

An algorithmic proof of the
Lovasz Local Lemma
via resampling oracles

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Simultaneously avoiding many events

Lovasz Local Lemma: [Erdos-Lovasz '75]

Let $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$ be events in a probability space. Suppose

- \mathcal{E}_i is jointly independent of all but d events
- $\mathbb{P}[\mathcal{E}_i] \leq 1/ed$ for all i

Then $\mathbb{P}[\overline{\bigcap_i \mathcal{E}_i}] > 0$ (typically exponentially small).



**Beyond what nature intended:
Finding a very rare object.**

Simultaneously avoiding many events

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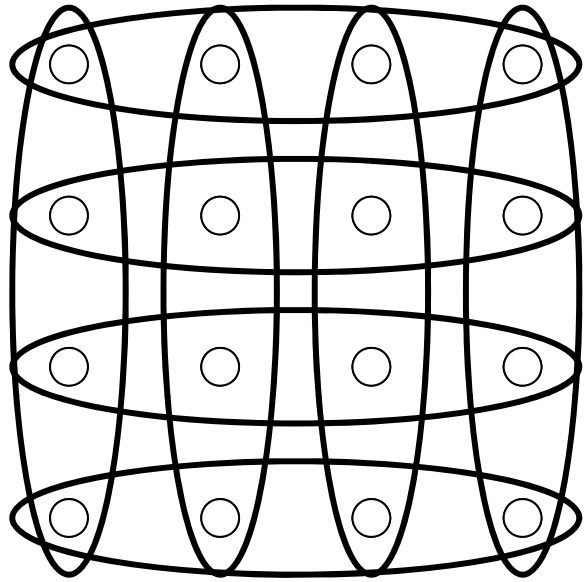
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Some applications:

- Near-Ramanujan expanders via 2-lifts [Bilu-Linial]
- $O(\text{congestion} + \text{dilation})$ packet routing [Leighton-Maggs-Rao]
- $O(1)$ -approx for Santa Claus problem [Feige], [Haeupler-Saha-Srinivasan]

Example: 2-coloring hypergraphs



- **Given:** System of sets of size k , each intersecting $\leq 2^{k-1}/e$ sets.
 - **Goal:** Color vertices **red/blue** so that each set has both colors.
 - **Random approach:** color each vertex independently **red/blue**.
-
- Let \mathcal{E}_i be event i^{th} set is **all-red** or **all-blue**. Note $\mathbb{P}[\mathcal{E}_i] = 2^{1-k}$.
 - \mathcal{E}_i is independent of all but $2^{k-1}/e =: d$ sets.
 - Since $\mathbb{P}[\mathcal{E}_i] \leq 1/ed$, LLL implies $\mathbb{P}[\bigcap_i \overline{\mathcal{E}_i}] > 0$.
 - So, there is a coloring where no set is **all-red** or **all-blue**.

Algorithmic LLL

- Under the original distribution \mathbb{P} , avoiding $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$ is exponentially unlikely.
- Can we find another distribution (i.e. a randomized algorithm) in which it is likely to avoid $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$?
- Yes: Hypergraph case, weaker parameters: [Beck '91], [Alon '91], [Molloy-Reed '98], [Czumaj-Scheideler '00], [Srinivasan '08]



**Beyond what nature intended:
Amplifying probability of rare event.**

Moser-Tardos Variable Model

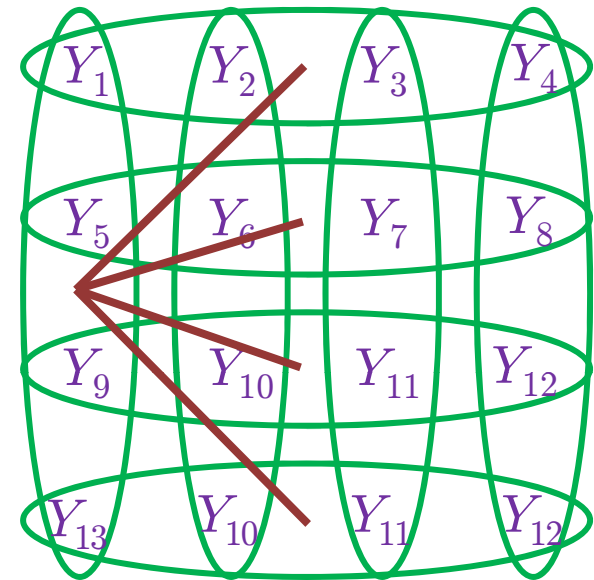
(dependency based on shared variables)

- Independent random variables Y_1, \dots, Y_m
- “Bad” events $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$
- \mathcal{E}_i depends on variables $\text{var}(\mathcal{E}_i)$
- A dependency graph G :
 $i \sim j$ if $\text{var}(\mathcal{E}_i) \cap \text{var}(\mathcal{E}_j) \neq \emptyset$.

Moser-Tardos Algorithm [Moser-Tardos '08]

While some event \mathcal{E}_i occurs

Resample all variables in $\text{var}(\mathcal{E}_i)$

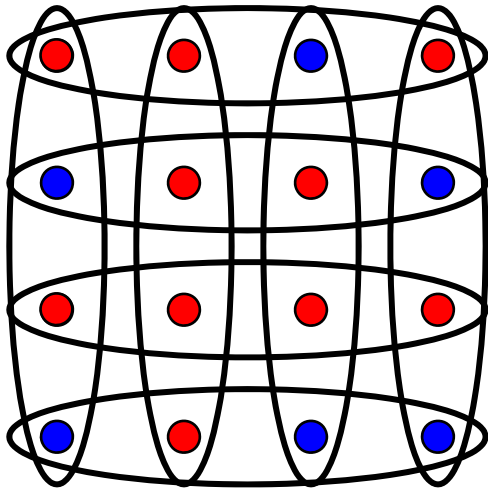


Sets sharing variables
are neighbors

Theorem: Suppose $\text{max-degree} < d$ and $\mathbb{P}[\mathcal{E}_i] \leq 1/ed$. The algorithm finds a point in $\bigcap_i \overline{\mathcal{E}_i}$ after $O(n)$ resampling operations, in expectation.

Algorithmic Improvements

- Many extensions of Moser-Tardos:
 - deterministic LLL algorithm [Chandrasekaran-Goyal-Haupler '10]
 - exponentially many events [Hauptler-Saha-Srinivasan '10]
 - better conditions on probabilities [Kolipaka-Szegedy '11], [Harris '14]
- Require **variable model** (dependencies based on Y_1, \dots, Y_m)



Hypergraph coloring

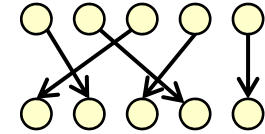
$$(\bar{x}_1 \vee x_2 \vee \bar{x}_3) \wedge (x_4 \vee \bar{x}_5 \vee x_6) \dots$$

k -SAT

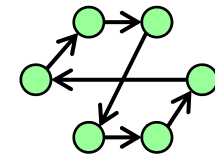
Algorithmic Improvements

- Original LLL works for **arbitrary probability spaces**

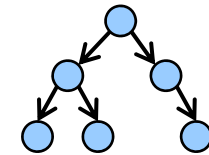
- Permutations [Erdos-Spencer '91]



- Hamilton cycles [Albert-Frieze-Reed '95]

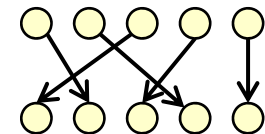


- Spanning trees [Lu-Mohr-Szekely '13]

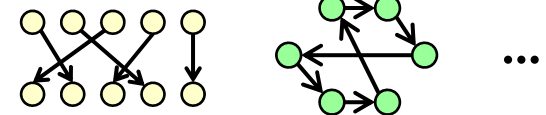


- Algorithms beyond **variable model**

- Permutations [Harris-Srinivasan '14]

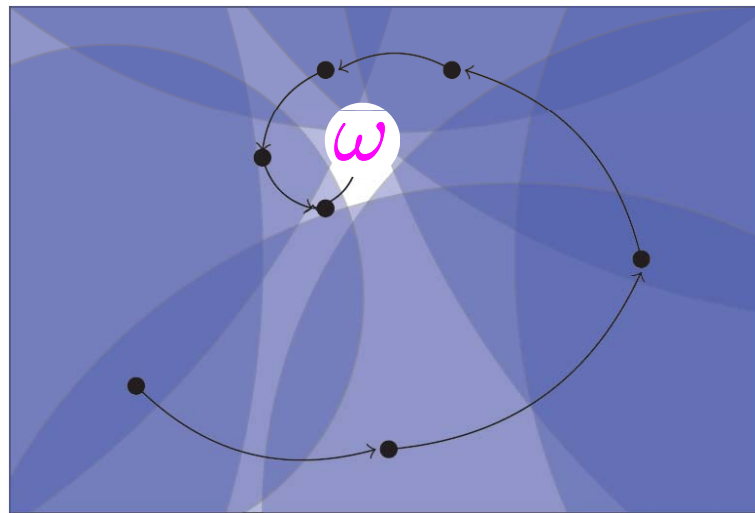


- Abstract “flaw-correction” framework [Achlioptas-Iliopoulos '14], [Kolmogorov '15]



Algorithmic Local Lemma for general probability spaces?

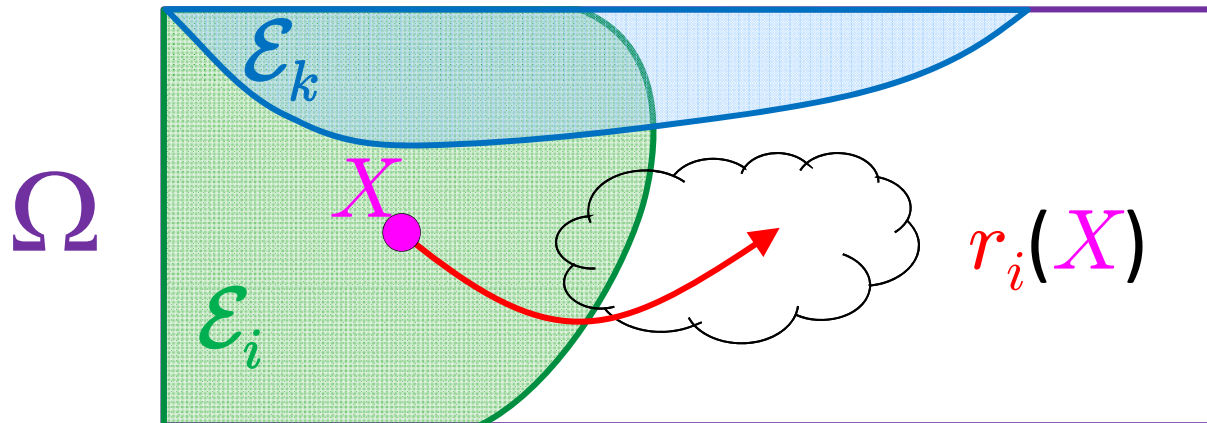
- For the LLL in any probability space, can we design a randomized algorithm to quickly find $\omega \in \bigcap_i \overline{\mathcal{E}_i}$?



- How can algorithm “move about” in general probability space?
 - Flaw-correcting actions [Achlioptas-Iliopoulos '14]
 - **Resampling oracles** [This paper]

Resampling Oracles

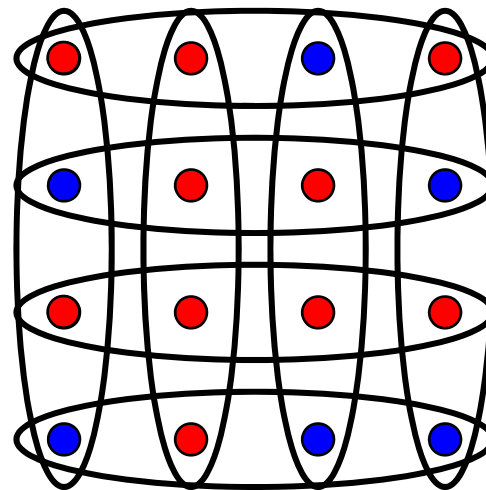
- Consider probability space Ω , measure \mathbb{P} , events $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$ and dependency relation denoted \sim .
- A **resampling oracle** for \mathcal{E}_i is a random function $r_i : \Omega \rightarrow \Omega$
 - **Removes conditioning on \mathcal{E}_i :**
If X has measure \mathbb{P} cond. on \mathcal{E}_i , then $r_i(X)$ has measure \mathbb{P} .
 - **Does not cause non-neighbor events:**
If $\mathcal{E}_k \sim \mathcal{E}_i$ and $X \notin \mathcal{E}_k$, then $r_i(X) \notin \mathcal{E}_k$.



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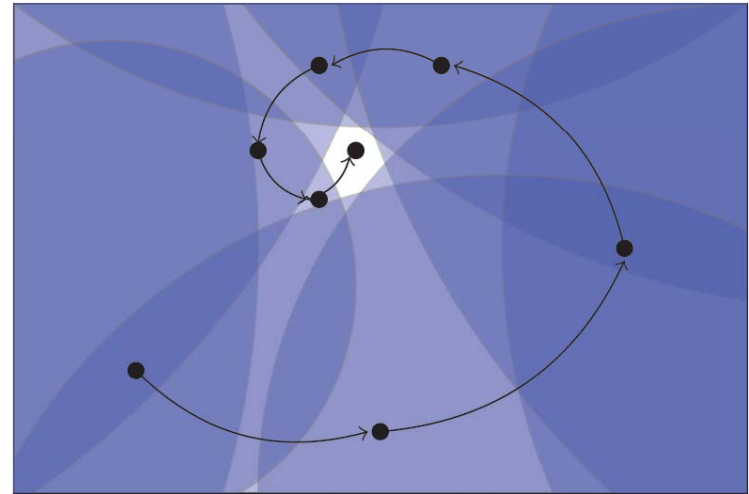
Example: Resampling Oracle
for Hypergraph Coloring



Our Main Result:

An Algorithmic LLL in a General Setting

- Arbitrary probability space Ω
- Events $\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_n$
- An arbitrary graph G
- A **resampling oracle** for each \mathcal{E}_i , with respect to G

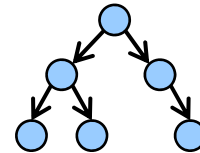
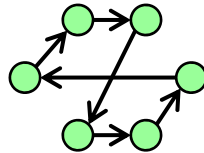
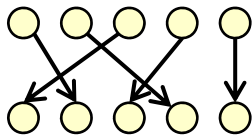


- **Theorem:** [H.-Vondrak '15] Suppose max-degree $< d$ and $\mathbb{P}[\mathcal{E}_i] \leq 1/ed$. Our algorithm finds a point in $\bigcap_i \overline{\mathcal{E}_i}$ after $O(n^2)$ **resampling operations**, with high probability.
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- Holds much more generally: Lovasz's conditions, Shearer's conditions...
- We design efficient resampling oracles for essentially every known application of the LLL (and generalizations)



...

Algorithmic LLL via Resampling Oracles

MIS Resample

Draw ω from \mathbb{P}

Repeat

$I \leftarrow \emptyset$

While there is $i \notin \Gamma^+(I)$ s.t. \mathcal{E}_i occurs in ω

Pick smallest such i

$\omega \leftarrow r_i(\omega)$

$I \leftarrow I \cup \{i\}$

End

Until $I = \emptyset$

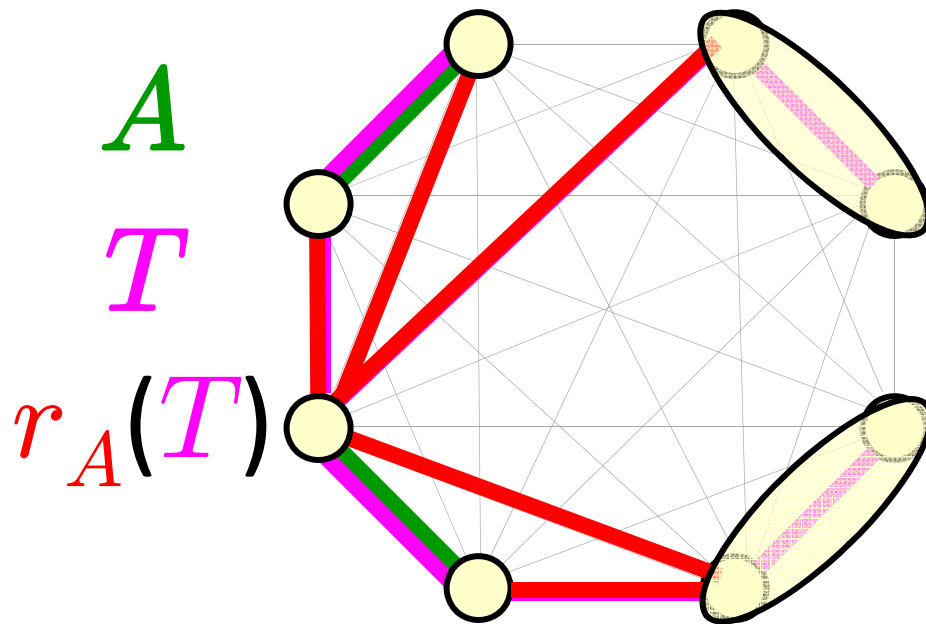
Output ω

} Like finding
a maximal
indep set

Resampling Spanning Trees in K_n

- Let T be a uniformly random spanning tree in K_n
- For edge set A , let $\mathcal{E}_A = \{A \subseteq T\}$.
- **Dependency Graph:** Make \mathcal{E}_A a neighbor of \mathcal{E}_B , unless A and B are vertex-disjoint.
- **Resampling oracle r_A :**
 - If T uniform conditioned on \mathcal{E}_A , want $r_A(T)$ uniform.
 - But, should not disturb edges that are vtx-disjoint from A .

- $\mathcal{E}_A = \{A \subseteq T\}$.
- **Resampling oracle** $r_A(T)$:
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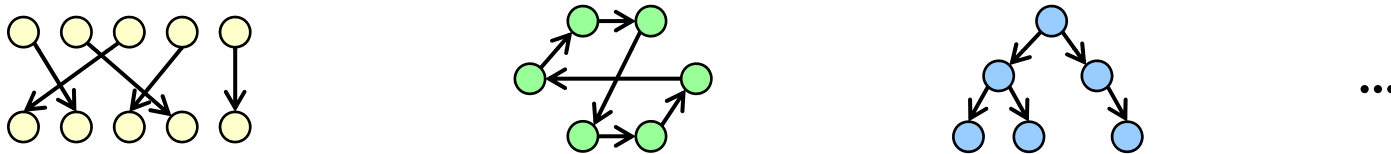


- Contract edges of T vtx-disjoint from A
- Delete edges adjacent to A
- Let $r_A(T)$ be a uniformly random spanning tree in resulting (multi)-graph.

- **Lemma:** $r_A(T)$ is uniformly random.

Summary

- Our algorithmic proof of LLL works for any probability space and any events, under usual LLL conditions, so long as you can design **resampling oracles**.



- Efficiency is similar to Moser-Tardos, but quadratically worse
- Analysis is similar to Moser-Tardos, perhaps simpler
 - no “log” or branching processes
- Works under Lovasz’s condition, cluster expansion condition, Shearer’s condition (no slack needed!)