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REFINING UML INTERACTIONS WITH UNDERSPECIFICATION AND NONDETERMINISM

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Abstract. STAIRS is an approach to the compositional development of UML interactions, such as sequence diagrams and interaction overview diagrams. An important aspect of STAIRS is the ability to distinguish between underspecification and inherent nondeterminism through the use of potential and mandatory alternatives. This paper investigates this distinction in more detail. Refinement notions explain when (and how) both kinds of nondeterminism may be reduced during the development process. In particular, in this paper we extend STAIRS with guards, which may be used to specify the choice between alternatives. Finally, we introduce the notion of an implementation and define what it means for an implementation to be correct with respect to a specification.

ACM CCS Categories and Subject Descriptors: D.2.1 [Software Engineering]: Requirements/Specifications; D.3.1 [Programming Languages]: Formal Definitions and Theory; F.3.1 [Logics and Meanings of Programs]: Specifying and Verifying and Reasoning about Programs

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1. Introduction

STAIRS [9, 8] is an approach to the compositional development of UML interactions, such as sequence diagrams and interaction overview diagrams. Interactions in UML 2.0 [13] are behavioural definitions that describe some, but not necessarily all, of the behaviour that a given system performs. Most often the interactions will describe positive behaviours, i.e. behaviours that the system is allowed to perform. There may also be behaviours that the interactions define as negative, meaning that they are unacceptable, and there may even be behaviours of the system that are not at all covered by any of the interactions defined.
This partiality of interactions is motivated by several factors. First of all, the description of a real system requires far too many interaction diagrams to define all the behaviours. To manage such a volume of diagrams would be impractical. Also, the goal of interactions is to visualize important interaction patterns. Thus the emphasis is on importance, rather than completeness. This is in contrast to most other kinds of behavioural specifications, including UML state machines. The definition of a state machine is complete in the sense that it may be seen to define all the possible behaviours of that entity.

A methodology may initially use interactions to capture user requirements, and use these as stepping stones for the next development stages where emphasis is placed more on completeness and realizability. STAIRS supports this through the notion of refinement. In particular, the refinement definitions take into account that initial specifications in the form of interactions typically describe only a few example scenarios. A scenario not described by an initial specification is not necessarily unwanted, but it has not been thought of yet. Thus, a refinement step may be to include new scenarios in the specification, as well as to reduce the amount of underspecification and nondeterminism in the specification. Refinement may also be to describe some of the aspects of a scenario in more detail.

In this paper we focus on defining and refining specifications with nondeterminism. In the introductory chapter of the UNITY-book [3] Chandy and Misra observe:

Nondeterminism is useful in two ways. First, it is employed to derive simple programs, where simplicity is achieved by avoiding unnecessary determinism; such programs can be optimized by limiting the nondeterminism, i.e., by disallowing executions unsuitable for a given architecture. Second, some systems (e.g., operating systems and delay-insensitive circuits) are inherently nondeterministic; programs that represent such systems have to employ some nondeterministic constructs.

STAIRS is based on this overall observation. However, contrary to Chandy and Misra we take the position that the two useful ways of using nondeterminism should be described differently.

Avoiding unnecessary determinism may for instance be achieved through underspecification. By underspecification we mean that the specification gives several alternative behaviours that are equivalent in the sense that they all serve the same purpose. For an implementation to be correct, it is sufficient to fulfil only one of the alternative behaviours. Underspecification may also be used as an abstraction mechanism, for instance by giving several alternative behaviours but not stating how to select between them. This will typically later be refined into an if-then-else construct in the implementation.

On the other hand, inherent nondeterminism is used to capture alternative behaviours that must all be possible for the implementation. A typical example is the tossing of a coin, where both heads and tails should be
possible outcomes, and no legal refinement should remove one of these two alternatives. A system may also need to exhibit nondeterministic behaviour due to differences in its environment.

Inherent nondeterminism is very different from underspecification, and should be described differently. One important reason for this is that unless we do not distinguish these two, there will be no way to ensure that inherently nondeterministic behaviour is implemented as such. This may not seem like a major problem at first. If the development team knows that a given specification should be implemented as delay-insensitive circuits you will probably get the inherently nondeterministic implementation that you expect. However, in the domain of information security, the inherently nondeterministic behaviour is fundamental for the validity of the specification. As pointed out in e.g. [10] and [12], security properties are in general not preserved by standard refinement. If nondeterminism is used as a means to hide the internal workings of a system, it is essential that it is not treated as underspecification, which allows elimination of all uncertainty (nondeterminism) in a refinement.

In [14] Roscoe points out that using inherent nondeterminism ensures security as it prevents the making of any inference about the possible outcomes, while for nondeterminism based on underspecification there are three possible conclusions about the security of a system: secure, insecure, or don’t know. Hence, it makes things a lot easier if the specification language provides a way to distinguish between these two ways of using nondeterminism.

In the setting of UML interactions, the operator $\text{alt}$ is used to specify alternative behaviours. As the UML standard [13] is rather vague on whether these alternatives represent underspecification or inherent nondeterminism, people interpret the same interaction differently, leading to confusion. This could be avoided by having two different operators for specifying alternative behaviours, as we have in STAIRS. This is particularly important as the partiality of interactions makes it important to know which of the described scenarios represent significantly different behaviours and which scenarios only serve as examples of how to achieve the same purpose.

The remainder of this paper is structured into six sections. Section 2 introduces the basic STAIRS formalism, while Section 3 uses this in an example specification illustrating nondeterminism. In Section 4 we extend the formalism with guards, and in Section 5 we discuss refinement in STAIRS with emphasis on nondeterminism. Section 6 defines what it means for a system to be a correct implementation of a STAIRS specification. Section 7 provides a brief summary and relates STAIRS to approaches known from the literature.
2. Background: UML interactions with denotational trace semantics

In this section, we present the basic STAIRS formalism. Section 2.1 gives the fundamental trace mechanisms. In Section 2.2 we present our textual syntax for interactions, while Section 2.3 formally defines denotational trace semantics for UML interactions.

2.1 Representing executions by traces

In STAIRS, we define the semantics of interactions by using sequences of events. By $A^\omega$ we denote the set of all finite and infinite sequences over the set $A$. We use $\langle \rangle$ to denote the empty sequence. Moreover, by $\langle e_1, e_2, \ldots, e_m \rangle$ we denote the sequence of $m$ elements, whose first element is $e_1$, whose second element is $e_2$, and so on. We define the functions

$$\# \in A^\omega \to \mathbb{N}_0 \cup \{\infty\}, \quad [\cdot] \in A^\omega \times \mathbb{N} \to A$$

to yield the length and the $n$th element of a sequence. Hence, $\#a$ yields the number of elements in $a$ and $a[n]$ yields $a$’s $n$th element if $n \leq \#a$.

We also need functions for concatenation, truncation and filtering:

$$\| \in A^\omega \times A^\omega \to A^\omega, \quad \|_i \in A^\omega \times \mathbb{N}_0 \to A^\omega, \quad \circ \in \mathcal{P}(A) \times A^\omega \to A^\omega$$

Concatenating two sequences implies gluing them together. Hence, $a_1 \circ a_2$ denotes a sequence of length $\#a_1 + \#a_2$ that equals $a_1$ if $a_1$ is infinite, and is prefixed by $a_1$ and suffixed by $a_2$, otherwise. For any $0 \leq i \leq \#a$, we define $a|_i$ to denote the prefix of $a$ of length $i$.

The filtering function $\circ$ is used to filter away elements. By $B \circ a$ we denote the sequence obtained from the sequence $a$ by removing all elements in $a$ that are not in the set of elements $B$. For example, we have that

$$\{1, 3\} \circ \langle 1, 1, 2, 1, 3, 2 \rangle = \langle 1, 1, 1, 3 \rangle$$

A trace $h$ is a sequence of events, used to represent a system run. For any single message, transmission must happen before reception if both events are present. Thus we get the following well-formedness requirement on traces, stating that if at any point in the trace we have a transmission event, up to that point we must have had at least as many transmissions as receptions of that particular message:

$$\forall i \in [1, \#h] : k.h[i] = ! \Rightarrow \#(\{!\} \times \{m.h[i]\}) \circ h[i] > \#(\{?\} \times \{m.h[i]\}) \circ h[i]$$

$\mathcal{H}$ denotes the set of all well-formed traces.
2.2 Syntax of interactions

The set of syntactically correct interactions, denoted by $D$, is defined by the BNF-grammar in Fig. 1. $\text{Signal}$ represents the actual content of a message, $\text{Lifeline}$ is the name of a lifeline (representing a component) in the diagram and $\text{Set}$ should be an expression that evaluates to a subset of $\mathbb{N}_0$ (the natural numbers including 0).

As can be seen from the definition, a message is a triple $(s, tr, re)$ of a signal $s$, a transmitter $tr$, and a receiver $re$. As a shorthand, we will often use the name of the signal to stand for the whole message in cases where the transmitter and receiver are clear from the context. We let $\mathcal{L}$ denote the set of all lifelines, and $\mathcal{M}$ denote the set of all messages. We distinguish between two kinds of events; a transmission event tagged by an exclamation mark “!” represents the transmission of a message, while a reception event tagged by a question mark “?” represents the reception of a message. $\mathcal{E}$ denotes the set of all events, while $\mathcal{K}$ denotes \{!, ?\}.

We define the functions

$$k. - \in \mathcal{E} \rightarrow \mathcal{K}, \quad m. - \in \mathcal{E} \rightarrow \mathcal{M}, \quad tr. - , re. - \in \mathcal{E} \rightarrow \mathcal{L}$$

to yield the kind, message, transmitter and receiver of an event, respectively.
We also define the functions

\[ ll. \in D \to \mathbb{P}(\mathcal{L}), \quad ev. \in D \to \mathbb{P}(\mathcal{E}), \quad msg. \in D \to \mathbb{P}(\mathcal{M}) \]

to yield the set of lifelines, events and messages of an interaction, respectively.

Interactions are built from events through the application of various operators as defined by the grammar in Fig. 1. We do not cover the complete set of operators in UML 2.0 [13], but rather focus on a few essential operators. These fundamental operators may be used to define other useful, high-level operators as demonstrated in Section 5.2. See [7] for STAIRS definitions of additional operators like parallel execution and gates.

The operators assert, alt, seq and loop are UML 2.0 operators. The operator xalt is new, proposed in [9] to model mandatory alternatives, i.e. alternatives that must all be present in the final implementation. For negation, UML 2.0 uses the operator neg. However, this operator is used in several contexts, with slightly different meanings as we explain in [15]. Therefore, we have in this paper chosen to introduce a new operator refuse that covers one of these traditional uses of neg.

We only consider interactions that are well-formed in the sense that if both the transmitter and the receiver lifelines of a message are present in the diagram, then both the transmission and the reception event of that message must be present as well. Formally:

\[ \forall m \in \text{msg.d} : (\#\text{ev.d} > 1 \land \text{tr.m} \in \text{ll.d} \land \text{re.m} \in \text{ll.d}) \Rightarrow \\
\#\{ e \in \text{ev.d} \mid k.e = ! \land m.e = m \} = \#\{ e \in \text{ev.d} \mid k.e = ? \land m.e = m \} \]

where \{ \} denotes a multi-set and \# is overloaded to yield the number of elements in such a set. A multi-set is needed here as the same message (consisting of a signal, a transmitter and a receiver) may occur more than once in the same diagram.

Also, we assume that for all operators except from seq, the operand(s) consist only of complete messages, i.e. messages with both the transmission and the reception event within the operand.

### 2.3 Semantics of interactions

The semantics of interactions is defined by a function \([ \_\_ \] \) that for any interaction \(d\) yields a set \([ d\] \) of interaction obligations. The term obligation is used to explicitly convey that any implementation of a specification is obliged to fulfil each specified alternative. (What it formally means to fulfil an obligation is discussed in Section 6.) An interaction obligation is a pair \((p,n)\) of sets of traces. The first set \(p\) represents positive traces that may be the result of running the final system, while the second set \(n\) represents negative traces that must not appear in the implementation of the obligation. Traces not defined as positive or negative are called inconclusive. As will be formally defined in Section 5, a refinement may later redefine (some of)
these inconclusive traces as positive or negative. An obligation pair \((p, n)\) is contradictory if \(p \cap n \neq \emptyset\).

The empty diagram, denoted by \textit{skip}, is a specification without any events that corresponds to a program doing nothing. The empty diagram defines the empty trace as positive:

\[
\left\llbracket \text{skip} \right\rrbracket \overset{\text{def}}{=} \{(\emptyset, \emptyset)\}
\] (1)

For an interaction consisting of a single event \(e\), its semantics is given by:

\[
\left\llbracket e \right\rrbracket \overset{\text{def}}{=} \{(\{e\}, \emptyset)\}
\] (2)

The actual content of the messages is not significant for the purpose of this paper. Hence, we do not give any semantic interpretation of messages as such.

The rest of this section will define the semantics of the different composition operators described briefly in Section 2.2. Table I lists the notational conventions that will be used in the following definitions.

### 2.3.1 Weak sequencing

Weak sequencing is the implicit composition mechanism combining constructs of an interaction. The operator \textit{seq} is defined by the following invariants:

- The ordering of events within each of the operands is maintained in the result.
- Events on different lifelines from different operands may come in any order.
- Events on the same lifeline from different operands are ordered such that an event of the first operand comes before that of the second operand, and so on.

First, we define weak sequencing of trace sets:

\[
s_1 \triangleright s_2 \overset{\text{def}}{=} \{h \in H | \exists h_1 \in s_1, h_2 \in s_2 : \forall l \in \mathcal{L} : e.l \odot h = e.l \odot h_1 \setminus e.l \odot h_2\}
\] (3)
where \( e.l \) denotes the set of events that may take place on the lifeline \( l \).

Formally:

\[
e.l \overset{\text{def}}{=} \{ e \in E \mid (k.e = ! \land tr.e = l) \lor (k.e = ? \land re.e = l) \}
\]  

(4)

Weak sequencing of interaction obligations is defined as:

\[
(p_1, n_1) \succeq (p_2, n_2) \overset{\text{def}}{=} (p_1 \succeq p_2, (n_1 \succeq n_2) \cup (n_1 \succeq p_2) \cup (p_1 \succeq n_2))
\]  

(5)

Notice that all traces obtained by combining a negative and a positive trace-set, will also be negative. Weak sequencing of sets of interaction obligations is defined as:

\[
O_1 \succeq O_2 \overset{\text{def}}{=} \{ o_1 \succeq o_2 \mid o_1 \in O_1 \land o_2 \in O_2 \}
\]  

(6)

Finally, the \texttt{seq} construct is defined by:

\[
\begin{align*}
[ \texttt{seq} \ [d] ] & \overset{\text{def}}{=} [ \{d\}] \\
[ \texttt{seq} \ [D, d] ] & \overset{\text{def}}{=} [ \texttt{seq} \ [D] ] \succeq [ \{d\}]
\end{align*}
\]  

(7)

As an example, the interaction in Fig. 2 shows two messages both originating from L1 and targeting L2. Its semantics is calculated as:

\[
\begin{align*}
[ \texttt{W} ] &= [ \texttt{seq} \ [x, ?x, !y, ?y] ] \\
&= (\langle \{x\}, \emptyset \rangle \succeq \langle \{y\}, \emptyset \rangle) \succeq \langle \{y\}, \emptyset \rangle \\
&= \{\{\{x\}, \emptyset\}\} \succeq \{\{y\}, \emptyset\}\} \succeq \{\{y\}, \emptyset\}\} \\
&= \{\{\{x\}, \emptyset\}\} \succeq \{\{\{y\}, \emptyset\}\} \succeq \{\{y\}, \emptyset\}\} \\
&= \{\{\{x\}, \emptyset\}\} \succeq \{\{\{y\}, \emptyset\}\} \succeq \{\{y\}, \emptyset\}\} \\
&= \{\{\{x\}, \emptyset\}\} \succeq \{\{\{y\}, \emptyset\}\} \succeq \{\{y\}, \emptyset\}\}
\end{align*}
\]  

(Defs. (2) - (6))

Hence, this interaction specifies one interaction obligation with two positive traces and no negative ones. The positive traces state that the transmission of \( x \) must be the first event to happen, but after that either \( y \) may be transmitted (by L1) or \( x \) may be received (by L2).
2.3.2 Negative behaviour

The refuse construct defines negative traces:

\[
\llbracket \text{refuse} \, d \rrbracket \overset{\text{def}}{=} \{(\emptyset, p \cup n) \mid (p, n) \in \llbracket d \rrbracket\}
\]  

(8)

Notice that a negative trace cannot be made positive by reapplying refuse. Negative traces remain negative, since negation should be seen as an operation that characterizes traces absolutely and not relatively.

2.3.3 Assertion

The assert construct makes all inconclusive traces negative. Except for that the sets of positive and negative traces are left unchanged:

\[
\llbracket \text{assert} \, d \rrbracket \overset{\text{def}}{=} \{(p, n \cup (\mathcal{H} \setminus p)) \mid (p, n) \in \llbracket d \rrbracket\}
\]  

(9)

Notice that contradictory obligation pairs remain contradictory.

2.3.4 Potential alternatives

The alt construct is used when specifying underspecification, i.e. to define potential traces that are equivalent in the sense that it is sufficient for an implementation to include only one of them. The semantics of alt is the inner union of each point-wise selection of interaction obligations from its operands:

\[
\llbracket \text{alt} \, d_1, \ldots, d_m \rrbracket \overset{\text{def}}{=} \left\{ \biguplus_{o_1, \ldots, o_m} \mid \forall i \in [1, m] : o_i \in \llbracket d_i \rrbracket \right\}
\]

(10)

The inner union of interaction obligations is defined as:

\[
\biguplus_{i \in [1, m]} (p_i, n_i) \overset{\text{def}}{=} \bigcup_{i \in [1, m]} p_i \cup \bigcup_{i \in [1, m]} n_i
\]

(11)
Fig. 3(a) gives a simple example using the \texttt{alt} construct. The dashed horizontal line separates the operands. We get:

\[
\begin{align*}
\langle A \rangle &= \langle \texttt{alt} \langle \texttt{seq} \langle x, ?x \rangle, \texttt{seq} \langle y, ?y \rangle \rangle \rangle \\
&= \bigcup \left\{ \left\{ \langle \{x, ?x \}, \emptyset \rangle, \langle \{y, ?y \}, \emptyset \rangle \right\} \right\} \quad \text{(Defs. (3) – (7), (10))} \\
&= \bigcup \left\{ \langle \{x, ?x \}, \emptyset \rangle, \langle \{y, ?y \}, \emptyset \rangle \right\} \quad \text{(Def. (11))}
\end{align*}
\]

\[2.3.5 \textbf{Mandatory alternatives}\]

The \texttt{xalt} construct is used to specify inherent nondeterminism, i.e. mandatory alternatives that must all be present in an implementation:

\[
\langle [x\texttt{alt} [d_1, \ldots d_m] \rangle \rangle \quad \text{def} = \bigcup_{i \in [1,m]} \langle d_i \rangle \quad \text{(12)}
\]

Fig. 3(b) has the same messages as Fig. 3(a), but separated by \texttt{xalt} instead of \texttt{alt}. In this case, we get two interaction obligations:

\[
\begin{align*}
\langle A' \rangle &= \langle x\texttt{alt} [\texttt{seq} \langle !x, ?x \rangle, \texttt{seq} \langle !y, ?y \rangle] \rangle \\
&= \bigcup \left\{ \langle \texttt{seq} \langle !x, ?x \rangle \rangle, \langle \texttt{seq} \langle !y, ?y \rangle \rangle \right\} \quad \text{(Def. (12))} \\
&= \bigcup \left\{ \left\{ \langle \{x, ?x \}, \emptyset \rangle \right\}, \left\{ \langle \{y, ?y \}, \emptyset \rangle \right\} \right\} \quad \text{(Defs. (3) – (7))} \\
&= \left\{ \left\{ \langle !x, ?x \rangle \rangle, \left\{ \langle !y, ?y \rangle \rangle \right\} \right\} \quad \text{(Def. of \bigcup)}
\end{align*}
\]

\[2.3.6 \textbf{Loop}\]

For a set of interaction obligations we define a finite loop construct \(\mu_n\), where \(n \in \mathbb{N}_0\) denotes the number of times the body of the loop is iterated. \(\mu_n O\) is defined inductively as follows:

\[
\mu_n O \quad \text{def} = \begin{cases} 
\{\emptyset, \emptyset\} & \text{if } n = 0 \\
O & \text{if } n = 1 \\
\mu_{n-1} O \circledcirc O & \text{otherwise}
\end{cases} \quad \text{(13)}
\]

For a definition of infinite loop, see [7].

In the UML 2.0 standard [13], \texttt{loop} is used together with limits stating the minimum and maximum number of times the content of the loop should be executed. In our definition, the set \(I\) is a generalization of this, such that the numbers in \(I\) specify the possible alternatives for how many times the loop content should be executed. Not all of these need to be actual alternatives in an implementation, meaning that the definition of \texttt{loop} uses the point-wise inner union between these alternatives, similar to the definition of \texttt{alt}:

\[
\langle \texttt{loop} I [d] \rangle \quad \text{def} = \bigcup_{i \in I} \langle o_i \rangle \quad \forall i \in I : o_i \in \mu_i [d] \quad \text{(14)}
\]
As an example, the interaction in Fig. 4 has the following semantics:

\[
[ L ] = \left\{ \text{loop } \{0, 1, 2\} \begin{array}{c}
\text{seq } \langle x, ?x \rangle
\end{array} \right\}
= \left\{ \bigcup_{i \in \{0, 1, 2\}} o_i \mid \forall i \in \{0, 1, 2\} :
\begin{array}{c}
\text{alt } \{\langle x, ?x \rangle \}\end{array}
\right\} (\text{Def. (14)})
\]

\[
= \left\{ \bigcup_{i \in \{0, 1, 2\}} o_i \mid o_0 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\wedge
\begin{array}{c}
o_1 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\wedge
o_2 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\end{array}
\right\} (\text{Def. (13)})
\]

\[
= \left\{ \bigcup_{i \in \{0, 1, 2\}} o_i \mid o_0 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\wedge
\begin{array}{c}
o_1 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\wedge
o_2 \in \left\{ \bigcup_{i \in \{0, 1, 2\}} \left\{ \langle x, ?x \rangle \right\} \right\}
\end{array}
\right\} (\text{Def. (11)})
\]

3. STAIRS and nondeterminism

As seen in the previous section, weak sequencing may result in several different traces with the same events in a somewhat different order. These traces are alternative means to achieve the same goal, and they are therefore grouped into the same interaction obligation as it is sufficient to keep only one of them in an implementation.

In UML 2.0, the other means to specify alternative behaviours is by using the operator \text{alt}. This is used both for specifying potential alternatives where keeping only one is sufficient, and for mandatory alternatives that must all be present in a correct implementation. In STAIRS, we have distinguished
these two uses by separating between our two operators $\text{alt}$ and $\text{xalt}$. Each use of UML 2.0 $\text{alt}$ corresponds in STAIRS to either $\text{alt}$ or $\text{xalt}$. In this section we present an example illustrating the use of these two operators.

Consider a situation where a sender communicates with a receiver through a network of type S as shown in the UML composite structure diagram in Fig. 5 (notice that this is not an interaction). A very simple communication is shown by the interaction in Fig. 6, its semantics being:

$$\{ \langle !(m, A, S), ?(m, A, S), !(m, S, B), ?(m, S, B) \rangle \}, \emptyset \}$$

Next, we would like to specify that there is a need for redundant communication through the network S. That is, the network S needs to support more than one way of bringing the message $m$ from one end of the network to the other. There may be several reasons for requiring this redundancy:

- Several paths through the network will make it easier to exploit the full capacity of the network.
- Multiple paths will ensure increased internal robustness of the network and as such improve the availability of the full communication.
- Multiple paths will make it more difficult to attack the network to jeopardize the communication, and as such the communication security is improved.

We indicate in Fig. 7 a simple network architecture for S where there are alternative branches. A real communication network may of course have far
more paths, but giving a few is sufficient for the purpose of this paper. We want to make an interaction where we require two (different) communication possibilities, and we may do this by introducing an `xalt` construct as shown in Fig. 8, where `S` is expanded according to the structure in Fig. 7.

We have used `xalt` here in order to express that the network must support at least two communication paths. Of course, for each concrete communicat-
tion only one of them will be applied. After node N2, the network S has yet another branch giving two alternative paths. For the sake of the discussion we assume that it is not important to have both of these available, and so we specify the alternatives using \textit{alt} and not \textit{xalt} in Fig. 8.

The semantics of $S_{\text{Comm}}$ is:

$$\{ \{ !(m, A, G), ?(m, A, G), !(m, G, N1), ?(m, G, N1),
\textit{alt}!(m, N1, B), \textit{not}!(m, N1, B)) \}, \emptyset \}$$

$$\{ \{ !(m, A, G), ?(m, A, G), !(m, G, N2), ?(m, G, N2),
\textit{alt}!(m, N2, N3), ?(m, N2, N3), !(m, N3, B), ?(m, N3, B)),
\textit{alt}!(m, A, G), ?(m, A, G), !(m, G, N2), ?(m, G, N2),
\textit{alt}!(m, N2, N4), ?(m, N2, N4), !(m, N4, B), ?(m, N4, B)) \}, \emptyset \}$$

Fig. 9 illustrates this semantics using a specialized Venn-diagram with one ellipse for each interaction obligation. Traces not shown as positive or negative in an obligation are inconclusive for this obligation.

Formally, $S_{\text{Comm}}$ is a refinement of Comm. Refinement will be formally defined in Section 5. In Section 5 we will also develop this example further, by giving some possible refinements to illustrate the similarities and differences between the two operators \textit{alt} and \textit{xalt}. But first, in the next section, we formally extend STAIRS with guards, which may be used to specify the choice between alternatives.

4. Extending STAIRS with data and guards

Although the focus of interactions is on the messages, the diagrams may also be decorated with data. The most common use of data in interactions is in guards, which is a mechanism for choosing between alternatives. Data is also used in assignments and general constraints. In this section we extend our basic formalism with definitions of these concepts. The extension ensures that (sub-)interactions not including data have the same semantics as before.

4.1 Data

Since interactions mainly specify events and not data, the exact data values will most of the time be underspecified (or unspecified). Changes in the
data may in general happen at any time, also when there is nothing in the diagram indicating such a change. As a consequence, in the semantic model we do not include data as such. Instead, data is represented indirectly through events representing its use in assignments, constraints, and guards.

Formally, we extend the syntax of interactions as defined by the BNF-grammar in Fig. 10. Nonterminals that are unchanged from the original syntax in Fig. 1 are not repeated. Variable should be either a global variable or a variable local to the lifeline on which the assignment is placed (not shown in our textual syntax), while Expression is a mathematical expression and Constraint an expression that evaluates to true or false. If an operand of guarded alt or guarded xalt does not contain an explicit guard, we interpret this as being the guard true.

In the semantics, we extend the set of trace events with the two special events write (for assignments) and check (for constraints). We also need the notion of a state. Let Var be the set of all variables and Val be the set of all variable values. A state \( \sigma \) is then a total function assigning a value to each variable. Formally:

\[
\sigma \in \text{Var} \rightarrow \text{Val}
\]

For any expression \( expr \), we use \( expr(\sigma) \) to denote its value in \( \sigma \).

4.2 Assignment

Explicit specification of variable values may be done by using assignments. In UML 2.0, assignments are written inside a rounded box on the appropriate lifeline, as illustrated in Fig. 11.

Semantically, we represent an assignment \( var = expr \) by the special event write(\( \sigma, \sigma' \)) where \( \sigma \) is the state immediately before the assignment and \( \sigma' \)
the state immediately after:
\[
\begin{align*}
\llbracket \text{assign}(\text{var}, \text{expr}) \rrbracket & \overset{\text{def}}{=} (15) \\
\{ \langle \text{write}(\sigma, \sigma') \rangle | \sigma'(\text{var}) = \text{expr}(\sigma) \land \\
& \forall v \in \text{Var} : (v = \text{var} \lor \sigma'(v) = \sigma(v)) \}, \emptyset \}
\end{align*}
\]

### 4.3 Constraints (state invariants)

In UML 2.0, constraints are written within curly brackets, as illustrated in Fig. 12. A constraint is a restriction that must be fulfilled by the system, meaning that we have a negative trace if the constraint is broken.

Semantically, a constraint is represented by the special event \textit{check}(\sigma), where \sigma is the state in which the constraint is evaluated:
\[
\llbracket \text{constr}(c) \rrbracket = \{ \langle \text{check}(\sigma) \rangle | c(\sigma) \}, \{ \langle \text{check}(\sigma) \rangle | \neg c(\sigma) \}\}
\]

This definition ensures that if the constraint is a tautology, then the semantics of \text{constr}(c) has no negative traces, and that a contradiction gives no positive traces:
\[
\begin{align*}
\llbracket \text{constr(true)} \rrbracket & = \{ \langle \text{check}(\sigma) \rangle | \text{true}(\sigma) \}, \{ \langle \text{check}(\sigma) \rangle | \text{false}(\sigma) \}\} \\
& = \{ \langle \text{check}(\sigma) \rangle | \sigma \in \text{Var} \rightarrow \text{Val}, \emptyset \}\}
\end{align*}
\]
Notice that one constraint in itself gives potentially an infinite number of system traces, varying with respect to the state component only.

As an example of the use of constraints in an interaction, the complete semantics of the interaction in Fig. 12 may be calculated as:

\[
\begin{align*}
&\text{constraint} = \\
&\text{seq} (\text{constr}(\text{avar} = 0), \langle m, \lambda m, \text{constr}(\text{avar} > 0) \rangle) \\
&\text{=} ( ( ( [\text{constr}(\text{avar} = 0)] \geq [\langle m \rangle] ) \geq [\langle ?m \rangle] ) \geq [\text{constr}(\text{avar} > 0) ] \\
&\quad (\text{Def. (7)}) \\
&\geq ( ( [\text{constr}(\text{avar} = 0)] \geq \{(\langle m \rangle, \emptyset)\} ) \geq \{(\langle ?m \rangle, \emptyset)\} ) \\
&\geq \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Def. (2)}) \\
&\geq ( ( \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Def. (16)}) \\
&\geq ( \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}) \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Defs. (5) - (6)}) \\
&\geq ( \{(\text{check}(\text{sigma}), \langle m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Def. (3)}) \\
&\geq ( \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Defs. (3) - (6)}) \\
&\geq ( \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle, \langle \text{check}(\text{sigma}) \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle, \langle \text{check}(\text{sigma}) \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle, \langle \text{check}(\text{sigma}) \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \{(\text{check}(\text{sigma}), \langle m \rangle, \langle ?m \rangle, \langle \text{check}(\text{sigma}) \rangle \geq \langle \text{sigma}(\text{avar}) \geq \langle ?m \rangle \rangle \}, \\
&\quad (\text{Defs. (3) - (6)}, \text{ and formula manipulation})
\end{align*}
\]
4.4 Guards (interaction constraints)

According to UML 2.0, alternatives (and other combined fragments) in an interaction may be guarded by an interaction constraint (also called a guard). A guard is a special kind of constraint that may only occur at the beginning of the interaction operand in question. As opposed to general constraints, guards are written inside square brackets, as illustrated in Fig. 13. As the example illustrates, the guards used in an alt (or xalt) may be overlapping and need not be exhaustive.

If the guard is true, the interaction operand describes positive traces of the system. The semantics in the case of a false guard is not stated explicitly in the UML 2.0 standard [13]. However, with guards being a specialization of general constraints, it is natural to interpret traces with a false guard as negative. As will be demonstrated in Section 5, this is advantageous as it means that adding guards to an alt/xalt-construct constitutes a valid refinement step. A side effect of this is that we will be able to model guards by using the more general notion of constraints as defined in the previous section.

4.4.1 Guarded alt

UML 2.0 [13] states that if none of the operands of an alt construct has a guard that evaluates to true, none of the operands are executed and the remainder of the enclosing interaction is executed. This gives the following semantics for guarded alt:

\[
[\text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m]] \overset{\text{def}}{=} (17)
\]

\[
\{ \bigcup \{ o_1, \ldots, o_m, \left( \left\langle \langle \text{check}(\sigma) \rangle \mid \left( \bigwedge_{j \in [1, m]} \neg c_j(\sigma) \right) \right\rangle, 0 \right\} \mid
\forall i \in [1, m] : o_i \in \left\langle \text{seq} \left[ \text{constr}(c_i), d_i \right] \right\rangle \}
\]

The semantics of Fig. 13 is informally illustrated in Fig. 14. Formally, its
Figure 14: Semantics of guarded \texttt{alt} in Fig. 13

complete semantics may be calculated as:

\[
\begin{align*}
[\text{guards}] &= \left[\text{alt} \ [\text{avar} = 0 \rightarrow \text{seq} \ [l_x, ?x], \ \text{avar} \geq 0 \rightarrow \text{seq} \ [l_y, ?y]]\right] \\
&= \bigcup \left\{ \left\{ \langle \text{check}(\sigma), l_x, ?x \rangle \mid \sigma(\text{avar}) = 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_x, ?x \rangle \mid \sigma(\text{avar}) \neq 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_y, ?y \rangle \mid \sigma(\text{avar}) \geq 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_y, ?y \rangle \mid \sigma(\text{avar}) < 0 \right\}\right\} \\
&= \left\{ \left\{ \langle \text{check}(\sigma), l_x, ?x \rangle \mid \sigma(\text{avar}) = 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_y, ?y \rangle \mid \sigma(\text{avar}) \geq 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_y, ?y \rangle \mid \sigma(\text{avar}) \neq 0 \right\}, \\
&\quad \left\{ \langle \text{check}(\sigma), l_y, ?y \rangle \mid \sigma(\text{avar}) < 0 \right\}\right\}
\end{align*}
\]  

Definition (17) giving the semantics of guarded \texttt{alt} is consistent with definition (10) of unguarded \texttt{alt} in Section 2.3. In our new setting, a specification \texttt{alt} \[D\] without guards is interpreted as the specification \texttt{alt} \[D'\] where \[D'\] is the same list of interactions as \[D\], each one guarded by \textit{true}. Calculating this semantics using definition (17), gives us the same semantics as definition (10) when abstracting away all \textit{check}-events. This is proved in Appendix C.

4.4.2 Guarded \texttt{xalt}

We define the semantics of guarded \texttt{xalt} as:

\[
[\texttt{xalt} \ [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m]] = \bigcup_{i \in [1,m]} [\text{seq} \ [\text{constr}(c_i), d_i]]
\]  

(18)

Unlike guarded \texttt{alt}, the semantics of guarded \texttt{xalt} does not implicitly include the case where all guards are false, since \texttt{xalt} is used to specify explicit choices that must be present in the implementation.

As an example, the semantics of Fig. 13 with \texttt{alt} replaced by \texttt{xalt}, is informally illustrated in Fig. 15. Formally, its complete semantics may be
calculated as:

\[
\begin{align*}
\left[ \text{guards} \right] &= \left[ \text{xalt} \middle| \begin{array}{l}
avar = 0 \rightarrow \text{seq } [!x, ?x], \\
avar \geq 0 \rightarrow \text{seq } [!y, ?y]
\end{array} \right] \\
= \bigcup \left\{ \begin{array}{l}
\{ \{ \text{check}(\sigma), !x, ?x \} | \sigma(\avar) = 0 \}, \\
\{ \{ \text{check}(\sigma), !x, ?x \} | \sigma(\avar) \neq 0 \}\}, \\
\{ \{ \text{check}(\sigma), !y, ?y \} | \sigma(\avar) \geq 0 \}, \\
\{ \{ \text{check}(\sigma), !y, ?y \} | \sigma(\avar) < 0 \}\}\right\} \\
\text{(Defs. (3) – (7)),} \\
\{ \{ \text{check}(\sigma), !x, ?x \} | \sigma(\avar) = 0 \}, \\
\{ \{ \text{check}(\sigma), !x, ?x \} | \sigma(\avar) \neq 0 \}\}, \\
\{ \{ \text{check}(\sigma), !y, ?y \} | \sigma(\avar) \geq 0 \}, \\
\{ \{ \text{check}(\sigma), !y, ?y \} | \sigma(\avar) < 0 \}\}\bigcup \\
\text{(Def. \bigcup)}
\end{align*}
\]

As for \text{xalt}, removing the guards in definition (18) gives the original \text{xalt}-semantics in definition (12) as proved in Appendix C.

5. Refinement

In this section we discuss some important aspects of refinement in the setting of STAIRS. Section 5.1 gives the necessary background for this discussion, presenting the main refinement definitions. In the rest of Section 5 we focus on underspecification and inherent nondeterminism, and how guards may be introduced as a refinement step in both cases.

5.1 Background: Formal definitions

Refinement means to add information to a specification such that the specification becomes more complete. This may be achieved by categorizing inconclusive traces as either positive or negative, or by reducing the set of positive traces. Negative traces always remain negative. A specification may also become more complete by introducing more details.
5.1.1 Glass-box refinement

Formally, an interaction obligation \((p', n')\) is a refinement of an interaction obligation \((p, n)\), written \((p, n) \preceq_r (p', n')\), iff

\[ n \subseteq n' \quad \land \quad p \subseteq p' \cup n' \]  

(19)

An interaction \(d'\) is a glass-box refinement of an interaction \(d\), written \(d \preceq_g d'\), iff

\[ \forall o \in [d] : \exists o' \in [d'] : o \preceq_r o' \]  

(20)

**Theorem.** The refinement operator \(\preceq_g\) is

- reflexive: \(d \preceq_g d\)
- transitive: \(d \preceq_g d' \land d' \preceq_g d'' \Rightarrow d \preceq_g d''\)
- monotonic with respect to \(\text{refuse, loop, seq, (guarded) alt and (guarded) xalt}\):

\[
\begin{align*}
\text{refuse: } & \quad d \preceq_g d' \Rightarrow \text{refuse } [d] \preceq_g \text{refuse } [d'] \\
\text{loop: } & \quad d \preceq_g d' \Rightarrow \text{loop } [d] \preceq_g \text{loop } [d'] \\
\text{seq: } & \quad d_1 \preceq_g d'_1, \ldots, d_m \preceq_g d'_m \Rightarrow \text{seq } [d_1, \ldots, d_m] \preceq_g \text{seq } [d'_1, \ldots, d'_m] \\
\text{alt: } & \quad d_1 \preceq_g d'_1, \ldots, d_m \preceq_g d'_m \Rightarrow \text{alt } [d_1, \ldots, d_m] \preceq_g \text{alt } [d'_1, \ldots, d'_m] \\
\text{xalt: } & \quad d_1 \preceq_g d'_1, \ldots, d_m \preceq_g d'_m \Rightarrow \text{xalt } [d_1, \ldots, d_m] \preceq_g \text{xalt } [d'_1, \ldots, d'_m]
\end{align*}
\]

**Proof.** Reflexivity, transitivity and monotonicity with respect to \(\text{seq, loop and unguarded alt and xalt}\) is proved in [7]. Monotonicity with respect to \(\text{refuse}\) and guarded \(\text{alt}\) and \(\text{xalt}\) is proved in Appendix E. □

By definition (20), new interaction obligations may be freely added to the specification, thus increasing the mandatory nondeterminism required of an implementation. Adding new obligations is an important aspect of the STAIRS methodology. Sometimes, however, it is desirable to restrict this possibility.

A more restrictive notion of refinement is *limited glass-box refinement*, where each obligation in the new refined interaction must correspond to an obligation in the original interaction.

Formally, an interaction \(d'\) is a limited glass-box refinement of an interaction \(d\), written \(d \preceq_l d'\), iff

\[ d \preceq_g d' \land \forall o' \in [d'] : \exists o \in [d] : o \preceq_r o' \]  

(21)

The refinement theorem above is valid also when replacing \(\preceq_g\) with \(\preceq_l\), as proved in Appendix D (reflexivity and transitivity) and Appendix E (monotonicity).

Notice that a step of refinement may still increase the total number of obligations, but only if two different obligations in \([d']\) refine the same obligation in \([d]\).

Methodologically, a STAIRS specification would typically be developed by using \(\preceq_g\) initially and switching to the more restrictive \(\preceq_l\) after the desired level of nondeterminism in the specification has been reached.
5.1.2 Black-box refinement

Black-box refinement may be understood as refinement restricted to the externally visible behaviour. We define the function

$$ ext \in \mathcal{H} \times \mathcal{P}(\mathcal{L}) \rightarrow \mathcal{H} $$

to yield the trace obtained from the trace given as first argument by filtering away those events that are internal with respect to the set of lifelines given as second argument:

$$ ext(h, l) \overset{\text{def}}{=} \{ e \in \mathcal{E} \mid tr.e \notin l \lor re.e \notin l \} \otimes h $$

(22)

The $ ext $ operator is overloaded to sets of traces, to pairs of sets of traces, and sets of pairs of sets of traces in the standard pointwise manner:

$$ ext(s, l) \overset{\text{def}}{=} \{ ext(h, l) \mid h \in s \} $$

(23)

$$ ext((p, n), l) \overset{\text{def}}{=} (ext(p, l), ext(n, l)) $$

(24)

$$ ext(O, l) \overset{\text{def}}{=} \{ ext((p, n), l) \mid (p, n) \in O \} $$

(25)

An interaction $ d' $ is a black-box refinement of an interaction $ d $, written $ d \sim \rightarrow b d' $, iff

$$ \forall o \in ext([d], ll.d) : \exists o' \in ext([d'], ll.d') : o \rightarrow r o' $$

(26)

The refinement theorem above is valid also when replacing $ \rightarrow q $ with $ \rightarrow b $, as the properties are independent of the content of the actual traces.

Black-box refinements will often include lifeline decompositions that are not externally visible. Some lifeline decompositions may also be externally visible due to a change in the sender or receiver of a message. We have already used this in Fig. 8, where the network $ S $ was decomposed into several nodes. Formally, an interaction $ d' $ is a lifeline decomposition of an interaction $ d $ with respect to a lifeline substitution $ ls $, written $ d \sim \rightarrow l^* d' $, iff

$$ d \sim \rightarrow l^* \text{subst}(d', ls) $$

(27)

where $ ls \in L \rightarrow L $ is a function defining the lifeline substitution and the function $ \text{subst}(d, ls) $ yields the interaction $ d $ with every lifeline $ l $ in $ d $ substituted with the lifeline $ ls(l) $.

5.2 Adding positive behaviour

We now return to our running example from Section 3. Even with two different communication paths, we have no guarantee that any of them will be available at a certain time. This is made explicit in Fig. 16, where the empty diagram (i.e. $ \text{skip} $) is added as a third operand to the $ \text{xalt} $-construct. When this operand is selected, we get a positive trace consisting of only
Negative two events, the transmission of m from A to G, and the reception at G. No further communication will take place, and B will never receive the message.

The semantics of N_Comm is illustrated in Fig. 17. Comparing this with Fig. 9, which illustrates the semantics of S_Comm (Fig. 8), we see that every interaction obligation given by S_Comm is also an interaction obligation by N_Comm. By definitions (19)–(20), this means that the modified specification is a valid refinement of the original one, S_Comm \( \leadsto_g \) N_Comm. The last obligation in Fig. 17 illustrates that new obligations may be added freely when using standard glass-box refinement, \( \leadsto_g \).

Assume now that our communication network describes the emergency network used by the police, that a police officer needs to communicate, but that the communication for some reason fails. In practice, a police officer may grab his personal mobile phone and call his colleague. This is not a
mandatory choice (the police are not set up with personal mobile phones), but may be used as an alternative. The resulting specification is shown in Fig. 18. The opt-construct is a high-level operator, which may be defined as

\[
\text{opt } d \overset{\text{def}}{=} \text{alt skip}
\]  

The modified specification affects only the last of the interaction obligations in Fig. 17, where a positive behaviour is added as illustrated in Fig. 19. By definition (19), this is a valid refinement as the negative trace-sets in both interaction obligations are empty and the positive trace-set in the N\text{Comm} one is a subset of the new positive trace set in the M\text{Comm} one:

\[
\{ !(m, A, G), ?(m, A, G) \} \subseteq \\
\{ !(m, A, G), ?(m, A, G), !(m, G, Mobile), ?(m, G, Mobile), \\
!{(m, Mobile, B), ?(m, Mobile, B)} \}
\]
5.3 Adding negative behaviour

The refinement examples in the previous section categorized earlier inconclusive traces as positive. Similarly, earlier inconclusive traces may be categorized as negative, either by specifying the negative traces explicitly through the use of refuse, or by using assert. In our network example, we decide that M_Comm is a complete description of the possible behaviours, and that everything not in the interaction should be considered negative. This gives us the interaction in Fig. 20.

The semantics of A_Comm is illustrated in Fig. 21. Comparing this with
5.4 Redefining positive behaviour as negative

Refinement may also be used to reduce the set of positive traces by redefining them as negative. Looking at the specification in Fig. 20, we may decide that there really is no need to have both communication choices specified by the alt-construct. A refinement of this sub-specification could then be as given by Fig. 22. The complete semantics for this refinement is illustrated in Fig. 23. We see that the refined specification only affects the obligation in the middle. By definition (19), this is a valid refinement step as the negative trace-set is extended and the traces that were previously positive are now either positive or negative.

Another possible refinement of $A_{Comm}$ could be to specify how the choice between the different communication paths should be made. In the case of our emergency network, using a mobile phone should only be an option if
the main network fails. In the interaction in Fig. 24, the node G makes
the choice between the different alternatives specified by the xalt-construct. Similarly, N2 makes the choice between the alt-operands.

We have assumed that G and N2 have information about the capacity of
the different nodes. This may in practice be achieved either by continuous
information back from the nodes (not shown in the described behaviour) or
through evaluating the communication historically relative to known para-

meters of the nodes. For our purpose, it is not significant how G and N2 get
their data. It is interesting, however, that for xalt the two first guards may
both be true, both false, or one true and one false. All of these situations
represent cases in real life. If both guards are true, the choice between the
two paths may be done arbitrarily. If both guards are false, the else operand
comes into effect.

We have not specified what should happen if both guards are false in the
alt-fragment. However, according to definition (17) giving the semantics of
 guarded alt, this is equal to the empty trace, i.e. no further communication
takes place.

Fig. 25 illustrates the semantics of G_comm. All traces with a false guard
are negative as specified by definitions (16)–(18). This makes G_comm a
valid refinement of A_comm. In general, introducing guards in an alt- or
xalt-construct will always be a legal refinement step as proved in Appendix
E.
5.5 Adding more details

As another example, assume that our sender and receiver suspect that somewhere inside the network there is someone listening to and possibly manipulating their messages. They would like to encrypt their messages and agree (openly) to exchange information to set up a secret key that they shall use for subsequent encryption. Following the procedure outlined by Simon Singh in [16] on how to achieve exchanging of secret keys through insecure communication, we need to be able to describe a number of similar sequences differing basically in the value of some critical numbers.

In Fig. 26 we have shown the protocol with a generalized notation for \( x_{\text{alt}} \). We have supplied the \( x_{\text{alt}} \) with an extra clause which gives one or more parameters with finite domains associated. This generalized notation is identical to replicating the operand for all values of the variable inside the domain.

The behaviour of Fig. 26 means that the sender chooses a natural number (between 0 and 255 in this example) and from that calculates another natural (here in the range 0 . . . 10), and this calculated number is transmitted over the insecure network to the receiver. The receiver does exactly the same the
other way with a number that he/she chooses. From the numbers that they initially chose and the numbers that they received from each other, they are able to calculate a common key, $p$. This key is secret since the network does not have sufficient information to calculate it directly. (Of course, in a real situation the one-way function will be more complicated and the numbers far larger.)

To give a couple of concrete examples, we assume in Fig. 27 that the sender has only the naturals 2 and 3 to choose from, while the receiver chooses only from 4 and 5. The specification in Fig. 27 gives rise to four interaction obligations (with $p = 1, 5, 9$ or 10), one for each possible combination of values for the two lifelines. The choice between these should be nondeterministic, giving the intruder four possible values for the key. With more alternatives for $na$ and $nb$, as in the original specification, we get a lot of obligations and potential keys making it difficult for the intruder to find the correct key by plain guessing or by trial-and-error.

In Fig. 28 we indicate a possible decomposition of the sender A in the first xalt-construct in Fig. 26. A is decomposed into a random generator and a sender lifeline C. The generator loops a sufficient number of times, each time sending either 0 or 1 to the sender. Taken together, these messages
will constitute the binary representation of the number $na$ in Fig. 26. Using \texttt{xalt} here, means that both 0 and 1 must be possible in each round in the loop, giving a totally nondeterministic choice for $na$.

Simple calculations show that we will get the same possible values for $na$ in both diagrams, leading to the same obligations and the same values of the parameter $a$ in both cases, meaning that the decomposition is indeed a valid refinement.

6. Implementation

In this section we explain what we mean by an implementation and what it means for an implementation to be correct with respect to a STAIRS specification.

Intuitively, if the specification has only one interaction obligation, a cor-
rect implementation may only produce traces belonging to the positive and inconclusive trace sets of the obligation, i.e. no negative trace must be produced by the implementation. With more than one interaction obligation, we may in general find the same trace being positive in one obligation while negative in another.

Semantically, we represent implementations in the same way as we represent interactions, namely by sets of interaction obligations. From a semantic point of view, an implementation is a special kind of specification characterized by the following three criteria:

- Its interaction obligations contain no inconclusive traces. Hence, each interaction obligation is of the form \((p, \mathcal{H} \setminus p)\), where \(p \neq \emptyset\).
- Whatever typecorrect input it receives from its environment it has at least one output (doing nothing is for example also a response). This means that for any possible environment behaviour, the implementation has at least one trace that is consistent with this behaviour. This corresponds to the notion of winning strategy in Focus [1].
- It behaves causally. Its behaviour at any point in time depends only on
what has happened in its past. This is obviously a characteristic of any real-life system (but not necessarily a characteristic of a specification expressed by an interaction). This corresponds to the notion of strong causality in FOCUS [1].

We say that an implementation $I$ implements a STAIRS specification $S$ if and only if $I$ is a limited refinement of $S$, i.e. $[S] \Rightarrow_{l} [I]$. This means that an implementation may not add interaction obligations beyond those given by the specification.

7. Conclusions

In this paper we have explored different kinds of nondeterminism and underspecification, and motivated the need for having two different operators ($\text{alt}$ and $\text{xalt}$) for specifying alternative behaviours. Basically, $\text{alt}$ defines implicit nondeterminism in the sense of underspecification or abstraction, while $\text{xalt}$ defines inherent nondeterminism in the form of explicit choices that must all be present in a valid implementation. We claim that together, these two operators are sufficient to capture the necessary distinctions.

In this paper we have also proposed an extension to STAIRS making it possible to use guards to choose between both implicit (specified by $\text{alt}$) and explicit (specified by $\text{xalt}$) nondeterminism. In particular, the proposed semantics ensures that adding guards to a specification is a valid refinement step. It is straightforward to combine this extension with Timed STAIRS [6], which extends STAIRS with time and three-event semantics.

7.1 Related work

Most formalisms do not distinguish between nondeterminism and underspecification as we have done here. In [17], Walicki and Meldal makes a similar distinction in the setting of algebraic specifications. Their main motivation is that underspecification may sometimes in fact lead to overspecification, and that in these cases it would be better to use explicit nondeterminism.

In LSC (Live Sequence Charts) [4, 5], charts, locations, messages and conditions may all be characterized as either mandatory or provisional. Provisional charts are called existential and they may happen if their initial condition holds. This is comparable to potential alternatives in STAIRS. Mandatory charts in LSC are called universal. Their interpretation is that provided their initial condition holds, these charts must happen. A universal chart specifies all allowed traces, and is therefore not the same as mandatory alternatives in STAIRS, which only specifies some of the traces that must be present in an implementation.

In [2], Cengarle and Knapp define the semantics of UML 2.0 interactions by notions of positive and negative satisfaction. This approach has many similarities with ours, but they do not distinguish between underspecification and explicit nondeterminism as we do in STAIRS. With respect to negative traces, their semantics is somewhat different from ours. For alternatives,
they define that a trace is negative only if it is negative in both operands. Also, they define that for all possible traces, the trace is negative if a prefix of it is specified as negative, even though the complete trace itself is not described by the diagram. This allows for earlier identification of negative traces. In contrast, we regard such a trace as inconclusive, arguing that if a trace is not described in the diagram, then the specifier has either not thought about the situation or not wanted to classify it as either positive or negative.

In this paper we have modelled data in interactions indirectly through special events representing its use in assignments, constraints, and guards. An example of an alternative approach may be found in [11], where Jonsson and Padilla define a global semantics for an MSC (Message Sequence Chart) by using an Abstract Execution Machine. Here, data are included in the model by associating with each instance an environment consisting of its local variables together with those received as message parameters.

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References

Appendix A. Refinement by adding assignments and constraints

Intuitively, adding assignments to an interaction means adding more information to the specification and should therefore be considered a valid refinement step. Similarly, adding contraints means redefining positive behaviours as negative and should also be a valid refinement step.

As assignments and constraints are not part of the externally visible behaviour, adding new assignments and constraints will always constitute a black-box refinement according to definition (26). However, black-box refinement is often not sufficient as it in general also allows removal of assignments and constraints.

By definition (20) of glass-box refinement, removing assignments and constraints are not allowed. Constraints may be strengthened, but adding assignments and constraints is not allowed as this means inserting new events into the traces.

In order to allow addition, but not removal, of assignments and constraints, we need a refinement relation which requires that the traces of the original interaction are traces also of the refinement when abstracting away a subset of the concrete check- and write-events.

Formally, we first define $C$ and $W$ to be the set of all possible check- and write-events, respectively:

\[
C \overset{\text{def}}{=} \{\text{check}(\sigma) \mid \sigma \in \text{Var} \to \text{Val}\} \tag{29}
\]

\[
W \overset{\text{def}}{=} \{\text{write}(\sigma, \sigma') \mid \sigma, \sigma' \in \text{Var} \to \text{Val}\} \tag{30}
\]

We then define the function $\text{filt}(t)$ to be the set of all traces that are equal to the trace $t$ when removing a subset of the check- and write-events in $t$:

\[
\text{filt}(t) \overset{\text{def}}{=} \{h \in \mathcal{H} \mid h \prec t \land (\overline{C \cup W}) \oplus h = (\overline{C \cup W}) \oplus t\} \tag{31}
\]

where $\overline{C \cup W}$ means set complement (i.e. all events not in $C$ or $W$) and $h \prec t$ means that $h$ is a subtrace of $t$ (but not necessarily a consecutive subsequence), formally defined by:

\[
h_1 \prec h_2 \overset{\text{def}}{=} \exists p \in \{1, 2\}^\infty : \pi_2((\{1\} \times \mathcal{E}) \oplus (p, h_2)) = h_1 \tag{32}
\]

where $A^\infty$ is the set of all infinite sequences over the set $A$, $\pi_2$ is a projection operator returning the second element of a pair, and the filtering operator $\oplus$ is a generalization of $\oplus$, filtering pairs of sequences with respect to pairs of elements (for a formal definition of $\oplus$, see [1]). The infinite sequence $p$ may be understood as an oracle, determining which of the events in $h_2$ that are present in the subtrace $h_1$.

The $\text{filt}$ function is overloaded to sets of traces in standard pointwise manner, i.e.:

\[
\text{filt}(s) \overset{\text{def}}{=} \bigcup_{t \in s} \text{filt}(t) \tag{33}
\]
Finally, we redefine refinement of interaction obligations by:

\[(p, n) \rightsquigarrow_r (p', n') \equiv n \subseteq \text{filt}(n') \land p \subseteq \text{filt}(p') \cup \text{filt}(n') \]  

(34)
Appendix B. Identity of skip

Lemma 1. For all syntactically well-formed interactions $d$:
\[ \forall (p, n) \in [ d ] : \{()\} \succcurlyeq p = p \land \{()\} \succcurlyeq n = n \]

Proof sketch: By induction on the structure of $d$.

Base cases:

1. Case: $d = \text{skip}$
   1.1. $[\text{skip}] = \{(\{()\}, \emptyset)\}$
      Proof: Definition (1) of skip.
   1.2. $\{()\} \succeq p = p$, i.e. $\{()\} \succeq \{()\} = \{()\}$
      Proof: (1)1 and definition (3) of $\succcurlyeq$.
   1.3. $\{()\} \succeq n = n$, i.e. $\{()\} \succeq \emptyset = \emptyset$
      Proof: (1)1 and definition (3) of $\succcurlyeq$.
   1.4. Q.E.D.

2. Case: $d = e$, where $e$ is an event,
   \[ d = \text{assign}(\text{var}, \text{expr}) \text{, or} \]
   \[ d = \text{constr}(c) \]
   Proof sketch: All cases follow the same pattern, defined below.
   
   Let: $ev = e$
   
   \[ \begin{align*}
   \text{cond}_1 &= \text{true} \\
   \text{cond}_2 &= \text{false}
   \end{align*} \]
   in the case $d = e$
   
   Let: $ev = \text{write}(\sigma, \sigma')$
   
   \[ \begin{align*}
   \text{cond}_1 &= \left((\sigma'(\text{var}) = \text{expr}(\sigma) \land \forall v \in \text{Var} : (v = \text{var} \lor \sigma'(v) = \sigma(v)))\right) \\
   \text{cond}_2 &= \text{false}
   \end{align*} \]
   in the case $d = \text{assign}(\text{var}, \text{expr})$
   
   Let: $ev = \text{check}(\sigma)$
   
   \[ \begin{align*}
   \text{cond}_1 &= \text{c}(\sigma) \\
   \text{cond}_2 &= \neg\text{c}(\sigma)
   \end{align*} \]
   in the case $d = \text{constr}(c)$
   
   (1)1. $[ d ] = \{(\{ev\} \mid \text{cond}_1), \{(ev) \mid \text{cond}_2\}\}$
   Proof: Definition (2) of an event, definition (15) of assign, or definition (16) of constr.
   
   (1)2. $\{()\} \succeq \{(ev) \mid c\} = \{(ev) \mid c\}$ for arbitrary event $ev$ and arbitrary condition $c$.

   (2)1. Case: $c$ is a contradiction, i.e. $\{(ev) \mid c\} = \emptyset$.
      Proof: $\{()\} \succeq \emptyset = \emptyset$ by definition (3) of $\succcurlyeq$.
   
   (2)2. Case: $c$ is not a contradiction
PROOF: For all traces \( t \), \( \langle t \rangle \sim t = t \), giving
\[ \{ \langle \rangle \} \sim \{ \langle \text{ev} \rangle \mid c \} = \{ \langle \text{ev} \rangle \mid c \} \] by definition (3) of \( \sim \).

\[ \langle 2 \rangle 3. \quad \text{Q.E.D.} \]

PROOF: The cases are exhaustive.
\[ \langle 1 \rangle 3. \quad \{ \langle \rangle \} \sim p = p, \text{ i.e. } \{ \langle \rangle \} \sim \{ \langle \text{ev} \rangle \mid \text{cond}_1 \} = \{ \langle \text{ev} \rangle \mid \text{cond}_1 \} \]

PROOF: (1)1 and (1)2.
\[ \langle 1 \rangle 4. \quad \{ \langle \rangle \} \sim n = n, \text{ i.e. } \{ \langle \rangle \} \sim \{ \langle \text{ev} \rangle \mid \text{cond}_2 \} = \{ \langle \text{ev} \rangle \mid \text{cond}_2 \} \]

PROOF: (1)1 and (1)2.
\[ \langle 1 \rangle 5. \quad \text{Q.E.D.} \]

**Induction cases:**

Let: \( d \) be an interaction constructed from the (sub-)interactions \( d_1, \ldots, d_m \) using the composition operators defined in this paper.

Assume: \( \forall i \in [1, m] : \forall (p_i, n_i) \in \left[ d_i \right] : \{ \langle \rangle \} \sim p_i = p_i \wedge \{ \langle \rangle \} \sim n_i = n_i \) (induction hypothesis)

**PROVE:** \( \forall (p, n) \in \left[ d \right] : \{ \langle \rangle \} \sim p = p \wedge \{ \langle \rangle \} \sim n = n \), i.e.
\[ \{ \langle \rangle \} \sim p = p \wedge \{ \langle \rangle \} \sim n = n \text{ for arbitrary } (p, n) \in \left[ d \right] \] by \( \forall \)-rule.

(3) **CASE:** \( d = \text{seq } [D], D \) a list of interactions

**PROOF SKETCH:** By induction on the length of \( D \).
\[ \langle 1 \rangle 1. \quad \text{Base case: } D = d_1, \text{ i.e. } d = \text{seq } [d_1] \]
\[ \langle 2 \rangle 1. \quad \left[ \text{seq } [d_1] \right] = \left[ d_1 \right] \]

PROOF: Definition (7) of seq.
\[ \langle 2 \rangle 2. \quad \text{Q.E.D.} \]

**PROOF:** (2)1 and the induction hypothesis.
\[ \langle 1 \rangle 2. \quad \text{Induction step: } D = D', d_i \text{ for } i \in [1, m], \text{ i.e. } d = \text{seq } [D', d_i] \]

Assume: \( \forall (p', n') \in \left[ \text{seq } [D'] \right] : \{ \langle \rangle \} \sim p' = p' \wedge \{ \langle \rangle \} \sim n' = n' \) (induction hypothesis 2)

**PROVE:** \( \{ \langle \rangle \} \sim p = p \wedge \{ \langle \rangle \} \sim n = n \) for arbitrary \( (p, n) \in \left[ \text{seq } [D', d_i] \right] \)
\[ \langle 2 \rangle 1. \quad \text{Choose } (p', n') \in \left[ \text{seq } [D'] \right] \text{ and } (p_i, n_i) \in \left[ d_i \right] \text{ such that } p = p' \gtrsim p_i \text{ and } n = n' \gtrsim n_i \cup n' \gtrsim n_i \]

**PROOF:** Definitions (5)–(7) of seq.
\[ \langle 2 \rangle 2. \quad \{ \langle \rangle \} \sim p = p, \text{ i.e. } \{ \langle \rangle \} \sim (p' \gtrsim p_i) = p' \gtrsim p_i \]

**PROOF:** (2)1 and associativity of \( \gtrsim \) (lemma 11 in [7]), which gives that \( \{ \langle \rangle \} \sim (p' \gtrsim p_i) \) is equal to \( \{ \langle \rangle \} \sim p' \gtrsim p_i \), which is equal to \( p' \gtrsim p_i \) by induction hypothesis 2.
\[ \langle 2 \rangle 3. \quad \{ \langle \rangle \} \sim n = n, \]
\[ \text{i.e. } \{ \langle \rangle \} \sim (n' \gtrsim p_i \cup n' \gtrsim n_i \cup p' \gtrsim n_i) \]
\[ = n' \gtrsim p_i \cup n' \gtrsim n_i \cup p' \gtrsim n_i \]

\[ \langle 3 \rangle 1. \quad \{ \langle \rangle \} \sim (n' \gtrsim p_i) = n' \gtrsim p_i \]

**PROOF:** Associativity of \( \gtrsim \) (lemma 11 in [7]) and induction hypothesis 2.
\[ \langle 3 \rangle 2. \quad \{ \langle \rangle \} \sim (n' \gtrsim n_i) = n' \gtrsim n_i \]
Proof: Associativity of $\succ$ (lemma 11 in [7]) and induction hypothesis 2.

(3.3) $\{\{} \succ (p' \succ n_i) = p' \succ n_i$

Proof: Associativity of $\succ$ (lemma 11 in [7]) and induction hypothesis 2.

(3.4) Q.E.D.

Proof: (2.1), distributivity of $\succ$ over $\cup$ (lemma 14 in [7]) and associativity of $\cup$.

(2.4) Q.E.D.

(1.3) Q.E.D.

(4) Case: $d = \text{refuse } [d_1]$

(1.1) $\{\{} \succ p = p$, i.e. $\{\} \succ \emptyset = \emptyset$

Proof: (1.1) and definition (3) of $\succ$.

(1.2) $\{\} \succ n = n$, i.e. $\{\} \succ (p_1 \cup n_1) = p_1 \cup n_1$

Proof: By distributivity of $\succ$ over $\cup$ (lemma 14 in [7]).

(1.3) $\{\} \succ n_1 = n_1$

Proof: The induction hypothesis.

(1.4) Q.E.D.

Proof: (1.1) and (2.1)–(2.3).

(1.4) Q.E.D.

(5) Case: $d = \text{assert } [d_1]$

(1.1) Choose $(p_1, n_1) \in [d_1]$ such that $p = p_1$ and $n = n_1 \cup (H \setminus p_1)$

Proof: Definition (9) of $\approx$.

(1.2) $\{\} \succ p = p_1$

Proof: (1.1) and the induction hypothesis.

(1.3) $\{\} \succ n = n$, i.e. $\{\} \succ (n_1 \cup (H \setminus p_1)) = n_1 \cup (H \setminus p_1)$

Proof: By distributivity of $\succ$ over $\cup$ (lemma 14 in [7]).

(1.4) $\{\} \succ n_1 = n_1$

Proof: The induction hypothesis.

(2.1) $\{\} \succ (H \setminus p_1) = (H \setminus p_1)$

Proof: Definition (3) of $\succ$ and $\langle \rangle \sim t = t$ for all traces $t$.

(3.1) $H \setminus p_1 \subseteq \{\} \preceq (H \setminus p_1)$

Proof sketch: Proof by contradiction.

Assume: 1. $h \in \{\} \preceq (H \setminus p_1)$
2. $h \not\in H \setminus p_1$, i.e. $h \in p_1$

Prove: false

(4.1) $h \in \{\} \preceq p_1$
Proof: Assumption 2 and the induction hypothesis.

(4) 2. Choose \( h_2 \in \mathcal{H} \setminus p_1 \) such that

\[
\forall l \in \mathcal{L} : e.l \circ h = e.l \circ \{\} \sim e.l \circ h_2
\]

Proof: Assumption 1 and definition (3) of \( \succsim \).

(4) 3. Choose \( h'_2 \in p_1 \) such that

\[
\forall l \in \mathcal{L} : e.l \circ h = e.l \circ \{\} \sim e.l \circ h'_2
\]

Proof: (4) 1 and definition (3) of \( \succsim \).

(4) 4. \( \forall l \in \mathcal{L} : e.l \circ h_2 = e.l \circ h'_2 \)

Proof: (4) 2, (4) 3 and \( \{\} \sim t = t \) for all traces \( t \).

(4) 5. \( \{\} \succsim p_1 = \{h' \in \mathcal{H} \mid \exists h'_2 \in p_1 : \forall l \in \mathcal{L} : e.l \circ h' = e.l \circ h'_2\} = p_1 \)

Proof: The induction hypothesis, definition (3) of \( \succsim \) and \( \{\} \sim t = t \) for all traces \( t \).

(4) 6. \( \{h' \in \mathcal{H} \mid \forall l \in \mathcal{L} : e.l \circ h' = e.l \circ h'_2\} \subseteq p_1 \)

Proof: (4) 3 and (4) 5.

(4) 7. \( \{h' \in \mathcal{H} \mid \forall l \in \mathcal{L} : e.l \circ h' = e.l \circ h_2\} \subseteq p_1 \)

Proof: (4) 4 and (4) 6.

(4) 8. \( h_2 \in p_1 \)

Proof: (4) 7, \( h_2 \in \{h' \in \mathcal{H} \mid \forall l \in \mathcal{L} : e.l \circ h' = e.l \circ h_2\} \) and elementary set theory \( x \in A \land A \subseteq B \Rightarrow x \in B \).

(4) 9. Q.E.D.

Proof: Contradiction by (4) 2 and (4) 8.

(3) 3. Q.E.D.

Proof: By elementary set theory \( A \subseteq B \land B \subseteq A \Rightarrow A = B \).

(2) 4. Q.E.D.

Proof: (1) 1 and (2) 1–(2) 3.

(1) 4. Q.E.D.

(6) Case: \( d = \text{alt} [d_1, \ldots, d_m] \)

(1) 1. For all \( i \in [1, m] \), choose \( (p_i, n_i) \in [d_i] \) such that \( p = \bigcup_{i \in [1, m]} p_i \) and \( n = \bigcup_{i \in [1, m]} n_i \)

Proof: Definition (10) of \( \text{alt} \) and definition (11) of \( \cup \).

(1) 2. \( \{\} \succsim p = p_i \), i.e. \( \{\} \succsim \bigcup_{i \in [1, m]} p_i = \bigcup_{i \in [1, m]} p_i \)

Proof: Distributivity of \( \succsim \) over \( \cup \) (lemma 14 in [7]).

(1) 2. \( \bigcup_{i \in [1, m]} \{\} \succsim p_i = \bigcup_{i \in [1, m]} p_i \)

Proof: The induction hypothesis.

(2) 3. Q.E.D.

Proof: (1) 1 and (2) 1–(2) 2.

(1) 2. \( \{\} \succsim n = n_i \), i.e. \( \{\} \succsim \bigcup_{i \in [1, m]} n_i = \bigcup_{i \in [1, m]} n_i \)

Proof: Distributivity of \( \succsim \) over \( \cup \) (lemma 14 in [7]).

(2) 2. \( \bigcup_{i \in [1, m]} \{\} \succsim n_i = \bigcup_{i \in [1, m]} n_i \)

Proof: The induction hypothesis.

(2) 3. Q.E.D.
(7) Case: \( d = \text{xalt} [d_1 \ldots d_m] \)

\(1\) Choose \( i \in [1, m] \) such that \( (p, n) \in [ d_i ] \)

Proof: Definition (12) of \text{xalt}.

\(2\) \( \{ \langle \rangle \} \triangleright p = p \)

Proof: \(1\) and the induction hypothesis.

\(3\) \( \{ \langle \rangle \} \triangleright n = n \)

Proof: \(1\) and the induction hypothesis.

\(4\) Q.E.D.

(8) Case: \( d = \text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \)

\(1\) For all \( i \in [1, m] \), choose \( (p'_i, n'_i) \in [ \text{seq} \{ \text{constr}(c_i), d_i \} ] \) such that

\( p = \bigcup_{i \in [1, m]} p'_i \cup \{ \langle \text{check}(\sigma) \rangle | (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \} \)

\( n = \bigcup_{i \in [1, m]} n'_i \)

Proof: Definition (17) of guarded \text{alt} and definition (11) of \( \bigcup \).

\(2\) \( \forall i \in [1, m]: \forall (p'_i, n'_i) \in [ \text{seq} \{ \text{constr}(c_i), d_i \} ] : \)

\( \{ \langle \rangle \} \triangleright p'_i = p'_i \land \{ \langle \rangle \} \triangleright n'_i = n'_i \)

Proof: The induction hypothesis and the induction cases (3) and (2) of \text{seq} and \text{constr}.

\(3\) \( \{ \langle \rangle \} \triangleright p = p, \)

i.e. \( \{ \langle \rangle \} \triangleright (\bigcup_{i \in [1, m]} p'_i \cup \{ \langle \text{check}(\sigma) \rangle | (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \}) \)

\( = \bigcup_{i \in [1, m]} p'_i \cup \{ \langle \text{check}(\sigma) \rangle | (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \} \)

Proof: Distributivity of \( \triangleright \) over \( \bigcup \) (lemma 14 in [7]).

\(4\) \( \bigcup_{i \in [1, m]} \{ \langle \rangle \} \triangleright p'_i = \bigcup_{i \in [1, m]} p'_i \)

Proof: \(1\).

\(5\) \( \{ \langle \rangle \} \triangleright \{ \langle \text{check}(\sigma) \rangle | (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \} = \{ \langle \text{check}(\sigma) \rangle | (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \} \)

Proof: Definition (3) of \( \triangleright \).

\(6\) Q.E.D.

Proof: \(1\), (2)–(3) and distributivity of \( \triangleright \) over \( \bigcup \) (lemma 14 in [7]).

\(7\) \( \{ \langle \rangle \} \triangleright n = n, \) i.e. \( \{ \langle \rangle \} \triangleright \bigcup_{i \in [1, m]} n'_i = \bigcup_{i \in [1, m]} n'_i \)

Proof: Distributivity of \( \triangleright \) over \( \bigcup \) (lemma 14 in [7]).

\(8\) \( \bigcup_{i \in [1, m]} \{ \langle \rangle \} \triangleright n'_i = \bigcup_{i \in [1, m]} n'_i \)

Proof: \(1\).

(9) Case: \( d = \text{xalt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \)

\(1\) Choose \( i \in [1, m] \) such that \( (p, n) \in [ \text{seq} \{ \text{constr}(c_i), d_i \} ] \)
Proof sketch: By induction on $j$.

(1)1. For all $j \in I$, choose $(p_j, n_j) \in \mu_j[[d_1]]$ such that $p = \bigcup_{j \in I} p_j$ and $n = \bigcup_{j \in I} n_j$

Proof: Definition (14) of loop and definition (11) of $[d]$. 

(1)2. $\forall j \in I : \forall (p_j, n_j) \in \mu_j[[d_1]] : \{j\} \succ p_j = p_j \land \{j\} \succ n_j = n_j$

Proof sketch: By induction on $j$.

(2)1. Base case: $j = 0$

(i) $\forall j, n_j = \emptyset$

Proof: Definition (13) of $\mu_0$.

(ii) $\forall j, n_j = \emptyset$

Proof: (3)1 and definition (3) of $\succ$.

(3)3. $\forall j, n_j = \emptyset$

Proof: (3)1 and associativity of $\succ$.

(3)4. Q.E.D.

(2)2. Base case: $j = 1$

(i) $(p_j, n_j) \in [[d_1]]$

Proof: Definition (13) of $\mu_0$.

(ii) $(p_j, n_j) \in [[d_1]]$

Proof: (3)1 and the induction hypothesis.

(3)3. $(p_j, n_j) \in [[d_1]]$

Proof: (3)1 and the induction hypothesis.

(3)4. Q.E.D.

(2)3. Induction step: $j > 1$

Assume: $\forall (p_j, n_j) \in \mu_{j-1}[[d_1]] : \{j\} \succ p_j \land \{j\} \succ n_j = n_j$

Proof: $\forall (p_j, n_j) \in \mu_j[[d_1]] : \{j\} \succ p_j \land \{j\} \succ n_j = n_j$, i.e. $(p_j, n_j) \in \mu_j[[d_1]]$ by $\forall$-rule.

(3)1. $(p_j, n_j) \in \mu_{j-1}[[d_1]] \succ [[d_1]]$

Proof: Definition (13) of $\mu_n$.

(3)2. Choose $(p'_j, n'_j) \in \mu_{j-1}[[d_1]]$ and $(p''_j, n''_j) \in [[d_1]]$ such that

$p_j = p'_j \succ p''_j$ and $n_j = n'_j \succ n''_j$

Proof: (3)1 and definitions (5)–(6) of $\succ$.

(3)3. $(p_j, n_j) \in \mu_j[[d_1]]$, i.e. $(p_j, n_j) \in \mu_j[[d_1]]$

Proof: (3)1 and associativity of $\succ$ (lemma 11 in [7]), which
Proof sketch: By induction on the structure of $d$.

Proof:

All cases except from seq and the induction step for loop are symmetrical to the cases in the proof of lemma 1, but using the symmetrical lemma 15 in [7] instead of lemma 14 in [7]. The cases for seq and loop are treated below.

\[
\begin{align*}
\text{Lemma 2. For all syntactically well-formed interactions } d: \\
\forall(p, n) \in [d]: p \succeq \{\} &= p \land n \succeq \{\} = n
\end{align*}
\]

Proof: By induction on the structure of $d$. 

\[
\begin{align*}
\text{1. } \forall(p, n) \in [d]: p \succeq \{\} &= p \\
\text{2. } \forall(p, n) \in [d]: n \succeq \{\} &= n
\end{align*}
\]
(3) Case: \( d = \text{seq} \{ D \} \), \( D \) a list of interactions

1. Case: \( D = d_1 \), i.e. \( d = \text{seq} \{ d_1 \} \)
   
   **Proof:** Definition (7) of seq.

2. Q.E.D.
   
   **Proof:** (2)1 and the induction hypothesis.

1. Choose \( (p', n') \in \text{seq} \{ D' \} \) and \( (p_i, n_i) \in \text{seq} \{ d_i \} \) such that

   \[
   p = p' \succ n \quad \text{and} \quad n = n' \succ p_i \cup n' \cup p' \succ n_i
   \]

   **Proof:** Definitions (5)–(7) of seq.

2. \( p \succ \{ \} = p \), i.e. \( (p' \succ p_i) \succ \{ \} = p' \succ p_i \)

   **Proof:** (2)1 and associativity of \( \succ \) (lemma 11 in [7]), which gives that \( (p' \succ p_i) \succ \{ \} \) is equal to \( p' \succ (p_i \succ \{ \}) \), which is equal to \( p' \succ p_i \) by the induction hypothesis.

3. \( n \succ \{ \} = n \), i.e. \( (n' \succ p_i \cup n' \succ n_i \cup p' \succ n_i) \succ \{ \} \)

   **Proof:** Associativity of \( \succ \) (lemma 11 in [7]) and the induction hypothesis.

4. \( (n' \succ n_i) \succ \{ \} = n' \succ n_i \)

   **Proof:** Associativity of \( \succ \) (lemma 11 in [7]) and the induction hypothesis.

5. \( (p' \succ n_i) \succ \{ \} = p' \succ n_i \)

   **Proof:** Associativity of \( \succ \) (lemma 11 in [7]) and the induction hypothesis.

6. Q.E.D.

7. Q.E.D.

   **Proof:** The cases are exhaustive by definition (7) of seq.

(10) Case: \( d = \text{loop} I \{ d_1 \} \)

1. Case: \( j > 1 \)

   1. \( (p_j, n_j) \in \mu_{j-1} \{ d_1 \} \succ \{ d_1 \} \)

      **Proof:** Definition (13) of \( \mu_n \).

   2. Choose \( (p_j', n_j') \in \mu_{j-1} \{ d_1 \} \) and \( (p_j'', n_j'') \in \{ d_1 \} \) such that

      \[
      p_j = p_j' \succ p_j'' \quad \text{and} \quad n_j = n_j' \succ n_j'' \cup n_j' \cup p_j' \succ n_j''
      \]

      **Proof:** (3)1 and definitions (5)–(6) of \( \succ \).
Theorem 1. skip is the left identity element for weak sequencing

Proof: \( \text{seq} \ [\text{skip}, d] = d \)

1. \( \forall(p, n) \in [d] : \{\} \not\subseteq p = p \land \{\} \not\subseteq n = n \)
   Proof: Lemma 1
2. \( \{\{\}, \}, \} \not\subseteq p, \{\} \not\subseteq n \mid (p, n) \in [d] = \{(p, n) \mid (p, n) \in [d]\} \)
   Proof: (1)1.
3. \( \{(\}, \}, \} \not\subseteq p, \{\} \not\subseteq n \mid (p, n) \in [d] = \{(p, n) \mid (p, n) \in [d]\} \)
   Proof: (1)2 and definitions (3)–(6) of \( \not\subseteq \).
4. \( [\text{skip}] \not\subseteq [d] = [d] \)
   Proof: (1)3, definition (1) of \( \text{skip} \) and elementary set theory
   \( \{a \mid a \in A\} = A \) for all sets \( A \).
5. \( [\text{seq} \ [\text{skip}, d] = [d] \)
   Proof: (1)4 and definition (7) of \( \text{seq} \).
6. Q.E.D.

Theorem 2. skip is the right identity element for weak sequencing

Proof: \( \text{seq} \ [d, \text{skip}] = d \)

Proof:
Symmetrical to the proof of theorem 1, using lemma 2 instead of lemma 1.
Appendix C. Comparing the guarded and unguarded versions of \( \texttt{alt} \) and \( \texttt{xalt} \)

**Theorem 3.** The definitions of guarded and unguarded \( \texttt{alt} \) are consistent.

Setting the guards to \( \texttt{true} \) in definition (17) of guarded \( \texttt{alt} \), results in the same semantics as definition (10) of unguarded \( \texttt{alt} \) when abstracting away all check-events introduced by the guarded \( \texttt{alt} \).

**Proof:**

\[
\left[ \texttt{alt} \left[ \texttt{true} \rightarrow d_1, \ldots, \texttt{true} \rightarrow d_m \right] \right] \quad \text{(with abstraction)} \\
= \{ \bigcup \{ o_1, \ldots, o_m, \{() \mid \left( \wedge_{j \in [1,m]} \neg \texttt{true} \right)(\sigma), \emptyset \} \} \mid \\
\forall i \in [1,m] : o_i \in \left[ \texttt{seq} \left[ \texttt{skip}, d_i \right] \right] \} \\
= \{ \bigcup \{ o_1, \ldots, o_m, (\emptyset, \emptyset) \} \mid \forall i \in [1,m] : o_i \in \left[ \texttt{seq} \left[ \texttt{skip}, d_i \right] \right] \} \quad \text{(see (*) below)} \\
= \{ \bigcup \{ o_1, \ldots, o_m \} \mid \forall i \in [1,m] : o_i \in \left[ \texttt{d}_i \right] \} \quad \text{(def. (11) of \( \bigcup \))} \\
= \{ \texttt{alt} \left[ d_1, \ldots, d_m \right] \} \quad \text{(lemma 1)} \\
= \{ \texttt{xalt} \left[ d_1, \ldots, d_m \right] \} \quad \text{(def. (12) of \( \texttt{xalt} \))}
\]

\(^(*)\) definition (17), calculation of \( \texttt{constr(\texttt{true})} \) on page 16, abstracting away all check-events introduced by definition (17) and definition (1) of \( \texttt{skip} \).

\(^{(**)}\) \( \{ \langle \texttt{check(\sigma)} \rangle \mid \left( \wedge_{j \in [1,m]} \neg \texttt{true} \right)(\sigma) \} = \{ \langle \texttt{check(\sigma)} \rangle \mid \left( \wedge_{j \in [1,m]} \texttt{false} \right)(\sigma) \} \\
= \{ \langle \texttt{check(\sigma)} \rangle \mid \texttt{false}(\sigma) \} = \{ \langle \texttt{check(\sigma)} \rangle \mid \texttt{false} \} = \emptyset \)

**Theorem 4.** The definitions of guarded and unguarded \( \texttt{xalt} \) are consistent.

Setting the guards to \( \texttt{true} \) in definition (18) of guarded \( \texttt{xalt} \), results in the same semantics as definition (12) of unguarded \( \texttt{xalt} \) when abstracting away all check-events introduced by the guarded \( \texttt{xalt} \).

**Proof:**

\[
\left[ \texttt{xalt} \left[ \texttt{true} \rightarrow d_1, \ldots, \texttt{true} \rightarrow d_m \right] \right] \quad \text{(with abstraction)} \\
= \bigcup_{i \in [1,m]} \left[ \texttt{seq} \left[ \texttt{skip}, d_i \right] \right] \quad \text{(see (*) below)} \\
= \bigcup_{i \in [1,m]} \left[ d_i \right] \quad \text{(theorem 1)} \\
= \left[ \texttt{xalt} \left[ d_1, \ldots, d_m \right] \right] \quad \text{(def. (12) of \( \texttt{xalt} \))}
\]

\(^{*}\) definition (18), calculation of \( \texttt{constr(\texttt{true})} \) on page 16, abstracting away all check-events introduced by definition (18) and definition (1) of \( \texttt{skip} \).
Appendix D. Reflexivity and transitivity of limited refinement

Lemma 3.
For all syntactically well-formed interactions \( d \): \( \llbracket d \rrbracket \neq \emptyset \)

Proof: Straightforward by induction on the structure of \( d \).

Theorem 5. The limited refinement operator \( \sim_l \) is reflexive.

Proof: \( d \sim_l d \)

1. \( d \sim_g d \)
   Proof: By reflexivity of \( \sim_g \) (theorem 8 in [7]).
2. Choose arbitrary \( o' \in \llbracket d \rrbracket \)
   Proof: \( \llbracket d \rrbracket \) is non-empty by lemma 3.
3. Choose \( o = o' \).
   Proof: (1)2.
4. \( o' \sim_r o' \)
   Proof: By reflexivity of \( \sim_r \) (lemma 25 in [7]).
5. \( \forall o' \in \llbracket d \rrbracket : \exists o \in \llbracket d \rrbracket : o \sim_r o' \)
   Proof: (1)2, (1)3 and (1)4.
6. Q.E.D.
   Proof: (1)1, (1)5 and definition (21) of \( \sim_l \).

Theorem 6. The limited refinement operator \( \sim_l \) is transitive.

Assume: (1) \( d \sim_l d' \)
(2) \( d' \sim_l d'' \)

Proof: \( d \sim_l d'' \)

1. \( d \sim_g d'' \)
   Proof: The assumptions, definition (21) of \( \sim_l \), and transitivity of \( \sim_g \)
   (theorem 9 in [7]).
2. Choose arbitrary \( o'' = (p'', n'') \in \llbracket d'' \rrbracket \)
   Proof: \( \llbracket d'' \rrbracket \) is non-empty by lemma 3.
3. Choose \( o' = (p', n') \in \llbracket d' \rrbracket \) such that \( (p', n') \sim_r (p'', n'') \)
   Proof: (1)2, assumption 2 and definition (21) of \( \sim_l \).
4. Choose \( o = (p, n) \in \llbracket d \rrbracket \) such that \( (p, n) \sim_r (p', n') \)
   Proof: (1)3, assumption 1 and definition (21) of \( \sim_l \).
5. \( (p, n) \sim_r (p'', n'') \)
   Proof: (1)4, (1)3 and transitivity of \( \sim_r \) (lemma 26 in [7]).
6. \( \forall o'' \in \llbracket d'' \rrbracket : \exists o \in \llbracket d \rrbracket : o \sim_r o'' \)
   Proof: (1)2, (1)4 and (1)5.
7. Q.E.D.
   Proof: (1)1, (1)6 and definition (21) of \( \sim_l \).
Appendix E. Monotonicity results

General proof sketch for all monotonicity proofs for limited refinement, $\rightsquigarrow_l$: The first part of definition (21) of $\rightsquigarrow_l$ follows from the assumption(s) and the corresponding monotonicity theorem for general refinement, $\rightsquigarrow_g$. For the second part of definition (21), the proof is symmetrical to the corresponding monotonicity proof for $\rightsquigarrow_g$. The difference is that for $\rightsquigarrow_g$ we choose an arbitrary interaction obligation for the original interaction and find a refining interaction obligation in the refinement, while for $\rightsquigarrow_l$ we choose an arbitrary interaction obligation in the refining interaction and find a corresponding interaction obligation in the original interaction.

Appendix E.1 Interactions without data

Lemma 4. (To be used when proving monotonicity with respect to refuse.)

Assume: $(p, n) \rightsquigarrow_r (p', n')$
Prove: $(\emptyset, p \cup n) \rightsquigarrow_r (\emptyset, p' \cup n')$

(1)1. Requirement 1: $p \cup n \subseteq p' \cup n'$
   Proof: $p \subseteq p' \cup n'$ and $n \subseteq n'$ by the assumption and definition (19) of $\rightsquigarrow_r$.
(1)2. Requirement 2: $\emptyset \subseteq \emptyset \cup (p' \cup n')$
   Proof: Trivial.
(1)3. Q.E.D.
   Proof: Definition (19) of $\rightsquigarrow_r$.

Theorem 7. Monotonicity of $\rightsquigarrow_g$ with respect to the refuse operator

Assume: $d_1 \rightsquigarrow_g d'_1$
Prove: $\text{refuse } [d_1] \rightsquigarrow_g \text{refuse } [d'_1]$

Proof sketch: Each obligation $o \in [\text{refuse } [d_1]]$ is constructed from an obligation $o_1 \in [d_1]$. By the assumption, we may select an obligation $o'_1 \in [d'_1]$ such that $o_1 \rightsquigarrow_r o'_1$. Using $o'_1$ we then construct an obligation $o' \in [\text{refuse } [d'_1]]$ and prove by lemma 4 that $o \rightsquigarrow_r o'$.

(1)1. Choose arbitrary $o = (p, n) \in [\text{refuse } [d_1]]$
   Proof: $[\text{refuse } [d_1]]$ is non-empty by lemma 3.
(1)2. Choose $(p_1, n_1) \in [d_1]$ such that $p = \emptyset$ and $n = p_1 \cup n_1$
   Proof: (1)1 and definition (8) of refuse.
(1)3. Choose $(p'_1, n'_1) \in [d'_1]$ such that $(p_1, n_1) \rightsquigarrow_r (p'_1, n'_1)$
   Proof: (1)2, the assumption and definition (20) of $\rightsquigarrow_g$.
(1)4. $d' = (p', n') = (\emptyset, p'_1 \cup n'_1) \in [\text{refuse } [d'_1]]$
   Proof: (1)3 and definition (8) of refuse.
(1)5. $(p, n) \rightsquigarrow_r (p', n')$
Assume Theorem 8. Monotonicity of $\triangleright$ with respect to the refuse operator

PROVE: refusal $[d_1] \triangleright$ refusal $[d'_1]$

Proof: The assumption and theorem 7 (monotonicity of $\triangleright$ with respect to refusal).

Proof sketch: By induction on $d_1$. 

Theorem 9. Monotonicity of $\triangleright$ with respect to the loop operator

Assume: $d_1 \triangleright d'_1$

Proof: loop $I [d_1] \triangleright$ loop $I [d'_1]$

Proof: The assumption and monotonicity of $\triangleright$ with respect to loop (theorem 16 in [7]).

Proof sketch: By induction on $i$. 

(1.6) $\forall o \in [\triangleright refusal [d_1]] : \exists o' \in [\triangleright refusal [d'_1]] : o \triangleright_r o'$

Proof: (1.1), (1.4), (1.5) and $\forall$-rule.

(1.7) Q.E.D.

Proof: (1.6) and definition (20) of $\triangleright$. 

Proof: (1.2), (1.4), (1.5) and lemma 4.

(1.3) $\forall o' \in [\triangleright refusal [d'_1]] : \exists o \in [\triangleright refusal [d_1]] : o \triangleright_r o'$

Proof: (1.2), (1.5), (1.6) and $\forall$-rule.

(1.8) Q.E.D.

Proof: (1.1), (1.7) and definition (21) of $\triangleright$. 

Proof: (1.1), (1.3), (1.4), (1.5) and lemma 4.
(3.1) \( \exists o \in \mu_i \parallel d_i \mid : o \leadsto_r o' \) for arbitrary \( i \), \( o' \in \mu_i \parallel d_i' \)

(4.1) Case: \( i = 0 \)

(5.1) \( o' = \{\{\}, \emptyset\} \)

Proof: Definition (13) of \( \mu_0 \).

(5.2) \( o' = \{\{\}, \emptyset\} \in \mu_0 \parallel d_i \)

Proof: Definition (13) of \( \mu_0 \).

(5.3) \( o' \leadsto_r o' \)

Proof: Reflexivity of \( \leadsto_r \) (lemma 25 in [7]).

(5.4) Q.E.D.

Proof: (5.2) and (5.3).

(4.2) Case: \( i = 1 \)

(5.1) \( o' \in \parallel d_i' \)

Proof: Definition (13) of \( \mu_1 \).

(5.2) Choose \( o \in \parallel d_i \) such that \( o \leadsto_r o' \)

Proof: (5.1), the assumption and definition (21) of \( \leadsto_l \).

(5.3) \( o \in \mu_1 \parallel d_i \)

Proof: (5.2) and definition (13) of \( \mu_1 \).

(5.4) Q.E.D.

Proof: (5.2) and (5.3).

(4.3) Case: \( i > 1 \)

(5.1) Assume: \( \forall o' \in \mu_k \parallel d_i' \parallel : \exists o \in \mu_k \parallel d_i \parallel : o \leadsto_r o' \)

(induction hypothesis)

Prove: \( \forall o' \in \mu_{k+1} \parallel d_i' \parallel : \exists o \in \mu_{k+1} \parallel d_i \parallel : o \leadsto_r o' \)

(6.1) \( \exists o \in \mu_{k+1} \parallel d_i \parallel : o \leadsto_r o' \) for arbitrary \( o' = (p', n') \in \mu_{k+1} \parallel d_i' \)

(7.1) Choose \( (p'_k, n'_k) \in \mu_k \parallel d_i' \) and \( (p'_l, n'_l) \in \parallel d_i' \) such that \( (p', n') = (p'_k, n'_k) \equiv (p'_l, n'_l) \)

Proof: (6.1), definition (13) of \( \mu_n \) and definition (6) of \( \equiv \).

(7.2) Choose \( (p_k, n_k) \in \mu_k \parallel d_i \) such that \( (p_k, n_k) \leadsto_r (p'_k, n'_k) \)

Proof: (7.1) and the induction hypothesis.

(7.3) Choose \( (p_1, n_1) \in \parallel d_i \) such that \( (p_1, n_1) \leadsto_r (p'_1, n'_1) \)

Proof: (7.1) and the main assumption.

(7.4) \( o = (p, n) = (p_k, n_k) \equiv (p_1, n_1) \in \mu_{k+1} \parallel d_i \)

Proof: (7.2), (7.3), definition (13) of \( \mu_n \) and definition (6) of \( \equiv \).

(7.5) \( o \leadsto_r o' \)

Proof: (7.1), (7.2), (7.3), (7.4) and monotonicity of \( \leadsto_r \) with respect to \( \equiv \) (lemma 30 in [7]).

(7.6) Q.E.D.

Proof: (7.4) and (7.5).

(6.2) Q.E.D.

Proof: \( \forall \)-rule.

(5.2) Q.E.D.

(4.4) Q.E.D.

Proof: The cases are exhaustive as \( i \) must be a natural number.
Theorem 10. Monotonicity of $\sim_1$ with respect to the $\text{seq}$ operator

Assume: $\forall i \in [1, m]: d_i \sim_1 d'_i$

Prove: $\text{seq} [d_1, \ldots, d_m] \sim_1 \text{seq} [d'_1, \ldots, d'_m]$

(1.1). $\text{seq} [d_1, \ldots, d_m] \sim_g \text{seq} [d'_1, \ldots, d'_m]$

Proof: The assumption and monotonicity of $\sim_g$ with respect to $\text{seq}$ (Theorem 13 in [7]).

(1.2). Choose arbitrary $o' = (p', n') \in [\text{seq} [d'_1, \ldots, d'_m]]$

Proof: $[\text{seq} [d'_1, \ldots, d'_m]]$ is non-empty by Lemma 3.

(1.3). $\exists o \in [\text{seq} [d_1, \ldots, d_m]]: o \sim_r o'$

Proof sketch: By induction on $m$, the number of $\text{seq}$-operands.

(2.1). Base case: $m = 1$

(3.1). $o' \in [d'_1]$

Proof: (1.2) and Definition (7) of $\text{seq}$.

(3.2). Choose $o \in [d_1]$ such that $o \sim_r o'$

Proof: (3.1), the assumption and definition (21) of $\sim_1$.

(3.3). $o \in [\text{seq} [d_1]]$

Proof: (3.2) and definition (7) of $\text{seq}$.

(3.4). Q.E.D.

Proof: (3.2) and (3.3).

(2.2). Induction step: $m = k + 1$

Assume: $\forall o' \in [\text{seq} [d'_1, \ldots, d'_k]]: \exists o \in [\text{seq} [d_1, \ldots, d_k]]: o \sim_r o'$ (induction hypothesis)

Prove: $\forall o' \in [\text{seq} [d'_1, \ldots, d'_{k+1}]]: \exists o \in [\text{seq} [d_1, \ldots, d_{k+1}]]: o \sim_r o'$

(3.1). Choose arbitrary $o' = (p', n') \in [\text{seq} [d'_1, \ldots, d'_{k+1}]]$
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Proof: [ seq [d'_1, ..., d'_k+1]] is non-empty by lemma 3.

(3.2) Choose (p'_{i,k}, n'_{i,k}) ∈ [ seq [d'_1, ..., d'_k]] and
        (p'_{i+1,k}, n'_{i+1,k}) ∈ [ d'_k+1] such that (p', n') = (p'_{i,k}, n'_{i,k}) ∼ (p'_{i+1,k}, n'_{i+1,k})

Proof: (3.1) and definitions (6)–(7) of seq.

(3.3) Choose (p_{i,k}, n_{i,k}) ∈ [ seq [d_1, ..., d_k]] such that
        (p_{i,k}, n_{i,k}) ∼_r (p'_{i,k}, n'_{i,k})

Proof: (3.2) and the induction hypothesis.

(3.4) Choose (p_{i+k+1, n_{i+k+1}}) ∈ [ d_k+1] such that
        (p_{i+k+1, n_{i+k+1}}) ∼_r (p'_{i+k+1, n'_{i+k+1}})

Proof: (3.3), (3.4), and definitions (6)–(7) of seq.

(3.5) a = (p, n) = (p_{i+k, n_{i+k}}) ∼ (p_{i+k+1, n_{i+k+1}}) ∈ [ seq [d_1, ..., d_k+1]]

Proof: (3.3) and definitions (6)–(7) of seq.

(3.6) a ∼_r o'

Proof: (3.3)–(3.5) and monotonicity of ∼_r with respect to ∼ (lemma 30 in [7]).

(3.7) Q.E.D.

Proof: (3.5) and (3.6).

(2.3) Q.E.D.

Proof: The cases are exhaustive as m is a natural number.

(1.4) ∀o' ∈ [ d'] : ∃o ∈ [ d] : o ∼_r o'

Proof: (1.2), (1.3) and ⋀-rule.

(1.5) Q.E.D.

Proof: (1.1), (1.4) and definition (21) of ∼_l.

\[ \square \]

Theorem 11. Monotonicity of ∼_l with respect to the \textit{alt} operator

Assume: ∀i ∈ [1, m] : d_i ∼_l d'_i

Prove: \textit{alt} [d_1, ..., d_m] ∼_l \textit{alt} [d'_1, ..., d'_m]

(1.1) \textit{alt} [d_1, ..., d_m] ∼_g \textit{alt} [d'_1, ..., d'_m]

Proof: The assumption and monotonicity of ∼_g with respect to \textit{alt} (theorem 11 in [7]).

(1.2) Choose arbitrary o' = (p', n') ∈ [ \textit{alt} [d'_1, ..., d'_m]]

Proof: [ \textit{alt} [d'_1, ..., d'_m]] is non-empty by lemma 3.

(1.3) For all i ∈ [1, m], choose (p'_i, n'_i) ∈ [ d'_i] such that p' = \bigcup_{i∈[1,m]} p'_i and
        n' = \bigcup_{i∈[1,m]} n'_i

Proof: (1.2), definition (10) of \textit{alt} and definition (11) of \textit{alt}.

(1.4) For all i ∈ [1, m], choose (p_i, n_i) ∈ [ d_i] such that (p_i, n_i) ∼_r (p'_i, n'_i)

Proof: (1.3), the assumption and definition (21) of ∼_l.

(1.5) o = (p, n) = (\bigcup_{i∈[1,m]} p_i, \bigcup_{i∈[1,m]} n_i) ∈ [ \textit{alt} [d_1, ..., d_m]]

Proof: (1.4), definition (10) of \textit{alt} and definition (11) of \textit{alt}.

(1.6) (p, n) ∼_r (p', n')

(2.1) Requirement 1: n ⊆ n', i.e. \bigcup_{i∈[1,m]} n_i ⊆ \bigcup_{i∈[1,m]} n'_i

Proof: \forall i ∈ [1, m] : n_i ⊆ n'_i by (1.4) and definition (19) of ∼_r.

(2.2) Requirement 2: p ⊆ p' ∪ n', i.e. \bigcup_{i∈[1,m]} p_i ⊆ \bigcup_{i∈[1,m]} p'_i ∪ \bigcup_{i∈[1,m]} n'_i

Proof: (2.1) and (2.2).
Let Lemma 5.

Appendix E.2 Interactions with data

Proof: Definition (19) of $\sim_r$.

(1.7) $\forall o' \in \lbrack \text{alt} \lbrack d_1', \ldots, d_m' \rbrack \rbrack : \exists o \in \lbrack \text{alt} \lbrack d_1, \ldots, d_m \rbrack \rbrack : o \sim_r o'$

Proof: (1.2), (1.5), (1.6) and $\forall$-rule.

(1.8) Q.E.D.

Proof: (1.1), (1.7) and definition (21) of $\sim_l$.

\[\Box\]

Theorem 12. Monotonicity of $\sim_l$ with respect to the xalt operator

Assume: $\forall i \in [1,m] : d_i \sim_l d_i'$

Prove: $\text{xalt} \lbrack d_1, \ldots, d_m \rbrack \sim_l \text{xalt} \lbrack d_1', \ldots, d_m' \rbrack$

(1.1) $\text{xalt} \lbrack d_1, \ldots, d_m \rbrack \sim_g \text{xalt} \lbrack d_1', \ldots, d_m' \rbrack$

Proof: The assumption and monotonicity of $\sim_g$ with respect to xalt (Theorem 12 in [7]).

(1.2) Choose arbitrary $o' = (p', n') \in \lbrack \text{xalt} \lbrack d_1', \ldots, d_m' \rbrack \rbrack$

Proof: $\lbrack \text{xalt} \lbrack d_1', \ldots, d_m' \rbrack \rbrack$ is non-empty by Lemma 3.

(1.3) Choose $i \in [1,m]$ such that $(p', n') \in \lbrack d_i' \rbrack$

Proof: (1.2) and definition (12) of xalt.

(1.4) Choose $o = (p, n) \in \lbrack d_i \rbrack$ such that $(p, n) \sim_r (p', n')$

Proof: (1.3), the assumption and definition (21) of $\sim_l$.

(1.5) $(p, n) \in \lbrack \text{xalt} \lbrack d_1, \ldots, d_m \rbrack \rbrack$

Proof: (1.4) and definition (12) of xalt.

(1.6) $\forall o' \in \lbrack \text{alt} \lbrack d_1', \ldots, d_m' \rbrack \rbrack : \exists o \in \lbrack \text{alt} \lbrack d_1, \ldots, d_m \rbrack \rbrack : o \sim_r o'$

Proof: (1.2), (1.4), (1.5) and $\forall$-rule.

(1.7) Q.E.D.

Proof: (1.1), (1.6) and definition (21) of $\sim_l$.

\[\Box\]

Appendix E.2 Interactions with data

Lemma 5. (To be used when proving monotonicity with respect to guarded alt.)

Assume: (1) $\forall i \in [1,m] : c_i' \Rightarrow c_i$

(2) $\forall i \in [1,m] : (p_i, n_i) \sim_r (p_i', n_i')$

Let: (1) $p = \bigcup_{i \in [1,m]} p_i \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1,m]} \neg c_j)(\sigma) \}$

(2) $n = \bigcup_{i \in [1,m]} n_i$

(3) $p' = \bigcup_{i \in [1,m]} p_i' \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1,m]} \neg c_j')(\sigma) \}$

(4) $n' = \bigcup_{i \in [1,m]} n_i'$

Prove: $(p,n) \sim_r (p', n')$

(1.1) Requirement 1: $n \subseteq n'$, i.e. $\bigcup_{i \in [1,m]} n_i \subseteq \bigcup_{i \in [1,m]} n_i'$

Proof: $\forall i \in [1,m] : n_i \subseteq n'_i$ by assumption 2 and definition (19) of $\sim_r$. 

\[\Box\]
(1)2. Requirement 2: \( p \subseteq p' \cup n' \),
i.e. \( \left( \bigcup_{i \in [1, m]} p_i \right) \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \lnot c_j)(\sigma) \} \subseteq \left( \bigcup_{i \in [1, m]} p_i' \right) \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \lnot c_j')(\sigma) \} \cup \bigcup_{i \in [1, m]} n_i' \)

(2.1) \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \lnot c_j)(\sigma) \} \subseteq \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \lnot c_j') (\sigma) \} \}

(3.1) \forall j \in [1, m] : c'_j(\sigma) \Rightarrow c_j(\sigma)

Proof: Assumption 1.

(3.2) \forall j \in [1, m] : \lnot c_j(\sigma) \Rightarrow \lnot c_j'(\sigma)

Proof: \( (3.1) \) and propositional logic \((a \Rightarrow b) \) is equivalent to \((\lnot b \Rightarrow \lnot a) \).

(3.3) \bigwedge_{j \in [1, m]} \lnot c_j(\sigma) \Rightarrow \bigwedge_{j \in [1, m]} \lnot c_j'(\sigma)

Proof: \( (3.2) \) and propositional logic \(((a_1 \Rightarrow b_1) \land (a_2 \Rightarrow b_2)) \Rightarrow (a_1 \land a_2 \Rightarrow b_1 \land b_2) \).

(3.4) Q.E.D.

Proof: \( (3.3) \) and elementary set theory \((a \Rightarrow a') \) gives \( \{x \mid a\} \subseteq \{x \mid a'\} \).

(2.2) \bigcup_{i \in [1, m]} p_i \subseteq \bigcup_{i \in [1, m]} p_i' \cup \bigcup_{i \in [1, m]} n_i'

Proof: \( \forall i \in [1, m] : p_i \subseteq p_i' \cup n_i' \) by assumption 2 and definition (19) of \( \sim \).

(2.3) Q.E.D.

Proof: \( (2.2) \) and \( (2.2) \).

(1.3) Q.E.D.

Proof: Definition (19) of \( \sim \).

\[
\begin{align*}
\text{Lemma 6. Strengthening constraints} \\
& (c' \Rightarrow c) \Rightarrow (\text{constr}(c) \sim_I \text{constr}(c'))
\end{align*}
\]

Assume: \( c' \Rightarrow c \)

Prove: \( \text{constr}(c) \sim_I \text{constr}(c') \)

Proof sketch: \( \text{constr}(c) \) and \( \text{constr}(c') \) has only one interaction obligation each, where the different \( \langle \text{check}(\sigma) \rangle \)-traces are positive or negative depending on the value of \( c(\sigma) \) and \( c'(\sigma) \), respectively. The trace \( \langle \text{check}(\sigma) \rangle \) is negative for \( \text{constr}(c) \) if \( c(\sigma) \) is false. In this case, \( c'(\sigma) \) is false as well (by the assumption), meaning that the trace is also negative for \( \text{constr}(c') \) as required. The trace \( \langle \text{check}(\sigma) \rangle \) is positive for \( \text{constr}(c) \) if \( c(\sigma) \) is true. As required, this trace is either positive or negative in \( \text{constr}(c') \), depending on the value of \( c'(\sigma) \).

(1.1) \[\text{[constr}(c)\text{]} = \{(p,n)\} \]

where \( p = \{ \langle \text{check}(\sigma) \rangle \mid c(\sigma) \} \) and \( n = \{ \langle \text{check}(\sigma) \rangle \mid \lnot c(\sigma) \} \)

Proof: Definition (16) of constr.

(1.2) \[\text{[constr}(c')\text{]} = \{(p',n')\} \]

where \( p' = \{ \langle \text{check}(\sigma) \rangle \mid c'(\sigma) \} \) and \( n' = \{ \langle \text{check}(\sigma) \rangle \mid \lnot c'(\sigma) \} \)

Proof: Definition (16) of constr.

(1.3) \( (p, n) \sim_I (p', n') \)
(2.1) Requirement 1: \( n \subseteq n' \),
i.e. \( \{ \langle \text{check}(\sigma) \rangle \mid \neg c(\sigma) \} \subseteq \{ \langle \text{check}(\sigma) \rangle \mid \neg c'(\sigma) \} \)

Proof: The assumption gives \( c'(\sigma) \Rightarrow c(\sigma) \), i.e. \( \neg c(\sigma) \Rightarrow \neg c'(\sigma) \).

(2.2) Requirement 2: \( p \subseteq p' \cup n' \),
i.e. \( \{ \langle \text{check}(\sigma) \rangle \mid c(\sigma) \} \subseteq \{ \langle \text{check}(\sigma) \rangle \mid c'(\sigma) \} \cup \{ \langle \text{check}(\sigma) \rangle \mid \neg c'(\sigma) \} \)

Proof: Trivial, as the right side equals \( \{ \langle \text{check}(\sigma) \rangle \mid \sigma \in \text{Var} \rightarrow \text{Val} \} \).

(2.3) Q.E.D.

Lemma 7. \((c' \Rightarrow c \land d \rightsquigarrow_g d') \Rightarrow (\text{seq } [\text{constr}(c), d] \rightsquigarrow_g \text{seq } [\text{constr}(c'), d'])\)

Assume: (1) \( c' \Rightarrow c \)
(2) \( d \rightsquigarrow_g d' \)

Prove: \( \text{seq } [\text{constr}(c), d] \rightsquigarrow_g \text{seq } [\text{constr}(c'), d'] \)

(1.1) \( \text{constr}(c) \rightsquigarrow_g \text{constr}(c') \)

Proof: Assumption 1, lemma 6 and definition (21) of \( \rightsquigarrow_l \).

(1.2) \( d \rightsquigarrow_g d' \)

Proof: Assumption 2.

(1.3) Q.E.D.

Proof: By monotonicity of \( \rightsquigarrow_g \) with respect to the seq operator (theorem 13 in [7]).

Lemma 8. \((c' \Rightarrow c \land d \rightsquigarrow_l d') \Rightarrow (\text{seq } [\text{constr}(c), d] \rightsquigarrow_l \text{seq } [\text{constr}(c'), d'])\)

Assume: (1) \( c' \Rightarrow c \)
(2) \( d \rightsquigarrow_l d' \)

Prove: \( \text{seq } [\text{constr}(c), d] \rightsquigarrow_l \text{seq } [\text{constr}(c'), d'] \)

(1.1) \( \text{constr}(c) \rightsquigarrow_l \text{constr}(c') \)

Proof: Assumption 1 and lemma 6.

(1.2) \( d \rightsquigarrow_l d' \)

Proof: Assumption 2.

(1.3) Q.E.D.

Proof: Theorem 10 (monotonicity of \( \rightsquigarrow_l \) with respect to the seq operator).

Theorem 13. Monotonicity of \( \rightsquigarrow_g \) with respect to the guarded alt operator.
For guarded alt,

(i) the operands may be refined separately, and

(ii) constraining the guards is a valid refinement step.

**Assume:** (1) \( \forall i \in [1, m] : c'_i \Rightarrow c_i \)
(2) \( \forall i \in [1, m] : d \Rightarrow g d'_i \)

**Prove:** \( \text{alt}[c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \Rightarrow \text{g alt}[c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \)

**Proof sketch:** Each obligation \( o \in \text{alt}[c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \) is constructed as the inner union of a set of obligations \( o_i \in \text{seq}[\text{constr}(c_i), d_i] \) (for \( i \in [1, m] \)), together with the extra no-guard-true obligation. By the assumptions and lemma 7, we may for each \( o_i \) select a refining obligation \( o_i' \in \text{seq}[\text{constr}(c_i'), d'_i] \). Using these \( o_i' \)’s and the extra no-guard-true obligation, we then construct an obligation \( o' \in \text{alt}[c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \)

Each negative trace in \( o \) is negative in one of the \( o_i \)'s. By definition (19) of refinement it is also negative in the corresponding \( o_i' \) and therefore negative in \( o' \) as required. Similarly, each positive trace in \( o \) is either positive in the no-guard-true obligation and therefore positive also in \( o' \), or positive in one of the \( o_i \)'s meaning that by definition (19) it is positive or negative in the corresponding \( o_i' \), and therefore positive or negative in \( o' \) as required.

(1)1. Choose arbitrary \( o = (p, n) \in \text{alt}[c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \)

**Proof:** \( \text{alt}[c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \) is non-empty by lemma 3.

(1)2. For all \( i \in [1, m] \), choose \( (p_i, n_i) \in \text{seq}[\text{constr}(c_i'), d'_i] \) such that

\( p = (\bigcup_{i \in [1, m]} p_i) \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \} \) and \( n = \bigcup_{i \in [1, m]} n_i \)

**Proof:** (1)1, definition (17) of guarded alt and definition (11) of \( \text{by} \).

(1)3. For all \( i \in [1, m] \), choose \( (p'_i, n'_i) \in \text{seq}[\text{constr}(c'_i), d'_i] \) such that

\( (p_i, n_i) \Rightarrow_r (p'_i, n'_i) \)

**Proof:** (1)2, the assumptions, lemma 7 and definition (20) of \( \Rightarrow_g \).

(1)4. \( o' = (p', n') = (\bigcup_{i \in [1, m]} p'_i) \cup \{ \langle \text{check}(\sigma) \rangle \mid (\bigwedge_{j \in [1, m]} \neg c'_j)(\sigma) \}, \bigcup_{i \in [1, m]} n'_i \)
\( \in \text{alt}[c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \)

**Proof:** (1)3, definition (17) of guarded alt and definition (11) of \( \text{by} \).

(1)5. \( (p, n) \Rightarrow_r (p', n') \)

**Proof:** Assumption 1, (1)2, (1)3, (1)4 and lemma 5.

(1)6. \( \forall o \in \text{alt}[c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \)
\( \exists o' \in \text{alt}[c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] : o \Rightarrow_r o' \)

**Proof:** (1)1, (1)4, (1)5 and \( \forall \)-rule.

(1)7. Q.E.D.

**Proof:** (1)6 and definition (20) of \( \Rightarrow_g \).

\[ \square \]

**Theorem 14.** **Monotonicity of** \( \Rightarrow_g \)** with respect to the guarded xalt **operator**

For guarded xalt,

(i) the operands may be refined separately, and
(ii) constraining the guards is a valid refinement step.

**Assume:**
1. $\forall i \in [1, m]: c'_i \Rightarrow c_i$
2. $\forall i \in [1, m]: d_i \sim_g d'_i$

**Prove:** $\text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \sim_g \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m]$

**Proof sketch:** For each obligation $o \in \{ \text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \}$, there exists an $i$ such that $o \in \{ \text{seq} [\text{constr}(c_i), d_i] \}$. By the assumptions and lemma 7, we may select an obligation $o' \in \{ \text{seq} [\text{constr}(c'_i), d'_i] \}$ such that $o \sim_r o'$. By definition (18) of guarded $\text{alt}$, $o'$ is also an obligation in $\{ \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \}$.

1.1. Choose arbitrary $o = (p, n) \in \{ \text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \}$

**Proof:** $\{ \text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \}$ is non-empty by lemma 3.

1.2. Choose $i \in [1, m]$ such that $(p, n) \in \{ \text{seq} [\text{constr}(c_i), d_i] \}$

**Proof:** (1.1) and definition (17) of guarded $\text{alt}$.

1.3. Choose $o' = (p', n') \in \{ \text{seq} [\text{constr}(c'_i), d'_i] \}$ such that $(p, n) \sim_r (p', n')$

**Proof:** (1.2), the assumptions, lemma 7 and definition (20) of $\sim_g$.

1.4. $(p', n') \in \{ \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \}$

**Proof:** (1.3) and definition (18) of guarded $\text{alt}$.

1.5. $\forall o' \in \{ \text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \}$:

\[ \exists o' \in \{ \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \} : o \sim_r o' \]

**Proof:** (1.1), (1.3), (1.4) and $\forall$-rule.

1.6. Q.E.D.

**Proof:** (1.5) and definition (20) of $\sim_g$.

\[ \square \]

**Theorem 15.** Monotonicity of $\sim_I$ with respect to the guarded $\text{alt}$ operator

**Assume:**
1. $\forall i \in [1, m]: c'_i \Rightarrow c_i$
2. $\forall i \in [1, m]: d_i \sim_I d'_i$

**Prove:** $\text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \sim_I \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m]$

1.1. $\text{alt} [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \sim_g \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m]$

**Proof:** The assumptions and theorem 13 (monotonicity of $\sim_g$ with respect to guarded $\text{alt}$).

1.2. Choose arbitrary $o' = (p', n') \in \{ \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \}$

**Proof:** $\{ \text{alt} [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \}$ is non-empty by lemma 3.

1.3. For all $i \in [1, m]$, choose $(p'_i, n'_i) \in \{ \text{seq} [\text{constr}(c'_i), d'_i] \}$ such that $p' = \bigcup_{i \in [1, m]} p'_i) \cup \{ (\text{check}(\sigma)) \mid (\bigwedge_{j \in [1, m]} \neg c'_j)(\sigma) \}$ and $n' = \bigcup_{i \in [1, m]} n'_i$

**Proof:** (1.2), definition (17) of guarded $\text{alt}$ and definition (11) of $\cup$.

1.4. For all $i \in [1, m]$, choose $(p_i, n_i) \in \{ \text{seq} [\text{constr}(c_i), d_i] \}$ such that $(p_i, n_i) \sim_r (p'_i, n'_i)$

**Proof:** (1.3), the assumptions, lemma 8 and definition (21) of $\sim_I$.

1.5. $o = (p, n) = (\bigcup_{i \in [1, m]} p_i) \cup \{ (\text{check}(\sigma)) \mid (\bigwedge_{j \in [1, m]} \neg c_j)(\sigma) \}, \bigcup_{i \in [1, m]} n_i$

**Proof:** (1.4), definition (17) of guarded $\text{alt}$ and definition (11) of $\cup$. 

\[ \square \]
Theorem 16. Monotonicity of \( \sim_l \) with respect to the guarded \( xalt \) operator

Assume:

1. \( \forall i \in [1, m] : c'_i \Rightarrow c_i \)
2. \( \forall i \in [1, m] : d_i \sim_l d'_i \)

Prove: \( xalt [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \sim_l xalt [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \)

1. Choose \( i \in [1, m] \) such that \( (p', n') \in \left[ xalt [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \right] \)

Proof: The assumptions and theorem 14 (monotonicity of \( \sim_l \) with respect to guarded \( xalt \)).

1. Choose arbitrary \( o' = (p', n') \in \left[ xalt [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \right] \)

Proof: \( \left[ xalt [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \right] \) is non-empty by lemma 3.

1. Choose \( o = (p, n) \in \left[ \text{seq} [\text{constr}(c'_i), d'_i] \right] \)

Proof: (1)3, the assumptions, lemma 8 and definition (21) of \( \sim_l \).

1. \( (p, n) \in \left[ xalt [c_1 \rightarrow d_1, \ldots, c_m \rightarrow d_m] \right] \)

Proof: (1)4 and definition (18) of guarded \( xalt \).

1. \( \forall o' \in \left[ xalt [c'_1 \rightarrow d'_1, \ldots, c'_m \rightarrow d'_m] \right] : o \sim_r o' \)

Proof: (1)2, (1)4, (1)5 and \( \forall \)-rule.

1. Q.E.D.

Proof: (1)1, (1)6 and definition (21) of \( \sim_l \).