Successive Wyner-Ziv Coding Scheme and its Application to the Quadratic Gaussian CEO Problem

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Abstract

We introduce a distributed source coding scheme called successive Wyner-Ziv coding scheme. We show that any point in the rate region of the quadratic Gaussian CEO problem can be achieved via the successive Wyner-Ziv coding. The notion of successive refinement in the single source coding is generalized to the distributed source coding scenario, which we refer to as distributed successive refinement. For the quadratic Gaussian CEO problem, we establish a necessary and sufficient condition for distributed successive refinement, where the successive Wyner-Ziv coding scheme plays an important role.

Index Terms


I. INTRODUCTION

The problem of distributed source coding has assumed renewed interest in recent years. Many practical compression schemes have been proposed for Slepian-Wolf coding (e.g. [1], [2] and the reference therein) and Wyner-Ziv coding (e.g. [3] and the reference therein), whose performances are close to the fundamental theoretical bounds [4], [5]. Therefore it is of interest to reduce the general distributed source coding problem to these well-studied cases.

Given $L$ i.i.d. discrete sources $X_1, X_2, \cdots, X_L$, the Slepian-Wolf rate region is the union of all the rate vectors $(R_1, R_2, \cdots, R_L)$ satisfying

$$\sum_{i \in A} R_i \geq H(X_A|X_{A^c}), \quad \forall \text{ nonempty set } A \subseteq I_L,$$

(1)

where $I_L = \{1, 2, \cdots, L\}$ and $X_A = \{X_i\}_{i \in A}$. The Slepian-Wolf region is a contra-polymatroid [6], [7] with $L!$ vertices. Specifically, if $\pi$ is a permutation on $I_L$, define the vector $(R_1(\pi), R_2(\pi), \cdots, R_L(\pi))$ by

$$R_{\pi(i)}(\pi) = H(X_{\pi(i)}|X_{\pi(i+1)}, \cdots, X_{\pi(L)}), \quad i = 1, \cdots, L - 1,$$

(2)

$$R_{\pi(L)}(\pi) = H(X_{\pi(L)}).$$

(3)

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Then \((R_1(\pi), R_2(\pi), \ldots, R_L(\pi))\) is a vertex of the Slepian-Wolf region for every permutation \(\pi\). It is known that vertices of the Slepian-Wolf region can be achieved with a complexity which is significantly lower than that of a general point. It was observed in [8] that by splitting a source into two virtual sources one can reduce the problem of coding an arbitrary point in a \(L\)-dimensional Slepian-Wolf region to that of coding a vertex of a \((2L - 1)\)-dimensional Slepian-Wolf region. To use nested lattice Wyner-Ziv codes as building blocks, the source-splitting approach was also adopted in distributed lossy source coding [9]. In the distributed source coding scenario, we shall refer to source splitting as quantization splitting (from the encoder viewpoint) or description refinement (from the decoder viewpoint) since it is quantization, not source, that gets split. Finally we want to point out that the source-splitting idea has a dual in the problem of coding for multiple access channels, which is referred to as rate-splitting [10]–[13].

The rest of this paper is divided into 3 sections. In Section II, we introduce a low complexity successive Wyner-Ziv coding scheme and prove that any point in the rate region of the quadratic Gaussian CEO problem can be achieved via this scheme. The duality between the superposition coding for multiaccess communication and the successive Wyner-Ziv coding is briefly discussed. A notion called distributed successive refinement is introduced in Section III. The quadratic Gaussian CEO problem is used as an example, for which the necessary and sufficient condition for the distributed successive refinement is established. We conclude the paper in Section IV.

In this paper, we use boldfaced letters to indicate \((n\text{-dimensional})\) vectors, capital letters for random objects, and small letters for their realizations. For example, we let \(X = (X(1), \ldots, X(n))^T\) and \(x = (x(1), \ldots, x(n))^T\). Calligraphic letters are used to indicate a set \((\text{say}, \mathcal{A})\). We use \(U_\mathcal{A}\) to denote the vector \((U_i)_{i \in \mathcal{A}}\) with index \(i\) in an increasing order and use \(U_\mathcal{A,B}\) to denote \((U_{\mathcal{A},j})_{j \in \mathcal{B}}\). Here \(U_i\) (and \(U_{i,j}\)) can be a random variable, a constant or a function. For any positive integer \(K\), we let \(\mathcal{I}_K = \{1, 2, \ldots, K\}\).

### II. Successive Wyner-Ziv Coding Scheme

In this paper, we adopt the model of the CEO problem. But some of our results also hold for many other distributed source coding models. The CEO problem has been studied for years [14]–[16]. Here is a brief description of this problem (also see Fig. 1).

Let \(\{X(t), Y_1(t), \ldots, Y_L(t)\}_{t=1}^\infty\) be a temporally memoryless source with instantaneous joint probability distribution \(P(x, y_1, \ldots, y_L)\) on \(\mathcal{X} \times \mathcal{Y}_1 \times \cdots \times \mathcal{Y}_L\), where \(\mathcal{X}\) is the common alphabet of the random variables \(X(t)\) for \(t = 1, 2, \ldots, \) and \(\mathcal{Y}_i\) \((i = 1, 2, \ldots, L)\) is the common alphabet of the random variables \(Y_i(t)\) for \(t = 1, 2, \ldots, \) \(\{X(t)\}_{t=1}^\infty\) is the target data sequence that the decoder is interested in. This data sequence cannot be observed directly. \(L\) encoders are deployed, where encoder \(i\) observes \(\{Y_i(t)\}_{t=1}^\infty, i = 1, 2, \ldots, L\). The data rate at which encoder \(i\) \((i = 1, 2, \ldots, L)\) may communicate information about its observations to the decoder is limited to \(R_i\) bits per second. The encoders are not permitted to communicate with each other. Finally, the decision \(\hat{X}(t)\) is computed from the combined data at the decoder so that a desired fidelity can be satisfied.

1\(^{\text{Here the elements of } \mathcal{A} \text{ and } \mathcal{B} \text{ are assumed to be nonnegative integers.}}\)
**Definition 2.1:** An \(L\)-tuple of rates \(R_{I_L}\) is said to be \(D\)-admissible if \(\forall \varepsilon > 0, \exists n_0\) such that \(\forall n > n_0\) there exist encoders:

\[
    f_i^{(n)} : Y_i^n \to \left\{ 1, 2, \ldots, 2^{n(R_i + \varepsilon)} \right\}, \quad i = 1, 2, \ldots, L,
\]

and a decoder:

\[
    g^{(n)} : \left\{ 1, 2, \ldots, 2^{n(R_i + \varepsilon)} \right\} \times \left\{ 1, 2, \ldots, 2^{n(R_2 + \varepsilon)} \right\} \times \cdots \times \left\{ 1, 2, \ldots, 2^{n(R_L + \varepsilon)} \right\} \to \mathcal{X}^n,
\]

such that

\[
    \frac{1}{n} \mathbb{E} \left[ \sum_{t=1}^{n} d \left( X(t), \hat{X}(t) \right) \right] \leq D + \varepsilon,
\]

where \(\hat{X} = g^{(n)} \left( f_1^{(n)} (Y_1), \ldots, f_L^{(n)} (Y_L) \right)\) and \(d(\cdot, \cdot) : \mathcal{X} \times \mathcal{X} \to [0, d_{\text{max}}]\) is a given distortion measure. We use \(\mathcal{R}(D)\) to denote the set of all \(D\)-admissible rate tuples.

**Definition 2.2 (Berger-Tung rate region):** Let

\[
    \mathcal{R}(W_{I_L}) = \left\{ R_{I_L} : \sum_{i \in A} R_i \geq I (Y_A; W_{A'} | W_{A''}) , \forall \text{ nonempty set } A \subseteq I_L \right\}.
\]

The Berger-Tung rate region with respect to distortion \(D\) is

\[
    \mathcal{R}_{BT}(D) = \text{conv} \left( \bigcup_{W_{I_L} \in \mathcal{W}(D)} \mathcal{R}(W_{I_L}) \right),
\]

where \(\mathcal{W}(D)\) is the set of all \(W_{I_L}\) satisfying the following properties:

(i) \(W_i \to Y_i \to (X, Y_{I_L \setminus \{i\}}, W_{I_L \setminus \{i\}})\) form a Markov chain for all \(i \in I_L\).

(ii) There exists a function

\[
    f : W_1 \times \cdots \times W_L \to \mathcal{X}
\]

such that \(Ed(X, \hat{X}) \leq D\), where \(\hat{X} = f(W_{I_L})\).

It was shown in [17]-[19] that \(\mathcal{R}_{BT} \subseteq \mathcal{R}(D)\). The Berger-Tung rate region is the largest known achievable rate region for the general CEO problem although it was shown by Körner and Marton [20] that it is not always tight. Computing the Berger-Tung rate region involves complicated optimization and convexification. Hence we
shall only focus on $R(W_{IL})$. And we will see later that for the quadratic Gaussian CEO problem, the properties of the Berger-Tung rate region are determined completely by those of $R(W_{IL})$.

It was proved in [21], [22] that $R(W_{IL})$ is a contra-polymatroid with $L!$ vertices if $W_i \rightarrow Y_i \rightarrow (X, Y_{IL \setminus \{i\}}, W_{IL \setminus \{i\}})$ form a Markov chain for all $i \in I_L$ (which we will assume throughout this paper). Specifically, if $\pi$ is a permutation on $I_L$, define the vector $R_{IL}(\pi)$ by

$$R_{\pi(i)}(\pi) = I(Y_{\pi(i)}; W_{\pi(i)} | W_{\pi(i+1)}, \ldots, W_{\pi(L)}), \quad i = 1, \ldots, L - 1,$$

$$R_{\pi(L)}(\pi) = I(Y_{\pi(L)}; W_{\pi(L)}).$$

Then $R_{IL}(\pi)$ is a vertex of $R(W_{IL})$ for every permutation $\pi$. The dominant face of $R(W_{IL})$ is the convex polytope consisting of all points $R_{IL} \in R(W_{IL})$ such that $\sum_{i=1}^{L} R_i = I(Y_{IL}; W_{IL})$. Any rate tuple $R_{IL}$ on the dominant face of $R(W_{IL})$ has the property that

$$R'_{IL} \leq R_{IL} \Rightarrow R'_{IL} = R_{IL}, \quad \forall R'_{IL} \in R(W_{IL}),$$

where $R'_{IL} \leq R_{IL}$ means $R'_i \leq R_i$ for all $i \in I_L$. It is easy to check that the vertices of $R(W_{IL})$ are on its dominant face. For each vertex $R_{IL}(\pi)$, there exists a low-complexity successive Wyner-Ziv coding scheme which can be roughly described as follows:

(i) Encoder $\pi(L)$ employs conventional lossy source coding. Encoder $\pi(i)$ ($i = L - 1, L - 2, \ldots, 1$) employs Wyner-Ziv coding with side information $W_{\pi(i+1)}, \ldots, W_{\pi(L)}$ at decoder.

(ii) Decoder first decodes the codeword $W_{\pi(L)}$ from encoder $\pi(L)$, then successively decodes the codeword $W_{\pi(i)}$ ($i = L - 1, L - 2, \ldots, 1$) from encoder $\pi(i)$ with side information $W_{\pi(i+1)}, \ldots, W_{\pi(L)}$.

Rate tuples on the dominant face other than these $L!$ vertices were previously known to be attainable only by one of two methods. The first method known to achieve these difficult rate tuples was time sharing between vertices. This approach can require as many as $L$ successive decoding schemes, each scheme requiring $L$ decoding steps. The second approach to achieve these rate tuples is joint decoding of all users. This is very difficult to implement in practice since random codes have a decoding complexity of the order of $2^{nI(Y_{IL}; W_{IL})}$, where $n$ is the block length.

We will show that any rate tuple in $R(W_{IL})$ can be achieved by a low-complexity successive Wyner-Ziv coding scheme with at most $2L - 1$ steps. Without loss of generality, we only need to consider the rate tuple on the dominant face of $R(W_{IL})$. Before proceeding to prove this result, we shall first give a formal description of the general successive Wyner-Ziv coding scheme.

Let $(W_1, X_{m_1}, W_2, X_{m_2}, \ldots, W_L, X_{m_L})$ jointly distributed with the generic source variables $(X, Y_{IL})$ such that $W_i, X_{m_i} \rightarrow Y_i \rightarrow (X, Y_{IL \setminus \{i\}}, (W_j, X_{m_j})_{j \in I_L \setminus \{i\}})$ form a Markov chain for all $i \in I_L$. Let $\sigma$ be a permutation on $\{W_1, X_1, \ldots, W_L, X_{m_L}\}$ such that for all $i \in I_L$, $W_{i,j}$ is placed before $W_{i,k}$ if $j < k$ (we refer this type of

\footnote{By Carathéodory’s fundamental theorem [23], any point in the convex closure of a connected compact set $A$ in a $d$ dimensional Euclidean space can be represented as a convex combination of $d + 1$ or fewer points in the original set $A$.}
permutation as the well-ordered permutation. Let \(\{W_{i,j}\}_\sigma\) denote all the random variables that appear before \(W_{i,j}\) in the permutation \(\sigma\).

**Random Binning at Encoder i:** In what follows we shall adopt the notation and conventions of [24]. Let \(n\)-vectors \(W_{i,1}(1), \ldots, W_{i,1}(M_{i,1})\) be drawn independently according to a uniform distribution over the set \(T_\epsilon(W_{i,1})\) of \(\epsilon\)-typical \(W_{i,1}\)-vectors, where \(M_{i,1} = \left| 2^{n(I(Y; W_{i,1})+\epsilon_{i,j})} \right|\). That is, \(P(W_{i,1}(k) = w_{i,1}) = 1/\| T_\epsilon(W_{i,1}) \|\), if \(w_{i,1} \in T_\epsilon(W_{i,1})\), and \(= 0\) otherwise. Distribute these vectors into \(N_{i,1}\) bins: \(B_{i,1}(1), \ldots, B_{i,1}(N_{i,1})\), such that

\[
\left\lfloor \frac{M_{i,1}}{N_{i,1}} \right\rfloor \leq |B_{i,1}(b)| \leq \left\lceil \frac{M_{i,1}}{N_{i,1}} \right\rceil, \quad b = 1, 2, \ldots, N_{i,1},
\]

where \(N_{i,1} = \left| 2^{n(I(Y; W_{i,1})+\epsilon_{i,j})} \right|\) and \(|B_{i,1}(b)|\) denotes the number of \(W_{i,1}\)-vectors in \(B_{i,1}(b)\).

Successively from \(j = 2, j = 3, \ldots, \) to \(j = m_i\), for each vector \((k_1, \ldots, k_{j-1})\) with \(k_s \in \{1, 2, \ldots, M_{i,s}\} \) \((s = 1, 2, \ldots, j-1)\), let \(W_{i,j}(k_1, \ldots, k_{j-1}, 1), \ldots, W_{i,j}(k_1, \ldots, k_{j-1}, M_{i,j})\) be drawn i.i.d. according to a uniform distribution over the set \(T_\epsilon(W_{i,j}(1), \ldots, W_{i,j}(k_1, \ldots, k_{j-1}))\) of conditionally \(\epsilon\)-typical \(w_{i,j}\)'s, conditioned on \(w_{i,1}(k_1), \ldots, w_{i,j-1}(k_1, \ldots, k_{j-1})\), and distribute them uniformly into \(N_{i,j}\) bins: \(B_{i,j}(1), \ldots, B_{i,j}(N_{i,j})\) such that

\[
\left\lfloor \frac{M_{i,j}}{N_{i,j}} \right\rfloor \leq |B_{i,j}(b)| \leq \left\lceil \frac{M_{i,j}}{N_{i,j}} \right\rceil, \quad b = 1, 2, \ldots, N_{i,j},
\]

Here \(M_{i,j} = \left| 2^{n(I(Y; W_{i,j})+\epsilon_{i,j})} \right|, N_{i,j} = \left| 2^{n(I(Y; W_{i,j})+\epsilon_{i,j})} \right|\). Note: \(\epsilon_{i,j}, \epsilon_{i,j}'(i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i})\) are positive numbers of the same order as \(\epsilon\) which can be made arbitrarily small as \(n \to \infty\). Furthermore, we require

\[
\epsilon_{i,j} > \epsilon_{i,j}' \quad \text{for all} \quad i \in \mathcal{I}_L, \quad j \in \mathcal{I}_{m_i}
\]

**Encoding at Encoder i:** Given a \(y_i \in \mathcal{Y}_i^n\), find, if possible, a vector \((k_{i,1}^*, \ldots, k_{i,m_{i}}^*)\) such that

\[
(y_i, w_{i,1}(k_{i,1}^*), w_{i,2}(k_{i,1}^*, k_{i,2}^*), \ldots, w_{i,m_{i}}(k_{i,1}^*, \ldots, k_{i,m_{i}}^*)) \in T_\epsilon(Y_i, W_{i,1}, W_{i,2}, \ldots, W_{i,m_{i}}).
\]

Then find bins \(B_{i,1}(b_{i,1}^*), B_{i,2}(b_{i,2}^*), \ldots, B_{i,m_{i}}(b_{i,m_{i}}^*)\) such that \(B_{i,j}(b_{i,j}^*)\) contains \(w_{i,j}(k_{i,1}^*, \ldots, k_{i,j}^*), j = 1, 2, \ldots, m_{i}\). Send \((b_{i,1}^*, \ldots, b_{i,m_{i}}^*)\) to the decoder. If no such \((k_{i,1}^*, \ldots, k_{i,m_{i}}^*)\) exists, simply send \((0, \ldots, 0)\).

We can see the resulting transmission rate of encoder \(i\) is

\[
R_i = \frac{1}{n} \log \left( \prod_{j=1}^{m_i} N_{i,j} + 1 \right) \leq \sum_{j=1}^{m_i} I(Y_i; W_{i,j}) + \sum_{j=1}^{m_i} \epsilon_{i,j} + \frac{1}{n}.
\]  

**Decoding:** Given \((b_{i,1}^*, \ldots, b_{i,m_{i}}^*)\) for all \(i \in \mathcal{I}_L\), if \((b_{i,1}^*, \ldots, b_{i,m_{i}}^*) = (0, \ldots, 0)\) for some \(i\), declare a decoding fail. Otherwise decode as follows:

Let \(\sigma(j)\) denote the \(j^{th}\) element in permutation \(\sigma\). Let \(s_1(j), s_2(j)\) be the first and second subscript of \(\sigma(j)\) respectively. For example, if \(\sigma(j) = W_{3,2}\), then \(s_1(j) = 3, s_2(j) = 2\). Decoder first finds \(w_{\sigma_1(1), \sigma_2(1)}(\hat{k}_{\sigma_1(1), \sigma_2(1)})\) in \(B(b_{\sigma_1(1), \sigma_2(2)}^*)\). Note: \(s_2(1) = 1\). Since \(B(b_{\sigma_1(1), \sigma_2(2)}^*)\) contains at most one vector, we have \(\hat{k}_{\sigma_1(1), \sigma_2(1)} = k_{\sigma_1(1), \sigma_2(1)}^*\). Successively from \(j = 2, j = 3, \ldots, \) to \(j = \sum_{i=1}^{L} m_i\), if in \(B_{\sigma_1(1), \sigma_2(1)}(b_{\sigma_1(1), \sigma_2(1)}^*)\), there exists a unique \(\hat{k}_{\sigma_1(1), \sigma_2(1)}\) such that

\[
\left( w_{\sigma_1(1), \sigma_2(1)}(\hat{k}_{\sigma_1(1), \sigma_2(1)}), \ldots, \hat{k}_{\sigma_1(1), \sigma_2(1)} \right) \in T_{\epsilon'}(W_{\sigma_1(1), \sigma_2(2)}(i \in \mathcal{I}_j))
\]

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decode \(w_{s_1(j), s_2(j)}(\tilde{k}_{s_1(j), 1}, \tilde{k}_{s_1(j), 2}, \ldots, \tilde{k}_{s_1(j), s_2(j)})\), otherwise declare a decodding failure. Note: \(\epsilon'\) is of the same order as \(\epsilon\) which can be made arbitrarily small as \(n \to \infty\).

By the standard technique, it can be shown that \(Pr(\tilde{k}_{i,j} = k_{i,j}^*, \forall i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i}) \to 1\) as \(n \to \infty\). Furthermore, by Markov Lemma [17], we have

\[
Pr((X, W_{i,j}(k_{i,j}^*, \ldots, k_{i,j}^*), i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i}) \in T_{\epsilon'}(X, W_{i,j}, i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i})) \to 1
\]

as \(n \to \infty\). Hence for any function \(g : \prod_{j=1}^{L} \prod_{j=1}^{m_i} W_{i,j} \to X\), we have

\[
\frac{1}{n} E \left[ \sum_{t=1}^{n} d(X(t), g(W_{i,j}(k_{i,j}^*, \ldots, k_{i,j}^*), i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i})) \right] \leq E d(X, g(W_{i,j}, i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i})) + \epsilon'' d_{\text{max}}
\]

with high probability, where \(W_{i,j}(k_{i,j}^*, \ldots, k_{i,j}^*)\) is the \(t\)th entry of \(W_{i,j}(k_{i_1,j_1}^*, k_{i_2,j_2}^*, \ldots, k_{i_{L,j}^*})\) and \(\epsilon''\) is of the same order as \(\epsilon\) which can be made arbitrarily small as \(n \to \infty\).

It is easy to see that if we let \(W'_{i,j} = W_{i,j} (\forall i \in \mathcal{I}_L, j \in \mathcal{I}_{m_i})\), and replace \(W_{i,j}\) by \(W'_{i,j}\) in (8), \(R_i\) is unaffected. Hence there is no loss of generality to assume \(W_{i,1} \to W_{i,2} \to \cdots \to W_{i,m_i} \to Y_i, \forall i \in \mathcal{I}_L\). We can view \(W_{i,j}\) as a description of \(Y_i\), as \(j\) gets larger, the description gets finer.

The above coding scheme can be interpreted in the following intuitive way:

Encoder \(i\) first splits \(R_i\) into \(m_i\) pieces: \(r_{i,j} = I(Y_i; W_{i,j} | \{W_{i,j}^{\sigma}\}), \forall j \in \mathcal{I}_{m_i}\). Then successively from \(j = 1, j = 2, \ldots, j = m_i\), it uses Wyner-Ziv code with ratio \(r_{i,j}\) to convey \(W_{i,j}\) to decoder which has side information \(\{W_{i,j}^{\sigma}\} \). Decoder recovers \(\{W_{i,j}, j \in \mathcal{I}_{m_i}, i \in \mathcal{I}_L\}\) successively according to the order in the permutation \(\sigma\). We can see that this scheme requires \(\sum_{i=1}^{L} m_i\) Wyner-Ziv coding steps. Thus we call this scheme as \(\sum_{i=1}^{L} m_i\)-successive Wyner-Ziv coding scheme.

The successive Wyner-Ziv encoding and decoding structure of the above scheme significantly reduces the coding complexity compared with joint decoding or time sharing scheme and makes the available practical Wyner-Ziv coding technique directly applicable to the more general distributed source coding scenarios. Furthermore, the successive Wyner-Ziv coding scheme has certain robust property which is especially attractive in some applications, say sensor networks. Since in the successive Wyner-Ziv coding scheme, encoder \(i\) essentially transmits its codeword in \(m_i\) packets. Each packet contains a sub-codeword \(W_{i,j}\) \((j \in \mathcal{I}_{m_i})\). If a packet, say packet \(W_{i,k}\) is lost in transmission, the decoder is still able to decode packets \(\{W_{i,k}^{\sigma}\}\). On the contrary, the jointly decoding scheme does not possess this robust property since any corruption in the transmitted codewords may cause a total failure in decoding. A similar successive coding strategy was developed in [25] for tree-structured sensor networks.

We need introduce another definition before giving a formal statement of our first theorem.

**Definition 2.3 (Berger-Tung rate region with side information at decoder):** For any nonempty set \(A \subseteq \mathcal{I}_L\), let

\[
\mathcal{R}(W_A | Z) = \left\{ R_A : \sum_{i \in S} R_i \geq I(Y_S; W_S | W_A \setminus S, Z), \forall \text{ nonempty set } S \subseteq A \right\},
\]

where \(W_i \to (Y_i, Z) \to (Y_{\mathcal{I}_L \setminus \{i\}}, W_{\mathcal{I}_L \setminus \{i\}})\) form a Markov chain for all \(i \in \mathcal{I}_L\).
It’s easy to check that \( \mathcal{R}(W_A|Z) \) is a contra-polymatroid with \(|A|\) vertices. Specifically, if \( \pi \) is a permutation on \( A \), define the vector \( R_A(\pi) \) by

\[
R_{\pi(i)}(\pi) = I(Y_{\pi(i)}; W_{\pi(i)}|W_{\pi(i+1)}, \ldots, W_{\pi(|A|)}, Z), \quad i = 1, \ldots, |A| - 1, \\
R_{\pi(|A|)}(\pi) = I(Y_{\pi(|A|)}; W_{\pi(|A|)}|Z).
\]

Then \( R_A(\pi) \) is a vertex of \( \mathcal{R}(W_A|Z) \) for every permutation \( \pi \). The dominant face \( \mathcal{D}(W_A|Z) \) of \( \mathcal{R}(W_A|Z) \) is the convex polytope consisting of all points \( R_A \in \mathcal{R}(W_A|Z) \) such that \( \sum_{i=1}^L R_i = I(Y_A; W_A|Z) \). We have \( \text{dim} \mathcal{D}(W_A|Z) \leq |A| - 1 \). The equality holds only when the \( L! \) vertices are all distinct. Any rate tuple \( R_A \in \mathcal{D}(W_A|Z) \) has the property that

\[
R'_A \leq R_A \Rightarrow R'_A = R_A, \quad \forall R'_A \in \mathcal{R}(W_A|Z).
\]

As the name suggests, \( \mathcal{R}(W_{I_L}|Z) \) is an achievable rate region when the decoder has the side information \( Z \). When \( Z \) is constant, \( \mathcal{R}(W_{I_L}|Z) \) becomes the conventional Berger-Tung rate region. Moreover, it will be clear in the next section that \( \mathcal{R}(W_{I_L}|Z) \) plays an important role in the multistage source coding.

**Theorem 2.1:** For any rate tuple \( R_{I_L} \in \mathcal{D}(W_{I_L}|Z) \), there exist random variables \((W'_{i,1}, \ldots, W'_{i,m_i})_{i \in I_L}\) jointly distributed with \((Y_{I_L}, Z)\) satisfying

(i) \( (Y_{I_L}, W_{I_L}, Z) = (Y_{I_L}, (W'_{i,m_i})_{i \in I_L}, Z) \) in distribution,

(ii) \( \sum_{i=1}^L m_i \leq 2L - 1 \) and \( m_i \leq 2 \) for all \( i \in I_L \),

(iii) \( W'_{i,1} \rightarrow W'_{i,m_i} \rightarrow (Y_i, Z) \rightarrow (Y_{I_L \setminus \{i\}}, W'_{j,I_j \setminus \{j\}}) \) form a Markov chain for all \( i \in I_L \),

and a well-ordered permutation \( \sigma \) on \( \{W'_{1,I_1}, W'_{2,I_2}, \ldots, W'_{L,I_L}\} \) such that

\[
R_i = \sum_{j=1}^{m_i} I(Y_i; W'_{i,j}|\{W'_{i,j}\}_{\sigma}, Z), \quad \forall i \in I_L.
\]

**Proof:** The theorem can be proved in a similar manner as in [12]. The details are omitted. ■

Roughly speaking, Theorem 1 says that if the decoder has the side information \( Z \), then encoders \( 1, 2, \ldots, L \) can convey \( W_{I_L} \) to the decoder via a \( K \)-successive Wyner-Ziv coding scheme for some \( K \leq 2L - 1 \) as long as \( R_{I_L} \in \mathcal{R}(W_{I_L}|Z) \).

It is noteworthy that \( 2L - 1 \) is just an upper bound, for the rate tuple on the boundary of \( \mathcal{D}(W_{I_L}|Z) \), the coding complexity can be further reduced. For example, consider the case where \( L = 3 \). Let \( V_1 \) be the vertex corresponding to permutation \( \pi_1 = (1, 2, 3) \), i.e.,

\[
V_1 = (I(Y_1; W_1|Z, W_2, W_3), I(Y_2; W_2|Z, W_3), I(Y_3; W_3|Z)).
\]

Let \( V_2 \) be the vertex corresponding to permutation \( \pi_2 = (1, 3, 2) \), i.e.,

\[
V_2 = (I(Y_1; W_1|Z, W_2, W_3), I(Y_2; W_2|Z, W_3), I(Y_3; W_3|Z, W_2)).
\]

For any rate tuple \( R_{I_3} \) on the edge connecting \( V_1 \) and \( V_2 \), we have \( R_1 = I(Y_1; W_1|Z, W_2, W_3) \). Hence encoder 1 can use a Wyner-Ziv code to convey \( W_1 \) to the decoder if \( Z \) are already available at the decoder. Note that \((R_2, R_3)\) is on the dominant face of \( \mathcal{R}(W_2, W_3|Z) \), by Theorem 2.1, decoder 2 and encoder 3 can convey via \((W_2, W_3)\) to...
the decoder via a 3-successive Wyner-Ziv coding scheme if $Z$ are already available to the decoder. Thus it is a 4-successive Wyner-Ziv coding scheme in total.

In general we can imitate the approach in [26]. For $\emptyset \subset A \subset I_L$, define the hyperplane

$$\mathcal{H}(A) = \left\{ R_{I_L} \in \mathcal{R}_L : \sum_{i \in A} R_i = I(Y_A; W_A|Z) \right\}$$

and let $\mathcal{F}_A = \mathcal{H}(A) \cap D(W_{I_L}|Z)$. If $\emptyset \subset A_1 \subset A_2 \subset \cdots \subset A_k \subset I_L$, is a telescopic sequence of subsets, then $\mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k}$ is a face of $D(W_{I_L}|Z)$. Conversely, every face of $D(W_{I_L}|Z)$ can be written in this form. Let $B_i = A_i - A_{i-1}$, $i = 1, 2, \cdots, k + 1$, where we set $A_0 = \emptyset$ and $A_k = I_L$. Let $\Xi$ be the set of permutation $\pi$ on $I_L$, such that

$$\left\{ \pi \left( \sum_{j=0}^{k-i} |B_{k+1-j}| + 1 \right), \cdots, \pi \left( \sum_{j=0}^{k+1-i} |B_{k+1-j}| \right) \right\} = B_i, \quad i = 1, 2, \cdots, k + 1.$$

Each permutation $\pi \in \Xi$ is associated with a vertex of $\mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k}$ and vice versa. Hence $\mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k}$ has totally $|\Xi| = \prod_{i=1}^{k+1} (|B_i|!)$ vertices. Moreover, we have $\dim(\mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k}) \leq L - k - 1$, where the equality holds if these $|\Xi|$ vertices are all distinct. For any rate tuple $R_{I_L} \in \mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k}$, it is easy to verify that $\mathcal{R}_{B_i}$ is on the dominant face of $\mathcal{R}(W_{B_i}|W_{\bigcup_{j=1}^{k+1} B_{j}}|Z)$, $i = 1, 2, \cdots, k + 1$. Hence by successively applying Theorem 2.1, we can conclude that an $(L + \ell)$-successive Wyner-Ziv coding scheme is sufficient for conveying $W_{I_L,\ell}$ to the decoder if it has the side information $W_{I_L,\ell}$. Here $\ell = \dim(\mathcal{F}_{A_1} \cap \mathcal{F}_{A_2} \cap \cdots \cap \mathcal{F}_{A_k})$.

**Corollary 2.1:** Any rate tuple $R_{I_L}$ on the dominant face of $\mathcal{R}(W_{I_L})$ can be achieved via a $K$-successive Wyner-Ziv coding scheme for some $K \leq 2L - 1$.

**Proof:** Apply Theorem 1 with $Z$ being a constant.

This successive Wyner-Ziv coding scheme has a dual in the multiple access communication, which we call successive superposition coding scheme.

Consider an $L$-user discrete memoryless multiple-access channel. This is defined in terms of a stochastic matrix

$$W : \mathcal{X} \times \cdots \times \mathcal{X}_L \rightarrow \mathcal{Y}$$

with entries $W(y|x_1, \cdots, x_L)$ describing the probability that the channel output is $y$ when the inputs are $x_1, \cdots, x_L$.

Now we give a brief description of the successive superposition coding scheme.

Let $X_{1,I_{m_1}}, X_{2,I_{m_2}}, \cdots, X_{L,I_{m_L}}$ be independent, i.e.,

$$p(x_{1,I_{m_1}}, x_{2,I_{m_2}}, \cdots, x_{L,I_{m_L}}) = p(x_{1,I_{m_1}})p(x_{2,I_{m_2}}) \cdots p(x_{L,I_{m_L}}),$$

and $x_{i,1} \in \mathcal{X}_i$ for all $i \in I_L$. Let $\sigma$ be a well-ordered permutation on the set $\{X_{1,I_{m_1}}, X_{2,I_{m_2}}, \cdots, X_{L,I_{m_L}}\}$.

**Encoder i:** Let $n$-vectors $X_{i,1}(1), \cdots, X_{i,1}(M_{i,1})$ be drawn independently according to the marginal distribution $p(x_{i,1})$, where $M_{i,1} = \lceil 2^{n\left(I(Y_{X_i}; Y|X_{-i},X_{i,-1})/n\right)} \rceil$. Successively from $j = 2, j = 3, \cdots$, to $j = m_i$, for each vector $(k_1, \cdots, k_{j-1})$ with $k_s \in \{1, 2, \cdots, M_{i,s}\}$ ($s = 1, \cdots, j-1$), let $X_{i,j}(k_1, \cdots, k_{j-1}, 1), \cdots, X_{i,j}(k_1, \cdots, k_{j-1}, M_{i,j})$ be drawn i.i.d. according to the marginal conditional distribution $p(x_{i,j}|x_{i,1}, \cdots, x_{i,j-1})$, conditioned on $x_{i,1}(k_1), \cdots,$
Hence there is no loss of generality to assume a splitting function such that the rate-splitting scheme can be converted into a successive superposition scheme. To see this, for each user $i$, let $f_i$ be a splitting function such that $X_i = f_i(U_{i,1}, U_{i,2}, \cdots, U_{i,m_i})$ and let $X_{i,m_i} = X_i, X_{i,j} = U_{i,j}, j = 1, 2, \cdots, m_i - 1$. Then $X_{i,1} \rightarrow X_{i,2} \rightarrow \cdots \rightarrow X_{i,m_i} \rightarrow Y$ form a Markov chain. In [12] $U_{i,1}, U_{i,2}, \cdots, U_{i,m_i}$ are required to be independent, if we remove this condition, and call the resulting rate-splitting scheme as “generalized rate-splitting scheme”, then every successive superposition scheme can also be converted into a generalized rate-splitting scheme by simply setting $U_{i,j} = X_{i,j}, \forall j \in I_{m_i}$ and $f_i(U_{i,1}, U_{i,2}, \cdots, U_{i,m_i}) = U_{i,m_i}$.

Let $$\mathcal{R}(X_{IL}) = \left\{ R_{IL} \in \mathbb{R}^L_+ : \sum_{i \in A} R_i \leq I(X_{A'}; Y | X_{A}), \forall \text{nonempty set } A \subseteq I_{IL} \right\}.$$ Ahlswede [27] and Liao [28] proved that $$\mathcal{C} = \text{conv} \left( \bigcup_{p(x_1)p(x_2)\cdots p(x_L)} \mathcal{R}(X_{IL}) \right),$$ where $\mathcal{C}$ is the capacity region of the synchronous channel.

This independence condition is unnecessary since $U_{i,1}, U_{i,2}, \cdots, U_{i,m_i}$ are all controlled by user $i$. But this condition facilitates the codebook construction and storage since now the high-rate codebook at each user is essentially a product of two low-rate codebooks.
It can be shown that if \( p(x_1, x_2, \ldots, x_L) = p(x_1) p(x_2) \cdots p(x_L) \), then \( \mathcal{R}(X_{IL}) \) is a polymatroid \([6][7]\) with \( L! \) vertices. Specifically, if \( \pi \) is a permutation on \( \mathcal{I}_L \), define the vector \( R_{\pi(I)}(\pi) \) by

\[
R_{\pi(i)}(\pi) = I(X_{\pi(i)}(\pi); Y | X_{\pi(1)}(\pi), \ldots, X_{\pi(i-1)}(\pi)), \quad i = 1, \ldots, L - 1,
\]

\[
R_{\pi(L)}(\pi) = I(X_{\pi(L)}(\pi); Y).
\]

Then \( R_{\pi(I)}(\pi) \) is a vertex of \( \mathcal{R}(X_{IL}) \) for every permutation \( \pi \). The dominant face of \( \mathcal{R}(X_{IL}) \) is the convex polytope consisting of all points \( R_{\pi(I)} \in \mathcal{R}(X_{IL}) \) such that \( \sum_{i=1}^{L} R_i = I(X_{IL}; Y) \). Any rate tuple \( R_{\pi(I)} \) on the dominant face of \( \mathcal{R}(X_{IL}) \) has the property that

\[
R'_{\pi(I)} \geq R_{\pi(I)} \Rightarrow R'_{\pi(I)} = R_{\pi(I)}, \quad \forall R'_{\pi(I)} \in \mathcal{R}(X_{IL}).
\]

The following corollary is a dual result of Corollary 1. The proof is similar to that of Corollary 1 and thus omitted.

**Corollary 2.2:** Any rate tuple \( R_{\pi(I)} \) on the dominant face of \( \mathcal{R}(I_L) \) can be achieved via a \( K \)-successive superposition coding scheme for some \( K \leq 2L - 1 \).

Although we assumed discrete-alphabet sources and bounded distortion measure in the previous discussion, all our results can be extended to the Gaussian case with squared distortion measure along the lines of \([29][31]\). Now we proceed to study the quadratic Gaussian CEO problem \([32]\), for which some stronger conclusions can be drawn. Let \( \{X(t)\}_{t=1}^{\infty} \) are i.i.d. Gaussian random variables with zero mean and variance \( \sigma_X^2 \). Let \( \{Y_i(t)\}_{t=1}^{\infty} = \{X(t) + N_i(t)\}_{t=1}^{\infty} \) for all \( i \in \mathcal{I}_L \), where \( \{N_i(t)\}_{t=1}^{\infty} \) are i.i.d Gaussian random variables independent of \( \{X(t)\}_{t=1}^{\infty} \) with mean zero and variance \( \sigma_{N_i}^2 \). Also, the random processes \( \{N_k(t)\}_{t=1}^{\infty} \) and \( \{N_j(t)\}_{t=1}^{\infty} \) are independent for \( j \neq k \). For each \( i \in \mathcal{I}_L \), let \( W_i = Y_i + T_i \), where \( T_i \sim N(0, \sigma_T^2) \) is independent of \( (X, Y_L, T_{IL \setminus \{i\}}) \). Moreover, let

\[
r_i = I(Y_i, W_i | X) = \frac{1}{2} \log \frac{\sigma^2_{N_i} + \sigma^2_T}{\sigma^2_X}, \quad \forall i \in \mathcal{I}_L.
\]

It was computed in \([22][34]\) that

\[
\mathcal{R}(W_{IL}) = \left\{ R_{IL} : \sum_{i \in A} R_i \geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in A} \frac{1 - \exp(-2r_i)}{\sigma_{N_i}^2} \right) + \sum_{i \in A} r_i, \forall \text{ nonempty set } A \subseteq \mathcal{I}_L \right\}
\]

\[
\triangleq \mathcal{R}(r_{IL}).
\]

Furthermore, it was shown in \([33][34]\) that

\[
\mathcal{R}(D) = \bigcup_{r_{IL} \in \mathcal{F}(D)} \mathcal{R}(r_{IL}),
\]

where \( \mathcal{F}(D) = \left\{ r_{IL} \in \mathbb{R}^L : \frac{1}{\sigma_X^2} + \sum_{i=1}^{L} \frac{1 - \exp(-2r_i)}{\sigma_{N_i}^2} \geq \frac{1}{D} \right\} \).

**Definition 2.4:** Let \( \partial \mathcal{R}(D) \) denote the boundary of \( \mathcal{R}(D) \), i.e.,

\[
\partial \mathcal{R}(D) = \{ r_{IL} \in \mathcal{R}(D) : R'_{IL} \leq R_{IL} \Rightarrow R'_{IL} = R_{IL}, \quad \forall R'_{IL} \in \mathcal{R}(D) \}.
\]
Since \( R \) is attained at a vertex \( R_{x_L}(\pi^*) \) where is \( \pi^* \) any permutation such that \( \alpha_{x^*_{(i)}} \geq \cdots \geq \alpha_{x^*_{(L)}} \). That is,

\[
\min_{R_{x_L} \in \mathcal{R}(r_{x_L})} \sum_{i=1}^{L} \alpha_i R_i = \min_{R_{x_L} \in \mathcal{R}(r_{x_L})} \sum_{i=1}^{L} \alpha_i R_i(\pi^*) = \sum_{i=1}^{L} \alpha_i R_i(\pi^*) = \sum_{i=1}^{L} \left( \alpha_{x^*_{(i)}} - \alpha_{x^*_{(i+1)}} \right) \sum_{j=1}^{i} R_{x^*_{(j)}}(\pi^*) + \alpha_{x^*_{(L)}} \sum_{i=1}^{L} R_{x^*_{(i)}}(\pi^*)
\]

Hence we have

\[
\varphi(\alpha_{x_L}) = \min_{r_{x_L} \in \mathcal{R}_+} \sum_{i=1}^{L-1} \left( \alpha_{x^*_{(i)}} - \alpha_{x^*_{(i+1)}} \right) \left( \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{j=1}^{i} \frac{1-\exp(-2r_j)}{\sigma_{N_j}} \right) + \sum_{j=1}^{i} r_{x^*_{(j)}} \right)
\]

subject to

\[
\frac{1}{\sigma_X^2} + \sum_{i=1}^{L} \frac{1-\exp(-2r_i)}{\sigma_{N_i}} \geq \frac{1}{D}.
\]

Since we can decrease \( r_{x^*_{(1)}} \) to make the constraint in (24) tight while keep the sum in (23) decreasing at the same time (If \( r_{x^*_{(1)}} \) attains 0 but the constraint in (24) is still not tight, then apply the same procedure to \( r_{x^*_{(2)}} \))
and so on., we can rewrite (23) and (24) as

\[
\varphi(\alpha^*_{iL}) = \min_{r_{iL} \in \mathbb{R}^L_+} \sum_{i=1}^{L-1} (\alpha^{*}_{pi}(i) - \alpha^{*}_{pi}(i+1)) \left( \sum_{j=1}^{i} r^{*}_{pi}(j) - \frac{1}{2} \log \left( \frac{D}{\sigma^2_X} + \sum_{j=i+1}^{L} \frac{D - D \exp(-2r^{*}_{pi}(j))}{\sigma^2_{N,pi}(j)} \right) \right)
+ \alpha^{*}_{pi}(L) \left( \frac{1}{2} \log \frac{\sigma^2_X}{D} + \sum_{j=1}^{L} r_j \right)
\]

subject to

\[
\frac{1}{\sigma^2_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r_i)}{\sigma^2_{N,i}} = \frac{1}{D}
\]

Let \(r^*_{iL} \) be the minimizer of the above optimization problem. Introduce Lagrange multipliers \(\lambda_{iL} \in \mathbb{R}^L \) for the inequality constraints \(r_{iL} \in \mathbb{R}^L_+ \) and a multiplier \(\nu \in \mathbb{R} \) for the equality constraint \(\frac{1}{\sigma^2_X} + \sum_{i=1}^{L} (1 - \exp(-2r_i)) / \sigma^2_{N,i} = 1/D \). Define

\[
G(r^*_{iL}, \lambda_{iL}, \nu) = \sum_{i=1}^{L-1} (\alpha^{*}_{pi}(i) - \alpha^{*}_{pi}(i+1)) \left( \sum_{j=1}^{i} r^{*}_{pi}(j) - \frac{1}{2} \log \left( \frac{D}{\sigma^2_X} + \sum_{j=i+1}^{L} \frac{D - D \exp(-2r^{*}_{pi}(j))}{\sigma^2_{N,pi}(j)} \right) \right)
+ \alpha^{*}_{pi}(L) \left( \frac{1}{2} \log \frac{\sigma^2_X}{D} + \sum_{j=1}^{L} r_j \right) - \nu \left( \frac{1}{\sigma^2_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r_i)}{\sigma^2_{N,i}} \right) .
\]

We obtain the Karush-Kuhn-Tucker conditions [35]

\[
\frac{\partial G}{\partial r^{*}_{pi}(k)} \bigg|_{r^{*}_{pi}(k)=r^{*}_{pi}(k)} = \alpha^{*}_{pi}(k) - \lambda^{*}_{pi}(k) - \frac{2\nu \exp(-2r^{*}_{pi}(k))}{\sigma^2_{N,pi}(k)} = 0,
\]

\[
\frac{\partial G}{\partial r^{*}_{pi}(1)} \bigg|_{r^{*}_{pi}(1)=r^{*}_{pi}(1)} = \alpha^{*}_{pi}(1) - \lambda^{*}_{pi}(1) - \frac{2\nu \exp(-2r^{*}_{pi}(1))}{\sigma^2_{N,pi}(1)} = 0,
\]

By the complementary slackness condition, i.e., \(\lambda_k \geq 0 \Rightarrow r^*_{ik} = 0\), we can solve these equations to get

\[
r^{*}_{pi}(1) = \left[ \frac{\alpha^{*}_{pi}(1) \sigma^2_{N,pi}(1)}{2\nu} \right]^+, \quad k = 2, 3, \ldots, L,
\]

\[
r^{*}_{pi}(k) = \left[ \frac{2\nu + \sum_{i=1}^{k-1} (\alpha^{*}_{pi}(i) - \alpha^{*}_{pi}(i+1)) \left( \frac{1}{D} - \sum_{j=1}^{i} \frac{1 - \exp(-2r^{*}_{pi}(j))}{\sigma^2_{N,pi}(j)} \right)^{-1}}{\alpha^{*}_{pi}(k) \sigma^2_{N,pi}(k)} \right]^+, \quad k = 2, 3, \ldots, L.
\]
where $\nu$ is uniquely determined by the distortion constraint
\[ \frac{1}{\sigma_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r_i^*)}{\sigma_{N_i}^2} = \frac{1}{D} \]  
(30)
and $r^*_i$ can be computed recursively from $r^*_{i(1)}, r^*_{i(2)}, \ldots$, to $r^*_{i(L)}$.

In the above we assume $\alpha_i > 0$ for all $i \in I_L$. Now suppose $\alpha^*_{-i} \geq \cdots \geq \alpha^*_{L} > 0 \geq \alpha^*_{L+1} \geq \cdots \geq \alpha^*_{\pi^*(L)}$. We can let $r^*_{\pi^*(L+1)} = \cdots = r^*_{\pi^*(L)} = \infty$. If
\[ \frac{1}{\sigma_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r^*_{i(i)})}{\sigma_{N^*_{i(i)}}^2} > \frac{1}{D}, \]  
(31)
then we have $r^*_{\pi^*(1)} = \cdots = r^*_{\pi^*(L)} = 0$ and correspondingly $\varphi(\alpha_{I_L}) = 0$. Otherwise, solve $r^*_{\pi^*(1)}, \ldots, r^*_{\pi^*(L)}$ from (28) (29) with the distortion constraint (30) replaced by
\[ \frac{1}{\sigma_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r^*_{\pi^*(i)})}{\sigma_{N^*_{\pi^*(i)}}^2} + \sum_{i=L+1}^{L} \frac{1}{\sigma_{N^*_{\pi^*(i)}}^2} = \frac{1}{D}. \]  
(32)

Let $T(\alpha_{I_L}, D)$ with $\alpha_i > 0 \ (\forall i \in I_L)$ be a supporting hyperplane of $\mathcal{R}(D)$. By (18), we have
\[ T(\alpha_{I_L}, D) \cap \partial \mathcal{R}(D) = T(\alpha_{I_L}, D) \cap \mathcal{R}(D) = T(\alpha_{I_L}, D) \cap \left( \bigcup_{r_{I_L} \in \mathcal{F}(D)} \mathcal{R}(r_{I_L}) \right). \]

If $T(\alpha_{I_L}, D) \cap \mathcal{R}(r_{I_L}) \neq \emptyset$ for some $r_{I_L} \in \mathcal{F}(D)$, then we must have $R_{I_L}(\pi^*) \in T(\alpha_{I_L}, D) \cap \mathcal{R}(r_{I_L})$, where $R_{I_L}(\pi^*)$ is a vertex (associated with permutation $\pi^*$) of $\mathcal{R}(r_{I_L})$. Now it follows by the above Lagrangian optimization that $\mathcal{R}(r_{I_L}) = \mathcal{R}(r^*_{I_L})$. Therefore, we have
\[ T(\alpha_{I_L}, D) \cap \partial \mathcal{R}(D) = T(\alpha_{I_L}, D) \cap \mathcal{R}(r^*_{I_L}). \]

Clearly, $T(\alpha_{I_L}, D) \cap \mathcal{R}(r^*_{I_L})$ is a face of the dominant face of $\mathcal{R}(r^*_{I_L})$. Let $(B_1, \ldots, B_k)$ be a partition of $I_L$ such that $\alpha_m = \alpha_n$ for any $\alpha_m, \alpha_n \in B_i \ (i = 1, 2, \ldots, k)$ and $\alpha_m > \alpha_n$ for any $\alpha_m \in B_i, \alpha_n \in B_j \ (i < j)$. Let $\Xi'$ be the set of permutation $\pi$ on $I_L$ such that
\[ \left\{ \pi \left( \sum_{j=1}^{i-1} |B_j'| + 1 \right), \ldots, \pi \left( \sum_{j=1}^{i} |B_j'| \right) \right\} = B_i', \quad i = 1, 2, \ldots, k. \]
$T(\alpha_{I_L}, D) \cap \mathcal{R}(r^*_{I_L})$ has totally $|\Xi'| = \prod_{i=1}^{k} (|B_i'|)$ vertices, each of which is associated with a permutation $\pi \in \Xi'$. Furthermore, $\dim(T(\alpha_{I_L}, D) \cap \mathcal{R}(r^*_{I_L})) \leq L - k$, where the equality holds if these $|\Xi'|$ vertices are all distinct.

Finally, we want to point out that if $\alpha_1 = \cdots = \alpha_L$, then $T(\alpha_{I_L}, D) \cap \mathcal{R}(r^*_{I_L})$ is the minimum sum-rate region of $\mathcal{R}(D)$ [22].

**Corollary 2.3**: For the quadratic Gaussian CEO problem, any rate tuple $R_{I_L} \in \partial \mathcal{R}(D)$ can be achieved via a $K$-successive Wyner-Ziv coding scheme for some $K \leq 2L - 1$.

**Proof**: Since $\mathcal{R}(D) = \bigcup_{r_{I_L} \in \mathcal{F}(D)} \mathcal{R}(r_{I_L})$, for any rate tuple $R_{I_L} \in \partial \mathcal{R}(D)$, there exists a vector $r_{I_L} \in \mathcal{F}(D)$ such that $R_{I_L} \in \mathcal{R}(r_{I_L})$. Furthermore, by Definition 2.4, it’s easy to see that $R_{I_L}$ must be on the dominant face of $\mathcal{R}(r_{I_L})$. Now the corollary follows from Corollary 2.1.
To get detailed information about the coding complexity of a rate tuple \( R_{I_L} \in \partial R(D) \), we can proceed as follows. Let \( T(\alpha_{I_L}, D) \) be the supporting hyperplane of \( \partial R(D) \) such that \( R_{I_L} \in T(\alpha_{I_L}, D) \cap \partial R(D) \). Use the Lagrangian optimization method to find \( R(\tau_{I_L}^*) \) with \( \tau_{I_L}^* \in \mathcal{F}(D) \) such that \( T(\alpha_{I_L}, D) \cap \partial R(D) = T(\alpha_{I_L}, D) \cap R(\tau_{I_L}^*) \). Let \( \mathcal{F} \subseteq T(\alpha_{I_L}, D) \cap R(\tau_{I_L}^*) \) be the lowest dimensional face of \( R(\tau_{I_L}^*) \) that contains \( R_{I_L} \). We can conclude that an \((L + \text{dim}(\mathcal{F}))-\text{successive Wyner-Ziv coding scheme is sufficient for } R_{I_L}.

### III. Distributed Successive Refinement

In the previous section, we have shown that successive Wyner-Ziv coding scheme suffices to achieve any rate tuple on the boundary of rate region for the quadratic Gaussian CEO problem. We shall extend this result to the multistage source coding scenario.

**Definition 3.1:** For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \) and \( D_1 \geq D_2 \geq \cdots \geq D_M \), we say the \( M \)-stage source coding

\[
(R_{I_L,1}, D_1) \succ (R_{I_L,2}, D_2) \succ \cdots \succ (R_{I_L,M}, D_M)
\]

is feasible if for any \( \epsilon > 0 \), there exists an \( n_0 \) such that for \( n > n_0 \) there exist encoders:

\[
f^{(n)}_{i,j}: \mathcal{X}^n_i \rightarrow \left\{ 1, 2, \ldots, 2^n(R_{i,j} - R_{i,j-1} + \epsilon) \right\}, \quad i = 1, 2, \ldots, L, \; j = 1, 2, \ldots, M,
\]

and decoders:

\[
g^{(n)}_{j}: \prod_{k=1}^j \prod_{i=1}^L \left\{ 1, 2, \ldots, 2^n(R_{i,k} - R_{i,k-1} + \epsilon) \right\} \rightarrow \mathcal{X}^n, \quad j = 1, 2, \ldots, M,
\]

such that

\[
\frac{1}{n} E \left[ \sum_{t=1}^n d(X(t), \hat{X}_j(t)) \right] \leq D_j + \epsilon, \quad j = 1, 2, \ldots, M,
\]

where

\[
\hat{X}_j = g^{(n)}_{j} \left( f^{(n)}_{1,1}(Y_1), \ldots, f^{(n)}_{L,1}(Y_L), \ldots, f^{(n)}_{1,j}(Y_1), \ldots, f^{(n)}_{L,j}(Y_L) \right), \quad j = 1, 2, \ldots, M.
\]

Here we assume \( R_{I_L,0} = (0, \ldots, 0) \).

The following definition can be viewed as a natural generalization of the successive refinement in the single source coding [36]–[39] to the distributed source coding scenario.

**Definition 3.2 (Distributed Successive Refinement):** Let \( D^*(R_{I_L}) = \min \{ D : R_{I_L} \in \mathcal{R}(D) \} \). For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \), we say there exists an \( M \)-stage distributed successive refinement scheme from \( R_{I_L,1} \) to \( R_{I_L,2} \), to \( \ldots, \), to \( R_{I_L,M} \) if the \( M \)-stage source coding

\[
(R_{I_L,1}, D^*(R_{I_L,1})) \succ (R_{I_L,2}, D^*(R_{I_L,2})) \succ \cdots \succ (R_{I_L,M}, D^*(R_{I_L,M}))
\]

is feasible.

**Theorem 3.1:** For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \) and \( D_1 \geq D_2 \geq \cdots \geq D_M \), the \( M \)-stage source coding

\[
(R_{I_L,1}, D_1) \succ (R_{I_L,2}, D_2) \succ \cdots \succ (R_{I_L,M}, D_M)
\]
is feasible if there exist random variables $W_{I_L, I_M}$ jointly distributed with the generic source variables $(X, Y_{I_L})$ such that

$$(R_{I_L,j} - R_{I_L,j-1}) \in \mathcal{R}(W_{I_L,j} | W_{I_L,j-1}),$$

where $W_{I_L, I_M}$ satisfy the following properties:

(i) $W_{i,1} \rightarrow W_{i,2} \rightarrow \cdots \rightarrow W_{i,M} \rightarrow Y_i \rightarrow (X, Y_{I_L \setminus \{i\}}, W_{I_L \setminus \{i\}, I_M})$ form a Markov chain for all $i \in I_L$;

(ii) For each $j \in I_M$, there exists a function $\hat{X}_j : \prod_{i=1}^L W_{i,j} \rightarrow X$ such that $\mathbb{E}(X, \hat{X}_j(W_{I_L,j})) \leq D_j$.

**Proof:** By Theorem 1, we can see that each stage can be realized via a $(2L-1)$-successive Wyner-Ziv scheme.

The above scheme for the $M$-stage source coding is essentially concatenating $M$ versions of $(2L-1)$-successive Wyner-Ziv coding scheme. Actually itself can be viewed as a $(2ML - M)$-successive Wyner-Ziv coding scheme. But it is subject to more restricted conditions since a general $(2ML - M)$-successive Wyner-Ziv scheme (satisfying the rate constraints: $R_{I_L,M}$ and the distortion constraint: $D_M$) may not be decomposable into $M$ versions of $2L-1$ successive Wyner-Ziv scheme with rate and distortion constraints satisfied at each stage.

In the following part of this section, we shall focus on the quadratic Gaussian CEO problem.

**Lemma 3.1:** For $R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M}$ and $D_1 \geq D_2 \geq \cdots \geq D_M$, the $M$-stage source coding

$$(R_{I_L,1}, D_1) / (R_{I_L,2}, D_2) / \cdots / (R_{I_L,M}, D_M)$$

is feasible if there exist $r_{I_L,j} \in \mathbb{R}_+^L$, $j = 1, 2, \cdots, M$, satisfying

(i) $r_{I_L,j-1} \leq r_{I_L,j}$ for all $j \in I_M$,

(ii) $1/\sigma_X^2 + \sum_{i=1}^L (1 - \exp(-2r_{i,j})) / \sigma_{N_i}^2 = 1/D_j$ for all $j \in I_M$,

such that

$$\sum_{i \in \mathcal{A}} (R_{i,j} - R_{i,j-1}) \geq \frac{1}{2} \log \frac{1}{D_j} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in \mathcal{A}} \frac{1 - \exp(-2r_{i,j-1})}{\sigma_{N_i}^2} + \sum_{i \in \mathcal{A}^c} \frac{1 - \exp(-2r_{i,j})}{\sigma_{N_i}^2} \right)$$

$$+ \sum_{i \in \mathcal{A}} (r_{i,j} - r_{i,j-1}), \quad \forall j \in I_M, \forall \text{ nonempty set } \mathcal{A} \subseteq I_L. \quad (33)$$

Here we assume $r_{I_L,0} = (0, \cdots, 0)$.

**Proof:** Let $W_{i,M} = Y_i + T_{i,M}$ and $W_{i,j} = W_{i,j+1} + T_{i,j}$ ($j \in I_M - 1$), where $T_{i,j} \sim \mathcal{N}(0, \sigma_{T_{i,j}}^2), i \in I_L, j \in I_M$ are all independent and they are also independent of $(X, Y_{I_L})$. Let

$$r_{i,j} = I(Y_i; W_{i,j} | X) = \frac{1}{2} \log \frac{\sigma_{N_i}^2 + \sum_{k=j}^M \sigma_{T_{i,j}}^2}{\sum_{k=j}^M \sigma_{T_{i,j}}^2} \quad (34)$$

and $\mathbb{E}(X - \mathbb{E}(X | W_{I_L,j}))^2 = D_j$ for all $j \in I_M$, i.e.,

$$\frac{1}{\sigma_X^2} + \sum_{i=1}^L \frac{1 - \exp(-2r_{i,j})}{\sigma_{N_i}^2} = \frac{1}{D_j}. \quad (35)$$
Let $R_{I_L,0} = (0, \cdots, 0)$ and let $W_{I_L,0}$ be a constant vector. By Theorem 3.1, for any $R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M}$ with
\[
(R_{I_L,j} - R_{I_L,j-1}) \in \mathcal{R}(W_{I_L,j}|W_{I_L,j-1}), \quad \forall j \in \mathcal{I}_M,
\]
the $M$-stage source coding
\[
(R_{I_L,1}, D_1) \wedge (R_{I_L,2}, D_2) \wedge \cdots \wedge (R_{I_L,M}, D_M)
\]
is feasible. We can compute (36) explicitly as follows: for all nonempty set $A \subseteq \mathcal{I}_L$,
\[
\sum_{i \in A} (R_{i,j} - R_{i,j-1}) \geq I(Y_A; W_{A,j}|W_{A',j}, W_{A,j-1})
\]
\[
= I(X; Y_A; W_{A,j}|W_{A',j}, W_{A,j-1})
\]
\[
= I(X; W_{A,j}|W_{A',j}, W_{A,j-1}) + I(Y_A; W_{A,j}|X) - I(Y_A; W_{A,j-1}|X)
\]
\[
= h(X|W_{A',j}, W_{A,j-1}) - h(X|W_{I_L,j}) + \sum_{i \in A} (r_{i,j} - r_{i,j-1})
\]
\[
= \frac{1}{2} \log \frac{1}{D_j} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in A} \frac{1 - \exp(-2r_{i,j-1})}{\sigma_{N_i}^2} + \sum_{i \in A^c} \frac{1 - \exp(-2r_{i,j})}{\sigma_{N_i}^2} \right)
\]
\[
+ \sum_{i \in A} (r_{i,j} - r_{i,j-1}).
\]
The proof is now complete.

Lemma 3.2 ([31, Lemma 1]):
\[
\frac{1}{n} I(X; f_{I_L,j}^{(n)}(Y)) \geq \frac{1}{2} \log \frac{\sigma_X^2}{D_j}, \quad \forall j \in \mathcal{I}_M.
\]
The next lemma is a direct application of [34, Lemma 3.2] with $C_i = f_{i,I_L}^{(n)} (\forall i \in A)$ and $C_i = f_{i,I}^{(n)} (\forall i \in A^c)$, where $f_{i,I_L}^{(n)}$ is the abbreviation of $(f_{i,I_L}^{(n)}(Y_1), \cdots, f_{i,I_L}^{(n)}(Y_i))$.

Lemma 3.3: Let $r_{i,j} = \frac{1}{n} I(Y; f_{I_L,j}^{(n)}(X))$, $\forall i \in \mathcal{I}_L, \forall j \in \mathcal{I}_M$. We have, for all $0 \leq j \leq k \leq M$,
\[
\frac{1}{\sigma_X^2} \exp\left( \frac{2}{n} I(X; f_{A,L,j}^{(n)}, f_{A',L,j}^{(n)}) \right) \leq \frac{1}{\sigma_X^2} + \sum_{i \in A} \frac{1 - \exp(-r_{i,j})}{\sigma_{N_i}^2} + \sum_{i \in A^c} \frac{1 - \exp(-r_{i,j})}{\sigma_{N_i}^2},
\]
where $f_{i,I}^{(n)} (i \in \mathcal{I}_L)$ are constant functions and $r_{I_L,0} \equiv (0, \cdots, 0)$.

Lemma 3.4: For $R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M}$ and $D_1 \geq D_2 \geq \cdots \geq D_M$, if the $M$-stage source coding
\[
(R_{I_L,1}, D_1) \wedge (R_{I_L,2}, D_2) \wedge \cdots \wedge (R_{I_L,M}, D_M)
\]
is feasible, then there exist $r_{I_L,j} \in \mathbb{R}_+^L$, $j = 1, 2, \cdots, M$, satisfying
(i) $r_{I_L,j-1} \leq r_{I_L,j}$ for all $j \in \mathcal{I}_M$,
(ii) $1/\sigma_X^2 + \sum_{i=1}^L (1 - \exp(-2r_{i,j})) / \sigma_{N_i}^2 \geq 1/D_j$ for all $j \in \mathcal{I}_M$,
such that
\[
\sum_{i \in A} (R_{i,k} - R_{i,j}) \geq \frac{1}{2} \log \frac{1}{D_k} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in A} \frac{1 - \exp(-2r_{i,j})}{\sigma_{N_i}^2} + \sum_{i \in A^c} \frac{1 - \exp(-2r_{i,k})}{\sigma_{N_i}^2} \right)
\]
\[
+ \sum_{i \in A} (r_{i,k} - r_{i,j}), \quad \forall 0 \leq j \leq k \leq M, \forall \text{ nonempty set } A \subseteq \mathcal{I}_L.
\]
where \( r_{\mathcal{I}_L,0} = (0, \cdots, 0) \).

**Proof:** Let \( r_{i,j} = I(Y; f_{i,j}^{(n)}(X))/n \) \((\forall i \in \mathcal{I}_L, \forall j \in \mathcal{I}_M)\). It is clear that \( r_{\mathcal{I}_L,j-1} \leq r_{\mathcal{I}_L,j} \) for all \( j \in \mathcal{I}_M \). Moreover, if we let \( \mathcal{A} = \mathcal{I}_L \) in (43), we have

\[
\frac{1}{\sigma^2_X} + \sum_{i=1}^{L} \frac{1 - \exp(-r_{i,k})}{\sigma^2_{N_i}} \geq \frac{1}{\sigma^2_X} \exp \left( \frac{2}{n} I(X; f_{i,k}^{(n)}) \right) \geq \frac{1}{D_k}, \quad \forall k \in \mathcal{I}_M, \tag{45}
\]

where the last inequality follows from Lemma 3.2.

Furthermore, we have

\[
\sum_{i \in \mathcal{A}} (R_{i,k} - R_{i,j}) \geq \frac{1}{n} \sum_{i \in \mathcal{A}} \sum_{s=j+1}^{k} H(f_{i,s}^{(n)}) \geq \frac{1}{n} H(f_{i,s}^{(n)}, s = j+1, \cdots, k) \tag{46}
\]

\[
\geq \frac{1}{n} I(Y; f_{i,s}^{(n)}, s = j+1, \cdots, k|f_{A^c,X}, f_{A,X}, f_{\mathcal{I}_L}) \tag{47}
\]

\[
= \frac{1}{n} I(X; f_{A^c,X}, f_{A,X}) + \sum_{i \in \mathcal{A}} (r_{i,k} - r_{i,j}) \tag{49}
\]

\[
\geq 1 \frac{1}{2} \log \frac{1}{D_k} - \frac{1}{2} \log \left( \frac{1}{\sigma^2_X} + \sum_{i \in \mathcal{A}} \frac{1 - \exp(-2r_{i,j})}{\sigma^2_{N_i}} \right) \tag{50}
\]

\[
= \frac{1}{2} \sum_{i \in \mathcal{A}} (r_{i,k} - r_{i,j}), \tag{51}
\]

where (51) follows from Lemma 3.2 and Lemma 3.3. Now the proof is complete. \(\blacksquare\)

**Lemma 3.5:** For any \( R_{\mathcal{I}_L} \in \mathbb{R}^L_+ \), there exists a unique \( r_{\mathcal{I}_L} \in \mathbb{R}^L_+ \) satisfying

\[
\frac{1}{\sigma^2_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r_{i})}{\sigma^2_{N_i}} \geq \frac{1}{D^*(R_{\mathcal{I}_L})} \tag{52}
\]

and for any nonempty set \( \mathcal{A} \subseteq \mathcal{I}_L \)

\[
\sum_{i \in \mathcal{A}} R_i \geq 1 \frac{1}{2} \log \frac{1}{D^*(R_{\mathcal{I}_L})} - \frac{1}{2} \log \left( \frac{1}{\sigma^2_X} + \sum_{i \in \mathcal{A}} \frac{1 - \exp(-2r_{i})}{\sigma^2_{N_i}} \right) + \sum_{i \in \mathcal{A}} r_{i}. \tag{53}
\]

Denote this \( r_{\mathcal{I}_L} \) by \( r^*_L(R_{\mathcal{I}_L}) \). We have

\[
\frac{1}{\sigma^2_X} + \sum_{i=1}^{L} \frac{1 - \exp(-2r^*_i(R_{\mathcal{I}_L})}{\sigma^2_{N_i}} = \frac{1}{D^*(R_{\mathcal{I}_L})} \tag{54}
\]

and

\[
\sum_{i=1}^{L} R_i = 1 \frac{1}{2} \log \frac{\sigma^2_X}{D^*(R_{\mathcal{I}_L})} + \sum_{i=1}^{L} r^*_i(R_{\mathcal{I}_L}). \tag{55}
\]

**Proof:** See Appendix. \(\blacksquare\)

Now we are ready to prove the main theorem of this section.
**Theorem 3.2:** For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \), there exists an \( M \)-stage distributed successive refinement scheme from \( R_{I_L,1} \) to \( R_{I_L,2} \), to \( \cdots \), to \( R_{I_L,M} \) if and only if

\[
\sum_{i \in A} (R_{i,j} - R_{i,j-1}) \geq \frac{1}{2} \log \frac{1}{D^*_j(R_{I_L,j})} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in A} \frac{1 - \exp(-2r_i^*(R_{I_L,j-1}))}{\sigma_N^2} \right) + \sum_{i \in A} \frac{1 - \exp(-2r_i^*(R_{I_L,j}))}{\sigma_N^2} \]

\[+ \sum_{i \in A} (r_i^*(R_{I_L,j}) - r_i^*(R_{I_L,j-1})), \quad \forall j \in I_M, \forall \text{ nonempty set } A \subseteq I_L. \tag{56} \]

Here \( R_{I_L,0} = r_i^*(R_{I_L,0}) = (0, \cdots, 0) \).

**Proof:** Let \( D_j = D^*(R_{I_L,j}) \) \((\forall j \in I_M)\) in Lemma 3.4. Suppose the vector sequence \( r_{I_L,j} \) \((j = 1, 2, \cdots, M)\) satisfies all the constraints in Lemma 3.4. By Lemma 3.5, we must have \( 1/\sigma_X^2 + \sum_{i=1}^L (1 - \exp(-2r_{i,j}))/\sigma_N^i = 1/D^*(R_{I_L,j}) \). So the constraints in Lemma 3.4 imply the conditions in Lemma 3.1. Therefore the conditions in Lemma 3.1 are necessary and sufficient. Furthermore, by Lemma 3.5 \( r_{I_L,j} \), if exists, must be equal to \( r_i^*(R_{I_L,j}) \).

The proof is thus complete. \( \square \)

Remark: Applying (55) and then (54), we have

\[
\sum_{i=1}^L (R_{i,j} - R_{i,j-1}) = \frac{1}{2} \log \frac{\sigma_X^2}{D^*(R_{I_L,j})} + \sum_{i=1}^L r_i^*(R_{I_L,j}) - \frac{1}{2} \log \frac{\sigma_X^2}{D^*(R_{I_L,j-1})} - \sum_{i=1}^L r_i^*(R_{I_L,j-1}) \tag{57} \]

\[= \frac{1}{2} \log \frac{\sigma_X^2}{D^*(R_{I_L,j})} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i=1}^L \frac{1 - \exp(-2r_i^*(R_{I_L,j-1})))}{\sigma_N^i} \right) \]

\[+ \sum_{i=1}^L (r_i^*(R_{I_L,j}) - r_i^*(R_{I_L,j-1})), \quad \forall j \in I_M. \tag{58} \]

Hence in (56) the constraints on \( \sum_{i=1}^L (R_{i,j} - R_{i,j-1}) ; j = 1, 2, \cdots, M \), are tight.

The sequential structure of (56) leads straightforwardly to the following result.

**Corollary 3.1:** For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \), there exists an \( M \)-stage distributed successive refinement scheme from \( R_{I_L,1} \) to \( R_{I_L,2} \), to \( \cdots \), to \( R_{I_L,M} \) if and only if there exist a sequence of 2-stage distributed successive refinement schemes from \( R_{I_L,j-1} \) to \( R_{I_L,j} \), \( j = 1, 2, \cdots, M \).

Corollary 3.1 shows that for the quadratic Gaussian CEO problem, we only need to focus on 2-stage distributed successive refinement.

By (34), each monotone increasing vector sequence \( r_{I_L,j} \) \((j = 1, 2, \cdots, M)\) is associated with a unique \( \sigma_{I_L,j}^2 \) \((j = 1, 2, \cdots, M)\) and thus a unique \( W_{I_L,j} \) \((j = 1, 2, \cdots, M)\). We shall let \( W_{I_L,j}^* \) denote the \( W_{I_L,j} \) that is associated with \( r_i^*(R_{I_L,j}) \) \((j = 1, 2, \cdots, M)\). Now we state Theorem 3.2 in the following equivalent form, which highlights the underlying the geometric structure.

**Corollary 3.2:** For \( R_{I_L,1} \leq R_{I_L,2} \leq \cdots \leq R_{I_L,M} \), there exists an \( M \)-stage distributed successive refinement scheme from \( R_{I_L,1} \) to \( R_{I_L,2} \), to \( \cdots \), to \( R_{I_L,M} \) if and only if \( (r_{I_L,j} - r_{I_L,j-1}) \in D(W_{I_L,j}^*(R_{I_L,j})|W_{I_L,j}^*(R_{I_L,j-1})) \), where \( D(W_{I_L,j}^*(R_{I_L,j})|W_{I_L,j}^*(R_{I_L,j-1})) \) is the the dominant face of \( R(W_{I_L,j}^*(R_{I_L,j})|W_{I_L,j}^*(R_{I_L,j-1})) \), \( \forall j \in I_M \).
Proof: It is easy to verify that (56) is equivalent to
\[
\sum_{i \in \mathcal{A}} (R_{i,j} - R_{i,j-1}) \geq I(Y; W^*_A(R_{i,j}) | W^*_A(R_{i,j-1}), W^*_A(R_{i,j-1})), \quad \forall j \in \mathcal{I}_M, \forall \text{ nonempty set } \mathcal{A} \subseteq \mathcal{I}_L, \tag{59}
\]
which, by Definition 2.3, is equivalent to
\[
(R_{i,j} - R_{i,j-1}) \in \mathcal{R}(W^*_A(R_{i,j}) | W^*_A(R_{i,j-1})), \quad \forall j \in \mathcal{I}_M. \tag{60}
\]
Furthermore, (58) is equivalent to
\[
\sum_{i = 1}^{L} (R_{i,j} - R_{i,j-1}) = I(Y; W^*_A(R_{i,j}) | W^*_A(R_{i,j-1})), \quad \forall j \in \mathcal{I}_M, \tag{61}
\]
which means \(R_{i,j} = R_{i,j-1}\) is on the dominant face of \(\mathcal{R}(W^*_A(R_{i,j}) | W^*_A(R_{i,j-1})), \forall j \in \mathcal{I}_M.\)

Remark: Let \(\mathcal{F}_i\) be the lowest dimensional face of \(\mathcal{D}(W^*_A(R_{i,j}) | W^*_A(R_{i,j-1}))\) that contains \(R_{i,j} - R_{i,j-1}\).
By the discussion in the preceding section, we can see that this \(M\)-stage distributed successive refinement can be realized via an \((ML + \sum_{j=1}^{M} dim(\mathcal{F}_j))\)-successive Wyner-Ziv coding scheme.

Now we proceed to compute \(r^*_t(\mathcal{R}_L)\). It is easy to see that \(r^*_t(\mathcal{R}_L)\) is the maximizer to the following optimization problem:
\[
\max_{r^*_t \in \mathbb{R}^+_{\sigma_X^2}} \frac{1}{\sigma_X^2} + \sum_{i = 1}^{L} \frac{1 - \exp(-2r_i)}{\sigma_{N_i}}, \tag{62}
\]
subject to
\[
\frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in \mathcal{A}} \frac{1 - \exp(-2r_i)}{\sigma_{N_i}} \right) + \sum_{i \in \mathcal{A}} r_i \leq \sum_{i \in \mathcal{I}_L} R_i, \quad \forall \text{ nonempty set } \mathcal{A} \subseteq \mathcal{I}_L, \quad \forall \text{ nonempty set } \mathcal{A} \subseteq \mathcal{I}_L, \tag{63}
\]
and
\[
\frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i = 1}^{L} \frac{1 - \exp(-2r_i)}{\sigma_{N_i}} \right) + \frac{1}{2} \log \sigma_X^2 + \sum_{i = 1}^{L} r_i = \sum_{i = 1}^{L} R_i, \tag{64}
\]
which is essentially to find the contra-polymatroid \(\mathcal{R}(\mathcal{R}_L)\) that contains \(R_{i,j}\) and has the minimum achievable distortion \(D(r_{i,j}) = 1/\sigma_X^2 + \sum_{i = 1}^{L} (1 - \exp(-2r_i))/\sigma_{N_i}^2\). Another approach is use the Lagrangian formulation in the previous section. That is, first characterize \(r^*_t(\mathcal{R}_L)\) for \(R_{i,j} \in \partial V(D)\) via studying the supporting hyperplanes of \(\partial V(D)\) for fixed \(D\). Then change \(D\) to get \(r^*_t(\mathcal{R}_L)\) for all \(R_{i,j}\). This approach is in general more cumbersome than the first one. But for small \(L\), it is relatively easy to get the parametric expression of \(r^*_t(\mathcal{R}_L)\) via the second approach.

To give a concrete example of the distributed successive refinement, we choose to study the special case where \(L = 2\). We shall adopt the second approach. It is easy to see that \(R_{i,j}\) is either a vertex of \(\mathcal{R}(r^*_t(\mathcal{R}_L), r^*_t(\mathcal{R}_L))\) or an interior point of the dominant face (which is a line segment) of \(\mathcal{R}(r^*_t(\mathcal{R}_L), r^*_t(\mathcal{R}_L))\). For the first case, \((r^*_t(\mathcal{R}_L), r^*_t(\mathcal{R}_L))\) is completely determined. For the second case, \(R_{i,j}\) must be on the minimum sum-rate line of \(\partial V(D^*(R_{i,j})).\) Hence we only need to study one supporting line of \(\partial V(D),\) namely, \(\min_{r_1 + r_2} \partial V(D),\) which has been characterized for all \(D\) in [22].
Without loss of generality, we assume \( \sigma_{N_1}^2 \leq \sigma_{N_2}^2 \). Let
\[
L_D = \max \left\{ k \in \mathcal{I}_2 : \frac{k}{\sigma_{N_k}} + \frac{1}{D} - \frac{1}{D_{\min}(k)} \geq 0 \right\},
\]
where
\[
\frac{1}{D_{\min}(k)} = \frac{1}{\sigma_X^2} + \sum_{i=1}^k \frac{1}{\sigma_{N_i}^2}.
\]
Let \( \tilde{D} \) be the unique solution to the following equation:
\[
\frac{1}{2} \log \left( \frac{\sigma_X^2 L_D \prod_{i=1}^{L_D} \left( \frac{\sigma_X^2}{\sigma_{N_i}^2} \left( \frac{1}{\sigma_X^2} - \frac{1}{D} \right) \right) \right) = R_1 + R_2.
\]
Let
\[
\tilde{r}_1 = \frac{1}{2} \log \left( \frac{\sigma_X^2 L_{\tilde{D}}}{\sigma_{N_1}^2 \left( \frac{1}{\sigma_X^2} - \frac{1}{D} \right) \right),
\]
\[
\tilde{r}_2 = \begin{cases} 
0, & L_{\tilde{D}} = 1, \\
\frac{1}{2} \log \left( \frac{2}{\sigma_{N_2}^2} \left( \frac{1}{\sigma_X^2} + \frac{1}{\sigma_{N_1}^2} + \frac{1}{\sigma_{N_2}^2} - \frac{1}{D} \right)^{-1} \right), & L_{\tilde{D}} = 2.
\end{cases}
\]
We have
(i) If
\[
R_1 \geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_1)}{\sigma_{N_1}^2} \right) + \frac{1}{2} \log \sigma_X^2 + \tilde{r}_1,
\]
then
\[
\frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_1 \{R_{Z_2}\})}{\sigma_{N_1}^2} \right) + \frac{1}{2} \log \sigma_X^2 + r_1^* (R_{Z_2}) = R_1,
\]
\[
\frac{1}{2} \log \left( 1 + \sigma_{N_2}^2 \sum_{i=1}^2 \frac{1 - \exp(-2\tilde{r}_1^* \{R_{Z_2}\})}{\sigma_{N_i}^2} \right) + r_1^* (R_{Z_2}) + r_2^* (R_{Z_2}) = R_1 + R_2.
\]
(ii) If
\[
R_2 \geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_2)}{\sigma_{N_1}^2} \right) + \frac{1}{2} \log \sigma_X^2 + \tilde{r}_2,
\]
then
\[
\frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_2 \{R_{Z_2}\})}{\sigma_{N_2}^2} \right) + \frac{1}{2} \log \sigma_X^2 + r_2^* (R_{Z_2}) = R_2,
\]
\[
\frac{1}{2} \log \left( 1 + \sigma_{N_2}^2 \sum_{i=1}^2 \frac{1 - \exp(-2\tilde{r}_2 \{R_{Z_2}\})}{\sigma_{N_i}^2} \right) + r_1^* (R_{Z_2}) + r_2^* (R_{Z_2}) = R_1 + R_2.
\]
(iii) Otherwise \( r_i^* (R_{Z_2}) = \tilde{r}_i, i = 1, 2 \).
The above three conditions essentially divide $\mathbb{R}_+^2$ into 3 regions. Define

$$
\Omega_1 = \left\{ (R_1, R_2) \in \mathbb{R}_+^2 : R_1 \geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_1)}{\sigma_{N_1}^2} \right) + \frac{1}{2} \log \sigma_X^2 + \tilde{r}_1 \right\},
$$

$$
\Omega_3 = \left\{ (R_1, R_2) \in \mathbb{R}_+^2 : R_2 \geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_2)}{\sigma_{N_2}^2} \right) + \frac{1}{2} \log \sigma_X^2 + \tilde{r}_2 \right\},
$$

$$
\Omega_3 = \left\{ (R_1, R_2) \in \mathbb{R}_+^2 : R_i \leq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2\tilde{r}_i)}{\sigma_{N_i}^2} \right) + \frac{1}{2} \log \sigma_X^2 + \tilde{r}_i, i = 1, 2 \right\}.
$$

It is easy to check that except the boundaries (i.e., those rate tuples that satisfy (70) or (70) with equality), $\Omega_1, \Omega_2$ and $\Omega_3$ do not overlap. Typical shapes of $\Omega_1, \Omega_2$ and $\Omega_3$ are plotted in Fig.2. Any rate pair $R_{x_2} \in \{\Omega_1 \cup \Omega_2 \}$ is a vertex of $\mathcal{R}(r_1^*(R_{x_2}), r_2^*(R_{x_2}))$ and thus is associated with a 2-successive Wyner-Ziv coding scheme. Any rate pair $R_{x_2}$ strictly inside $\Omega_3$ is an interior point of the dominant face of $\mathcal{R}(r_1^*(R_{x_2}), r_2^*(R_{x_2}))$ and thus is associated with a 3-successive Wyner-Ziv coding scheme. Hence there is a clear distinction between $(\Omega_1, \Omega_2)$ and $\Omega_3$. We will see that this difference manifests itself in the behavior of distributed successive refinement.

Henceforth we shall assume $R_{x_2, 2} \geq R_{x_2, 1}$.

**Claim 3.1:** $(r_1^*(R_{x_2, 2}), r_2^*(R_{x_2, 2})) \geq (r_1^*(R_{x_2, 1}), r_2^*(R_{x_2, 1}))$.

**Proof:** If both $R_{x_2, 1}$ and $R_{x_2, 2}$ are in $\Omega_1$ or both $R_{x_2, 1}$ and $R_{x_2, 2}$ are in $\Omega_2$, the claim can be easily verified by checking the equations (71),(72),(74) and (75). Since $\tilde{r}_1$ and $\tilde{r}_2$ are monotone increasing functions of $R_1 + R_2$, the claim is also true when both $R_{x_2, 1}$ and $R_{x_2, 2}$ are in $\Omega_3$.

Now consider the general case when $R_{x_2, 1}$ and $R_{x_2, 2}$ are in different regions, say $R_{x_2, 1} \in \Omega_1$ and $R_{x_2, 2} \in \Omega_3$. Suppose the line segment that connects $R_{x_2, 1}$ and $R_{x_2, 2}$ intersects the boundary of $\Omega_1$ and $\Omega_3$ at point $R_{x_2}$. We have $(r_1^*(R_{x_2}^1), r_2^*(R_{x_2}^1)) \geq (r_1^*(R_{x_2, 1}), r_2^*(R_{x_2, 1}))$ since both $R_{x_2, 1}$ and $R_{x_2}^1$ are in $\Omega_1$ and $(r_1^*(R_{x_2, 2}), r_2^*(R_{x_2, 2})) \geq (r_2^*(R_{x_2, 2}), r_2^*(R_{x_2, 2}))$ since both $R_{x_2, 2}$ and $R_{x_2, 2}$ are in $\Omega_3$. Hence $(r_1^*(R_{x_2, 2}), r_2^*(R_{x_2, 2})) \geq (r_1^*(R_{x_2, 1}), r_2^*(R_{x_2, 1}))$.

The other cases can be discussed in a similar way.

**Claim 3.2:** If both $R_{x_2, 1}$ and $R_{x_2, 2}$ are in $\Omega_1$, then there exists a distributed successive refinement scheme from $R_{x_2, 1}$ to $R_{x_2, 2}$ if and only if $R_{1, 2} = R_{1, 1}$ or $R_{2, 1} = 0$.

**Proof:** If $R_{1, 2} = R_{1, 1}$, by (71) we have $r_1^*(R_{x_2, 2}) = r_1^*(R_{x_2, 1})$. It is easy to verify that the conditions in Theorem 3.2 are all satisfied. If $R_{2, 1} = 0$, by (71) and (72), we have $r_2^*(R_{x_2, 1}) = 0$. Again, it is easy to check that the conditions in Theorem 3.2 are all satisfied.
Now suppose there exists a distributed successive refinement scheme from $R_{I_2,2}$ to $R_{I_2,1}$. Since both $R_{I_2,1}$ and $R_{I_2,2}$ are in $\Omega_1$, by (71) and (72)

\[
R_{2,2} - R_{2,1} = \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i=1}^{2} \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma^2_{N_i}} \right) + r_2^*(R_{I_2,2}) - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma^2_{N_i}} \right)
\]

\[
\geq \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma^2_{N_2}} \right) + \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,1}))}{\sigma^2_{N_2}} \right) + r_2^*(R_{I_2,2}) - r_2^*(R_{I_2,1}) - r_2^*(R_{I_2,1}) - r_2^*(R_{I_2,1})
\]

By theorem 3.2, we must have

\[
\frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma^2_{N_2}} \right) + \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,1}))}{\sigma^2_{N_2}} \right) + r_2^*(R_{I_2,2}) - r_2^*(R_{I_2,1})
\]

which, after some algebraic manipulation, is equivalent to $r_1^*(R_{I_2,2})r_2^*(R_{I_2,1}) \leq r_1^*(R_{I_2,1})r_2^*(R_{I_2,1})$. Then we have either $r_1^*(R_{I_2,2}) \leq r_1^*(R_{I_2,1})$ (which further implies $r_1^*(R_{I_2,2}) = r_1^*(R_{I_2,1})$) or $r_2^*(R_{I_2,1}) = 0$. Hence, by (71) and (72), we have $R_{1,2} = R_{1,1}$ or $R_{2,1} = 0$.

The following claim follows by symmetry.

**Claim 3.3:** If both $R_{I_2,1}$ and $R_{I_2,2}$ are in $\Omega_2$, then there exists a distributed successive refinement scheme from $R_{I_2,1}$ to $R_{I_2,2}$ if and only if $R_{I_2,2} = R_{2,1}$ or $R_{1,1} = 0$.

Remark: Claim 3.2 and 3.3 imply that there exists a distributed successive refinement scheme from $R_{I_2,1}$ to $R_{I_2,2}$ if $R_{I_2,1}$ and $R_{I_2,2}$ are on the $R_1$-axis or $R_{I_2,1}$ and $R_{I_2,2}$ are on the $R_2$-axis. Actually in this case, the distributed successive refinement reduces to the conventional successive refinement in the single source coding [38]. Furthermore, if $R_1 = \infty$ and $\sigma^2_{N_2} = 0$ (or $R_2 = \infty$ and $\sigma^2_{N_2} = 0$), then the quadratic Gaussian CEO problem becomes the Wyner-Ziv problem of jointly Gaussian source. Claim 3.2 (or Claim 3.3) implies the successive refinability for the Wyner-Ziv problem of jointly Gaussian sources [40].

**Claim 3.4:** Suppose $R_{1,1} > 0, R_{2,1} > 0$. Then there is no distributed successive refinement scheme from $R_{I_2,1}$ to $R_{I_2,2}$ if $R_{I_2,1} \in \Omega_1$, $R_{I_2,2} \in \Omega_2$ or $R_{I_2,1} \in \Omega_2$, $R_{I_2,2} \in \Omega_1$.

**Proof:** We shall only prove the case for $R_{I_2,1} \in \Omega_1$, $R_{I_2,2} \in \Omega_2$. The other one follows by symmetry.

---

Footnote: There is a slight difference since the CEO problem, after reduced to the single encoder case, becomes the noisy (single) source coding problem. But the generalization of the successive refinement in the single source coding to the noisy (single) source coding is straightforward.
By (71) and (72), \( R_{1,1} > 0, R_{2,1} > 0 \) implies \( r_1^*(R_{I_2,2}) > 0, r_2^*(R_{I_2,1}) > 0 \), which further implies \( r_2^*(R_{I_2,2}) > 0 \) by Claim 3.1. Now it follows from (71), (72), (74) and (75) that

\[
R_{1,2} - R_{1,1} = \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i=1}^{2} \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma_{N_i}^2} \right) + r_1^*(R_{I_2,2}) - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_2^*(R_{I_2,2}))}{\sigma_{N_2}^2} \right)
\]

\[
= \frac{1}{2} \log \frac{1}{D^*(R_{I_2,2})} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_1^*(R_{I_2,2}))}{\sigma_{N_1}^2} \right) + r_1^*(R_{I_2,2}) - r_1^*(R_{I_2,1})
\]

which is strictly less than

\[
\frac{1}{2} \log \frac{1}{D^*(R_{I_2,2})} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \frac{1 - \exp(-2r_2^*(R_{I_2,2}))}{\sigma_{N_2}^2} \right) + r_2^*(R_{I_2,2}) - r_2^*(R_{I_2,1})
\]

if \( r_1^*(R_{I_2,1}) > 0, r_2^*(R_{I_2,2}) > 0 \). Thus by Theorem 3.2, the distributed successive refinement scheme can not exist.

\[\square\]

Fig. 2. Distributed successive refinement for the quadratic Gaussian CEO problem

In Fig. 2, the arrows denote the possible directions for the distributed successive refinement in \( \Omega_1 \) and \( \Omega_3 \). For illustration, we pick a point \( s \) in \( \Omega_2 \). The dark region is the set of points to which there exists a distributed successive refinement scheme from \( s \). We can see that the distributed successive refinement behaves very differently in these three regions. It is interesting to see that although successive refinability is a common phenomenon in the single source coding [41], it happens under much restricted conditions in the distributed source coding.
IV. Conclusion

We discussed two closely related problems in distributed source coding. The first one is how to decompose high complexity distributed source code into low complexity code. The second one is how to build high rate distributed source code upon low rate code via distributed successive refinement. It turns out that, at least for the quadratic Gaussian CEO problem, the successive Wyner-Ziv coding scheme gives the answer to both problems. Besides the features (say, low complexity and robustness) we discussed in the paper, the concatenable chain structure of the successive Wyner-Ziv coding scheme seems especially attractive in wireless sensor networks, where channels are subject to fluctuation. In this case, by properly converting a high-rate distributed source code to a multistage code via the successive Wyner-Ziv coding scheme, one can match source rates to the channel rates adaptively.

Appendix

Proof of Lemma 3.5

For any \( r_{IL} \in \mathbb{R}_+^L \), define two set functions \( f(\cdot, r_{IL}), f_D(\cdot, r_{IL}) : 2^I \to \mathbb{R}_+ : \)

\[
f(A, r_{IL}) = \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i=1}^L \frac{1-\exp(-2r_i)}{\sigma_{N_i}^2} \right) + \sum_{i \in A} r_i, \forall \text{ nonempty set } A \subseteq I_L,
\]

\[
f_D(A, r_{IL}) = \frac{1}{2} \log \frac{1}{D} - \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i \in A^c} \frac{1-\exp(-2r_i)}{\sigma_{N_i}^2} \right) + \sum_{i \in A} r_i, \forall \text{ nonempty set } A \subseteq I_L,
\]

and \( f(\emptyset, r_{IL}) = f_D(\emptyset, r_{IL}) = 0. \)

Note that \( f(\cdot, r_{IL}) \) is a rank function and induces the contra-polymatroid \( \mathcal{R}(r_{IL}) \) defined in (17). Furthermore, for any nonempty set \( A \subseteq I_L, \)

\[
f(A, r_{IL}) - f_D(A, r_{IL}) = \frac{1}{2} \log \left( \frac{1}{\sigma_X^2} + \sum_{i=1}^L \frac{1-\exp(-2r_i)}{\sigma_{N_i}^2} \right) = \frac{1}{2} \log \frac{1}{D}. \quad (79)
\]

By the supermodular property of \( f(\cdot, r_{IL}) \) and the equation (79), we can establish that, for any \( r_{IL} \) satisfying \( r_i > 0 \) (\( \forall i \in I_L \)) and nonempty sets \( S, T \subseteq I_L, \)

(i)

\[
f(S, r_{IL}) + f(T, r_{IL}) < f(S \cup T, r_{IL}) + f(S \cap T, r_{IL}); \quad (80)
\]

(ii) If \( 1/\sigma_X^2 + \sum_{i=1}^L (1 - \exp(-2r_i))/\sigma_{N_i}^2 \geq 1/D, \) and \( S \not\subset T, T \not\subset S, \) then

\[
f_D(S, r_{IL}) + f_D(T, r_{IL}) < f_D(S \cup T, r_{IL}) + f_D(S \cap T, r_{IL}). \quad (81)
\]

It was shown in [34] that

\[
\mathcal{R}(D) = \bigcup_{r_{IL} \in \mathcal{F}(D)} \left\{ R_{IL} : \sum_{i \in A} R_i \geq f_D(A, r_{IL}), \forall \text{ nonempty set } A \subseteq I_L \right\}, \quad (82)
\]
where $\mathcal{F}(D)$ is defined in (19). Hence there must exist a vector $r_{I_L} \in \mathbb{R}^L_+$ satisfying the constraints (52) and (53) in Lemma 3.5, i.e.,

$$\sum_{i \in A} R_i \geq f_{D^*}(R_{I_L})(A, r_{I_L}), \quad \forall \text{ nonempty set } A \subseteq I_L,$$

and

$$\frac{1}{\sigma^2_X} + \sum_{i=1}^L \frac{1 - \exp(-r_i)}{\sigma^2_{N_i}} \geq \frac{1}{D^*(R_{I_L})}.$$  \hfill (84)

Let $G = \{i \in I_L : r_i > 0\}$. Then (83) and (84) reduce to the following constraints:

$$\sum_{i \in A} R_i \geq f_{D^*}(R_{I_L})(A, r_{I_L}), \quad \forall \text{ nonempty set } A \subseteq G,$$

and

$$\frac{1}{\sigma^2_X} + \sum_{i \in G} \frac{1 - \exp(-r_i)}{\sigma^2_{N_i}} \geq \frac{1}{D^*(R_{I_L})}.$$ \hfill (86)

are still active. Thus without loss of generality, we can assume $G = I_L$.

It can be shown that in (83), if the constraints on $\sum_{i \in S} R_i$ and $\sum_{i \in T} R_i$ are tight, then either $S \subseteq T$ or $T \subseteq S$. Otherwise,

$$f_{D^*}(R_{I_L})(S, r_{I_L}) + f_{D^*}(R_{I_L})(T, r_{I_L})$$

$$\geq f_{D^*}(R_{I_L})(S \cup T, r_{I_L}) + f_{D^*}(R_{I_L})(S \cap T, r_{I_L}),$$  \hfill (90)

contradictory to (81). Let $\tilde{A} = \bigcap_{k \in I_K} A_k$, where $A_k(k \in I_K)$ are the sets for which the constraints on $\sum_{i \in A_k} R_i$ are tight in (83). If there is no such an $A_k$, let $\tilde{A} = I_L$, $\tilde{A}$ is thus always nonempty.

Now suppose

$$\frac{1}{\sigma^2_X} + \sum_{i=1}^L \frac{1 - \exp(-r_i)}{\sigma^2_{N_i}} > \frac{1}{D^*(R_{I_L})}.$$  \hfill (91)

Pick any $i^* \in \tilde{A}$, we can decreases $r_{i^*}$ to $r_{i^*} - \delta$ for some $\delta > 0$ so that all the constraints in (83) and (91) become non-tight. Then we can decrease $D^*(R_{I_L})$ to $D^*(R_{I_L}) - \varepsilon$ for some $\varepsilon > 0$ without violating any constraints in (83) and (91). By (82) we have $R_{I_L} \in \mathcal{R}(D^*(R_{I_L}) - \varepsilon)$, contradictory to the definition of $D^*(R_{I_L})$. Hence we can conclude that (54) holds, i.e.,

$$\frac{1}{\sigma^2_X} + \sum_{i=1}^L \frac{1 - \exp(-r_i)}{\sigma^2_{N_i}} = \frac{1}{D^*(R_{I_L})}.$$ \hfill (92)

Now we proceed to show that $r_{I_L}$ must be unique.

It is easy to check that $1/\sigma^2_X + \sum_{i=1}^L (1 - \exp(-2r_i))/\sigma^2_{N_i}$ is a strict concave function of $r_{I_L}$ and for any nonempty set $A \subseteq I_L$, $f_D(A, r_{I_L})$ is convex in $r_{I_L}$.

Suppose both $r_{I_L}'$ and $r_{I_L}''$ satisfy the constraints (83) and (84), and there exists some $i^*$ such that $r_{i^*}' \neq r_{i^*}''$. We shall first show that $r_{i^*}', r_{i^*}''$ are both finite. If not, without loss of generality suppose $r_{i^*}' = \infty$, which implies...
that $R_{i} = \infty$. Now construct a new vector $r''_{i}^{L}$ such that $r''_{i} = r_{i} = \infty$ if $i = i^{*}$ and $r''_{i} = r''_{i}$ otherwise. Note: we have $r''_{i} > r''_{i}$. It is easy to check that $r''_{i}^{L}$ satisfies the constraints (83) and (84) (Note: we let $-\infty - \infty = 0$).

But we have

$$\frac{1}{\sigma_{X}^{2}} + \sum_{i=1}^{L} \frac{1 - \exp(-2r''_{i})}{\sigma_{N_{i}}^{2}} > \frac{1}{\sigma_{X}^{2}} + \sum_{i=1}^{L} \frac{1 - \exp(-2r''_{i})}{\sigma_{N_{i}}^{2}} = \frac{1}{D^{*}(R_{L})}, \tag{93}$$

which is contradictory to (92).

Now let $\tau_{i} = (r'_{i} + r''_{i})/2$ for all $i \in \mathcal{I}_{L}$. Note that $\tau_{i}$ is equal to neither $r'_{i}$ nor $r''_{i}$ since $r'_{i} \neq r''_{i}$ and both are finite. It is obvious that $\tau_{L} \in \mathbb{R}_{+}^{L}$. Furthermore, we have

$$\frac{1}{\sigma_{X}^{2}} + \sum_{i=1}^{L} \frac{1 - \exp(-\tau_{i})}{\sigma_{N_{i}}^{2}} \geq \frac{1}{\sigma_{X}^{2}} + \frac{1}{2} \sum_{i=1}^{L} \frac{1 - \exp(-r'_{i})}{\sigma_{N_{i}}^{2}} + \frac{1}{2} \sum_{i=1}^{L} \frac{1 - \exp(-r''_{i})}{\sigma_{N_{i}}^{2}} \tag{94}$$

and

$$\sum_{i = A} R_{i} \geq \frac{1}{2} \int_{D^{*}(R_{L})}(\mathcal{A}, r'_{L}) + \frac{1}{2} \int_{D^{*}(R_{L})}(\mathcal{A}, r''_{L}) \tag{96}$$

$$\sum_{i = A} R_{i} \geq \int_{D^{*}(R_{L})}(\mathcal{A}, \tau_{L}), \quad \forall \text{ nonempty set } \mathcal{A} \subseteq \mathcal{I}_{L}. \tag{97}$$

Hence $\tau_{L}$ satisfies the constraints (83) and (84). Since $1/\sigma_{X}^{2} + \sum_{i=1}^{L} (1 - \exp(-2r_{i}))/\sigma_{N_{i}}^{2}$ is a strictly concave function of $r_{L}$, the inequality in (94) is strict, which results in a contradiction with (92).

Now only (55) remains to be proved. We shall first show that $r_{i}^{*}(R_{L}) = 0$ implies $R_{i} = 0$. Without loss of generality, suppose $r_{i}^{*}(R_{L}) = 0$. Then it is easy to check that (83) still holds if we set $R_{L} = 0$ on its left hand side.

So if $R_{L} > 0$, we can increase $r_{i}^{*}(R_{L})$ by a small amount without violating (83) and (84), which is contradictory to the fact that $r_{i}^{*}(R_{L})$ is unique. Hence without loss of generality, we can assume $r_{i}^{*}(R_{L}) > 0$ for all $i \in \mathcal{I}_{L}$. Otherwise by restricting to the set $\mathcal{G} = \{ i \in \mathcal{I}_{L} : r_{i}^{*}(R_{L}) > 0 \}$, the following argument can still be applied.

Since (54) holds, the righthand side of (83) becomes $f(\mathcal{A}, r_{L}^{*}(R_{L}))$. By (80), it can be shown that if in (83), the constraints on $\sum_{i \in \mathcal{S}} R_{i}$ and $\sum_{i \in \mathcal{T}} R_{i}$ are tight, then either $\mathcal{S} \subseteq \mathcal{T}$ or $\mathcal{T} \subseteq \mathcal{S}$. Let $\tilde{\mathcal{A}} = \bigcup_{k \in \mathcal{K}} \mathcal{A}_{k}$, where $\mathcal{A}_{k}(k \in \mathcal{K})$ are the sets for which the constraints on $\sum_{i \in \mathcal{A}_{k}} R_{i}$ are tight in (83). If there is no such an $\mathcal{A}_{k}$, let $\tilde{\mathcal{A}} = \mathcal{I}_{L}$. We are done. Otherwise pick any $i^{*} \in \tilde{\mathcal{A}}$. We can increase $r_{i^{*}}^{*}(R_{L})$ to $r_{i^{*}}^{*}(R_{L}) + \delta$ for some $\delta > 0$ without violating any constraints in (52) and (53), which is contradictory to the uniqueness of $r_{i^{*}}^{*}(R_{L})$. 

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