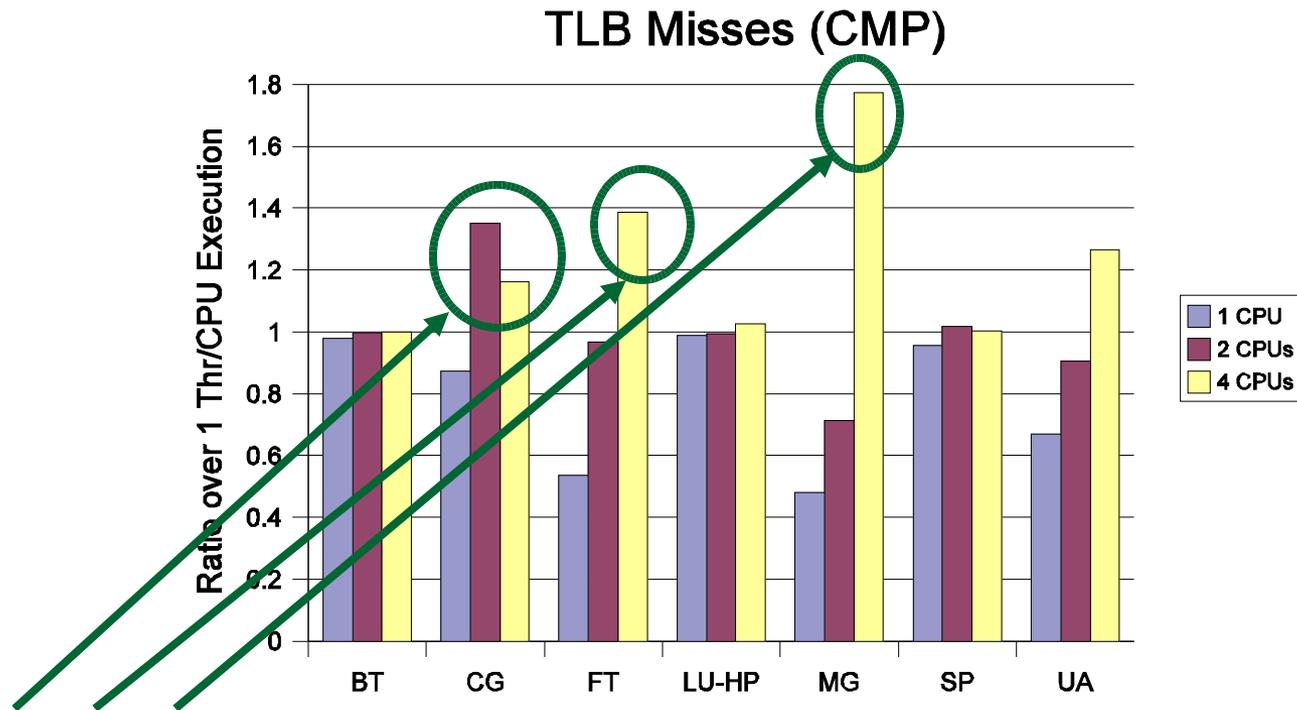
# Data TLB Misses CMP



DTLB misses may decrease with 2 threads due to the cumulatively larger DTLB size from the DTLB duplication



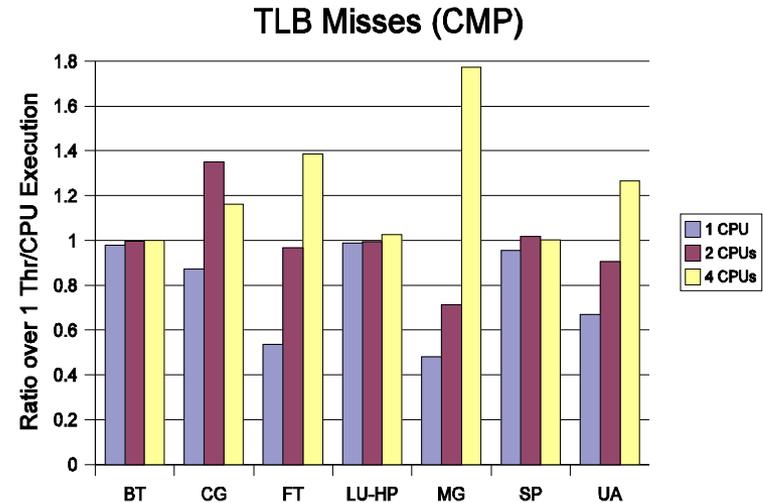
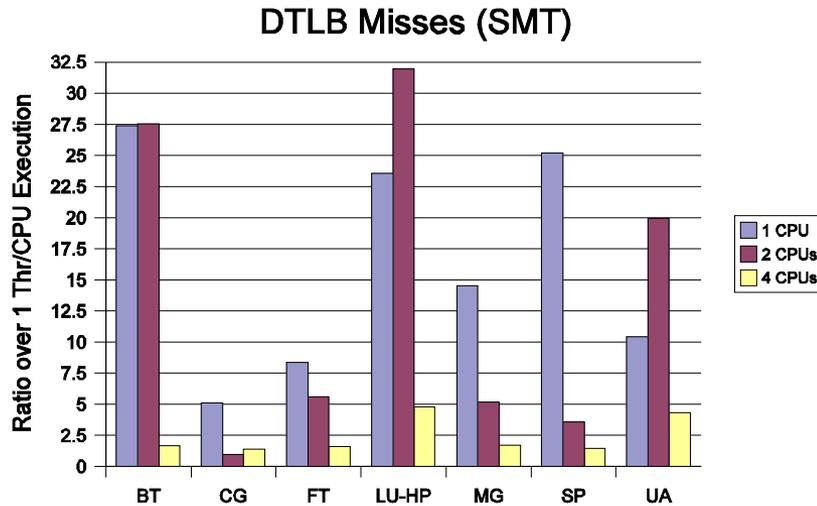
# Data TLB Misses CMP



But if entries are duplicated between threads, then benefits of replicated DTLBs are reduced



# Data TLB Misses Comparison



Privatizing the DTLB significantly reduces misses

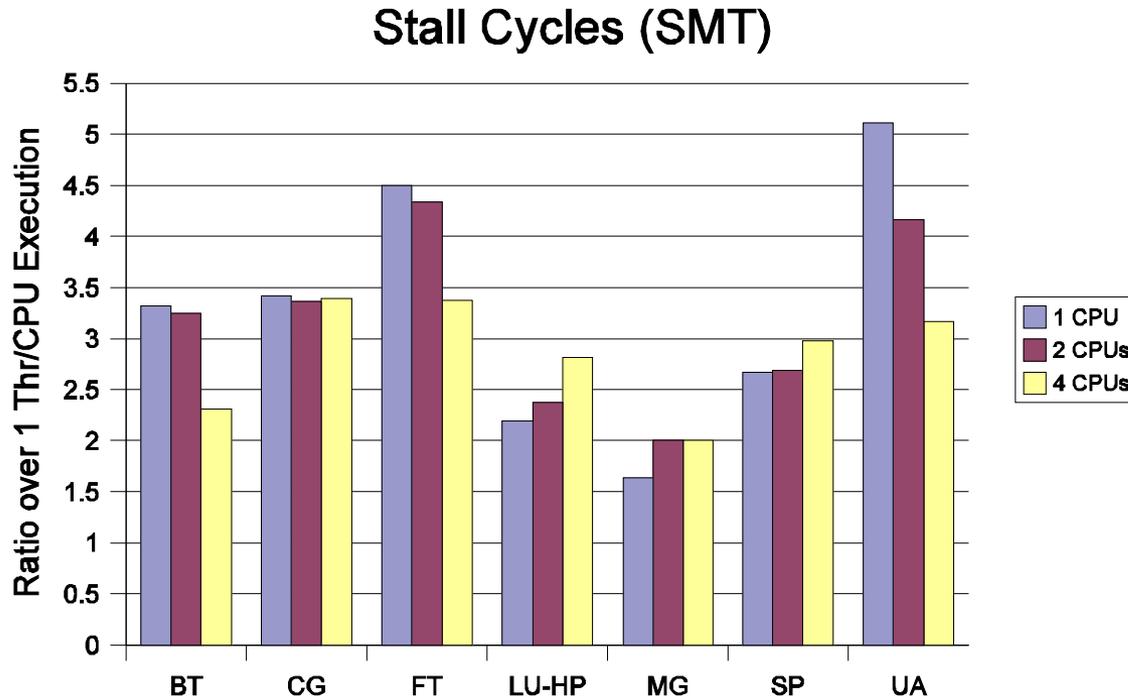
SMT average 10.8-fold increase

CMP average 0% increase

Not very affected by multiple threads on a processor



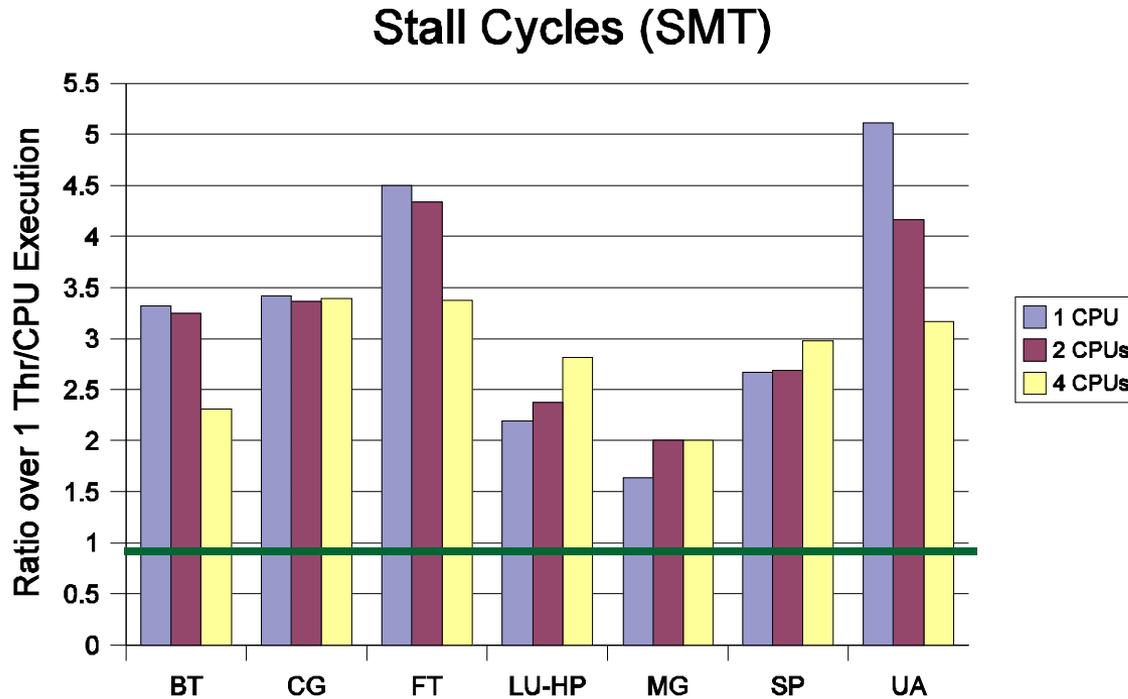
# Stall Cycles SMT



On SMT, stall cycles represent cumulative effects of waiting for memory accesses and resource contention between co-executing threads



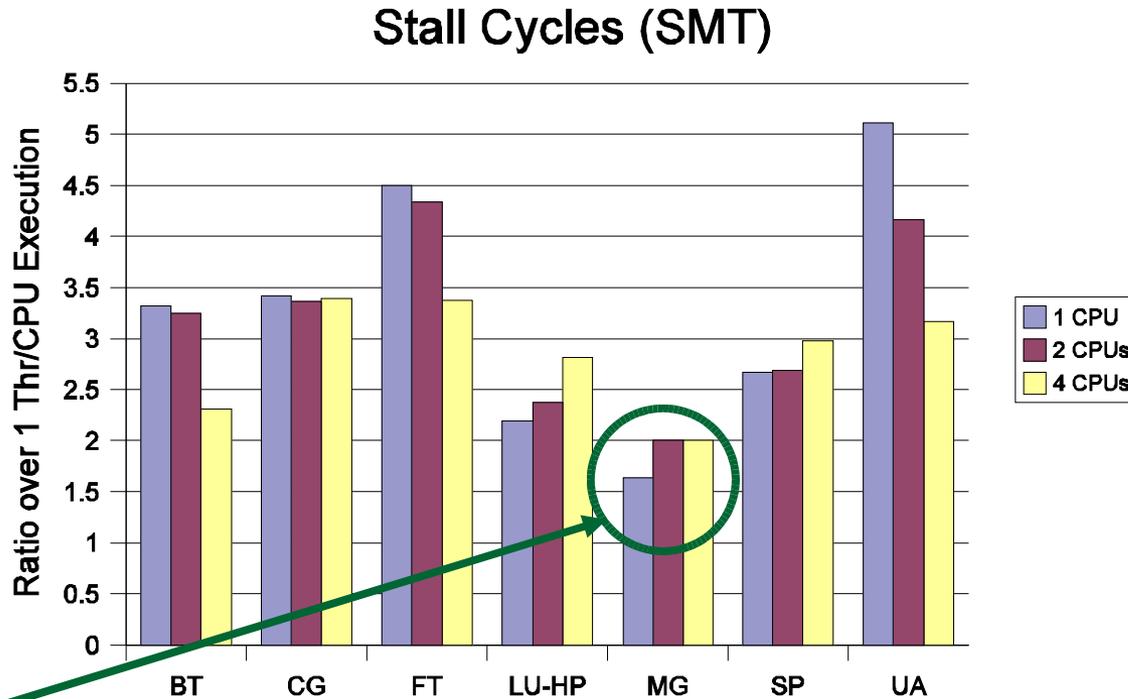
# Stall Cycles SMT



Stall cycles for all executions increase with use of second execution context



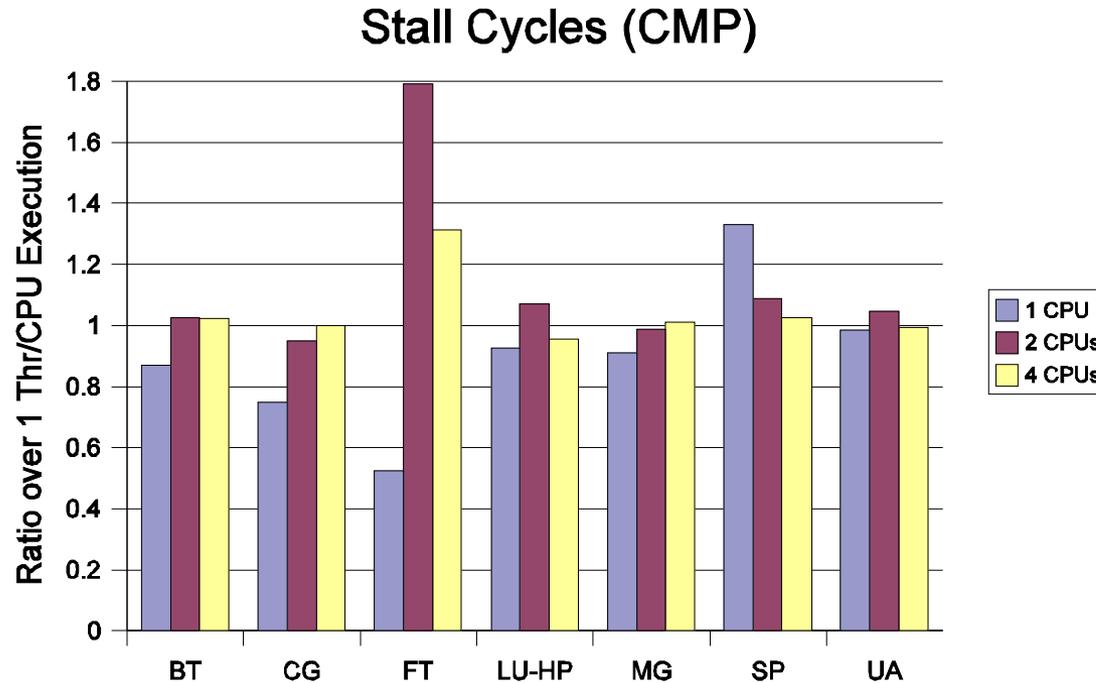
# Stall Cycles SMT



In the best case, MG, stall cycles still increase by about a factor of 2



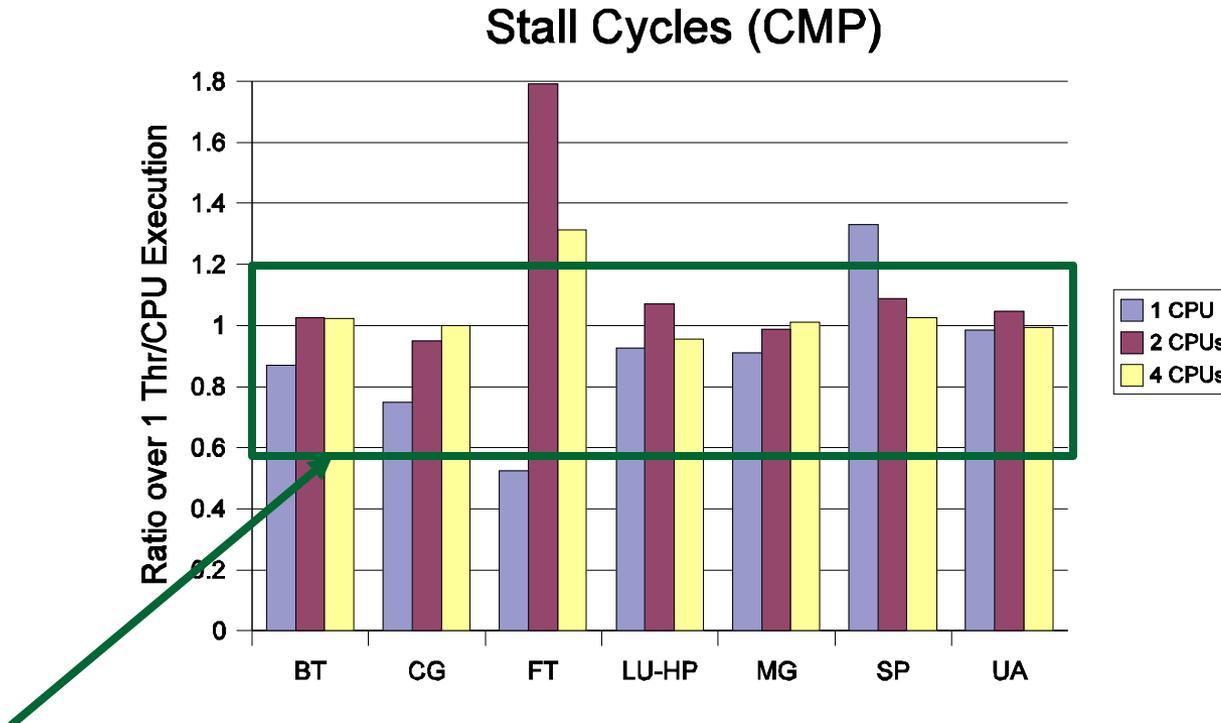
# Stall Cycles CMP



CMP only shares outer levels of cache and interface to external devices, which greatly reduces possible sources of stall cycles



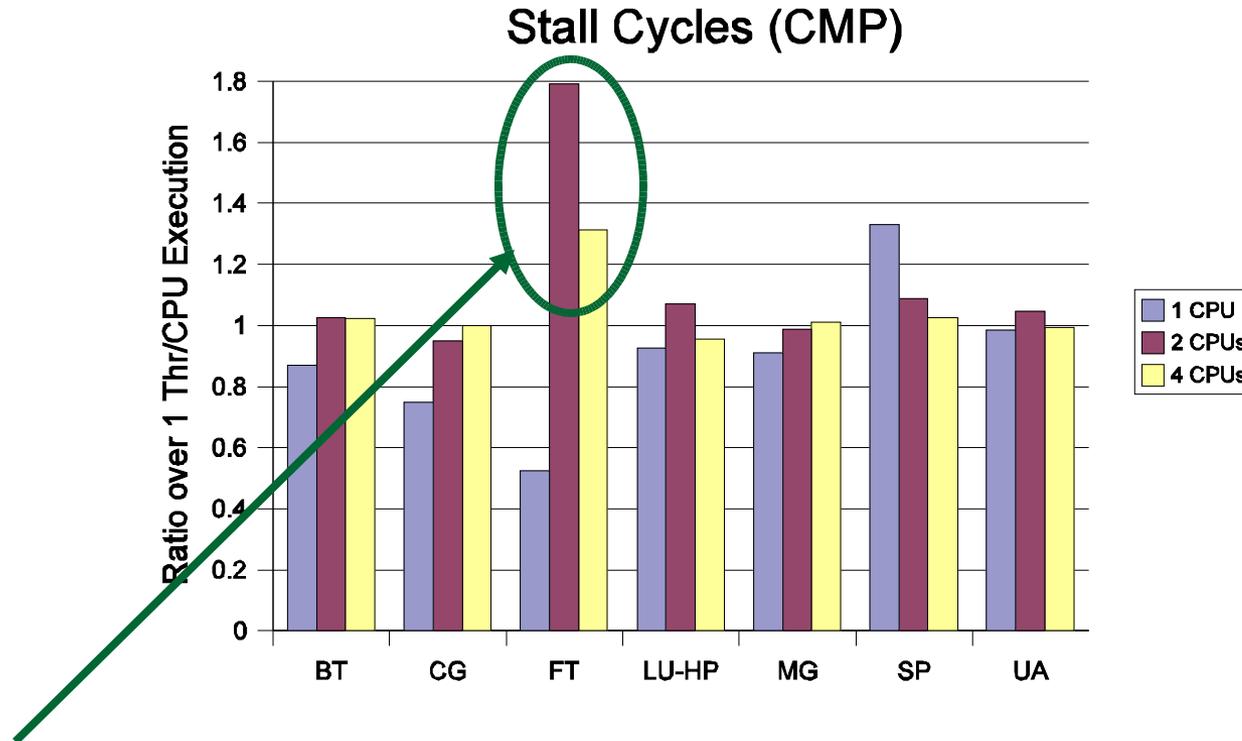
# Stall Cycles CMP



Once again, CMP's resource replication results in a stabilized number of stall cycles, close to 1



# Stall Cycles CMP

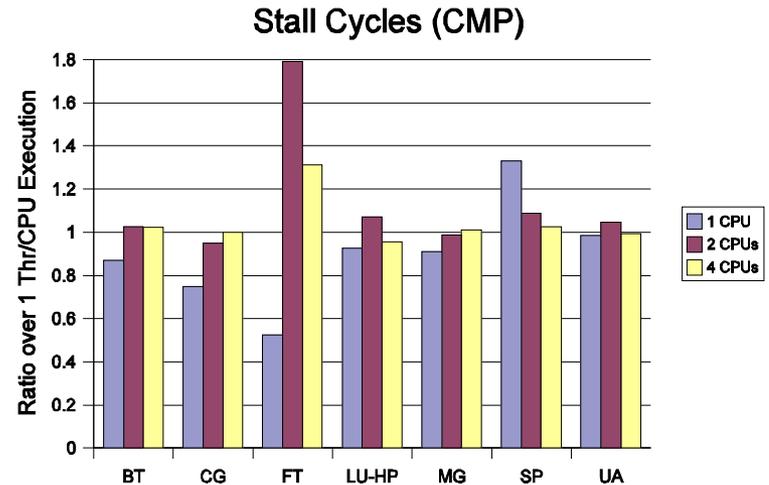
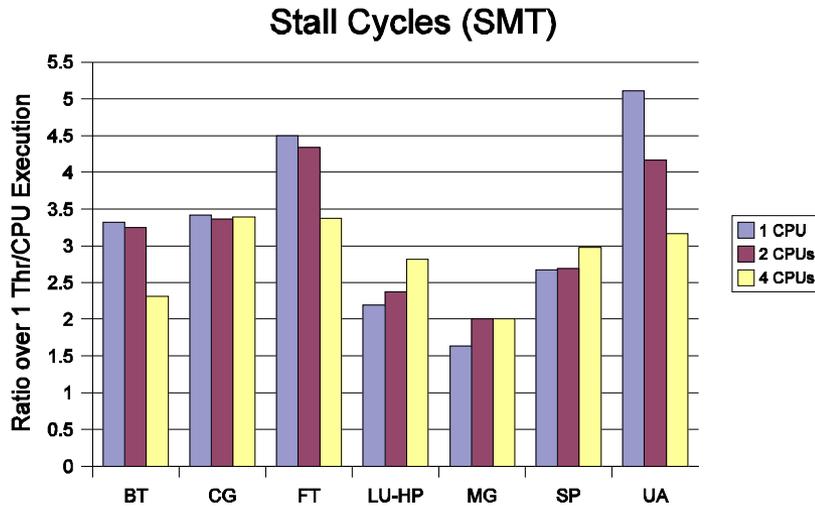


FT has a relatively large increase in stall cycles

As we have already seen, it suffers from contention in the L2 and DTLB, even on the CMP architecture



# Stall Cycles Comparison

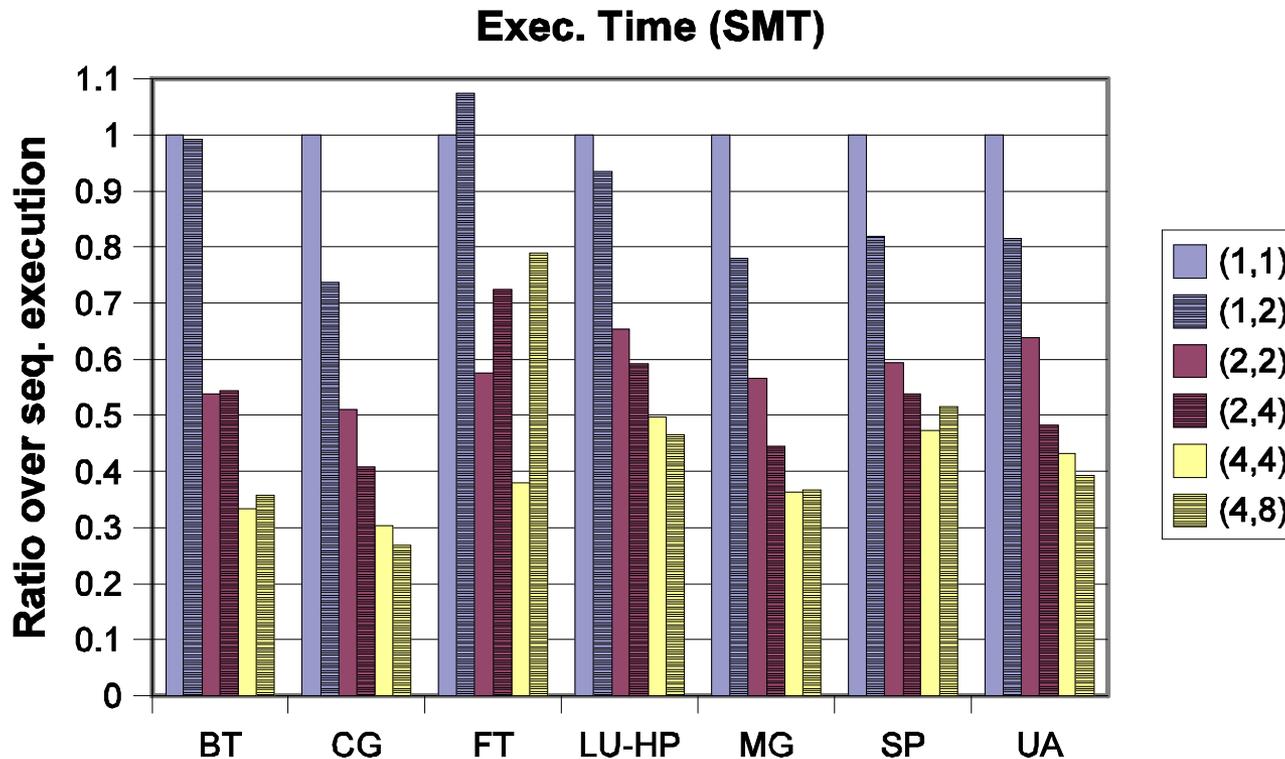


Increase of 310% for SMT vs. only 3% for CMP

Signifies that vast majority of stalls on SMT result from contention for internal processor resources



# Execution Time SMT



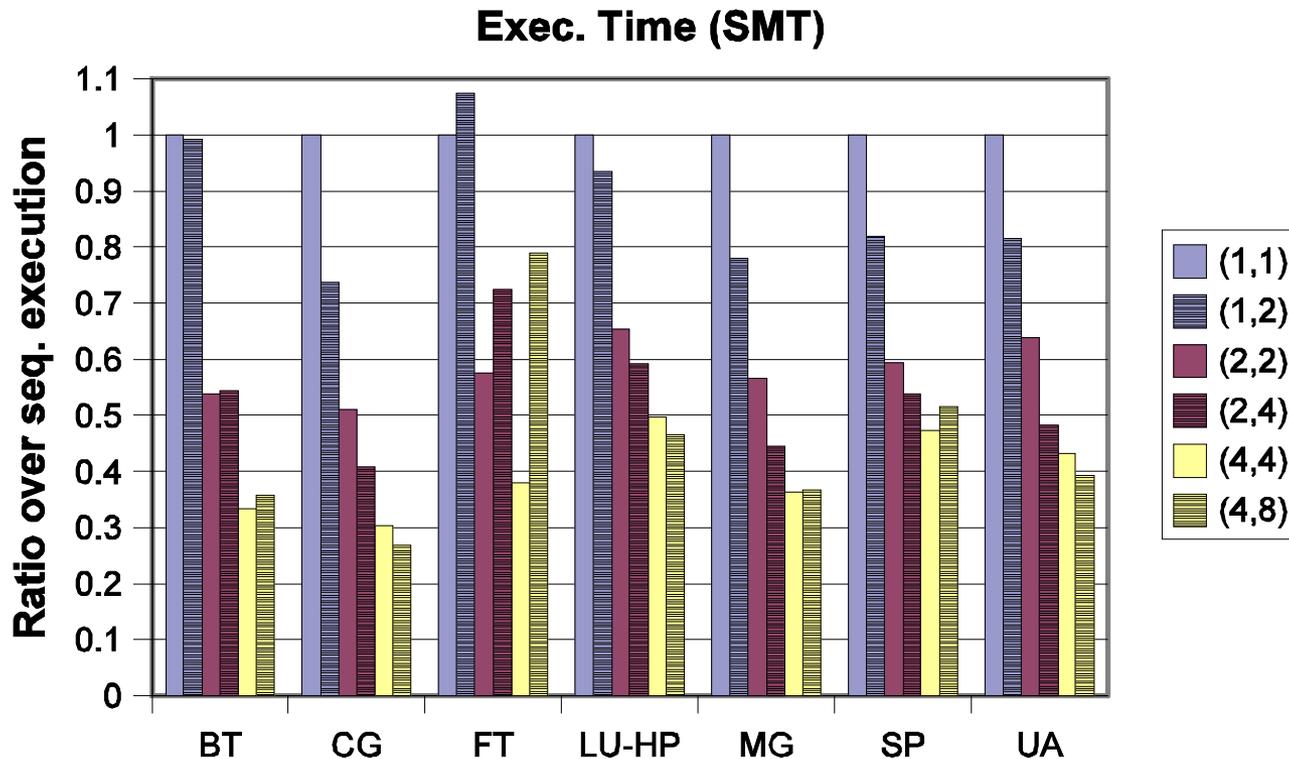
Two ways to evaluate the data:

Fixed number of CPUs, different number of threads

Fixed number of threads, different number of CPUs



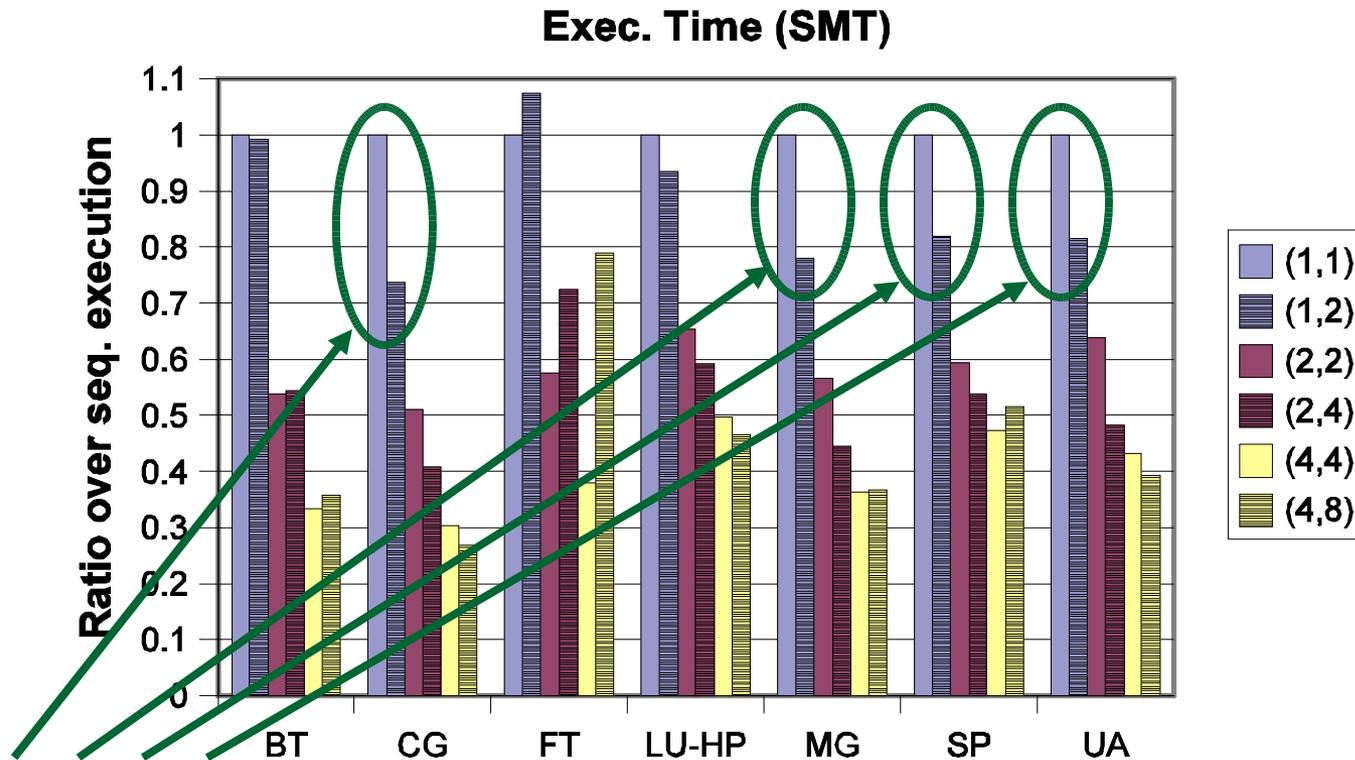
# Execution Time SMT



Running two threads on single CPU is not always beneficial for execution time compared to using a single thread



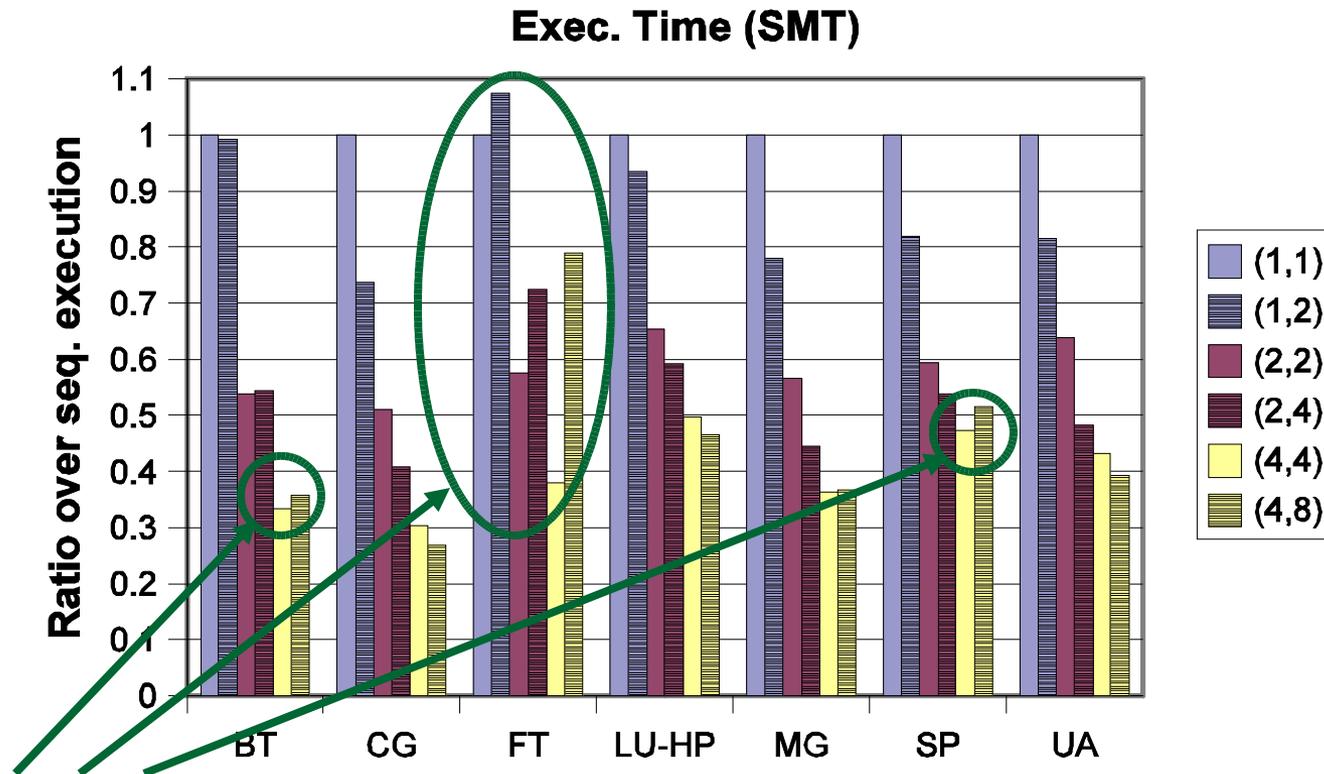
# Execution Time SMT



Running two threads on single CPU is not always beneficial for execution time  
Good in some cases...



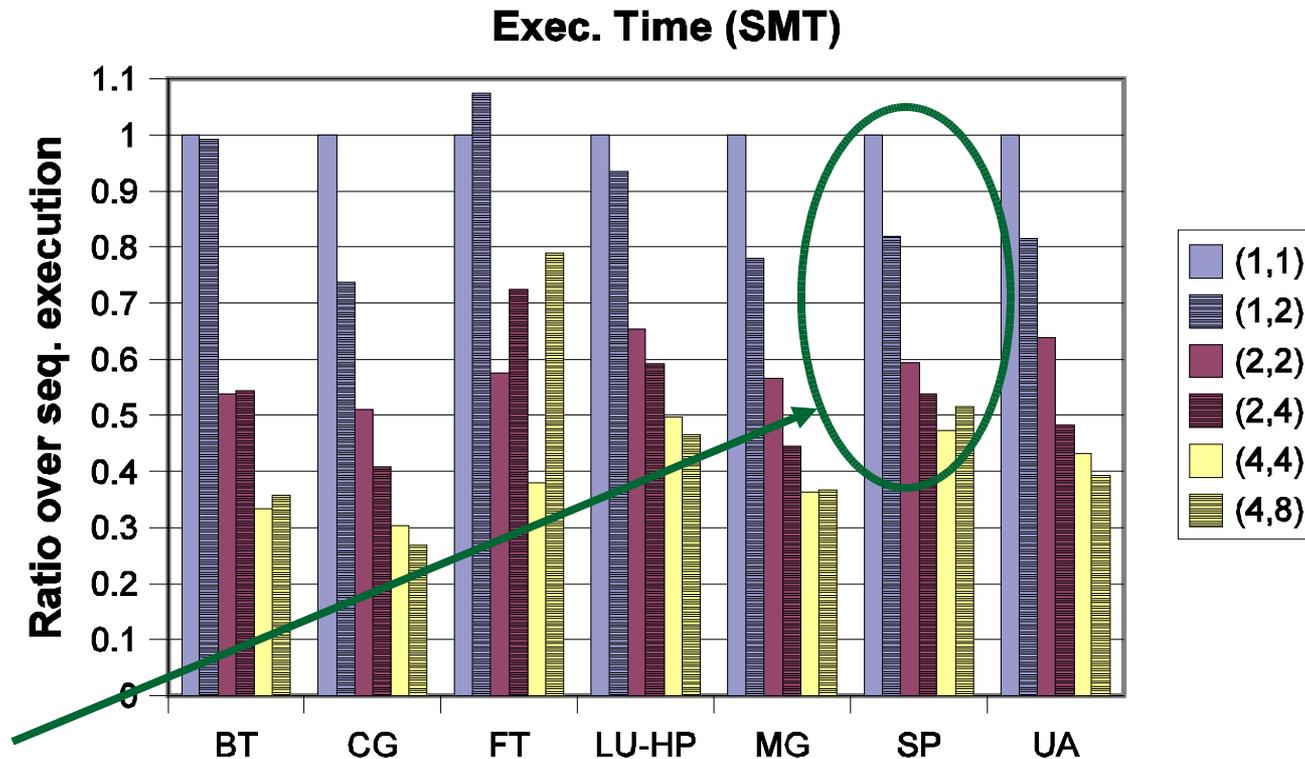
# Execution Time SMT



Running two threads on single CPU is not always beneficial for execution time  
...Bad in others



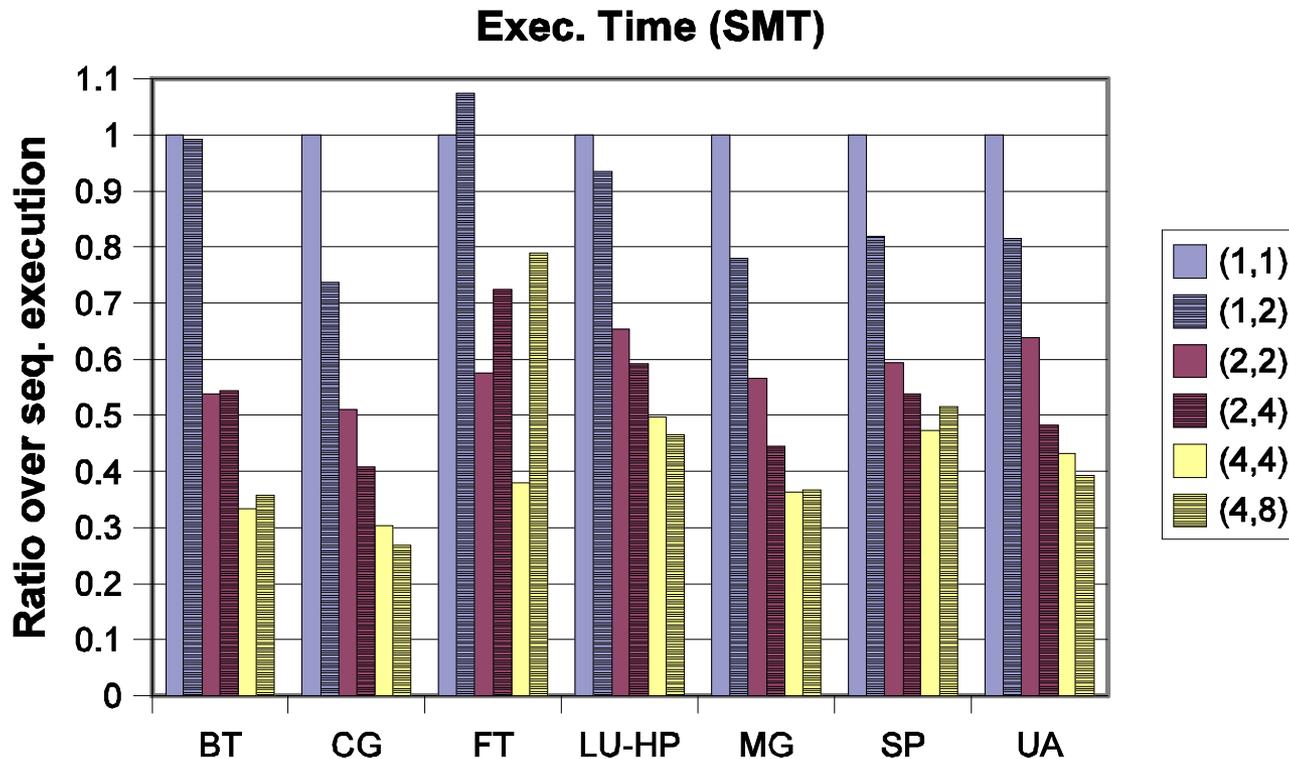
# Execution Time SMT



Even for a given application, neither one thread nor two threads per processor is always optimal



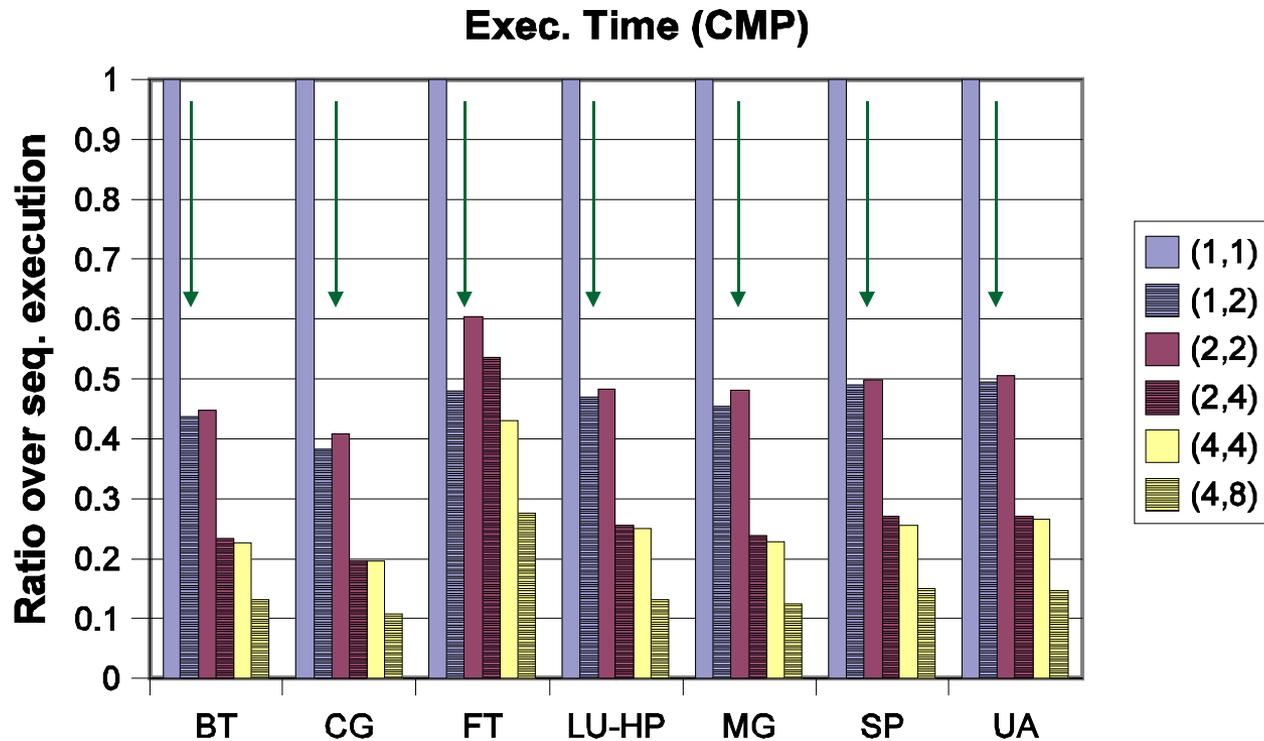
# Execution Time SMT



For a fixed number of threads, it is always better to execute them on as many different physical processors as possible



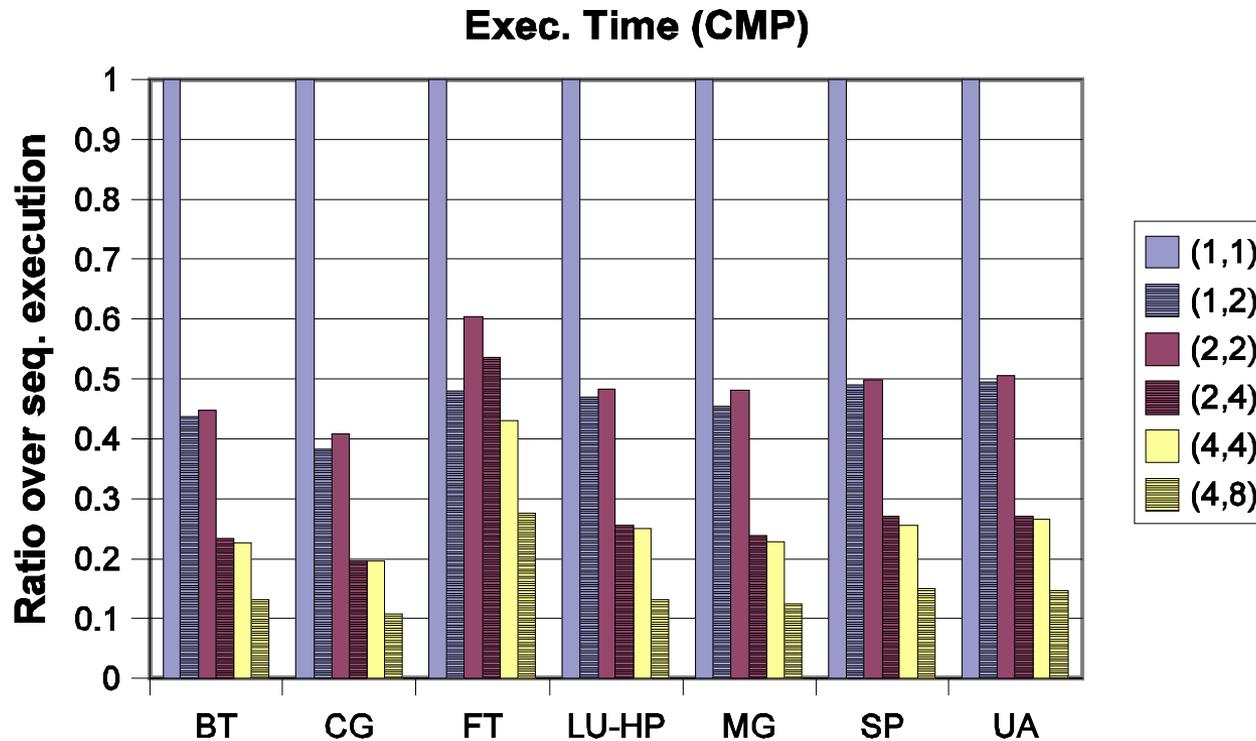
# Execution Time CMP



CMP, on the other hand, utilizes two threads per CPU very well



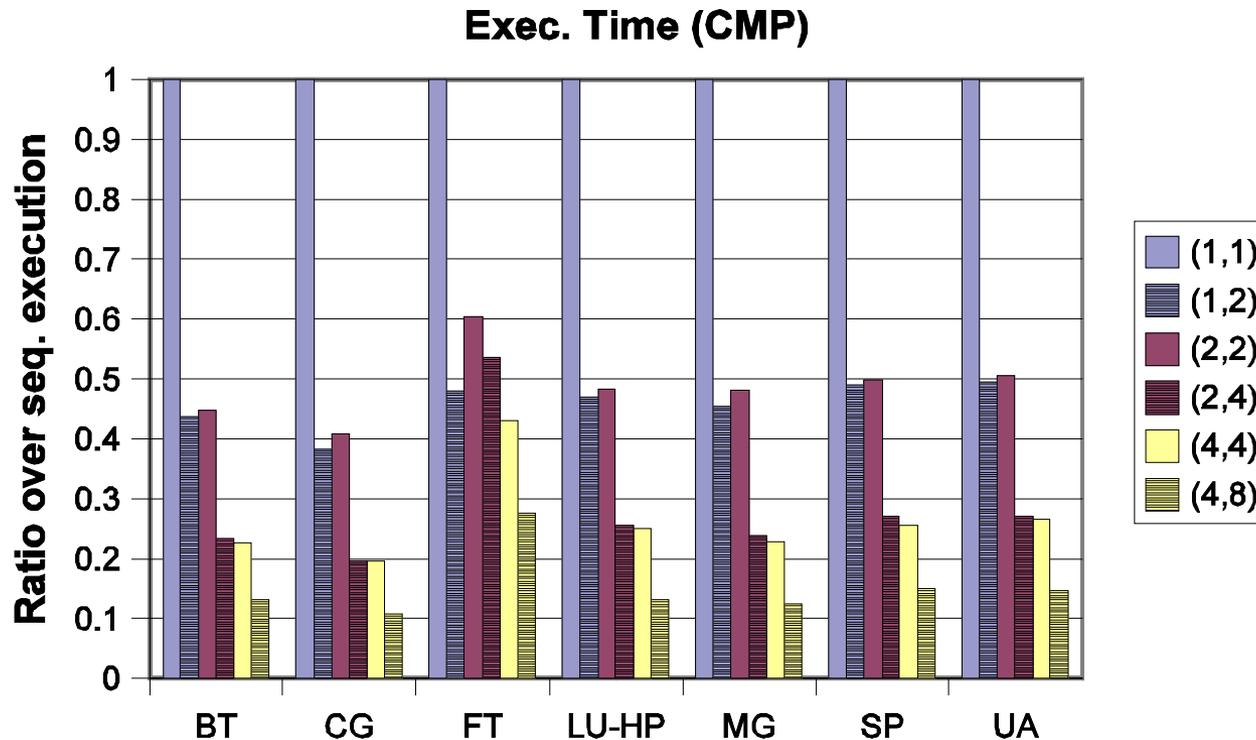
# Execution Time CMP



The activation of the second execution context was always beneficial



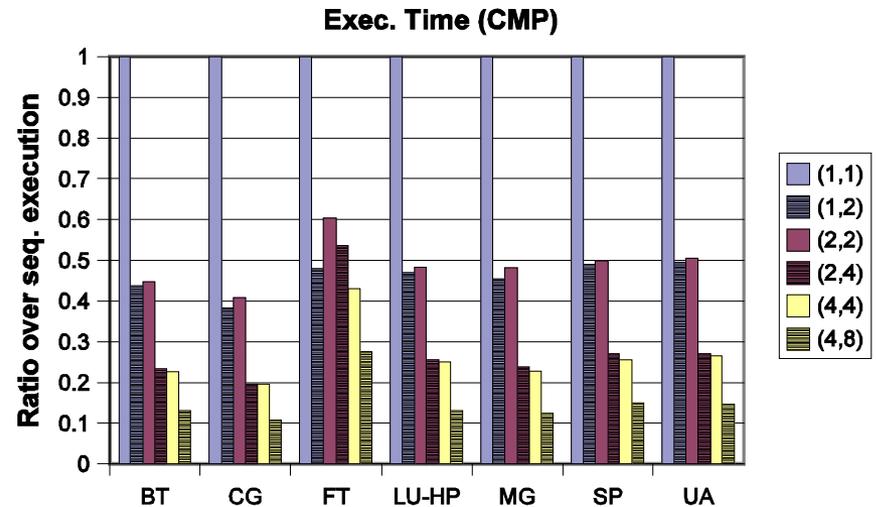
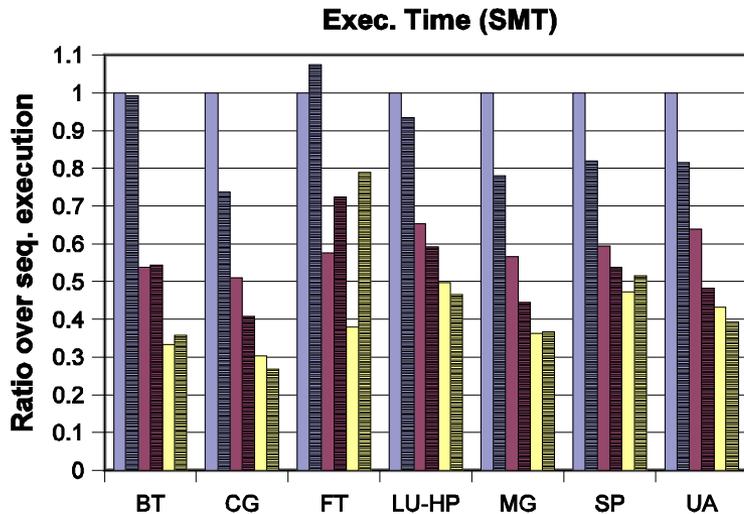
# Execution Time CMP



For a given number of threads, it was often better to run them on as few processors as possible



# Execution Time Comparison



CMP handles using two threads per processor much better than SMT

Due to greater resource replication in CMP, which reduces contention

CMP is a cost-effective means of improving performance



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**Adaptive Multithreading Degree Selection**

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# Adaptive Approach Description

Neither 1 or 2 threads per CPU is always better

Based on work by Zhang, et al from U. Toronto (PDCS'04)  
we try both and use whichever performs better

Selection is performed at the granularity of a parallel region

Function calls before and after each region, could be inserted by preprocessor

We only consider number of threads, rather than scheduling policy

However, no manual changes to source code

And no modifications to compiler or OpenMP runtime



# Description, cont.

```
Outermost Loop {  
    !$OMP PARALLEL{ ... } // Parallel Region 1  
    !$OMP PARALLEL{ ... } // Parallel Region 2  
    ...  
    !$OMP PARALLEL { ... } // Parallel Region N  
}
```

Since NPB are iterative, we record execution time of 2<sup>nd</sup> and 3<sup>rd</sup> iterations with 1 and 2 threads

Ignore 1<sup>st</sup> iteration as cache warm-up

Whichever number of threads performs better is used when the region is encountered in the future



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# Adaptive Experiments

Used the same 7 NPB benchmarks along with two other OpenMP codes

MM5: a mesoscale weather prediction model

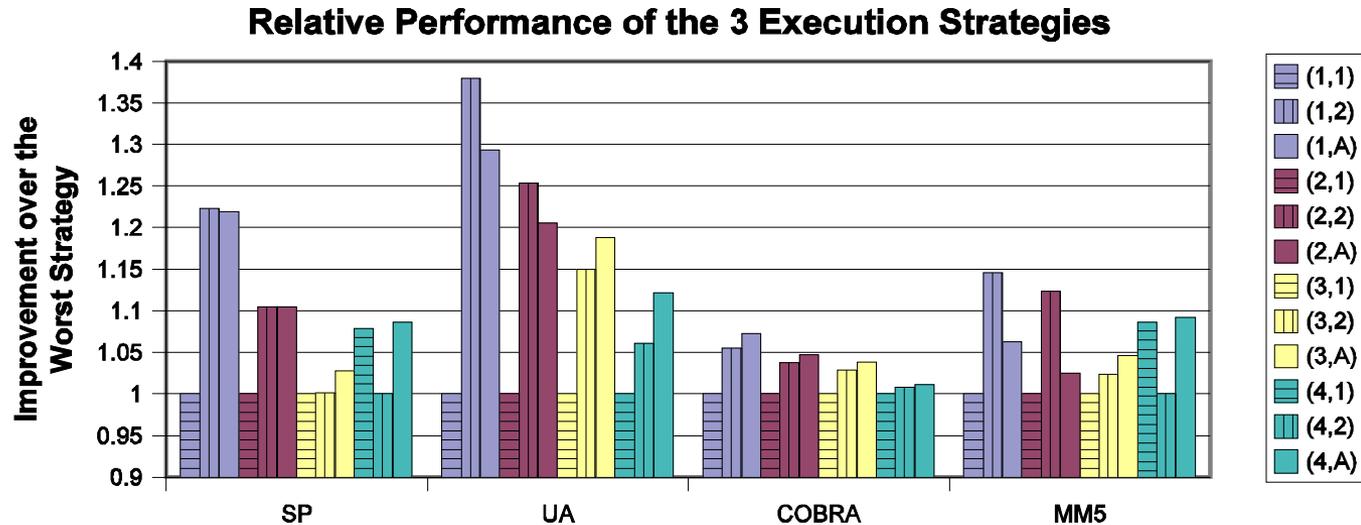
Cobra: a matrix pseudospectrum code

Ran on 1, 2, 3, and 4 processors

Compared adaptive execution times to both 1 and 2 threads per processor



# Results from Adaptation



Graph shows relative performance of each approach for 1, 2, 3, and 4 processors

- 1 thread per processor
- 2 threads per processor
- Adaptive approach



# Results from Adaptation

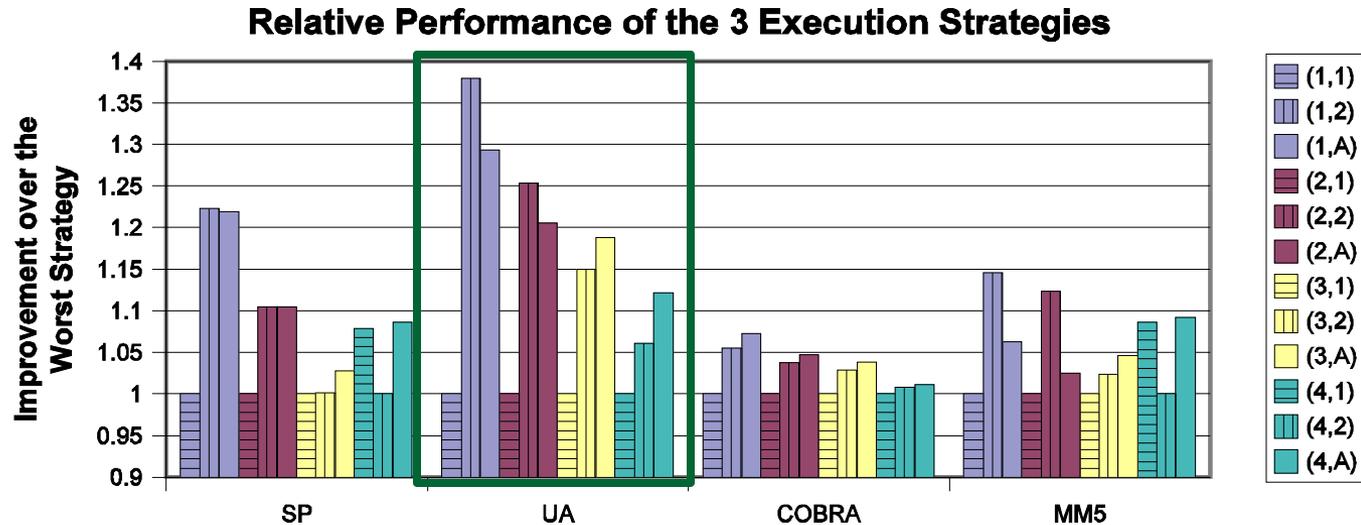


Graph shows relative performance of each approach for 1, 2, 3, and 4 processors

- 1 thread per processor
- 2 threads per processor
- Adaptive approach



# Results from Adaptation



Graph shows relative performance of each approach for 1, 2, 3, and 4 processors

1 thread per processor

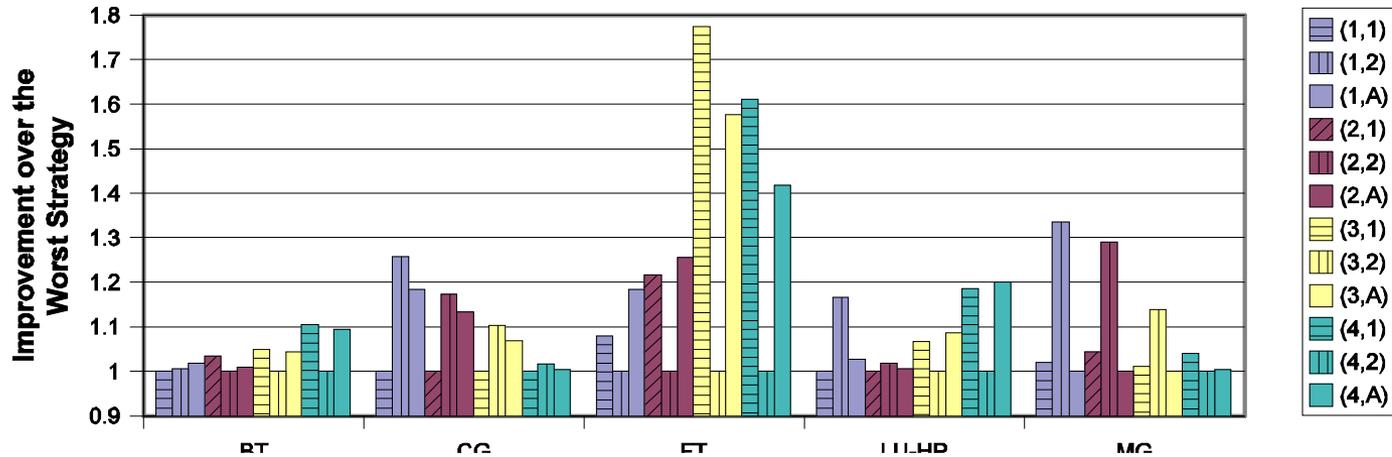
2 threads per processor

Adaptive approach

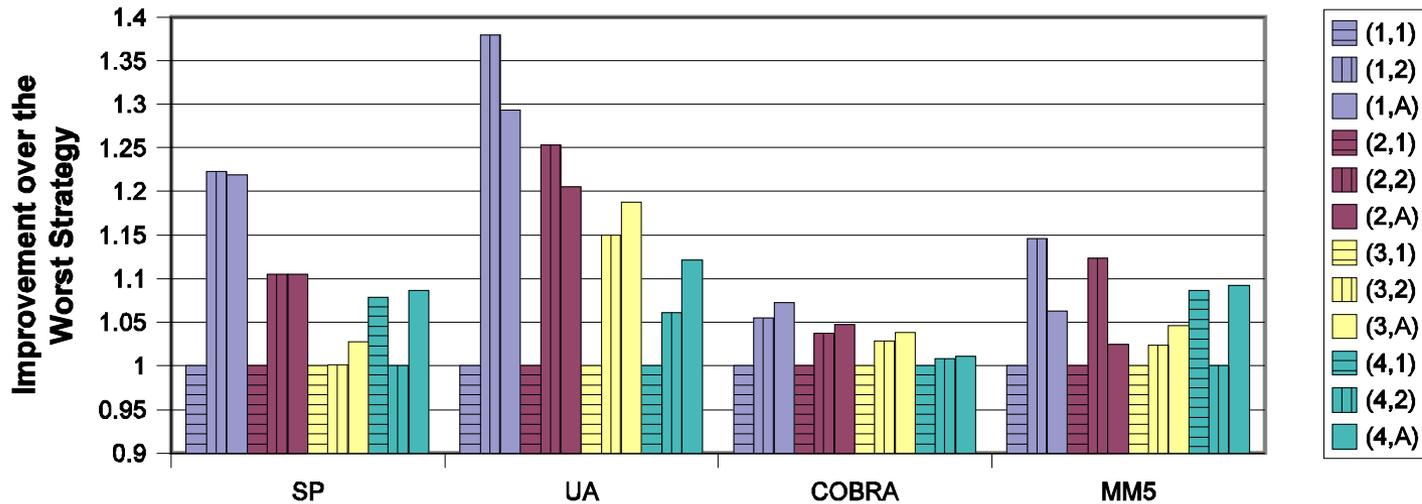


# Results from Adaptation

Relative Performance of the 3 Execution Strategies



Relative Performance of the 3 Execution Strategies



# Results from Adaptation

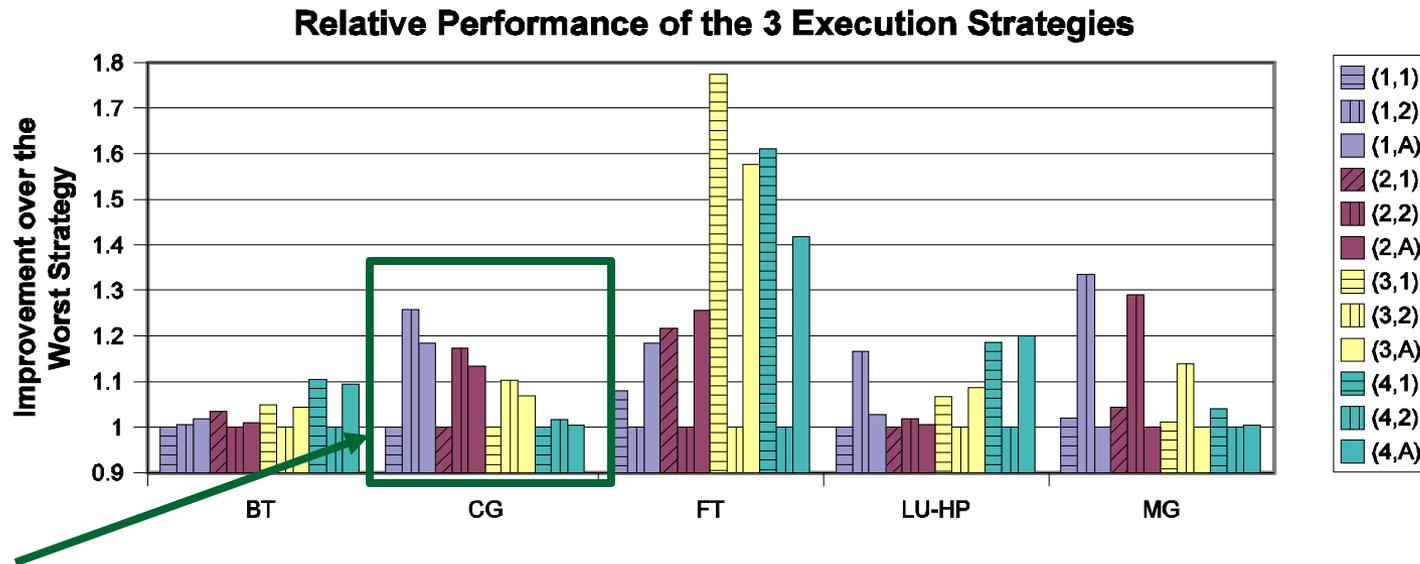


Adaptation does not perform well for MG

MG has only 4 iterations and our approach takes 3



# Results from Adaptation



Adaptation does not perform well for MG

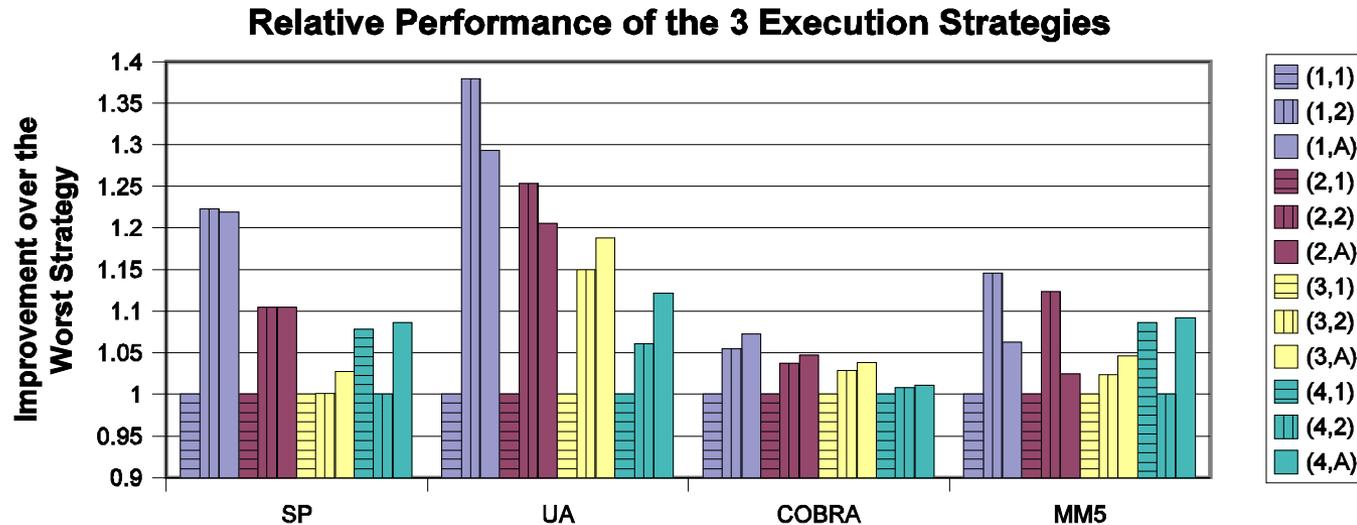
MG has only 4 iterations and our approach takes 3

CG, however, performs well with only 15 iterations

So it does not require many iterations to be profitable



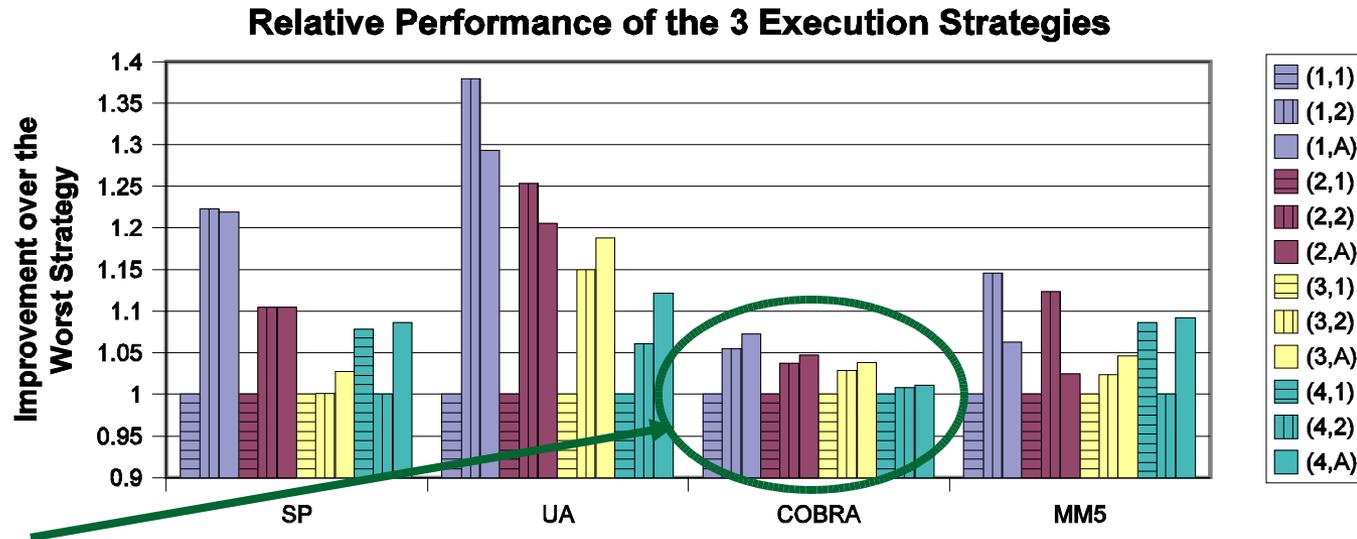
# Results from Adaptation



In 17 of the 36 experiments, adaptation did better than either static number of threads



# Results from Adaptation



In 17 of the 36 experiments, adaptation did better than either static number of threads

In Cobra, adaptation was the best for all numbers of processors



# Results from Adaptation

Compared to optimal static number of threads, adaptation was only 3.0% slower

It was, however, 10.7% faster than the worse static number of threads

The average overall speedup was 3.9%

This shows that adaptation provides a good approximation of the optimal number of threads

Requires no *a priori* knowledge

However, does not overcome inherent architectural bottlenecks



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# Content

Motivation of this Evaluation

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# Implications for OpenMP

Our study indicates that OpenMP scales effortlessly on CMPs

It is important to consider optimizations of OpenMP for SMT processors

    Viable technology for improving performance on a single core

These optimizations could come from:

    Additional runtime environment support

    Extensions to the programming interface



# OpenMP Optimizations for SMT

Co-executing thread identification is most important optimization

New *SCHEDULE* clause may be used

- Can assign iterations to SMTs

- These iterations can then be split between co-executing threads using SMT-aware policy

OpenMP thread groups extensions may be used

- Co-executing threads go to same group

- Use SMT-aware scheduling and local synchronization

- Not necessarily nested parallelism



# OpenMP Optimizations for SMT

## Necessity of thread binding

SMT-aware optimizations require threads to remain on the same processor

Some applications may benefit from running 2 threads on the same processor

Use of proposed mechanisms, like *ONTO* clause

However, exposing architecture internals in the programming interface is undesirable in OpenMP

New mechanisms for improving execution on SMT processors in an autonomic manner



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# Conclusions

Evaluated the performance of OpenMP applications on SMT/CMP-based multiprocessors

- SMTs suffer from contention on shared resources

- CMPs more efficient due to greater resource replication

- CMPs appear to be more cost effective

Adaptively selecting the optimal number of threads helps SMT performance

- However, inherent architectural bottlenecks hinder the efficient exploitation of these architectures

Identified OpenMP functionality that could be used to boost performance on SMTs

