

# A V2X Message Evaluation Methodology and Cross-Domain Modeling of Safety Applications in V2X-enabled E/E- Architectures

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# Motivation

- Communication between vehicles as well as infrastructure and environment (V2X Communication)
  - Enlargement of information exchange area beyond line of sight by cooperative applications

## Enhancement of Efficiency

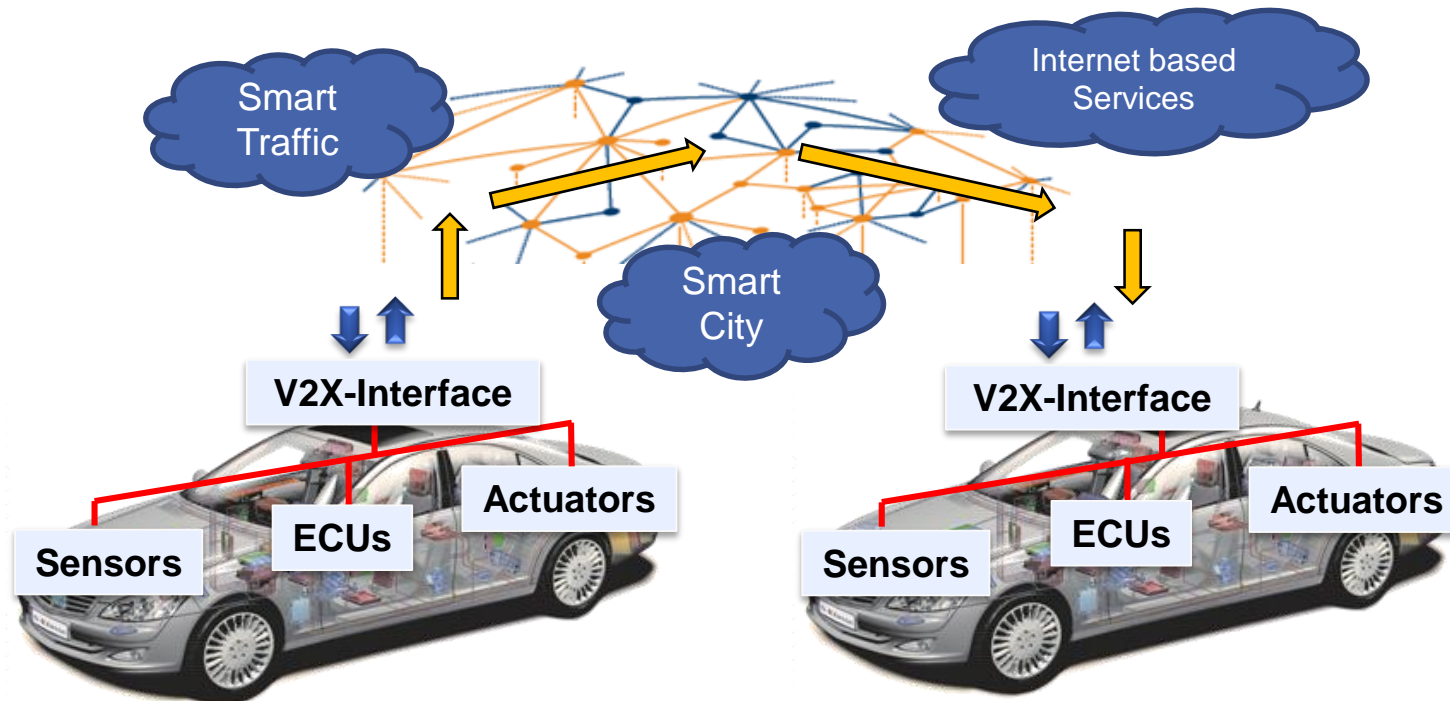
- Traffic Flow Management
- Energy Usage
- Energy Preservation
- ...

## Increasing Vehicle Safety

- Collision Warning
- Adaptive Cruise Control
- Traffic Jam Warning
- ...



# Challenges

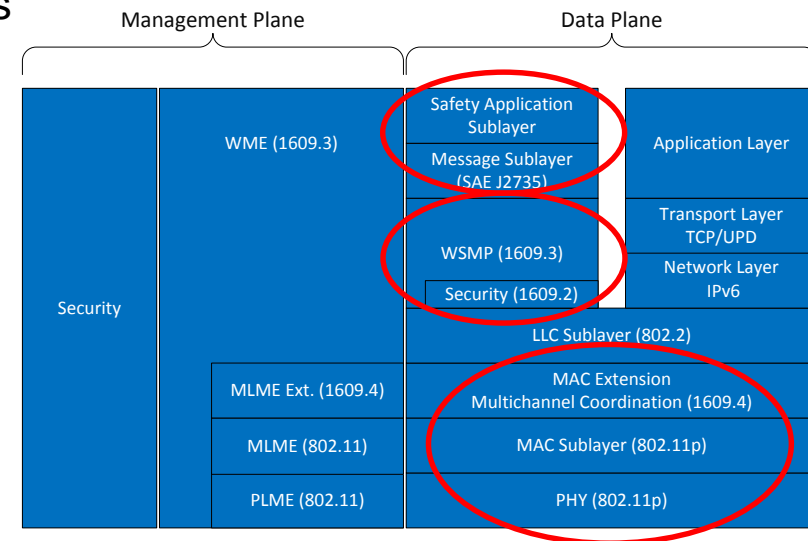


**Challenge I: How to holistically model and simulate V2X processing and communication chain?**

**Challenge II: How to cope with heavy incoming data traffic (up to 2500 Msg/s\*) in E/E Architecture and (real-time) safety applications?**

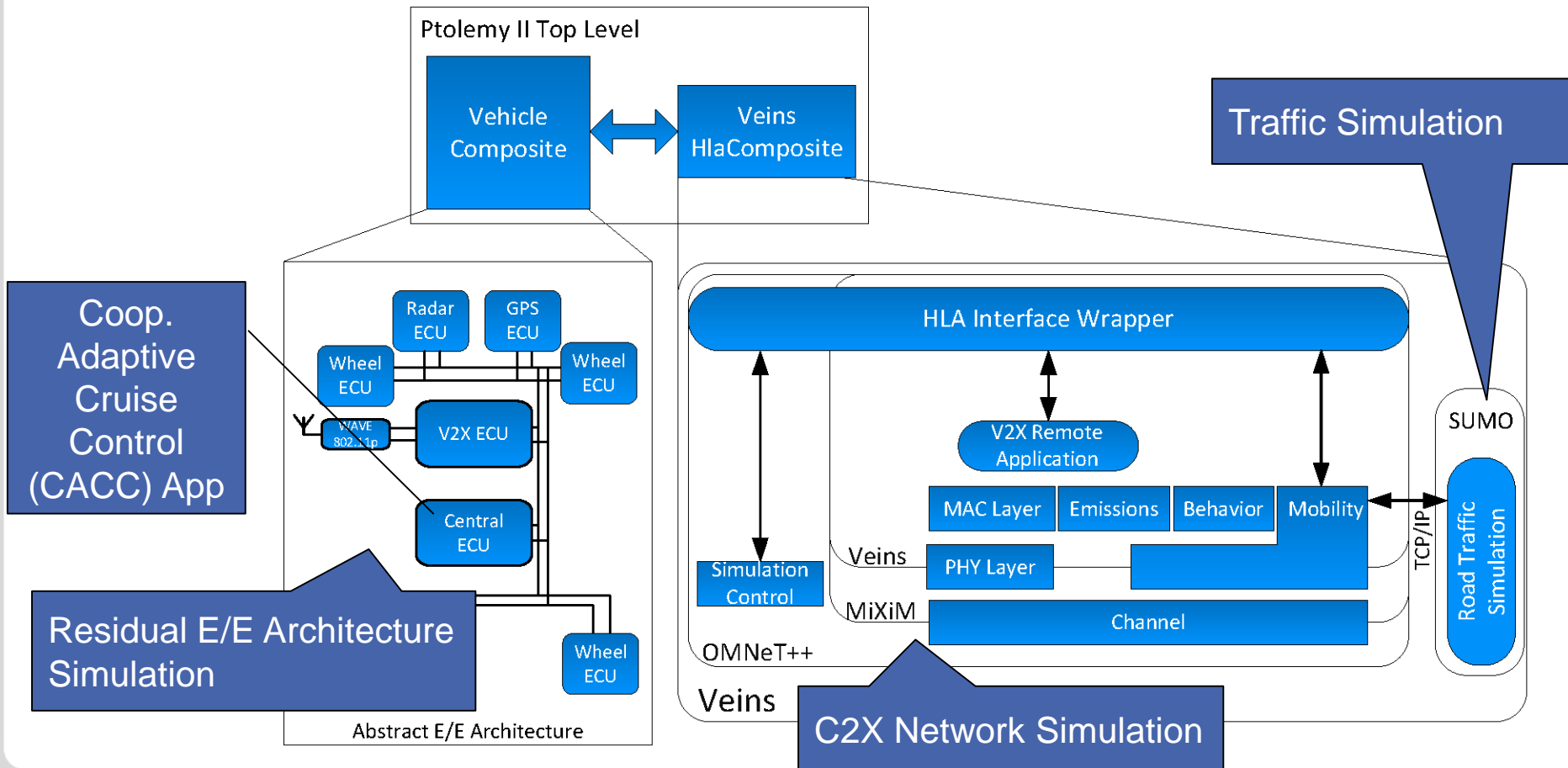
# Fundamentals – V2X Communication

- Vehicles regularly broadcasting their state as *beacons* or *SAE Basic Safety Message (BSM)* at 2-10Hz
- New Protocol and Message Type with minimized protocol overhead optimized for V2X and safety applications
  - PHY & MAC based on ordinary Wi-Fi with some extensions
    - One Control Channel (CCH) for Safety Messages and Beacons
    - 4-6 Service Channels for non-safety traffic
  - IEEE WAVE Short Message Protocol (WSMP)
  - IEEE WAVE Short Message (WSM) contains
    - Service Identifier (PSID)
    - Priority
    - Channel Number
    - Receiver Address
    - Payload (e.g. BSM)
    - ...



# Solution Challenge I: Heterogeneous Co-Simulation Tool-Chain\*

- Framework based on Ptolemy II as central heterogeneous manager tool and High-Level Architecture (HLA) as simulation backbone
- Used for Case Studies

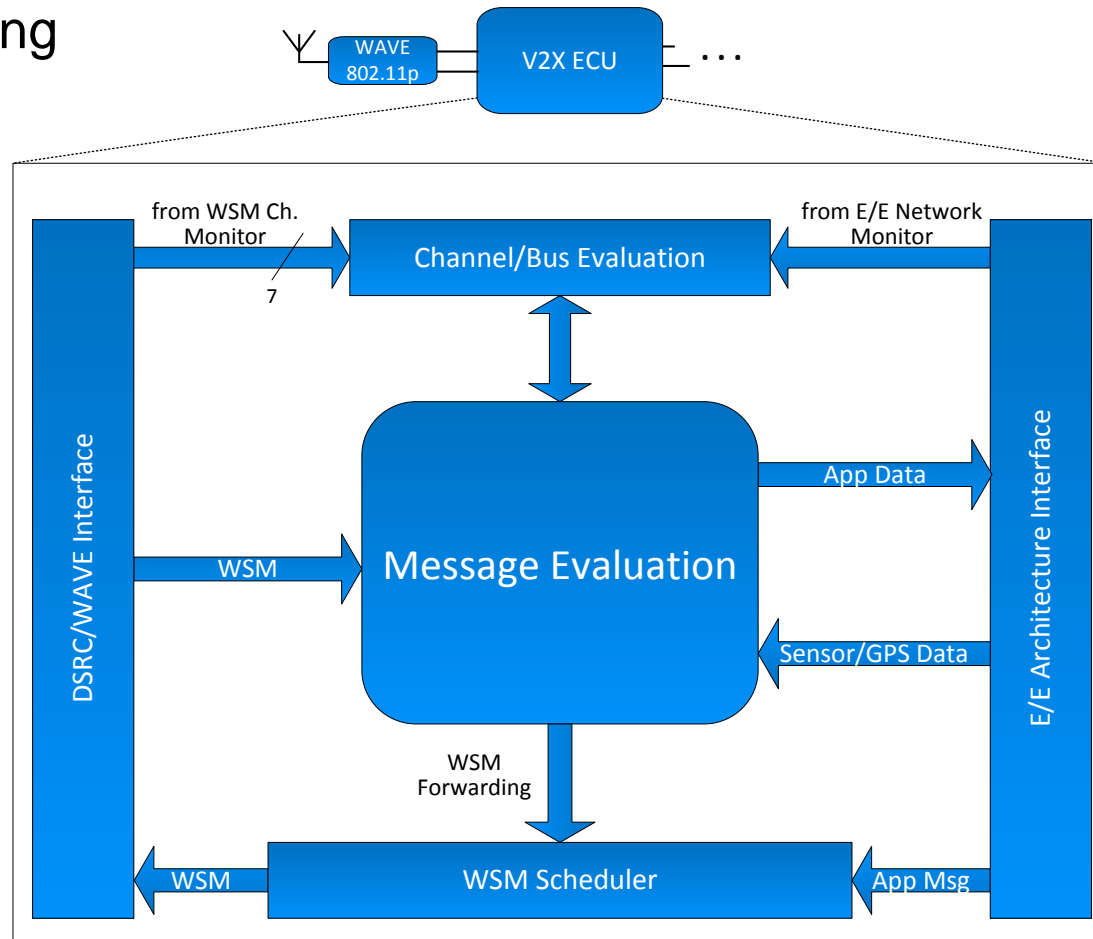


# Solution Challenge II: Proposed V2X Message Evaluation Methodology for Safety Applications

- Goal: Reduce internal E/E processing efforts and network traffic by discarding irrelevant V2X messages
- Idea
  - WAVE compliant methodology
    - Needs only beacon's *WSM header and payload* data for evaluation
  - *Cluster-based* evaluation reduces evaluation complexity
  - *Adaptive Acceptance Policies* based on network and vehicle state monitoring

# V2X Message Evaluation System Design

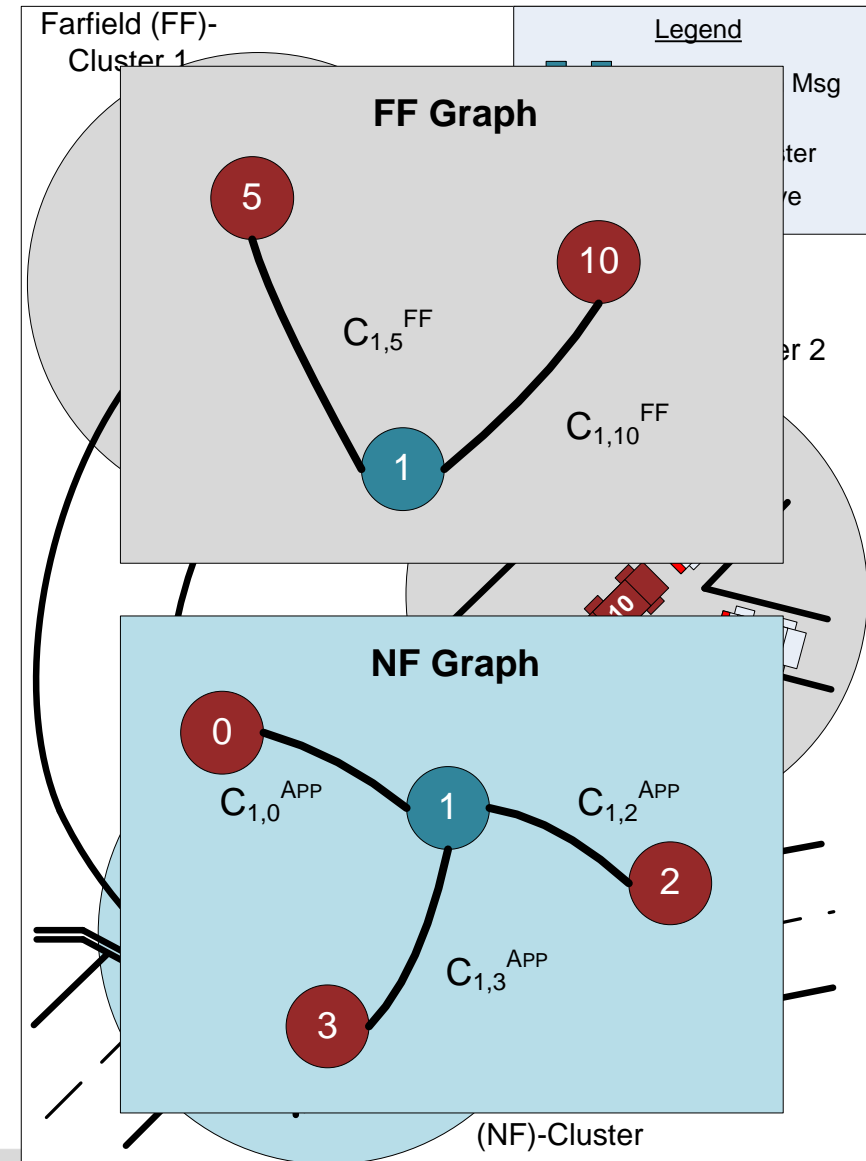
- Intelligent Gateway inside V2X ECU for evaluation based on incoming beacons as well as local sensor data and network/vehicle state monitoring





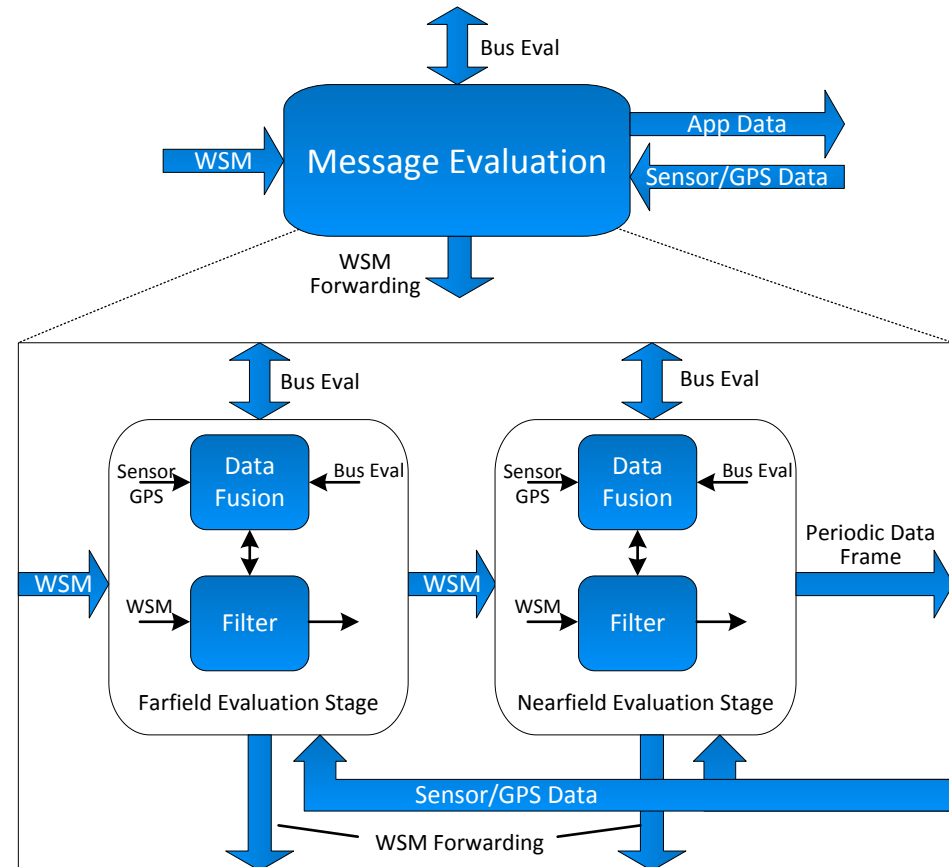
# Cluster-based V2X Message Evaluation

- Create virtual traffic view
- Classification into *Farfield* and *Nearfield* Networks (FFN / NFN)
  - Vehicles within NF range are potentially safety-critical
  - Vehicles outside NF range are clustered
    - FF Master/Slave with own NF range (First-Come-First-Serve)
    - inherent prefiltering of slaves
- Weighting of relations between nodes (vehicles) with cost-functions
  - Generic FF function
  - individual application-specific nearfield functions



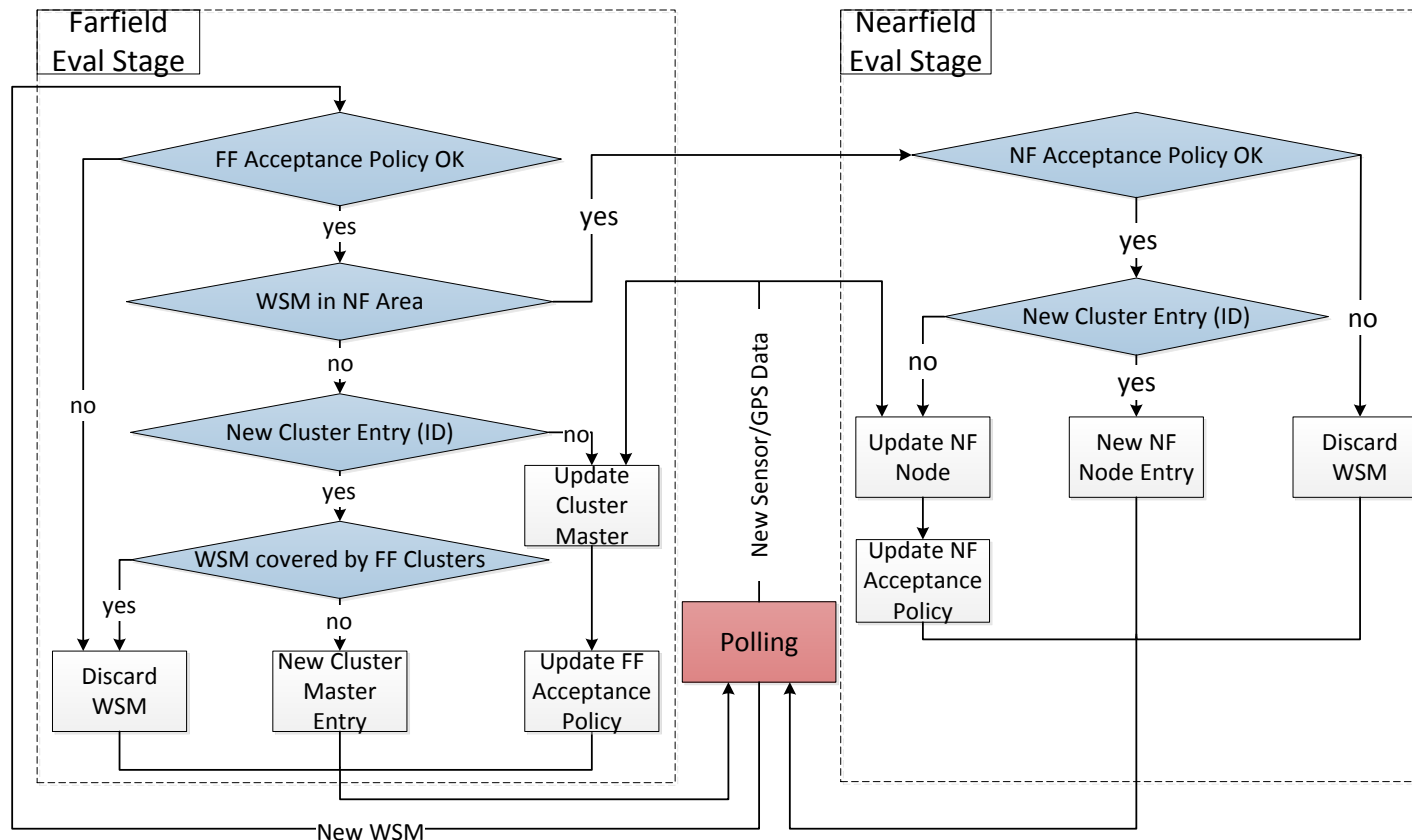
# Refined Cluster-based V2X Message Evaluation System

- NF and FF Stage composed of
  - Static *Filter* Unit
  - Dynamic *Data Fusion* Unit
- Filter Unit
  - Compares current *Acceptance Policies* with incoming WSM data
- Data Fusion Unit
  - Determines *Acceptance Policies* based on network monitoring and vehicle state
  - Forwards incoming event-driven WSMs based on PSID
  - Calculates cost functions  $C^{FF}$  and  $C^{NF}(CACC)$
  - Periodic forwarding of most relevant NF data frames to destination application (in this work CACC)



# Hybrid Clustering and Hierarchical Evaluation Strategy Procedure

- Update FF/NF Node: Updates mobility information between local vehicle  $v_i$  and remote vehicle  $v_j$  and calculates cost functions  $C_{i,j}^{FF} \forall j \in FFN$  and  $C_{i,j}^{CACC} \forall j \in NFN, j \neq i$
- Update FF/NF Acceptance Policy: Update Acceptance Policies  $A_{FF}$  and  $A_{NF}$  based on cost function and vehicle state as well as network utilization



# Cost Functions and Acceptance Policy Sets

- FF cost function detects hot-spots and serves as premature warning

$$C_{i,j}^{FF} = a * compDriveDir() + b * psidEval() + c * normDistance() + d * compRelPos(),$$

$$a = c = 0.1, b = 0.5, d = 0.3 \text{ and } a + b + c + d = 1.0$$

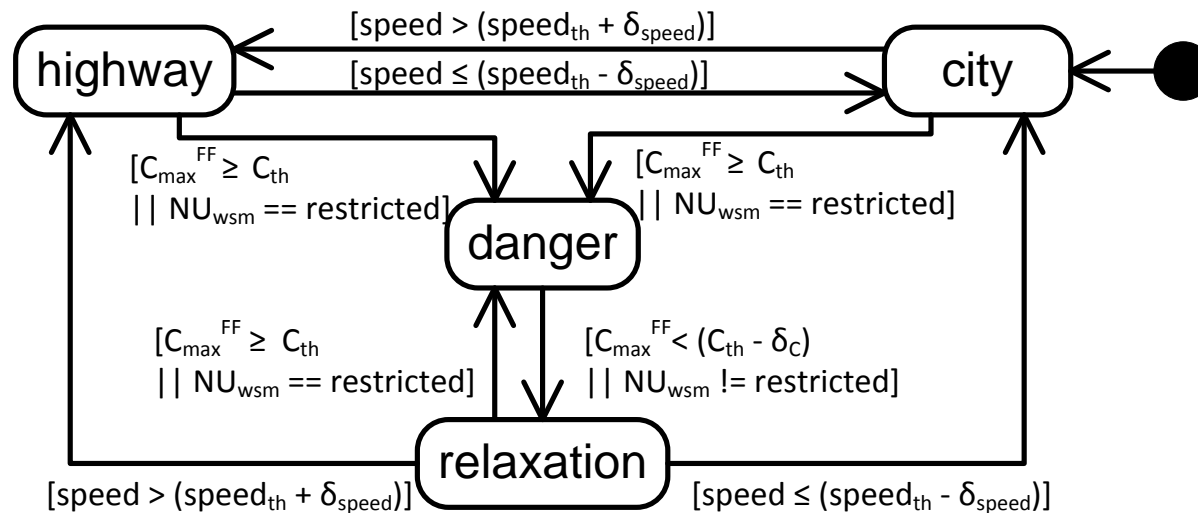
- NF cost function for detection of the leading vehicle for CACC app.
  - CACC Frame Rate  $\lambda_{CACC} = 10\text{Hz}$

$$C_{i,j}^{CACC} = compDriveDir() * normDistance() * compRelPos(), [0.0,1.0]$$

- Individual *strong* and *weak Acceptance Policies* for FF and NF
  - $A_{FF} = \{ID, psid, prio, age, range\}$
  - $A_{NF} = \{prio, age, range\}$

# Acceptance Policy Adjustments

- $A_{FF}$  are mainly determined by *Driving State FSM*



- $A_{NF}$  must not depend on FSM but mainly on internal network utilization (NU) because of the prefiltering in FF stage
  - High network utilization results in *strong* policies in order to relax internal network traffic for safety critical applications

# Network Monitoring and Evaluation

- Protocol independent metric for monitoring

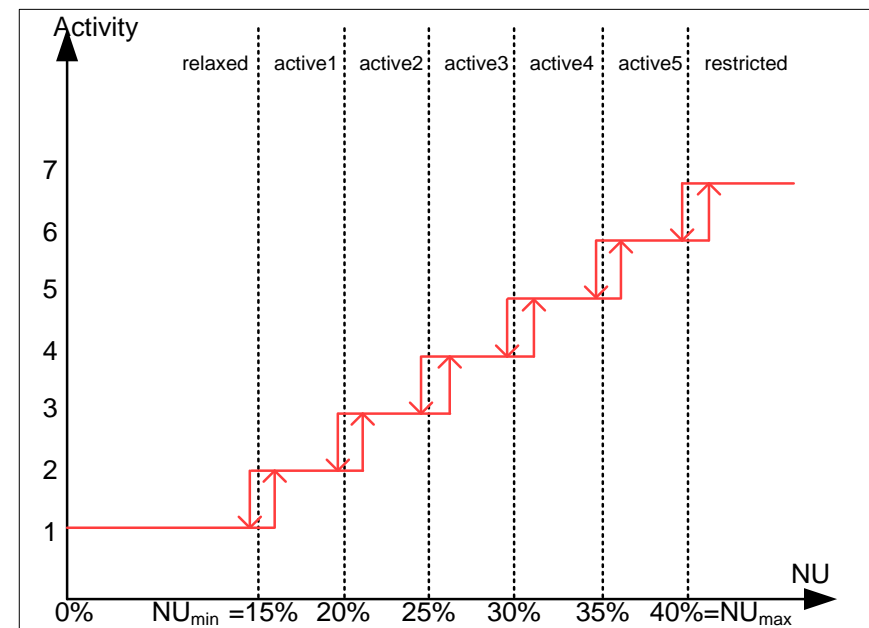
- Based on byte-rate  $B_{wsm}, B_{ee}$  measured over time interval  $T$  and nominal byte-rate  $N_{wsm}, N_{ee}$

- Smoothed linearly\*

- $$NU_x(\tau) = 0.5 * NU_x(\tau - 1) + 0.5 * \frac{B_x}{N_x},$$

$$x = \{wsm, ee\}$$

- Discretized into 7 NU activity states\*



# Case Study: Cross-Domain CACC Evaluation

## ■ Simulation Setup

- Platoon following scenario
- Approaching intersections every 200m

## ■ OMNeT++

- Transmit Power: 20 dBm
- WSM Channel: CCH
- WSM Bitrate  $N_{wsm} = 6 Mbps$
- Beacon Rate: 10Hz

## ■ SUMO

- Vehicles: 30
- Max. Speed: ~50 km/h
- Mobility Update Rate: 10Hz

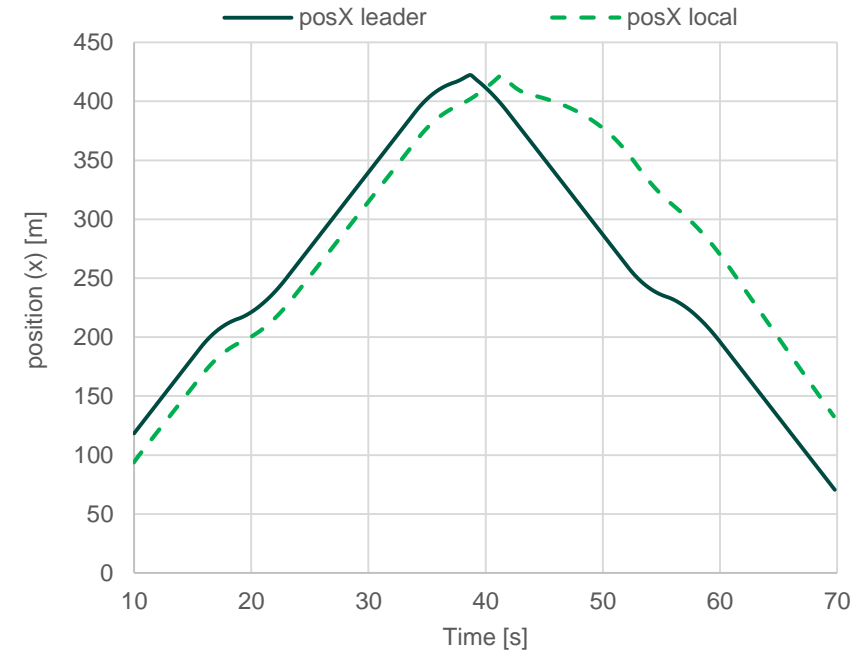
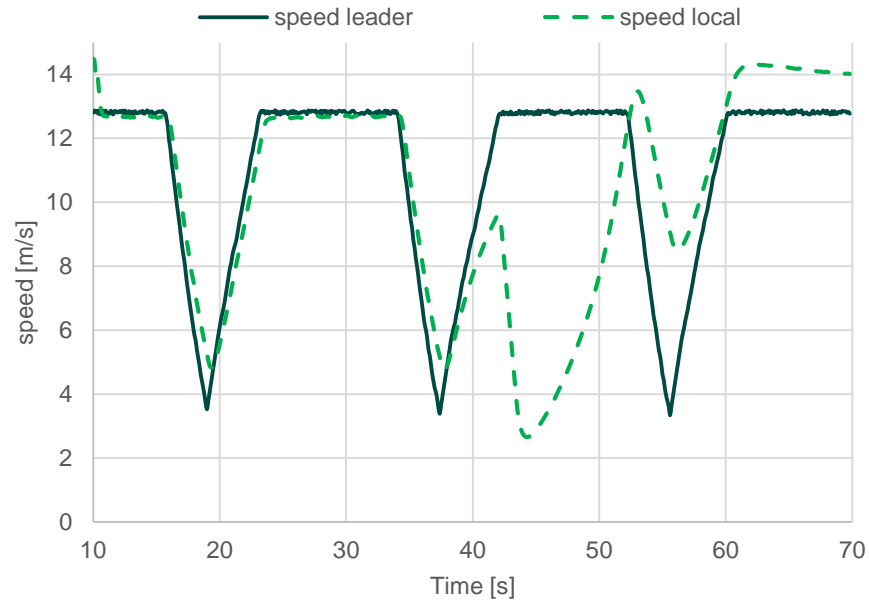
## ■ Message Evaluation (Ptolemy)

- Sensor Update Rate: 10Hz
- $N_{ee} = 500kbps$
- CACC Frame Rate  $\lambda_{CACC} = 10Hz$
- Acceptance Policies: cp. Table 1

Table 1: Acceptance Policy Specification

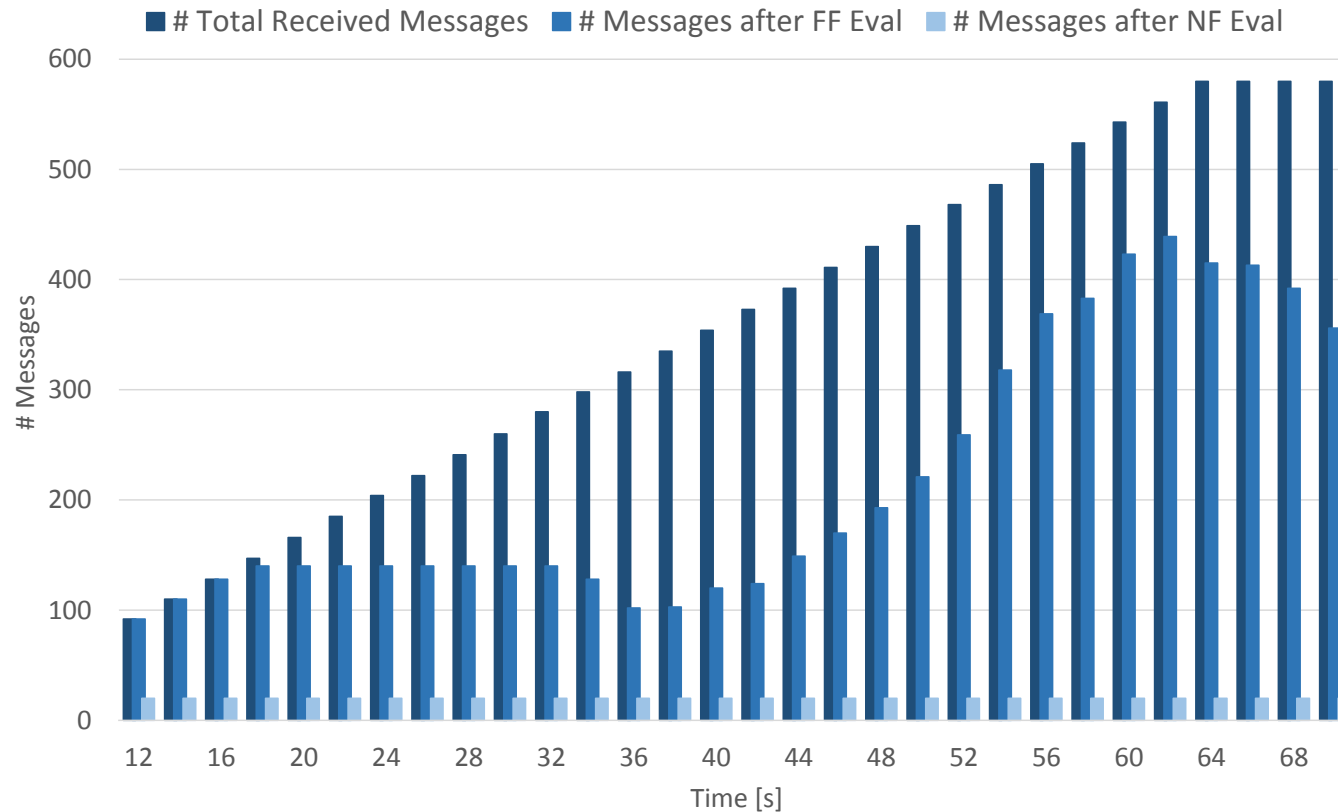
$A_{FF}$		
	weak	strong
PSID	all	safety related
prio	all	prio(BSM)
range (x,y,z)	300m	150m
age	1.0s	0.5s
$A_{NF}$		
	weak	strong
prio	all	prio(BSM)
range (x,y,z)	300m	100m
age	0.5s	0.2s

# Results Scenario I: Platoon Turnaround





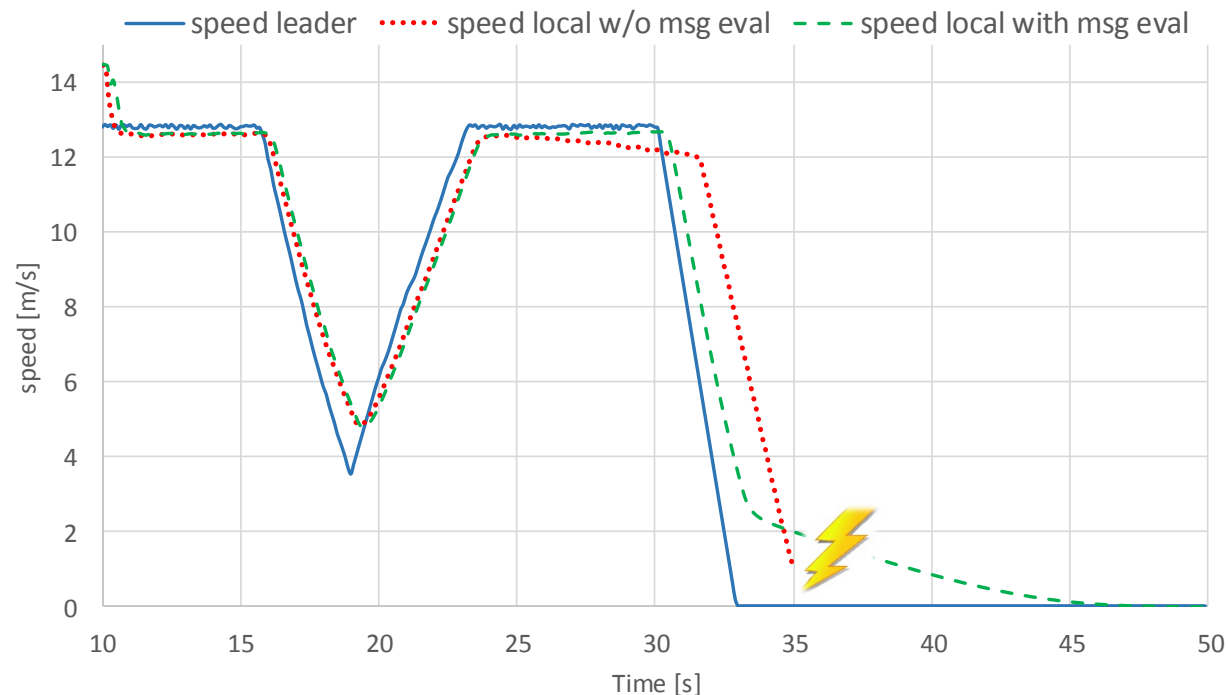
# Results Scenario I: Platoon Turnaround



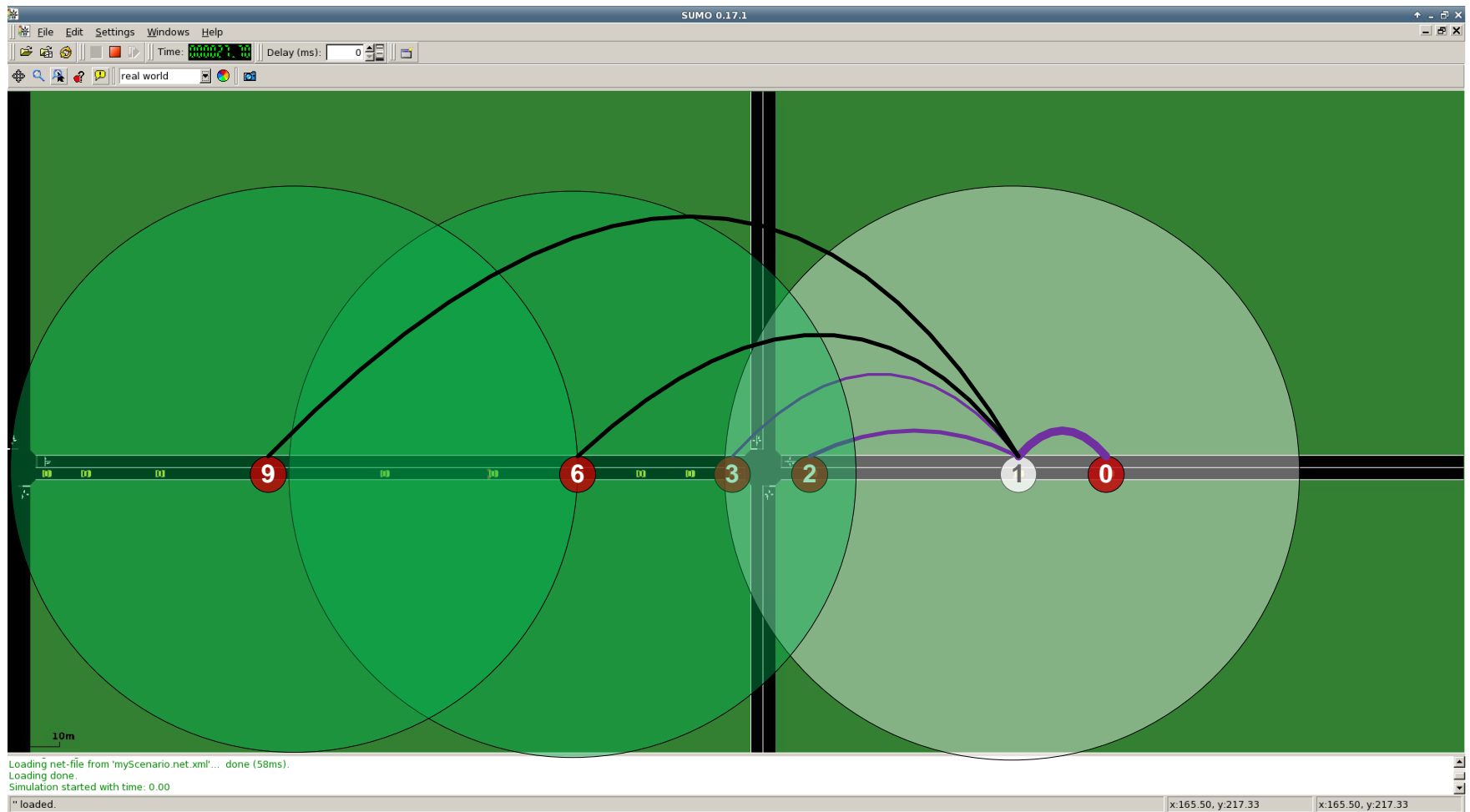
- Message Saving after FF Eval: **Max. 69,3% and 37,0% in average**
- Overall Message Saving after NF Eval: **Max. 96,6% and 92,7% in average**

# Results Scenario II: CACC Verification

- Broke down leading vehicle after 30s
  - Event-Driven warning with PSID  $0x8005$  sent out → *strong  $A_{FF}$*
- Modeled worst case reception latency per beacon inside E/E architecture model: *10ms\**
- Comparison of CACC behavior w/ and w/o Message Evaluation



# Example Simulation Snapshot

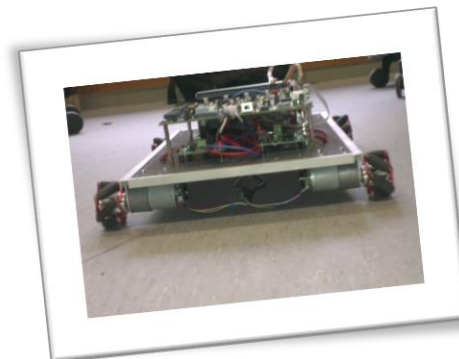


# Summary

- Presentation of a WAVE compliant V2X Message Evaluation Methodology
  - Hierarchical vehicle clustering strategy
  - Vehicle and network (internal/external) state monitoring (Cost Functions)
  - Adaptive Acceptance Policies
- Modeled inside V2X ECU together with abstract E/E architecture components reducing internal network traffic and message processing efforts
- Model-based cross-domain evaluation of CACC application with co-simulation framework
  - Taking into account internal processing and communication latencies
  - Enables early and deterministic exploration and evaluation of (abstract) E/E architectures in V2X scenarios
- Significant reduction of V2X messages need to be processed during run-time
  - 92.7% in average in reverse traffic scenario
  - Accident-free CACC behavior in case of worst-case WSM latencies and broke down leading vehicle

# Outlook

- Investigation of more complex traffic scenarios
- Deeper analysis of acceptance policies
- Analysis of power/energy consumption reduction of signature verification modules by the approach
- Implementing the approach on real target platforms
- Validation of the approach and CACC scenario by means of robot prototypes



Thank you very much for your attention!