Shape Analysis, Lebesgue Integration and Absolute Continuity Connections

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Abstract

As shape analysis of the form presented in Srivastava and Klassen's textbook "Functional and Shape Data Analysis" is intricately related to Lebesgue integration and absolute continuity, it is advantageous to have a good grasp of the latter two notions. Accordingly, in these notes we review basic concepts and results about Lebesgue integration and absolute continuity. In particular, we review fundamental results connecting them to each other and to the kind of shape analysis, or more generally, functional data analysis presented in the aforemetioned textbook, in the process shedding light on important aspects of all three notions. Many well-known results, especially most results about Lebesgue integration and some results about absolute continuity, are presented without proofs. However, a good number of results about absolute continuity and most results about functional data and shape analysis are presented with proofs. Actually, most missing proofs can be found in Royden's "Real Analysis" and Rudin's "Principles of Mathematical Analysis" as it is on these classic textbooks and Srivastava and Klassen's textbook that a good portion of these notes are based. However, if the proof of a result does not appear in the aforementioned textbooks, nor in some other known publication, or if all by itself it could be of value to the reader, an effort has been made to present it accordingly.

1 Introduction

The concepts of Lebesgue integration and absolute continuity play a major role in the theory of shape analysis or more generally in the theory of functional data analysis of the form presented in [23]. In fact, well-known connections between Lebesgue integration and absolute continuity are of great importance in the development of functional data and shape analysis of the kind in [23]. Accordingly, understanding functional data and shape analysis as presented in [23] requires understanding the basics of Lebesgue integration and absolute continuity, and the connections between them. It is the purpose of these notes to provide a way to do exactly that.

In Section 2, we review fundamental concepts and results about Lebesgue integration. Then, in Section 3, we review fundamental concepts and results about absolute continuity, some results connecting it to Lebesgue integration. Finally, in Section 4, we shed light on some important aspects of functional data and shape analysis of the type in Srivastava and Klassen's textbook [23], in the process illustrating its dependence on Lesbesgue integration, absolute continuity and the connections between them. Accordingly, without page numbers, a table of contents for these notes would be roughly as follows:

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The material in these notes about Lebesgue integration and absolute continuity is mostly based on Royden's "Real Analysis" [16] and Rudin's "Principles of Mathematical Analysis" [18]. The fundamental ideas on functional

data and shape analysis are mostly from Srivastava and Klassen's "Functional and Shape Data Analysis" [23]. An index of terms has been included at the end of the notes.

2 Lebesgue Integration

Algebras of sets, Borel sets, Cantor set

Definition 2.1: A collection \mathcal{A} of subsets of a set X is called an **algebra** on X if for A, B in \mathcal{A} , $A \cup B$ is in \mathcal{A} , and for A in \mathcal{A} , $\tilde{A} = X \setminus A$ is in \mathcal{A} .

Observation 2.1: From De Morgan's laws if \mathcal{A} is an algebra, then for A, B in \mathcal{A} , $A \cap B$ is in \mathcal{A} .

Definition 2.2: An algebra \mathcal{A} is called a σ -algebra if the union of every countable collection of sets in \mathcal{A} is in \mathcal{A} .

Observation 2.2: From De Morgan's laws if \mathcal{A} is a σ -algebra, then the intersection of a countable collection of sets in \mathcal{A} is in \mathcal{A} .

Definition 2.3: A set of real numbers O is said to be **open** if for each $x \in O$ there is $\delta > 0$ such that each number y with $|x - y| < \delta$ belongs to O. A set of real numbers F is said to be **closed** if its complement in \mathbf{R} is open, i.e., $\mathbf{R} \setminus F$ is open, where \mathbf{R} is the set of real numbers. The collection of **Borel** sets is the smallest σ -algebra on the set \mathbf{R} of real numbers which contains all open sets of real numbers.

Observation 2.3: The collection of Borel sets contains in particular all closed sets, all open intervals, all countable unions of closed sets, all countable intersections of open sets, etc.

Proposition 2.1: Every open set of real numbers is the union of a countable collection of disjoint open intervals. Proof in [16].

Proposition 2.2 (Lindelöf): Given a collection \mathcal{C} of open sets of real

numbers, then there is a countable subcollection $\{O_i\}$ of \mathcal{C} with

$$\bigcup_{O \in \mathcal{C}} O = \bigcup_{i=1}^{\infty} O_i.$$

Proof in [16].

Definition 2.4: A set of real numbers F is said to be **compact** if every open cover of F contains a finite subcover, i.e., if C is a collection of open sets of real numbers such that $F \subseteq \bigcup_{O \in C} O$, then there is a finite subcollection $\{O_i, i = 1, ..., n\}$ of C with $F \subseteq \bigcup_{i=1}^n O_i$.

Proposition 2.3 (Heine-Borel): A set of real numbers F is compact if and only if it is closed and bounded. Proof in [16] and [18].

Proposition 2.4: Given a collection \mathcal{K} of closed sets of real numbers such that at least one of the sets is bounded and the intersection of every finite subcollection of \mathcal{K} is nonempty, then $\bigcap_{F \in \mathcal{K}} F \neq \emptyset$. Proof in [16] and [18].

Definition 2.5: A number x is said to be a **limit point** of a set of real numbers E if every open set that contains x contains $y \neq x$, y in E.

Definition 2.6: A set of real numbers E is said to be **perfect** if it is closed and if every number in E is a limit point of E.

Proposition 2.5: A set is closed if and only if every limit point of the set is a point of the set. A nonempty perfect set is uncountable. Proofs in [18].

Corollary 2.1: Every interval is uncountable, thus the set of real numbers is uncountable.

Observation 2.4: Let E_1 be the union of the intervals $[0, \frac{1}{3}]$, $[\frac{2}{3}, 1]$ that are obtained by removing the open middle third of the interval [0, 1]. Let E_2 be the union of the intervals $[0, \frac{1}{9}]$, $[\frac{2}{9}, \frac{3}{9}]$, $[\frac{6}{9}, \frac{7}{9}]$, $[\frac{8}{9}, 1]$ that are obtained by removing the open middle thirds of the intervals $[0, \frac{1}{3}]$ and $[\frac{2}{3}, 1]$. Continuing this way, a sequence of compact sets E_n is obtained with $E_n \supset E_{n+1}$ for every positive integer n. The set $\bigcap_{n=1}^{\infty} E_n$, called the **Cantor set**, is compact, nonempty, perfect thus uncountable, and contains no interval. Proofs in [18].

Definition 2.7: The **extended real numbers** consist of the real numbers together with the two symbols $-\infty$ and $+\infty$. The definition of < is extended by declaring that if x is a real number, then $-\infty < x < \infty$. The operation $\infty - \infty$ is left undefined, the operation $0 \cdot (\pm \infty)$ is defined to be 0, while other definitions are extended: If x is a real number, then

$$\begin{array}{lll} x+\infty=\infty, & x-\infty=-\infty, & x/+\infty=x/-\infty=0, \\ x\cdot\infty=\infty, & x\cdot-\infty=-\infty & \text{if } x>0, \\ x\cdot\infty=-\infty, & x\cdot-\infty=\infty & \text{if } x<0. \\ \text{Finally} \\ \infty+\infty=\infty, & -\infty-\infty=-\infty, & \infty\cdot(\pm\infty)=\pm\infty, & -\infty\cdot(\pm\infty)=\mp\infty. \end{array}$$

Outer measure

Definition 2.8: Given a set A of real numbers, the **outer measure** m^*A of A is the extended real number defined by

$$m^*A = \inf_{A \subseteq \cup I_n} \sum l(I_n),$$

where the $\{I_n\}$ are countable collections of open intervals that cover A, and $l(I_n)$ is the length of the interval I_n .

Observation 2.5: m^* is a set function, $m^*\emptyset = 0$, $m^*A \leq m^*B$ if $A \subseteq B$, and the outer measure of a set consisting of a single point is zero.

Proposition 2.6: $m^*(I) = l(I)$ if I is an interval. Proof in [16].

Proposition 2.7: Countable subadditivity of m^* : $m^*(\cup A_n) \leq \sum m^* A_n$ for any countable collection $\{A_n\}$ of sets of real numbers. Proof in [16].

Corollary 2.2: $m^*A = 0$ if A is countable.

Observation 2.6: The Cantor set is an example of an uncountable set with outer measure zero. Proof in [18].

Proposition 2.8: m^* is translation invariant, i.e., $m^*(E+y) = m^*E$ for any

set E of real numbers and any number y, where $E + y = \{x + y : x \in E\}$.

Proof: If $\{I_n\}$ is a countable collection of open intervals that covers E, then $\{I_n + y\}$ is a countable collection of open intervals that covers E + y. Since $l(I_n) = l(I_n + y)$ for each n, then $m^*(E + y) \le m^*E$. Similarly, if $\{I_n\}$ is a countable collection of open intervals that covers E+y, then $\{I_n-y\}$ covers E, $l(I_n) = l(I_n - y)$, and therefore $m^*E \le m^*(E + y)$. Thus, $m^*E = m^*(E + y)$.

Proposition 2.9: For any set A of real numbers and any $\epsilon > 0$, there is an open set O with $A \subseteq O$ and $m^*O \le m^*A + \epsilon$ ($m^*O < m^*A + \epsilon$ if $m^*A < \infty$). In addition, there is a set G that is the intersection of a countable collection of open sets with $A \subseteq G$ and $m^*G = m^*A$.

Proof: From the definition of the outer measure there is a countable collection $\{I_n\}$ of open intervals that covers A with $\sum l(I_n) \leq m^*A + \epsilon$. With $O = \cup I_n$, then O is open, $A \subseteq O$, and $m^*O \leq \sum l(I_n) \leq m^*A + \epsilon$, which proves the first part. Now let k > 0 be an integer. Then from the first part there is an open set O_k , $A \subseteq O_k$, with $m^*O_k \leq m^*A + \frac{1}{k}$. With $G = \bigcap_{k=1}^{\infty} O_k$, then for any integer n > 0 we have $A \subseteq G \subseteq O_n$ and therefore $m^*A \leq m^*G \leq m^*O_n \leq m^*A + \frac{1}{n}$. Letting $n \to \infty$, then $m^*A \leq m^*G \leq m^*A$. Thus $m^*A = m^*G$, which proves the second part.

Measurable sets, Lebesgue measure

Definition 2.9 (Carathéodory's criterion): A set E of real numbers is said to be (**Lebesgue**) measurable if for every set A of real numbers, then

$$m^*A = m^*(A \cap E) + m^*(A \cap \tilde{E}),$$

 \tilde{E} the complement of E in \mathbf{R} , i.e., $\tilde{E} = \mathbf{R} \setminus E$, \mathbf{R} the set of real numbers.

Observation 2.7: Clearly \tilde{E} is measurable if and only if E is, and \emptyset and the set \mathbf{R} of real numbers are measurable. As for an example of a nonmeasurable set, a rather complex one is presented in [16]. Finally, note that it is always true that $m^*A \leq m^*(A \cap E) + m^*(A \cap \tilde{E})$, thus E is measurable if and only if for every set A we have $m^*A \geq m^*(A \cap E) + m^*(A \cap \tilde{E})$.

Proposition 2.10: If $m^*E = 0$, then E is measurable.

Proof: For any set A, since $A \supseteq A \cap \tilde{E}$, $m^*E = 0$, and $E \supseteq A \cap E$, then

$$m^*A \ge m^*(A \cap \tilde{E}) = m^*(A \cap \tilde{E}) + m^*(E) \ge m^*(A \cap \tilde{E}) + m^*(A \cap E).$$

Proposition 2.11: The collection of measurable sets is a σ -algebra on \mathbf{R} . Proof in [16].

Definition 2.10: The **Lebesgue measure** m is the set function obtained by restricting the set function m^* to the collection of (Lebesgue) measurable sets.

Proposition 2.12: Countable subadditivity of m: $m(\cup A_n) \leq \sum mA_n$ for any countable collection $\{A_n\}$ of measurable sets (Proposition 2.7). **Countable additivity** of m: $m(\cup A_n) = \sum mA_n$ if the sets in $\{A_n\}$ as above are pairwise disjoint. Proof in [16].

Observation 2.8: It is in the proof of countable additivity of the Lebesgue measure m that Carathéodory's criterion plays a major role. On the other hand, the importance of the countable additivity of m is immediately apparent in the proofs of the two parts of the following very useful proposition.

Proposition 2.13 (Nested sequences of measurable sets Lemma):

- 1. Given a countable collection of measurable sets $\{E_n\}$ with $E_{n+1} \subseteq E_n$ for each n, $mE_1 < \infty$, then $m(\bigcap_{i=1}^{\infty} E_i) = \lim_{n \to \infty} mE_n$.
- 2. Given a countable collection of (not necessarily measurable) sets $\{E_n\}$ with $E_{n+1} \supseteq E_n$ for each n, then $m^*(\bigcup_{i=1}^{\infty} E_i) = \lim_{n \to \infty} m^* E_n$.

Proof in [16] for the first part. In [14] for the second part using Proposition 2.9. As mentioned above, in the proofs of both parts the countable additivity of m (Proposition 2.12) is used.

Proposition 2.14: Every Borel set is measurable. Proof in [16].

Observation 2.9: A rather complex example of a measurable set that is not Borel is presented in [4].

Proposition 2.15 (Equivalent conditions for a measurable set): Let E be a set of real numbers. Then the following five conditions are equivalent: i. E is measurable.

ii. Given $\epsilon > 0$, there is an open set $O, O \supseteq E$ with $m^*(O \setminus E) < \epsilon$.

iii. Given $\epsilon > 0$, there is a closed set $F, F \subseteq E$ with $m^*(E \setminus F) < \epsilon$.

iv. There is a set G that is the intersection of a countable collection of open sets, $G \supseteq E$ with $m^*(G \setminus E) = 0$.

v. There is a set F that is the union of a countable collection of closed sets, $F \subseteq E$ with $m^*(E \setminus F) = 0$.

Proof: We only prove $i \Leftrightarrow ii$. Proofs of all cases in [17]. $i \Rightarrow ii$: E is measurable.

Case 1: $mE < \infty$.

There exists O open such that $E \subseteq O$, $mO < mE + \epsilon$ (Proposition 2.9). $mE < \infty$ then implies $mO - mE < \epsilon$. Accordingly,

$$\epsilon > m(O \cap E) + m(O \cap \tilde{E}) - mE$$

= $mE + m(O \setminus E) - mE$
= $m(O \setminus E)$.

Case 2: $mE = \infty$.

For each integer n > 0 let $E_n = E \cap ((n-1,n] \cup (-n,-n+1])$. Then each E_n is measurable, $mE_n < \infty$, and $E = \cup E_n$. From Case 1 above it follows that there is O_n open such that $E_n \subseteq O_n$ and $m(O_n \setminus E_n) < \epsilon/2^n$. With $O = \cup O_n$, then O is open, $E \subseteq O$ and $O \setminus E \subseteq \cup (O_n \setminus E_n)$. Thus,

$$m(O \setminus E) \le m(\cup (O_n \setminus E_n)) \le \sum m(O_n \setminus E_n) < \sum \epsilon/2^n = \epsilon.$$

ii \Rightarrow i: Given $\epsilon > 0$, there is an open set $O, O \supseteq E$ with $m^*(O \setminus E) < \epsilon$. O open implies O is measurable. Thus, for any set A, we have $m^*A = m^*(A \cap O) + m^*(A \cap \tilde{O})$. Accordingly,

$$m^*A + \epsilon > m^*A + m^*(O \cap \tilde{E})$$

$$= m^*(A \cap O) + m^*(A \cap \tilde{O}) + m^*(O \cap \tilde{E})$$

$$\geq m^*(A \cap E) + m^*(A \cap \tilde{O} \cap \tilde{E}) + m^*(O \cap \tilde{E} \cap A)$$

$$= m^*(A \cap E) + m^*(A \cap \tilde{E}).$$

 ϵ arbitrary implies $m^*A \geq m^*(A \cap E) + m^*(A \cap \tilde{E})$. Thus, E is measurable.

Corollary 2.3: Every (Lebesgue) measurable set is the union of a Borel set and a set of (Lebesgue) measure zero.

Proposition 2.16: The translate of a measurable set is measurable, i.e., if E is a measurable set, then E + y is measurable for any number y.

Proof: For any set A, setting B = A - y, F = E + y, and noting $(B \cap E) + y = A \cap F$, $(B \cap \tilde{E}) + y = A \cap \tilde{F}$, by Proposition 2.8, then

$$m^*A = m^*B = m^*(B \cap E) + m^*(B \cap \tilde{E}) = m^*(A \cap F) + m^*(A \cap \tilde{F}).$$

Thus, F = E + y is measurable.

Measurable functions, Step functions, Simple functions

Definition 2.11: Let f be an extended real-valued function defined on a (Lebesgue) measurable set. Then f is said to be (**Lebesgue**) measurable if the set $\{x \mid f(x) > a\}$ is (Lebesgue) measurable for every real number a.

Proposition 2.17 (Equivalent conditions for a measurable function): Let f be an extended real-valued function of measurable domain. Then the following conditions are equivalent:

- i. $\{x \mid f(x) > a\}$ is measurable for every real number a.
- ii. $\{x \mid f(x) \ge a\}$ is measurable for every real number a.
- iii. $\{x \mid f(x) < a\}$ is measurable for every real number a.
- iv. $\{x \mid f(x) \leq a\}$ is measurable for every real number a. Proof in [16] and [18].

Observation 2.10: Conditions ii, iii, iv can be used instead of condition i to define a measurable function. We note that if a real-vaued function f defined on a closed or open interval I is **continuous** [18], then f is measurable since the set in condition i is relatively open in I [18]. Also the restriction of a measurable function to a measurable subset of its domain, is measurable.

Definition 2.12: Given real numbers a, b, a < b, and an integer n > 0, by a **partition** or **subdivision** of [a,b] we mean a finite set of points $P = \{\xi_0, \xi_1, \dots, \xi_n\}$ with $a = \xi_0 < \xi_1 < \dots < \xi_n = b$. A function $\psi : [a,b] \rightarrow$

R is called a **step function** (on [a,b]) if for an integer n > 0, there are numbers c_i , i = 1, ..., n, and a partition or subdivision $P = \{\xi_0, \xi_1, ..., \xi_n\}$ of [a,b], such that $\psi(a) = \psi(\xi_0) = c_1$, $\psi(x) = c_i$, $\xi_{i-1} < x \le \xi_i$, i = 1, ..., n.

Definition 2.13: Given sets A, X of real numbers, $A \subseteq X$, the **characteristic function** χ_A of A on $X, \chi_A : X \to \{0, 1\}$, is defined by

$$\chi_A(x) = \begin{cases} 1 & x \in A \\ 0 & x \in X \setminus A. \end{cases}$$

Definition 2.14: Given a measurable set E, an integer n > 0, and for i = 1, ..., n, nonzero numbers c_i , measurable sets $E_i \subseteq E$, and characteristic functions χ_{E_i} of E_i on E, a function $\varphi : E \to \mathbf{R}$ defined by $\varphi(x) = \sum_{i=1}^n c_i \chi_{E_i}(x)$ for x in E is called a **simple function** on E.

Observation 2.11: Step functions are measurable and a function is simple if and only if it is measurable and assumes only a finite number of values. We note that the representation of a simple function φ is not unique. However it does have a so-called **canonical representation**: for some integer m > 0, $\varphi(x) = \sum_{i=1}^{m} a_i \chi_{A_i}(x)$ for x in E, where $\{a_1, \ldots, a_m\}$ is the set of distinct nonzero values of φ , and $A_i = \{x \in E : \varphi(x) = a_i\}, i = 1, \ldots, m$. This representation is characterized by the fact that the a_i 's are distinct and nonzero, and the A_i 's are pairwise disjoint.

Proposition 2.18: If f is a measurable function, then the function |f| is measurable. Proof in [18].

Proposition 2.19: Let f and g be measurable real-valued (not extended) functions defined on the same domain X, c a constant, and F a continuous real-valued function on \mathbf{R}^2 . Then the function h defined by $h(x) = F(f(x), g(x)), x \in X$, is measurable. In particular f + g, fg, cf, f + c, f - g are measurable; f/g is measurable if $g \neq 0$ on X. Proofs in [16] and [18].

Observation 2.12: For extended real-valued measurable functions f and g, the function fg is still measurable. However in order for f+g to be measurable, f+g must be given the same value at points where it is undefined, unless these points form a set of measure zero in which case it makes no

difference which values f + g is given on the set.

Proposition 2.20: Let $\{f_n\}$ be a sequence of measurable functions defined on the same domain X and let N > 0 be an integer. The functions defined for each $x \in X$ by $\sup_{n \le N} f_n(x)$, $\sup_n f_n(x)$, $\lim \sup_{n \to \infty} f_n(x)$, $\inf_{n \le N} f_n(x)$, $\inf_{n \le N} f_n(x)$, are all measurable. Proofs in [16] and [18].

Definition 2.15: Given a set of real numbers X, a property associated with points in X is said to hold **almost everywhere** (a.e. for short) in X if the set of points in X where the property fails has measure zero.

Proposition 2.21: Let f and g be functions defined on the same measurable domain X. If f is measurable and f = g a.e., then g is measurable.

Proof: Let a be any real number. f = g a.e. means the set $E = \{x : f(x) \neq g(x)\}$ has measure zero. Thus E and the set $\{x \in E : g(x) > a\} \subseteq E$ are measurable (Proposition 2.10). $X \setminus E$ must then be measurable and the set $\{x \in X \setminus E : f(x) > a\}$ is then measurable as f is measurable. Thus, since

$$\{x : g(x) > a\} = \{x \in X \setminus E : f(x) > a\} \cup \{x \in E : g(x) > a\}$$

it follows that $\{x: g(x) > a\}$ is measurable and therefore g is measurable.

Observation 2.13: The definition of a measurable function and 1 of Proposition 2.13 allow the following proposition to be true.

Proposition 2.22 (Egoroff's Theorem): Let $\{f_n\}$ be a sequence of measurable functions on a measurable set E, $mE < \infty$, that converge a.e. to a real-valued (not extended) function f on E, i.e., there is a set $B \subseteq E$ such that mB = 0, $f_n \to f$ pointwise on $E \setminus B$. Then for every $\delta > 0$ there is a closed set $F \subseteq E$ such that $m(E \setminus F) < \delta$ and $f_n \to f$ uniformly on F.

Proof: Let m > 0 be an integer. For each integer n > 0 let

$$G_n^m = \{x \in E : |f_n(x) - f(x)| \ge 1/m\},\$$

and for each integer N > 0 set

$$E_N^m = \bigcup_{n=N}^{\infty} G_n^m = \{x \in E : |f_n(x) - f(x)| \ge 1/m \text{ for some } n \ge N\}.$$

We note f is measurable (Proposition 2.20 and Proposition 2.21). It follows that each E_N^m is measurable and of finite measure, $E_{N+1}^m \subseteq E_N^m$, and for each $x \in E \setminus B$ there must be some N for which $x \notin E_N^m$, since $f_n(x) \to f(x)$. Thus $\cap E_N^m \subseteq B$ and must therefore have measure zero. It follows then that $\lim_{N\to\infty} mE_N^m = 0$ (1 of Proposition 2.13). Hence there exists N such that

$$mE_N^m = m(\{x \in E : |f_n(x) - f(x)| \ge 1/m \text{ for some } n \ge N\}) < \delta/2^{m+1}.$$

Letting $A^m = E_N^m$, then A^m is measurable, $mA^m < \delta/2^{m+1}$ and

$$E \setminus A^m = \{ x \in E : |f_n(x) - f(x)| < 1/m \text{ for all } n \ge N \}.$$

Now let $A = \bigcup_{m=1}^{\infty} A^m$. Then $mA \leq \sum_{m=1}^{\infty} mA^m < \sum_{m=1}^{\infty} \delta/2^{m+1} = \delta/2$. Given $\epsilon > 0$ choose integer m > 0 with $1/m < \epsilon$. For some N and for all $x \in E \setminus A$ then $x \in E \setminus A^m$ and $|f_n(x) - f(x)| < 1/m < \epsilon$ for all $n \geq N$. Thus, $f_n \to f$ uniformly on $E \setminus A$.

Finally, let $G = E \setminus A$. Clearly G is measurable and $m(E \setminus G) = mA < \delta/2$. Thus, there exists a closed set F, $F \subseteq G$ with $m(G \setminus F) < \delta/2$ (Proposition 2.15). It then follows that $m(E \setminus F) = m(E \setminus G) + m(G \setminus F) < \delta/2 + \delta/2 = \delta$ and $f_n \to f$ uniformly on F.

Proof also in [8] for spaces and measures more general than ${\bf R}$ and the Lebesgue measure.

Observation 2.14: The assumption $mE < \infty$ is necessary in the above proposition. To see this, let $E = \mathbf{R}$ and

$$f_n(x) = \begin{cases} 1 & x > n \\ 0 & x \le n. \end{cases}$$

Clearly $f_n \to 0$ pointwise on E. However, for any integer N > 0, $0 < \epsilon < 1$, the set $\{x \in E : f_N(x) \ge \epsilon\} = (N, \infty)$ is of infinite measure. Thus, the uniform convergence of f_n to 0 as proposed in the proposition can not occur.

Definition 2.16: Given a function f defined on a set E, the **positive part** f^+ of f and the **negative part** f^- of f are the functions defined respectively by $f^+(x) = \max\{f(x), 0\}$, and $f^-(x) = \max\{-f(x), 0\}$, $x \in E$.

Proposition 2.23 (Approximation of a measurable function by simple functions): Let f be a real-valued (not extended) measurable function on a measurable set E. Then there exists a sequence of simple functions $\{s_n\}$ on E such that $s_n \to f$ pointwise on E. Since $f = f^+ - f^-$, and f^+ and f^- are measurable because f is, then $\{s_n\}$ can be chosen so that $s_n = s_n^u - s_n^l$, where s_n^u and s_n^l are simple functions on E such that $s_n^u \to f^+$, $s_n^l \to f^-$ pointwise on E, and s_n^u and s_n^l increase monotonically to f^+ and f^- , respectively. If f is bounded, then $\{s_n\}$ can also be chosen to converge uniformly to f on E. Proof in [18].

Proposition 2.24 (Lusin's Theorem): Let f be a real-valued (not extended) measurable function on a measurable set E. Then given $\epsilon > 0$, there exists a closed set $F \subseteq E$ with $m(E \setminus F) < \epsilon$ such that $f|_F$ is continuous.

Proof: First we prove the proposition for f a simple function on E. Accordingly, for some integer n > 0, assume $f(x) = \sum_{i=1}^{n} c_i \chi_{E_i}(x)$ for x in E, $E_i \subseteq E$ for each i, the canonical representation of f. In addition let $E_0 = E \setminus \bigcup_{i=1}^{n} E_i$. Clearly the E_i 's are pairwise disjoint. Given $\epsilon > 0$, since each E_i is measurable there exists a closed set $F_i \subseteq E_i$ such that $m(E_i \setminus F_i) < \epsilon/(n+1)$, $i = 0, \ldots, n$ (Proposition 2.15). Accordingly, $F = \bigcup_{i=0}^{n} F_i$ is closed, and

$$m(E \setminus F) = m(\bigcup_{i=0}^{n} E_i \setminus \bigcup_{i=0}^{n} F_i) = m(\bigcup_{i=0}^{n} (E_i \setminus F_i)) = \sum_{i=0}^{n} m(E_i \setminus F_i) < \epsilon.$$

Now, to show $f|_F$ is continuous we show that if $\{x_k\}$, x in F are such that $x_k \to x$, then $f(x_k) \to f(x)$.

We note that for some unique $j, 0 \le j \le n$, it must be that $x \in F_j$. Thus, since f is constant on F_j , it then suffices to show that for some integer K > 0, x_k is in F_j for $k \ge K$. If this is not the case and since there is a finite number of F_i 's then for some $l, 0 \le l \le n, l \ne j$, there is a subsequence $\{x_{k_m}\}$ of $\{x_k\}$ all contained in F_l . But then $x_{k_m} \to x$ so that x is in F_l , a contradiction.

Now we prove the proposition for a general f.

Case 1: $mE < \infty$.

Let s_n be simple functions such that $s_n \to f$ pointwise on E (Proposition 2.23). Given $\epsilon > 0$, as established above for simple functions on E, for each n there exists a closed set $F_n \subseteq E$ with $m(E \setminus F_n) < \epsilon/2^{n+1}$ such that $s_n|_{F_n}$ is continuous. In addition, since $mE < \infty$, there exists a closed

set $F_0 \subseteq E$ such that $m(E \setminus F_0) < \epsilon/2$ and $s_n \to f$ uniformly on F_0 (Proposition 2.22 (Egoroff's Theorem)).

Finally let $F = \bigcap_{n=0}^{\infty} F_n$. Then F is closed and

$$m(E \setminus F) = m(\bigcup_{n=0}^{\infty} (E \setminus F_n)) \le \sum_{n=0}^{\infty} m(E \setminus F_n) < \sum_{n=0}^{\infty} \epsilon/2^{n+1} = \epsilon.$$

Since $s_n|_{F_n}$ is continuous so must be $s_n|_F$. And since $s_n \to f$ uniformly on $F \subseteq F_0$ then $f|_F$ must be continuous (proof in [18]).

Case 2: $mE = \infty$.

For each integer n > 0, let $\tilde{E}_n = (n-1, n] \cup (-n, -n+1]$ and $E_n = E \cap \tilde{E}_n$. Then each E_n is measurable, $mE_n < \infty$, and $E = \bigcup_{n=1}^{\infty} E_n$. From Case 1 above, given $\epsilon > 0$, it follows that there is a closed set $F_n \subseteq E_n$ with $m(E_n \setminus F_n) < \epsilon/2^n$ such that $f|_{F_n}$ is continuous. Let $F = \bigcup_{n=1}^{\infty} F_n$. Then

$$m(E \setminus F) = m(\bigcup_{n=1}^{\infty} E_n \setminus \bigcup_{n=1}^{\infty} F_n) = m(\bigcup_{n=1}^{\infty} (E_n \setminus F_n))$$
$$= \sum_{n=1}^{\infty} m(E_n \setminus F_n) < \sum_{n=1}^{\infty} \epsilon/2^n = \epsilon.$$

We show F is closed. Let x be a limit point of F so that for $\{x_k\}$ in F, then $x_k \to x$. Clearly for some integer j > 0 it must be that $x \in \tilde{E}_j$. It suffices to show that for some integer K > 0, x_k is in F_j for $k \ge K$ so that x is also in $F_j \subseteq F$. With $\tilde{E}_n = \emptyset$ for $n \le 0$, from the definition of the \tilde{E}_n 's a neighborhood of the point x exists that does not intersect \tilde{E}_i , i > j + 1 or i < j - 1. Thus, with $F_0 = \emptyset$, for k large enough the points x_k can only be in F_{j-i} , F_j and F_{j+1} . If it is not the case that K as described exists, then there must be a subsequence $\{x_{k_m}\}$ of $\{x_k\}$, all of it contained in either F_{j-1} or F_{j+1} . But then $x_{k_m} \to x$ so that x is in either F_{j-1} or F_{j+1} , a contradiction. (Actually showing that x is in the union of F_{j-1} , F_j and F_{j+1} , would have sufficed). Now, to show $f|_F$ is continuous we show that if $\{x_k\}$, x in F are such that $x_k \to x$, then $f(x_k) \to f(x)$.

We note that for some unique j > 0, it must be that $x \in F_j$. Thus, since f is continuous on F_j , it then suffices to show that for some integer K > 0, x_k is in F_j for $k \geq K$. If this is not the case, again with $F_0 = \emptyset$, an argument, similar to the one used above for proving F is closed, can be used to get the same contradiction that x is in either F_{j-1} or F_{j+1} .

The Riemann integral

Definition 2.17: Let [a, b] be an interval and f a bounded real-valued function defined on [a, b]. Given an integer n > 0, and $P = \{\xi_0, \xi_1, \dots, \xi_n\}$, a partition or subdivision of [a, b] (Definition 2.12), for $i = 1, \dots, n$, we define

$$m_i = \inf f(x), \ \xi_{i-1} \le x \le \xi_i,$$
 $M_i = \sup f(x), \ \xi_{i-1} \le x \le \xi_i, \text{ and}$
 $L(P, f) = \sum_{i=1}^n m_i(\xi_i - \xi_{i-1}),$
 $U(P, f) = \sum_{i=1}^n M_i(\xi_i - \xi_{i-1}).$

Then we define the **lower Riemann integral** and the **upper Riemann integral** of f over [a, b], respectively, by

$$\mathcal{R} \underline{\int_{a}^{b} f(x) dx} = \sup_{P} L(P, f),$$

$$\mathcal{R}\overline{\int_a^b}f(x)dx = \inf_P U(P, f),$$

where the infimum and supremum are taken over all partitions P of [a, b]. If the two are equal, f is said to be **Riemann integrable** over [a, b], and the common value is then called the **Riemann integral** of f over [a, b] and denoted by

$$\mathcal{R} \int_a^b f(x) dx$$
.

Observation 2.15: Since f is bounded, there exist numbers m and M, such that $m \leq f(x) \leq M$, $x \in [a,b]$. Thus, for every partition P, it must be that $m(b-a) \leq L(P,f) \leq U(P,f) \leq M(b-a)$, so that the lower and upper Riemann integrals of f over [a,b] are finite numbers.

Proposition 2.25: $\mathcal{R} \underline{\int_a^b} f(x) dx \leq \mathcal{R} \overline{\int_a^b} f(x) dx$. Proof in [18].

Observation 2.16: Let $\psi : [a,b] \to \mathbf{R}$ be a step function so that for an integer n > 0, there are numbers c_i , i = 1, ..., n, and a partition $P = \{\xi_0, \xi_1, ..., \xi_n\}$ of [a, b], such that $\psi(a) = \psi(\xi_0) = c_1$, $\psi(x) = c_i$, $\xi_{i-1} < x \le \xi_i$,

 $i=1,\ldots,n$. Clearly $L(P,\psi)=U(P,\psi)$ and since $L(P,\psi)\leq \mathcal{R}\underline{\int_a^b}\psi(x)dx\leq \mathcal{R}\overline{\int_a^b}\psi(x)dx\leq U(P,\psi)$ (Proposition 2.25), it must be that ψ is Riemann integrable over [a,b] and $\mathcal{R}\int_a^b\psi(x)dx=\sum_{i=1}^nc_i(\xi_i-\xi_{i-1})$. From this it is then apparent that

$$\mathcal{R} \underbrace{\int_{a}^{b}}_{f} f(x) dx = \sup_{P} L(P, f) = \sup_{\psi \le f} \mathcal{R} \int_{a}^{b} \psi(x) dx,$$

$$\mathcal{R} \overline{\int_a^b} f(x) dx = \inf_P U(P, f) = \inf_{\psi \ge f} \mathcal{R} \int_a^b \psi(x) dx,$$

where the ψ 's are all possible step functions on [a, b] satisfying the given conditions.

Definition 2.18: Given an interval [a, b], let $P = \{\xi_0, \xi_1, \dots, \xi_n\}$ be a partition of [a, b]. The number

$$\mu(P) = \max_{i=1,\dots,n} (\xi_i - \xi_{i-1})$$

is called the **mesh** of P.

Let f be a real-valued function defined on [a, b]. Given a partition $P = \{\xi_0, \xi_1, \dots, \xi_n\}$ of [a, b], a **Riemann sum** of f with respect to P is a sum of the form

$$S(P, f) = \sum_{i=1}^{n} f(t_i)(\xi_i - \xi_{i-1}),$$

where the choice of points t_1, \ldots, t_n , $\xi_{i-1} \leq t_i \leq \xi_i$, $i = 1, \ldots, n$, is arbitrary. The Riemann sums of f are said to converge to a finite number I as $\mu(P) \to 0$, i.e.,

$$I = \lim_{\mu(P) \to 0} S(P, f),$$

if given $\epsilon > 0$, there exists $\delta > 0$ such that for every partition P with mesh $\mu(P) < \delta$ it must be that

$$|S(P, f) - I| < \epsilon$$

(obviously for every choice of points $t_1, \ldots, t_n, \xi_{i-1} \leq t_i \leq \xi_i, i = 1, \ldots, n$).

Proposition 2.26 (Riemann sums of f that converge implies f is bounded): If $\lim S(P, f)$ exists as $\mu(P) \to 0$, then f is bounded on [a, b].

Proof in [13] and [15].

Proposition 2.27 (Riemann sums of f converge if and only f is Riemann integrable): Let [a,b] be an interval and f a bounded real-valued function defined on [a,b]. Then f is Riemann integrable over [a,b] if and only if

$$I = \lim_{\mu(P) \to 0} S(P, f)$$

exists. If this is the case, then I equals $\mathcal{R} \int_a^b f(x) dx$. Proof in [18] and [25].

Observation 2.17: Given an interval [a, b] and a set $A \subseteq [a, b]$, ideally the characteristic function χ_A of A on [a, b], $\chi_A : [a, b] \to \{0, 1\}$, defined by

$$\chi_A(x) = \begin{cases} 1 & x \in A \\ 0 & x \in [a, b] \setminus A \end{cases}$$

should be (Riemann) integrable over [a, b], especially if A is measurable, and its integral over [a, b] should equal the (outer) measure of A. However, if A is the set of rational numbers in [a, b], which is measurable with mA = 0, we see that $\mathcal{R} \int_a^b \chi_A(x) dx = 0$ and $\mathcal{R} \int_a^b \chi_A(x) dx = b - a$, not the ideal situation.

The Lebesgue integral

Definition 2.19: Given a measurable set E, let $\varphi(x) = \sum_{i=1}^{m} a_i \chi_{A_i}(x)$ be the canonical representation of a simple function φ on E, where for some integer m > 0, $\{a_1, \ldots, a_m\}$ is the set of distinct nonzero values of φ , and $A_i = \{x \in E : \varphi(x) = a_i\}, i = 1, \ldots, m$. We define the **Lebesgue integral** of φ over E as the extended real number

$$\int_{E} \varphi(x)dx = \sum_{i=1}^{m} a_{i} m A_{i}.$$

Observation 2.18: A consequence of the following two propositions is that if $\varphi(x) = \sum_{i=1}^{n} c_i \chi_{E_i}(x)$ is any representation of a simple function φ on a measurable set E, then the Lebesgue integral of φ over E (Definition 2.19) can be computed directly from the representation, i.e., by computing $\sum_{i=1}^{n} c_i m E_i$.

Proposition 2.28: Let $\varphi(x) = \sum_{i=1}^n c_i \chi_{E_i}(x)$ be a representation of a simple

function φ on a measurable set E, with $E_i \cap E_j = \emptyset$ for $i \neq j$ (not necessarily the canonical representation of φ). Then

$$\sum_{i=1}^{n} c_i m E_i = \int_E \varphi(x) dx.$$

Proof in [16] for E_i 's of finite measure. Same proof for the general case.

Proposition 2.29: Let φ and ψ be simple functions on a measurable set E. Then for any real numbers a and b we must have

$$\int_{E} (a\varphi + b\psi)(x)dx = a \int_{E} \varphi(x)dx + b \int_{E} \psi(x)dx,$$

and, if $\varphi \ge \psi$ a.e., then $\int_E \varphi(x) dx \ge \int_E \psi(dx)$.

Proof in [16] using Proposition 2.28 for E_i 's of finite measure. Proof essentially the same for the general case.

Corollary 2.4: Let $\varphi(x) = \sum_{i=1}^{n} c_i \chi_{E_i}(x)$ be any representation of a simple function φ on a measurable set E, the E_i 's not necessarily pairwise disjoint. Then

$$\sum_{i=1}^{n} c_i m E_i = \int_E \varphi(x) dx.$$

Proof: Apply the first part of Proposition 2.29 to $\varphi(x) = \sum_{i=1}^{n} c_i \chi_{E_i}(x)$.

Definition 2.20: Given a measurable set E, let f be a measurable nonnegative function on E. We define the **Lebesgue integral** of f over E as the extended real number

$$\int_{E} f(x)dx = \sup_{\varphi \le f} \int_{E} \varphi(x)dx,$$

where the φ 's are all possible simple functions on E satisfying the given condition.

Definition 2.21: Given a measurable set E, let f be a measurable function on E. With f^+ and f^- as the positive and negative parts of f (Definition 2.16), we define the **Lebesgue integral** of f over E as the extended real number

$$\int_{E} f(x)dx = \int_{E} f^{+}(x)dx - \int_{E} f^{-}(x)dx,$$

if at least one of the integrals $\int_E f^+(x)dx$, $\int_E f^-(x)dx$ (Definition 2.20) is finite

If $\int_E f(x)dx$ is finite, then f is said to be **Lebesgue integrable** over E.

Proposition 2.30: Let f and g be Lebesgue integrable functions over a measurable set E, and c a real number. Then

i. cf is Lebesgue integrable over E with $\int_E cf(x)dx = c \int_E f(x)dx$.

ii. f + g is Lebesgue integrable over E with

$$\int_{E} (f+g)(x)dx = \int_{E} f(x)dx + \int_{E} g(x)dx.$$

iii. If $f \leq g$ a.e., then $\int_E f(x)dx \leq \int_E g(x)dx$.

iv. If $A, B \subseteq E$ are disjoint measurable sets, then

$$\int_{A \cup B} f(x)dx = \int_{A} f(x)dx + \int_{B} f(x)dx.$$

Proofs in [16] and [18].

Proposition 2.31: A measurable function f is Lebesgue integrable over E if and only if |f| is Lebesgue integrable over E, in which case

$$\left| \int_{E} f(x)dx \right| \le \int_{E} |f(x)|dx.$$

Also, if $0 \le f \le g$ on E and g is Lebesgue integrable over E, then f is Lebesgue integrable over E. In particular, if $|f| \le g$ and g is Lebesgue integrable, then |f|, and therefore f, is Lesbegue integrable over E.

Proof: The first part follows from $f = f^+ - f^-$, $|f| = f^+ + f^-$, and iv of Proposition 2.30. The inequality from $f \leq |f|$, $-f \leq |f|$, and i and iii of Proposition 2.30. The rest from Definition 2.20.

Observation 2.19: Let f be a measurable function on a measurable set E with mE finite, and let a, b be real numbers such that $a \leq f(x) \leq b$ for $x \in E$. By looking at $\int_E f^+(x)dx$ and $\int_E f^-(x)dx$ for the different possible signs of a and b, then it is evident that $amE \leq \int_E f(x)dx \leq bmE$. Accordingly, if f is a measurable and bounded function on a measurable set E with mE finite, since then for some M > 0, $-M \leq f(x) \leq M$ for $x \in E$, it must be

that $-M mE \leq \int_E f(x)dx \leq M mE$, and therefore f is Lebesgue integrable. However, there is more to this situation as the following proposition shows.

Proposition 2.32 (Integrable equivalent to measurable): Let f be a bounded function defined on a measurable set E with mE finite. Let

$$L(f) = \sup_{\varphi \le f} \int_E \varphi(x) dx, \quad U(f) = \inf_{\varphi \ge f} \int_E \varphi(x) dx,$$

where the φ 's are all possible simple functions on E satisfying the given conditions. Then L(f) = U(f) if and only if f is measurable. Whenever L(f) = U(f) then f is Lebesgue integrable and $\int_E f(x)dx = L(f) = U(f)$. Proof in [16].

Proposition 2.33 (Riemann integrable implies Lebesgue integrable): Let f be a bounded function on interval [a, b]. If f is Riemann integrable over [a, b], then f is measurable and Lebesgue integrable over [a, b] with

$$\int_{[a,b]} f(x)dx = \mathcal{R} \int_a^b f(x)dx.$$

Proof: Since step functions are simple functions, then

$$\sup_{\psi \le f} \mathcal{R} \int_a^b \psi(x) dx \le \sup_{\varphi \le f} \int_{[a,b]} \varphi(x) dx \le \inf_{\varphi \ge f} \int_{[a,b]} \varphi(x) dx \le \inf_{\psi \ge f} \mathcal{R} \int_a^b \psi(x) dx,$$

where the ψ 's and the φ 's are all possible step functions and simple functions on [a,b], respectively, satisfying the given conditions. Since f is Riemann integrable over [a,b], then all the inequalities above are equalities so that f must be measurable and Lebesgue integrable over [a,b] with

$$\int_{[a,b]} f(x)dx = \sup_{\varphi < f} \int_{[a,b]} \varphi(x)dx = \inf_{\varphi \ge f} \int_{[a,b]} \varphi(x)dx = \mathcal{R} \int_a^b f(x)dx$$

by Proposition 2.32.

Proposition 2.34: Let f be a measurable function on a measurable set E. i. If $f \ge 0$ on E and $\int_E f(x)dx = 0$, then f = 0 a.e. on E. ii. If f is Lebesgue integrable over E, then f is finite a.e. on E.

Proof: For each integer n > 0 let $E_n = \{x \in E : f(x) > 1/n\}$. For each n, we note $mE_n = 0$ or else $\int_E f(x)dx > 0$. Let $A = \{x \in E : f(x) \neq 0\}$. Then $A = \bigcup_{n=1}^{\infty} E_n$. Thus, $mA = m(\bigcup_{n=1}^{\infty} E_n) \leq \sum_{n=1}^{\infty} m(E_n) = 0$ so that f = 0 a.e. on E, which proves i. In order to prove ii, for each integer n > 0 let $E_n = \{x \in E : |f(x)| \geq n\}$. Then $n \cdot mE_n \leq \int_{E_n} |f(x)|dx \leq \int_E |f(x)|dx = C$, so that $mE_n \leq C/n$. Let $A = \{x \in E : |f(x)| = \infty\}$. Then $A = \bigcap_{n=1}^{\infty} E_n$. Since for each n, $A \subseteq E_n$, then $mA \leq mE_n \leq C/n$ so that mA = 0, which proves ii.

Proposition 2.35 (Lebesgue's criterion for Riemann integrability): Let f be a bounded function on [a, b]. Then f is Riemann integrable over [a, b] if and only if f is continuous a.e. on [a, b]. Proof in [18]. It involves Proposition 2.33 and i of Proposition 2.34.

Observation 2.20: Function χ_A in Observation 2.17 with A equal to the set of rational numbers fails the continuity hypothesis of Proposition 2.35 and thus it is not Riemann integrable over [a, b] as observed there. Actually, it can be easily shown to be nowhere continuous on [a, b].

Proposition 2.36 (Countable additivity of the Lebesgue integral): Let $\{E_n\}$ be a countable collection of pairwise disjoint measurable sets. Let $E = \bigcup_{i=1}^{\infty} E_i$, and let f be a measurable function on E. Assume either $f \geq 0$ on E or f is Lebesgue integrable over E. Then

$$\int_{E} f(x)dx = \sum_{i=1}^{\infty} \int_{E_{i}} f(x)dx.$$

Proof in [18].

Observation 2.21: If f is a measurable function on a set E with mE = 0, then $\int_E f(x)dx = 0$. Also, if sets A, E are measurable with $A \subseteq E$, and f is Lebesgue integrable over E, then it is Lebesgue integrable over A. From all this then, if f and g are functions on a measurable set E, f = g a.e. on E, f Lebesgue integrable over E, then so is g and $\int_E g(x)dx = \int_E f(x)dx$. Finally, we note that since integrals over sets of measure zero are zero, throughout these notes, if sets F and E are measurable with $F \subseteq E$, mF = 0, and f is a function on $E \setminus F$, possibly not defined on part or all of F, f Lebesgue integrable over $E \setminus F$, we say f is Lebesgue integrable over E

with $\int_E f(x)dx = \int_{E\setminus F} f(x)dx$. This makes sense as it is always possible to define f arbitrarily for points in F so that then f is defined on all of E and $\int_E f(x)dx = \int_{E\setminus F} f(x)dx + \int_F f(x)dx = \int_{E\setminus F} f(x)dx + 0 = \int_{E\setminus F} f(x)dx$.

Proposition 2.37 (Lebesgue's Monotone Convergence Theorem): Let $\{f_n\}$ be an increasing sequence of nonnegative measurable functions on a measurable set E. Let f be defined by $f(x) = \lim_{n\to\infty} f_n(x)$ for $x \in E$. Then

 $\int_{E} f(x)dx = \lim_{n \to \infty} \int_{E} f_n(x)dx.$

Proof in [16] and [18]. It involves Proposition 2.13.

Corollary 2.5: Let $\{f_n\}$ be a sequence of nonnegative measurable functions on a measurable set E. Let f be defined by $f(x) = \sum_{n=1}^{\infty} f_n(x)$ for $x \in E$. Then

$$\int_{E} f(x)dx = \sum_{n=1}^{\infty} \int_{E} f_n(x)dx.$$

Proof: $\{h_n\}$ defined by $h_n(x) = \sum_{i=1}^n f_i(x)$ for $x \in E$ is an increasing sequence of nonnegative measurable functions on E.

Observation 2.22: Proposition 2.36 can now be proved more easily. It suffices to prove it for $f \geq 0$ on E. Let $f_n(x) = f(x) \cdot \chi_{E_n}(x)$ for $x \in E$. Then $f(x) = \sum_{n=1}^{\infty} f_n(x)$ for $x \in E$ and the result follows from Corollary 2.5.

Observation 2.23: The following proposition says that if a nonnegative function is Lebesgue integrable over a measurable set, then the Lebesgue integral of the function over a measurable subset of the set is arbitrarily small if the measure of the subset is small enough. Later we will see that it can be used to show that every indefinite integral is absolutely continuous (indefinite integrals and absolute continuity defined in the next section).

Proposition 2.38 (Absolute continuity of the Lebesgue integral): Let f be a nonnegative Lebesgue integrable function over a measurable set E. Then given $\epsilon > 0$ there is $\delta > 0$ such that for each measurable set $A \subseteq E$ with $mA < \delta$, then $\int_A f(x)dx < \epsilon$. Proof in [16]. It involves Lebesgue's Monotone Convergence Theorem (Proposition 2.37).

Proposition 2.39 (Fatou's Lemma): Let $\{f_n\}$ be a sequence of non-negative measurable functions on a measurable set E. Let f be defined by $f(x) = \liminf_{n\to\infty} f_n(x)$ for $x \in E$. Then

$$\int_{E} f(x)dx \le \liminf_{n \to \infty} \int_{E} f_n(x)dx.$$

Proof in [16] and [18]. It involves Proposition 2.37.

Proposition 2.40 (Lebesgue's Dominated Convergence Theorem): Let $\{f_n\}$ be a sequence of measurable functions on a measurable set E such that there is a function f on E with $f_n \to f$ pointwise a.e. on E. If there is a function g that is Lebesgue integrable over E such that $|f_n| \leq g$ on E for all n, then

$$\int_{E} f(x)dx = \lim_{n \to \infty} \int_{E} f_n(x)dx.$$

Proof in [16] and [18]. It involves Proposition 2.39.

Corollary 2.6 (Bounded Convergence Theorem): Let $\{f_n\}$ be a sequence of measurable functions on a measurable set E of finite measure such that there is a function f on E with $f_n \to f$ pointwise a.e. on E. If there is a real number M such that $|f_n| \leq M$ on E for all n, then

$$\int_{E} f(x)dx = \lim_{n \to \infty} \int_{E} f_n(x)dx.$$

The L^p Spaces

Definition 2.22: Given a real number p > 0, the $L^p[0,1]$ or L^p space is the space of measurable functions on [0,1] satisfying: the p-th power of the absolute value of each function in the space is Lebesgue integrable over [0,1]. Thus, a measurable function f on [0,1] is in L^p (the L^p space) if and only if

$$\int_{[0,1]} |f(x)|^p dx < \infty.$$

Writing $\int_0^1 |f(x)|^p dx$ instead of $\int_{[0,1]} |f(x)|^p dx$ for f in L^p , we define

$$||f||_p = \{\int_0^1 |f(x)|^p dx\}^{1/p}$$

and call $||\cdot||_p$ the L^p norm, and $||f||_p$ the L^p norm of f.

Finally, the $L^{\infty}[0,1]$ or L^{∞} space is the space of measurable functions on [0,1] satisfying: each function in the space is bounded on [0,1] except possibly on a set of measure zero. Thus, a measurable function f on [0,1] is in L^{∞} (the L^{∞} space) if and only if the essential supremum of |f| on [0,1] is finite, i.e.,

ess
$$\sup |f(t)| = \inf\{M : m(\{t : |f(t)| > M\}) = 0\} < \infty.$$

We also note ess $\sup |f(t)| = \inf \{\sup_{t \in [0,1]} |g(t)| : g = f \text{ a.e.} \}.$ Defining

$$||f||_{\infty} = \operatorname{ess sup} |f(t)|$$

we call $||\cdot||_{\infty}$ the L^{∞} **norm**, and $||f||_{\infty}$ the L^{∞} **norm** of f.

Observation 2.24: In the definition of the L^p spaces, the interval [0,1] was chosen for simplicity. Given a real number p>0, if $f\in L^p$, then clearly $cf\in L^p$ for any real number c. In addition, if $f, g\in L^p$, since $|f+g|^p \leq 2^p(|f|^p+|g|^p)$, then $f+g\in L^p$. Thus, L^p is a linear space and so is L^{∞} .

Given f in L^p , $0 , then the <math>L^p$ norm of f, i.e., $||f||_p$ (Definition 2.22), equals zero if and only if f = 0 a.e. on [0,1]. Accordingly, we think of the elements of L^p as equivalent classes of functions, each class composed of functions that are equal to one another a.e. on [0,1], and as noted in Observation 2.21, some functions undefined on subsets of [0,1] of measure zero. Thus, assuming there is no distinction between two functions in the same equivalence class, we note that given $p, 1 \le p \le \infty$, then the L^p norm $||\cdot||_p$ is indeed a norm since clearly $||cf||_p = c||f||_p$ for any real number c, and as will be seen below, if $f, g \in L^p$, then $||f+g||_p \le ||f||_p + ||g||_p$.

Proposition 2.41 (Hölder's inequality): Given $p, q, 1 \le p, q \le \infty$, with 1/p + 1/q = 1, if $f \in L^p$ and $g \in L^q$, then $f \cdot g \in L^1$ and

$$\int_0^1 |(f \cdot g)(x)| dx \le ||f||_p \cdot ||g||_q,$$

with equality for $p, q, 1 < p, q < \infty$ if and only if $\alpha |f|^p = \beta |g|^q$ a.e. for nonzero constants α and β . Proof in [16], [19]. Proof in [18] for p = q = 2.

Proposition 2.42 (Minkowski's inequality): Given $p, 1 \leq p \leq \infty$, if

 $f, g \in L^p$, then $f + g \in L^p$ and

$$||f+g||_p \le ||f||_p + ||g||_p.$$

Proof in [16], [19]. Proof in [18] for p = q = 2.

Observation 2.25: For p = q = 2, Hölder's inequality becomes **Schwarz's** inequality:

$$\int_0^1 |(f \cdot g)(x)| dx \le ||f||_2 \cdot ||g||_2 = \{ \int_0^1 |f(x)|^2 dx \}^{1/2} \cdot \{ \int_0^1 |g(x)|^2 dx \}^{1/2}.$$

Note all of the above inequalities (Hölder's, Minkowski's, Schwarz's), in which all integrations are over [0, 1], can be generalized by integrating everywhere over a measurable set instead. Proof in [19].

Definition 2.23: Given a norm $||\cdot||$ on a linear space X, we say X is a **normed linear space with norm** $||\cdot||$. We say this especially if among all the possible norms that can be defined on X, our current intent is to associate X exclusively with $||\cdot||$.

A sequence $\{x_n\}$ in a normed linear space with norm $||\cdot||$ is said to **converge** in **norm** to an element x in the space if, given $\epsilon > 0$, there is an integer N > 0 such that for $n \geq N$, then $||x_n - x|| < \epsilon$.

A sequence $\{x_n\}$ in a normed linear space with norm $||\cdot||$ is said to be a **Cauchy sequence** if, given ϵ , there is an integer N > 0 such that for $n, m \geq N$, then $||x_n - x_m|| < \epsilon$.

A normed linear space with norm $||\cdot||$ is called **complete** if every Cauchy sequence in the space converges in norm to an element of the space.

Proposition 2.43 (Riesz-Fischer): Given p, $1 \le p \le \infty$, then L^p is complete. Moreover, given $\{f_n\} \to f$ in L^p , then a subsequence of $\{f_n\}$ converges pointwise to f a.e. on [0,1]. Proof of first part in [16], [17]. It involves Proposition 2.37 (Lebesgue's Monotone Convergence Theorem), Proposition 2.39 (Fatou's Lemma), Proposition 2.40 (Lebesgue's Dominated Convergence Theorem) and ii of Proposition 2.34. Proof of last part in [17].

Proposition 2.44 (Density of simple and step functions in L^p space): Given $p, 1 \le p \le \infty$, then the subspace of simple functions on [0,1] in L^p is dense in L^p . Given $p, 1 \le p < \infty$, then the subspace of step functions on [0,1] is dense in L^p . Proof in [17].

3 Absolute Continuity and its Connections to Lebesgue Integration

Definition 3.1: Let f be a real-valued function defined on an interval [a, b]. Given $x \in [a, b]$, if for some finite number I,

$$I = \lim_{t \to x} \frac{f(t) - f(x)}{t - x}, \quad a < t < b, \quad t \neq x,$$

then f is said to be **differentiable** at x; a number f'(x) is defined and said to exist by setting f'(x) equal to I; and f' is said to exist at x. Accordingly, f' is a function associated with f, called the **derivative** of f, whose domain of definition is the set of points x at which f' exists. If f' exists at every point of a set $E \subseteq [a, b]$, we say f is differentiable on E or f' exists on E. Note that given $x \in [a, b]$, if the limit defining I above equals ∞ or $-\infty$ then the convention here is to say that f is not differentiable at x.

Proposition 3.1 (Fundamental Theorem of calculus I): Let f be Riemann integrable over an interval [a, b]. If there is a function F differentiable on [a, b] such that F' = f on [a, b], then

$$\mathcal{R} \int_{a}^{b} f(x)dx = F(b) - F(a).$$

Proof in [1] and [18].

Proposition 3.2 (Fundamental Theorem of calculus II): Let f be Riemann integrable over an interval [a, b]. Define a function F by

$$F(x) = \mathcal{R} \int_{a}^{x} f(t)dt, \quad x \in [a, b].$$

Then F is continuous on [a, b], and if f is continuous at $x \in [a, b]$, then F is differentiable at x with F'(x) = f(x). Proof in [1] and [18].

Corollary 3.1 (Differentiability of the Riemann integral - Fundamental Theorem of calculus for continuous functions):

i. If f is Riemann integrable over [a, b] and $F(x) = \mathcal{R} \int_a^x f(t) dt$, $x \in [a, b]$, then F' = f a.e. on [a, b].

ii. If f is continuous on [a, b], then there is a differentiable function F on [a, b]

such that F' = f on [a, b], and $\mathcal{R} \int_a^x f(t) dt = F(x)$. If G is any differentiable function on [a, b] such that G' = f on [a, b], then G - F = C, C a constant, and $\mathcal{R} \int_a^x f(t) dt = G(x) - G(a)$, G(a) = C.

Proof: i follows from Proposition 3.2 and Proposition 2.35 (Lebesgue's criterion). First part of ii from Proposition 3.2. Proof in [18] that G' - F' = 0 on [a, b] implies G - F = C on [a, b], C a constant. $\mathcal{R} \int_a^x f(t)dt = G(x) - G(a)$ from Proposition 3.1. Clearly G(a) = C as $\mathcal{R} \int_a^x f(t)dt = F(x)$.

Definition 3.2: Let f be a real-valued function defined on an interval [a, b]. Given $x \in [a, b]$, if for some finite number I, $I = \lim_{t \to x} f(t)$, $a \le t \le x$, then a number $f(x^-)$ called the **left-hand limit** of f at x is defined by setting $f(x^-)$ equal to I. Similarly, if for some finite number I, $I = \lim_{t \to x} f(t)$, $x \le t \le b$, then a number $f(x^+)$ called the **right-hand limit** of f at x is defined by setting $f(x^+)$ equal to I.

Observation 3.1: A function f is continuous at $x \in [a, b]$ if and only if $f(x^-)$ and $f(x^+)$ exist and $f(x) = f(x^-) = f(x^+)$.

Proposition 3.3 (Monotonic functions: continuity): Let f be a monotonic real-valued function on an interval [a, b]. Then $f(x^-)$ and $f(x^+)$ exist for every point $x \in [a, b]$, and the set of points of [a, b] at which f is discontinuous is at most countable. Proof in [18].

Corollary 3.2 (Monotonic surjective f implies f is continuous): If f is monotonic from [a, b] onto [c, d], then f is continuous on [a, b].

Proof: Assume f is discontinuous at $x \in [a, b]$. Since $f(x^-)$ and $f(x^+)$ exist from Proposition 3.3, it must be that $f(x^-) \neq f(x^+)$ so that y exists in [c, d] between $f(x^-)$ and $f(x^+)$, $y \neq f(x)$. But then y can not be in the range of f as f is monotonic, which contradicts that the range of f is all of [c, d].

Observation 3.2: A function f is described below from [0,1] into [0,1] that is strictly increasing on [0,1], discontinuous at each rational number in [0,1], continuous at each irrational number in [0,1] and at zero, f(0) = 0, f(1) = 1.

Let $\{r_n\}_{n=1}^{\infty}$ be an enumeration of the rational numbers in (0,1]. Given $x \in (0,1]$, let $R(x) = \{n : r_n \leq x\}$, and set $R(0) = \emptyset$. Define $f : [0,1] \to [0,1]$ by f(0) = 0 and

$$f(x) = \sum_{n \in R(x)} 1/2^n, \quad x \in (0, 1].$$

Given $x, x' \in [0, 1]$, x < x', then $R(x) \subseteq R(x')$, and since there is a rational number r such that x < r < x', then $R(x) \neq R(x')$. Thus, it must be that f(x) < f(x') so that f is strictly increasing on [0, 1].

Since R(1) includes every n then f(1) = 1.

Let x be a rational number in (0,1]. We show f is discontinuous at x. For some integer k > 0, $x = r_k$. Thus, $k \in R(x)$ but $k \notin R(x')$ for every $x' \in [0,1]$, x' < x. $R(x') \subseteq R(x)$ then implies $f(x) - f(x') > 1/2^k$. Thus, f is discontinuous at x (a rational number in (0,1]).

Let x be an irrational number in [0,1]. We show f is continuous at x. Given $\epsilon > 0$, choose integer N > 0 such that $1/2^N < \epsilon$, and let

$$\delta = \min_{n \le N} |x - r_n|.$$

Given $x' \in [0,1]$, x' < x, $|x-x'| < \delta$, then $R(x') \subseteq R(x)$, and if $n \in R(x) \setminus R(x')$, it must be that $x' < r_n < x$ so that $|x-r_n| < \delta$ and thus n > N. Accordingly, $f(x) - f(x') \le \sum_{n=N+1}^{\infty} 1/2^n = 1/2^N < \epsilon$. Finally, given $x' \in [0,1]$, x' > x, $|x'-x| < \delta$, then $R(x) \subseteq R(x')$, and if

Finally, given $x' \in [0,1]$, x' > x, $|x' - x| < \delta$, then $R(x) \subseteq R(x')$, and if $n \in R(x') \setminus R(x)$, it must be that $x < r_n \le x'$ so that $|x - r_n| < \delta$ and thus n > N. Accordingly, $f(x') - f(x) \le \sum_{n=N+1}^{\infty} 1/2^n = 1/2^N < \epsilon$.

Thus, f is continuous at x (an irrational number in [0,1]) and at zero by an argument similar to the one just used for the case x' > x.

Proposition 3.4 (Monotonic functions: differentiability): Let f be a monotonic real-valued function on an interval [a, b]. Then f is differentiable a.e. on [a, b], and f' is measurable. If, in addition, f is increasing on [a, b] (note $f' \geq 0$ where it exists), then f' is Lebesgue integrable over [a, b], and

$$\int_{a}^{b} f'(x)dx \le f(b) - f(a),$$

where we write $\int_a^b f'(x)dx$ instead of $\int_{[a,b]} f'(x)dx$. Proof in [3] and [16]. It involves Proposition 2.39 (Fatou's Lemma) and ii of Proposition 2.34.

Definition 3.3: Let f be a real-valued function defined on an interval [a, b]. Given a partition $P = \{x_0, x_1, \ldots, x_n\}$ of [a, b], set $\Delta f_i = f(x_i) - f(x_{i-1})$, $i = 1, \ldots, n$, and define

$$V(f; a, b) = \sup_{P} \sum_{i=1}^{n} |\Delta f_i|,$$

the supremum taken over all partitions P of [a, b]. f is said to be of **bounded variation** on [a, b] if $V(f; a, b) < \infty$.

Proposition 3.5 (Jordan decomposition): A function f is of bounded variation on [a, b] if and only if it is the difference of two monotonically increasing real-valued functions on [a, b]. Proof in [16] and [18].

Corollary 3.3: If f is of bounded variation on [a, b] then f is differentiable a.e. on [a, b], and f' is measurable and Lebesgue integrable over [a, b].

Proof: By Proposition 3.5, $f = f_1 - f_2$ on [a, b], where f_1 and f_2 are monotonically increasing on [a, b]. Thus, by Proposition 3.4, f' is measurable and exists a.e. on [a, b]. Since $|f'| \leq |f'_1| + |f'_2| = f'_1 + f'_2$ a.e. on [a, b], then again by Proposition 3.4,

$$\int_{a}^{b} |f'(x)| dx \le \int_{a}^{b} f_1'(x) dx + \int_{a}^{b} f_2'(x) dx \le f_1(b) - f_1(a) + f_2(b) - f_2(a),$$

and therefore f' is Lesbegue integrable over [a, b] (Proposition 2.31).

Definition 3.4: Given a Lebesgue integrable function f over [a, b], and a real-valued function F on [a, b] such that

$$F(x) = F(a) + \int_{a}^{x} f(t)dt, \quad x \in [a, b],$$

then the function F is said to be an **indefinite integral** of f over [a, b].

Proposition 3.6 (Indefinite integral of f zero everywhere, then f is

zero a.e.): If f is Lebesgue integrable over [a, b] and $\int_a^x f(t)dt = 0$ for all $x \in [a, b]$, then f = 0 a.e. on [a, b]. Proof in [16]. It involves Proposition 2.15.

Proposition 3.7 (Differentiability of the indefinite integral): Let f be Lebesgue integrable over an interval [a, b], and F a function such that

$$F(x) = F(a) + \int_{a}^{x} f(t)dt, \quad x \in [a, b],$$

i.e., an indefinite integral. Then F' = f a.e. on [a, b].

Proof in [16]. It involves Proposition 3.6, Corollary 2.6 (Bounded Convergence Theorem), the inequality in Proposition 3.4, and i of Proposition 2.34.

Definition 3.5: A real-valued function f defined on an interval [a, b] is said to be **absolutely continuous** on [a, b] if for every $\epsilon > 0$ there is $\delta > 0$ such that

$$\sum_{i=1}^{n} |f(x_i') - f(x_i)| < \epsilon$$

for any integer n > 0 and any disjoint collection of open intervals $(x_i, x_i') \subseteq [a, b], i = 1, ..., n$, with

$$\sum_{i=1}^{n} (x_i' - x_i) < \delta.$$

Proposition 3.8 (Absolutely continuous f is constant if f' is zero a.e.): If f is absolutely continuous on [a, b] with f' = 0 a.e. on [a, b], then f is constant on [a, b], i.e., f(x) = f(a) for all $x \in [a, b]$. Proof in [16].

Observation 3.3: Absolutely continuous \Rightarrow uniformly continuous [18] \Rightarrow continuous. Moreover, a continuous real-valued function of compact domain is uniformly continuous [18]. Accordingly, a function f called the Cantor function from [0, 1] onto [0, 1] that is continuous, thus uniformly continuous, but not absolutely continuous is described below. This function f is monotonically increasing on [0, 1] and thus differentiable a.e. on [0, 1]. Actually, f' = 0 at points not in the Cantor set (described in Observation 2.4) and does not exist at points in it. Thus, f' = 0 a.e. on [0, 1], f is not constant on [0, 1], hence f can not be absolutely continuous on [0, 1] by Proposition 3.8.

For this purpose, we note that given $x \in [0,1]$, x can be expressed in its

ternary expansion as $0.a_1a_2a_3\cdots$ so that $x=\sum_{n=1}^{\infty}a_n/3^n,\ a_n\in\{0,1,2\}$. Note x=1 is then expressed as $0.222\cdots$. Similarly, given $y\in[0,1],\ y$ can be expressed in its binary expansion as $0.b_1b_2b_3\cdots$ so that $y=\sum_{n=1}^{\infty}b_n/2^n,\ b_n\in\{0,1\}$. Note y=1 is then expressed as $0.111\cdots$.

In Observation 2.4 the Cantor set was identified as $\bigcap_{n=1}^{\infty} E_n$, where E_1 is the union of [0, 1/3] and [2/3, 1] obtained by removing the open middle third of [0,1], E_2 is the union of [0,1/9], [2/9,3/9], [6/9,7/9], [8/9,1] obtained by removing the open middle thirds of [0, 1/3] and [2/3, 1], and so on. Actually, with $E_0 = [0, 1]$, then at stage m, open intervals of the form $((3k-2)/3^m, (3k-1)/3^m), k \in \{1, \dots, 3^{m-1}\},$ are removed from E_{m-1} , if contained in it, to obtain E_m . We note that endpoints of any such intervals have two ternary expansions, and in what follows, only the expansion of any such point that contains no 1's is considered. Fixing one of these removed open intervals, we note it is the open middle third of a closed interval in E_{m-1} , all numbers in the closed interval in E_{m-1} having the same first m-1digits in their ternary expansions, none of them equal to 1. Finally, we note numbers in the removed open interval have 1 as the m^{th} digit of their ternary expansions, while numbers in the closed left and right thirds of the closed interval, closed thirds that become part of E_m , have 0 and 2, respectively, as the m^{th} digit of their ternary expansions. Thus, the Cantor set is exactly the set of numbers in [0, 1] that have no 1's in their ternary expansions.

An attempt can be made to identify the Cantor function as follows. Recalling that (1/3, 2/3) was the open middle third that was removed from [0, 1] to obtain E_1 , given x in its closure, i.e., in [1/3, 2/3], set f(x) = 1/2. Again, recalling that (1/9, 2/9) and (7/9, 8/9) were the open middle thirds that were removed from [0, 1/3] and [2/3, 1], respectively, to obtain E_2 , given x in the closure of (1/9, 2/9), i.e., in [1/9, 2/9], set f(x) = 1/4, and given x in the closure of (7/9, 8/9), i.e., in [7/9, 8/9], set f(x) = 3/4. Accordingly, f can be identified this way at each stage of the contruction of the Cantor set but this is not enough as it has not been identified for points in "the limit" that are part of the Cantor set.

The Cantor function is properly identified as follows. Given $x \in [0,1]$ with ternary expansion $0.a_1a_2a_3\cdots$ so that $x = \sum_{n=1}^{\infty} a_n/3^n$, $a_n \in \{0,1,2\}$, let N be the smallest n such that a_n equals 1. If such an n does not exist, i.e., x is

in the Cantor set, let $N = \infty$. With $b_n = a_n/2$ if n < N, $b_n = 1$ if n = N, and $b_n = 0$ if n > N, let y be the number in [0,1] with binary expansion $0.b_1b_2b_3\cdots$ so that $y = \sum_{n=1}^{\infty} b_n/2^n = \sum_{n=1}^{N} b_n/2^n$, and set f(x) = y. The function f identified this way is then called the Cantor function.

Proposition 3.9: Let f be the Cantor function. Then f is continuous, thus uniformly continuous, from [0,1] onto [0,1]. In addition, f is monotonically increasing on [0,1] and thus differentiable a.e. on [0,1]. Actually, f'=0 at points not in the Cantor set and does not exist at points in it.

Proof: Given $x_1, x_2 \in [0, 1], x_1 < x_2$, we show $f(x_1) \leq f(x_2)$. Let $0.a_1a_2a_3 \cdots, 0.c_1c_2c_3 \cdots$ be x_1, x_2 , respectively, in their ternary expansions. Let $0.b_1b_2b_3 \cdots, 0.d_1d_2d_3 \cdots$ be $f(x_1), f(x_2)$, respectively, in their binary expansions.

Let N_1 be the smallest n such that $a_n = 1$; $N_1 = \infty$ if there is no such n. Let N_2 be the smallest n such that $c_n = 1$; $N_2 = \infty$ if there is no such n. Let N' be the smallest n such that $a_n < c_n$.

If $N' > N_1$, since then $c_n = a_n$, $n = 1, ..., N_1$, and, in particular, $c_{N_1} = a_{N_1} = 1$, it must be that $N_2 = N_1$ so that $b_n = d_n$, $n = 1, ..., N_1 = N_2$, and therefore $f(x_1) = \sum_{n=1}^{N_1} b_n/2^n = \sum_{n=1}^{N_2} d_n/2^n = f(x_2)$.

Similarly if $N' > N_2$, and the case $N' = N_1 = N_2$ can not be.

If $N' = N_1$ and $N_2 > N'$, since $a_{N_1} = 1$, it must be that $c_{N_1} = 2$ so that $b_n = d_n$, $n = 1, \ldots, N_1 - 1$, $b_{N_1} = d_{N_1} = 1$. Therefore, $\sum_{n=1}^{N_1} b_n/2^n = \sum_{n=1}^{N_1} d_n/2^n$ thus $f(x_1) = \sum_{n=1}^{N_1} b_n/2^n \le \sum_{n=1}^{N_2} d_n/2^n = f(x_2)$.

If $N' = N_2$ and $N_1 > N'$, since $c_{N_2} = 1$, it must be that $a_{N_2} = 0$ so that $b_n = d_n$, $n = 1, \ldots, N_2 - 1$, $b_{N_2} = 0$, $d_{N_2} = 1$. Therefore, $\sum_{n=1}^{N_2} b_n/2^n < \sum_{n=1}^{N_2} d_n/2^n$ thus $f(x_1) = \sum_{n=1}^{N_1} b_n/2^n \le \sum_{n=1}^{N_2} d_n/2^n = f(x_2)$.

Finally, if $N_1 > N'$, $N_2 > N'$, since $a_{N'} < c_{N'}$, it must be that $a_{N'} = 0$, $c_{N'} = 2$, so that $b_n = d_n$, $n = 1, \ldots, N' - 1$, $b_{N'} = 0$, $d_{N'} = 1$. Therefore, $\sum_{n=1}^{N'} b_n/2^n < \sum_{n=1}^{N'} d_n/2^n$ thus $f(x_1) = \sum_{n=1}^{N_1} b_n/2^n \le \sum_{n=1}^{N_2} d_n/2^n = f(x_2)$. Thus, $f(x_1) \le f(x_2)$ for all cases and therefore f is monotonically increasing.

Given $y \in [0, 1]$, we show there is $x \in [0, 1]$ with f(x) = y. Let $0.b_1b_2b_3\cdots$ be y in its binary expansion. For each n, let $a_n = 2b_n$. Then for each n, a_n is either zero or two. Let x be the point in [0, 1] which in its ternary expansion is $0.a_1a_2a_3\cdots$. Then x is actually a point in the Cantor set and f(x) = y. Thus, f is onto [0, 1].

That f is continuous, thus uniformly continuous, on [0, 1], now follows from Corollary 3.2.

Finally, given $x \in [0, 1]$, if x is not in the Cantor set, we show f'(x) = 0. On the other hand, if x is in the Cantor set, we show that f'(x) does not exist. If x is not in the Cantor set, its ternary expansion must contain 1 as one of its digits. Then for some integer m, m > 0, the m^{th} digit of the expansion equals 1 with no previous digits equal to 1. It follows that x must be contained in an open interval of the form $((3k-2)/3^m, (3k-1)/3^m)$, $k \in \{1, \ldots, 3^{m-1}\}$. Thus, it suffices to show f is constant on any such interval. But this follows immediately since all numbers in the interval have the same first m digits in their ternary expansions with 1 as the mth digit and no previous digits equal to 1.

On the other hand, if x is in the Cantor set, its ternary expansion consists of 0's and 2's. Given an integer n > 0, define x_n to be the number in [0,1] whose ternary expansion is exactly that of x except at its n^{th} digit. Its n^{th} digit is 0 if the n^{th} digit of x is 2, and it is 2 if that of x is 0. It follows then that $|x_n - x| = 2/3^n$ so that $x_n \to x$. Also, $|f(x_n) - f(x)| = 1/2^n$. Thus, since f is monotonically increasing, $(f(x_n) - f(x))/(x_n - x) = |f(x_n) - f(x)|/|x_n - x| = (1/2)(3/2)^n \to \infty$ so that f'(x) does not exist.

Thus, f' does not exist at points in the Cantor set and equals zero otherwise.

Corollary 3.4: The Cantor function is not absolutely continuous on [0, 1].

Proof: Let f be the Cantor function and assume it is absolutely continuous on [0,1]. By Proposition 3.9, f'=0 a.e. on [0,1]. Thus, by Proposition 3.8, f must be constant on [0,1], i.e., f(x)=f(0) for all $x \in [0,1]$. But this is a contradiction as for instance f(0)=0 and f(1)=1. Thus, f is not absolutely continuous on [0,1].

Observation 3.4: For the sake of completeness, we analyze the nondifferentiability of the Cantor function f on the Cantor set.

Let x_L and x_R be points in the Cantor set that are the left and right endpoints of an open interval I removed at the m^{th} stage of the construction of the Cantor set. It must then be that in their ternary expansions, x_L

can be expressed as $0.a_1a_2\cdots a_{m-1}0\overline{2}$ (a bar on a digit means the digit is infinitely repeated), and x_R as $0.a_1a_2\cdots a_{m-1}2\overline{0}$, the set $\{a_1, a_2, \ldots, a_{m-1}\}$ with elements equal to 0 or 2 if m > 1, empty if m = 1. Given x in the open interval I, it must be that in its ternary expansion the m^{th} digit is 1, and if m > 1, then the first m - 1 digits are also $a_1, a_2, \ldots, a_{m-1}$. Define for each integer n, n > 0, a number x_L^n in I that in its ternary expansion the first m digits are as described above, and all other digits are 0 except the $(m+n)^{th}$ digit which is 1. Then $\lim_{n\to\infty} x_L^n = x_L$ and $f(x_L^n) = f(x_L)$ for all n so that $\lim_{n\to\infty} (f(x_L^n) - f(x_L))/(x_L^n - x_L) = 0$. Since for any sequence $\{x_n\}$ in I, with $\lim_{n\to\infty} x_n = x_L$, then $f(x_n) = f(x_L)$ for all n, it follows that $(f(t) - f(x_L))/(t - x_L)$ has a limit as $t \to x_L$ from the right side of x_L and it is zero. Similarly, define for each integer n, n > 0, a number x_R^n in I that in its ternary expansion the first m digits are as described above, and all other digits are 0 except the $(m+1)^{th},\ldots,(m+n)^{th}$ digits which are 2. Then $\lim_{n\to\infty}x_R^n=x_R$ and $f(x_R^n)=f(x_R)$ for all n so that $\lim_{n\to\infty} (f(x_R^n) - f(x_R))/(x_R^n - x_R) = 0$. Since for any sequence $\{x_n\}$ in I, with $\lim_{n\to\infty} x_n = x_R$, then $f(x_n) = f(x_R)$ for all n, it follows that $(f(t)-f(x_R))/(t-x_R)$ has a limit as $t\to x_R$ from the left side of x_R and it is zero.

In the proof of Proposition 3.9, given any x in the Cantor set, a sequence $\{x_n\}$ of points in the Cantor set was identifed with $x_n \to x$ and $(f(x_n) - f(x))/(x_n - x) \to \infty$. We show that with x_L , x_R as above, then $(f(t) - f(x_L))/(t-x_L)$ has a limit as $t \to x_L$ from the left side of x_L and it is ∞ , and $(f(t)-f(x_R))/(t-x_R)$ has a limit as $t \to x_R$ from the right side of x_R and it is also ∞ . Actually, we only show it for x_R as the proof for x_L can be similarly accomplished. Accordingly, let $n \ge m$ be an integer such that the ternary expansions of t and x_R coincide in the first n digits and the $(n+1)^{th}$ digit of t is 1 or 2. As mentioned above, all digits of x_R after the m^{th} digit equal 0. Thus, $f(t) - f(x_R) \ge 1/2^{n+1}$ and $t - x_R \le 2/3^{n+1} + 2/3^{n+2} + \cdots = 1/3^n$, so that

$$\lim_{t \to x_R^+} \frac{f(t) - f(x_R)}{t - x_R} \ge \lim_{n \to \infty} (1/2)(3/2)^n = \infty.$$

Finally, it is of interest to note that if x is any point in the Cantor set, then at stage m of the contruction of the Cantor set, x is in a closed interval $[a_m, b_m] \subset [0, 1]$, where if $0.x_1x_2\cdots$ is x in its ternary expansion, then $0.x_1\cdots x_m \overline{0}$ is a_m in its ternary expansion, and $0.x_1\cdots x_m \overline{2}$ is b_m in its ternary expansion. It follows that $b_m - a_m = \sum_{i=m+1}^{\infty} 2/3^i = 1/3^m$ and $f(b_m) - 1/3^m$

 $f(a_m) = \sum_{i=m+1}^{\infty} 1/2^i = 1/2^m$. Thus, with $a_m \leq x \leq b_m$, we have

$$\lim_{m \to \infty} \frac{f(b_m) - f(a_m)}{b_m - a_m} = \lim_{m \to \infty} (3/2)^m = \infty.$$

If $x = x_L$, x_L as above, then for some m, $x = b_m$ and $\lim_{m \to \infty} (f(x) - f(a_m))/(x - a_m) = \infty$, as expected. Similarly, if $x = x_R$, x_R as above, then for some m, $x = a_m$ and $\lim_{m \to \infty} (f(x) - f(b_m))/(x - b_m) = \infty$, also as expected. As for a point x in the Cantor set that is not an endpoint of an open interval removed at some stage of the construction of the Cantor set, it is easier to see that $\lim_{m \to \infty} (f(x) - f(a_m))/(x - a_m) = \infty$, and $\lim_{m \to \infty} (f(x) - f(b_m))/(x - b_m) = \infty$, by looking at the ternary expansions of x, a_m and b_m . Actually, we only show it for $\{a_m\}$ as the proof for $\{b_m\}$ can be similarly accomplished. Accordingly, let m > 0 be an integer such that the $(m+1)^{th}$ digit of x in its ternary expansion, i.e., x_{m+1} , equals 2. As mentioned above, the ternary expansions of x and a_m coincide in the first m digits and all digits of a_m after the mth digit equal 0. Thus, $f(x) - f(a_m) \ge 1/2^{m+1}$ and $x - a_m \le 2/3^{m+1} + 2/3^{m+2} + \cdots = 1/3^m$, so that

$$\lim_{m \to \infty} \frac{f(x) - f(a_m)}{x - a_m} \ge \lim_{n \to \infty} (1/2)(3/2)^m = \infty.$$

Note that $\lim_{m\to\infty} (f(x) - f(a_m))/(x - a_m) = \lim_{m\to\infty} (f(x) - f(b_m))/(x - b_m) = \infty$ does not imply that $\lim_{t\to x} (f(x) - f(t))/(x - t) = \infty$.

Observation 3.5: A function on [a, b] that is a finite linear combination of absolutely continuous functions on [a, b] is absolutely continuous on [a, b]. The proof is analogous to the proof that a finite linear combination of continuous functions is continuous. In addition, the product of two absolutely continuous functions on [a, b] is absolutely continuous on [a, b].

Proposition 3.10 (Absolutely continuous f implies f is of bounded variation): If f is absolutely continuous on [a, b], then f is of bounded variation on [a, b]. Proof in [16].

Corollary 3.5: If f is absolutely continuous on [a, b] then f is differentiable a.e. on [a, b], and f' is measurable and Lebesgue integrable over [a, b].

Proposition 3.11 (Absolute continuity of the indefinite integral): If F is an indefinite integral over [a, b], then F is absolutely continuous on [a, b].

Proof: Assume (Definition 3.4) $F(x) = F(a) + \int_a^x f(t)dt$, $x \in [a,b]$, f is Lebesgue integrable over [a,b]. By Proposition 2.31, |f| is Lebesgue integrable over [a,b]. Then by Proposition 2.38, given $\epsilon > 0$ there is $\delta > 0$ such that for each measurable set $A \subseteq [a,b]$ with $m(A) < \delta$, then $\int_A |f(t)|dt < \epsilon$. Given integer n > 0 and disjoint open intervals $(x_i, x_i') \subseteq [a,b]$, $i = 1, \ldots, n$, with $\sum_{i=1}^n (x_i' - x_i) < \delta$, let $A = \bigcup_{i=1}^n (x_i, x_i')$. Then A is measurable and $m(A) < \delta$. Thus, $\int_A |f(t)|dt < \epsilon$. Accordingly, then

$$\sum_{i=1}^{n} |F(x_i') - F(x_i)| = \sum_{i=1}^{n} |\int_{a}^{x_i'} f(t)dt - \int_{a}^{x_i} f(t)dt| = \sum_{i=1}^{n} |\int_{x_i}^{x_i'} f(t)dt|$$

$$\leq \sum_{i=1}^{n} \int_{x_i}^{x_i'} |f(t)|dt = \int_{A} |f(t)|dt < \epsilon.$$

Thus, F is absolutely continuous on [a, b].

Proposition 3.12 (Equivalent conditions for an absolutely continuous function): Given a real-valued function f on [a, b], then the following three conditions are equivalent:

i. f is absolutely continuous on [a, b].

ii. There exists a Lebesgue integrable function g over [a, b] such that $f(x) = f(a) + \int_a^x g(t)dt$, $x \in [a, b]$.

(Note that then by Proposition 3.7, f' = g a.e. on [a, b]).

iii. f' exists a.e. on [a, b] and is Lebesgue integrable over [a, b], and $f(x) = f(a) + \int_a^x f'(t)dt$, $x \in [a, b]$.

Proof:

iii \Rightarrow ii:

Take g = f'.

 $ii \Rightarrow i$:

This is Proposition 3.11.

 $i \Rightarrow iii$:

By Corollary 3.5, f' exists a.e. on [a, b] and is Lebesgue integrable over [a, b]. Let $G(x) = \int_a^x f'(t)dt$, $x \in [a, b]$. Then G is an indefinite integral of f' over [a, b] and by Proposition 3.11, is absolutely continuous on [a, b], and so is the function h = f - G by Observation 3.5.

By Proposition 3.7, G' = f' a.e. on [a, b]. Thus h' = 0 a.e. on [a, b], and by Proposition 3.8, h is constant on [a, b], i.e., f - G = C on [a, b] for some constant C, i.e., $f(x) - \int_a^x f'(t)dt = C$, $x \in [a, b]$.

Since C = f(a), it then follows that $f(x) = f(a) + \int_a^x f'(t)dt$, $x \in [a, b]$.

Corollary 3.6 (Fundamental Theorem of Lebesgue integral calculus): Given real-valued functions f, g on [a, b], f absolutely continuous on [a, b] and f' = g a.e. on [a, b], then $f(x) = f(a) + \int_a^x g(t)dt$, $x \in [a, b]$.

Proposition 3.13 (Fundamental Theorem of Lebesgue integral calculus (Alternate form)): Given a real-valued function f on [a, b], if f'(x) exists for every $x \in [a, b]$, and f' is Lebesgue integrable over [a, b], then $f(x) = f(a) + \int_a^x f'(t)dt$, $x \in [a, b]$. Proof in [19].

Corollary 3.7: Given a real-valued function f on [a, b], if f' exists everywhere on [a, b] and f' is Lebesgue integrable over [a, b], then f is absolutely continuous on [a, b].

Proof: From Proposition 3.13 and then Proposition 3.12.

Proposition 3.14 (Change of variable for Riemann integral): Given a strictly monotonic continuous function u from an interval [a, b] onto an interval [c, d] (u(a) = c, u(b) = d if u is strictly increasing, u(a) = d, u(b) = c if it is strictly decreasing), with u' Riemann integrable over [a, b], and a real-valued Riemann integrable function f over [c, d], then

$$\mathcal{R} \int_{u(a)}^{u(b)} f(x) dx = \mathcal{R} \int_{a}^{b} f(u(t))u'(t) dt,$$

with $\mathcal{R} \int_{u(a)}^{u(b)} f(x) dx = -\mathcal{R} \int_{c}^{d} f(x) dx$ if u is decreasing. Proof in [1] and [18]. Note that by Proposition 3.4, u' exists a.e. on [a, b].

Proposition 3.15 (Substitution rule for Riemann integral): Given a function u from an interval [a, b] into an interval I such that u'(x) exists for every $x \in [a, b]$ with u' Riemann integrable over [a, b], and a real-valued

continuous function f on I, then

$$\mathcal{R} \int_{u(a)}^{u(b)} f(x) dx = \mathcal{R} \int_{a}^{b} f(u(t))u'(t) dt,$$

with
$$\mathcal{R} \int_{u(a)}^{u(b)} f(x) dx = -\mathcal{R} \int_{u(b)}^{u(a)} f(x) dx$$
 if $u(b) < u(a)$.

Proof: By Proposition 3.2 (Fundamental Theorem of calculus II), with e the left endpoint of I, the function F defined by $F(x) = \mathcal{R} \int_e^x f(t)dt$, $x \in I$, satisfies F'(x) = f(x) for every $x \in I$ since f is continuous on I. From the definition of F, given c, $d \in I$, c not necessarily less than d, then $F(d) - F(c) = \mathcal{R} \int_c^d f(x)dx$. In particular,

$$F(u(b)) - F(u(a)) = \mathcal{R} \int_{u(a)}^{u(b)} f(x) dx.$$

Since u is differentiable on [a,b] and F is differentiable on I, the composite function $F \circ u$ is differentiable on [a,b] and by the usual chain rule of calculus, $(F \circ u)'(t) = F'(u(t))u'(t) = f(u(t))u'(t)$, for every $t \in [a,b]$. Thus, since f(u(t))u'(t) is clearly Riemann integrable over [a,b], by Proposition 3.1 (Fundamental Theorem of calculus I), it must be that

$$\mathcal{R} \int_a^b f(u(t))u'(t)dt = \mathcal{R} \int_a^b (F \circ u)'(t)dt = (F \circ u)(b) - (F \circ u)(a)$$
$$= F(u(b)) - F(u(a)) = \mathcal{R} \int_{u(a)}^{u(b)} f(x)dx.$$

Proposition 3.16 (Substitution rule for Lebesgue integral): Given an absolutely continuous function u from an interval [a, b] into an interval I, and a real-valued continuous function f on I, then

$$\int_{u(a)}^{u(b)} f(x)dx = \int_{a}^{b} f(u(t))u'(t)dt,$$

with
$$\int_{u(a)}^{u(b)} f(x)dx = -\int_{u(b)}^{u(a)} f(x)dx = -\int_{[u(b),u(a)]} f(x)dx$$
 if $u(b) < u(a)$.

Proof: By Proposition 3.2 (Fundamental Theorem of calculus II), with e the left endpoint of I, the function F defined by $F(x) = \mathcal{R} \int_e^x f(t)dt$, $x \in I$, satisfies F'(x) = f(x) for every $x \in I$ since f is continuous on I. From the

definition of F, given $c, d \in I$, c not necessarily less than d, then $F(d) - F(c) = \mathcal{R} \int_c^d f(x) dx$. In particular,

$$F(u(b)) - F(u(a)) = \mathcal{R} \int_{u(a)}^{u(b)} f(x) dx = \int_{u(a)}^{u(b)} f(x) dx,$$

where the last equation is by Proposition 2.33 (Riemann implies Lebesgue). Since u is differentiable a.e. on [a,b] and F is differentiable on I, the composite function $F \circ u$ is differentiable a.e. on [a,b]. Indeed it is differentiable exactly at the points where u is differentiable. Thus, by the usual chain rule of calculus, $(F \circ u)'(t) = F'(u(t))u'(t) = f(u(t))u'(t)$, for $t \in [a,b]$ at which u' exists.

Finally, we show $F \circ u$ is absolutely continuous on [a,b] in order to use Corollary 3.6 (Fundamental Theorem of Lebesgue integral calculus) with $F \circ u$ as the absolutely continuous function in the hypothesis of the corollary. For this purpose, since f is continuous, assume |f| < M on [a,b], for some M > 0. Given $\epsilon > 0$, let $\delta > 0$ correspond to ϵ/M in the definition of the absolute continuity of u. Given integer n > 0 and disjoint open intervals $(t_i, t_i') \subseteq [a, b]$, $i = 1, \ldots, n$, with $\sum_{i=1}^n (t_i' - t_i) < \delta$, then

$$\sum_{i=1}^{n} |F \circ u(t'_{i}) - F \circ u(t_{i})| = \sum_{i=1}^{n} |\mathcal{R} \int_{u(t_{i})}^{u(t'_{i})} f(x) dx|$$

$$< \sum_{i=1}^{n} |u(t_{i}) - u(t'_{i})| M = M \sum_{i=1}^{n} |u(t_{i}) - u(t'_{i})|$$

$$< M\epsilon/M = \epsilon.$$

Thus, $F \circ u$ is absolutely continuous and by Corollary 3.6, it must be that

$$\int_{a}^{b} f(u(t))u'(t)dt = \int_{a}^{b} (F \circ u)'(t)dt = (F \circ u)(b) - (F \circ u)(a)$$
$$= F(u(b)) - F(u(a)) = \int_{u(a)}^{u(b)} f(x)dx.$$

Observation 3.6: Note that in the proof of Proposition 3.16 above, while proving that $F \circ u$ is absolutely continuous on [a, b], we have actually proved that if u, [a, b], I, e are as given there and f is Lebesgue integrable over I and bounded on I, and the function F is defined by $F(x) = \int_e^x f(t)dt$, $x \in I$, then $F \circ u$ is absolutely continuous on [a, b]. At the end of this section, results are presented for carrying out a change of variable in Lebesgue integrals, useful

in shape analysis.

Proposition 3.17 (Saks' inequality [20]): Given a real-valued function f on [a,b], a real number $r \geq 0$, and $E \subseteq [a,b]$ such that $|f'(x)| \leq r$ for each $x \in E$, then

$$m^*(f(E)) \le r \, m^*(E).$$

Proof: Given $\epsilon > 0$, for every integer n > 0, and any $y \in (a, b)$, define

$$E_n = \{x \in E : \text{ if } 0 < |x - y| < 1/n, \text{ then } |f(x) - f(y)| < (r + \epsilon)|x - y|\}.$$

Since $E_n \subseteq E_{n+1}$ for all n and $\bigcup_{n=1}^{\infty} E_n = E$, then by 2 of Proposition 2.13, $m^*(E) = \lim_{n \to \infty} m^*(E_n)$. Similarly, since $f(E_n) \subseteq f(E_{n+1})$ for all n and $\bigcup_{n=1}^{\infty} f(E_n) = f(E)$, then again by 2 of Proposition 2.13,

$$m^*(f(E)) = \lim_{n \to \infty} m^*(f(E_n)).$$

Given integer n > 0, let $\{I_k\}$ be a countable collection of open intervals covering E_n , i.e., $E_n \subseteq \bigcup_{k=1}^{\infty} I_k$, with

$$\sum_{k=1}^{\infty} m(I_k) < m^*(E_n) + \epsilon.$$

Note $\{I_k\}$ can be chosen so that $m(I_k) < 1/n$ for each k. Then, for each k, given $x, x' \in E_n \cap I_k$, $x \neq x'$, from the definition of E_n , since |x - x'| < 1/n, it must be that

$$|f(x) - f(x')| < (r + \epsilon) |x - x'| < (r + \epsilon) m(I_k).$$

Thus,

$$m^*(f(E_n \cap I_k)) \le \sup_{x,x' \in E_n \cap I_k} |f(x) - f(x')| \le (r + \epsilon) m(I_k).$$

Since $E_n = \bigcup_{k=1}^{\infty} (E_n \cap I_k)$, then $f(E_n) = \bigcup_{k=1}^{\infty} f(E_n \cap I_k)$, therefore,

$$m^*(f(E_n)) \leq \sum_{k=1}^{\infty} m^*(f(E_n \cap I_k)) \leq \sum_{k=1}^{\infty} (r+\epsilon) m(I_k)$$
$$= (r+\epsilon) \sum_{k=1}^{\infty} m(I_k) < (r+\epsilon) (m^*(E_n) + \epsilon).$$

Thus, since as established above $m^*(E) = \lim_{n\to\infty} m^*(E_n)$ and $m^*(f(E)) = \lim_{n\to\infty} m^*(f(E_n))$, it must be that

$$m^*(f(E)) = \lim_{n \to \infty} m^*(f(E_n))$$

$$\leq \lim_{n \to \infty} (r + \epsilon) (m^*(E_n) + \epsilon)$$

$$= (r + \epsilon) (m^*(E) + \epsilon).$$

Hence, since $\epsilon > 0$ is arbitrary, it must be that $m^*(f(E)) \leq r m^*(E)$.

Corollary 3.8: Given a real-valued function f on [a, b], let E be a subset of [a, b] on which f' = 0. Then $m(f(E)) = m^*(f(E)) = 0$.

Proof: By Proposition 3.17, $m^*(f(E)) \leq 0 \cdot m^*(E) = 0$. Thus, m(f(E)) = 0.

Corollary 3.9: Given a real-valued function f on [a, b], and $E \subseteq [a, b]$ with m(E) = 0, such that f' exists on E, then $m(f(E)) = m^*(f(E)) = 0$.

Proof: Without any loss of generality assume $E \subseteq (a, b)$. Given $\epsilon > 0$, let $\{I_k\}$ be a countable collection of open intervals covering E, i.e., $E \subseteq \bigcup_{k=1}^{\infty} I_k$, with $\sum_{k=1}^{\infty} m(I_k) < \epsilon$, $I_k \subseteq (a, b)$ for each k.

Given an integer $l \geq 0$, and an integer k > 0, let

$$E_l = \{x \in E : f'(x) \text{ exists and } |f'(x)| \le l\}$$

and

$$E_{lk} = \{x \in I_k : f'(x) \text{ exists and } |f'(x)| \le l\}.$$

Note $E_l \subseteq \bigcup_{k=1}^{\infty} E_{lk}$ so that $f(E_l) \subseteq \bigcup_{k=1}^{\infty} f(E_{lk})$.

By Proposition 3.17, $m^*(f(E_{lk})) \leq l m^*(E_{lk})$ for each k, and therefore,

$$m^*(f(E_l)) \le \sum_{k=1}^{\infty} m^*(f(E_{lk})) \le \sum_{k=1}^{\infty} l \, m^*(E_{lk}) \le \sum_{k=1}^{\infty} l \, m(I_k) < l \, \epsilon.$$

Since $\epsilon > 0$ is arbitrary, then $m^*(f(E_l)) = 0$.

Finally, note $f(E_{l+1}) \supseteq f(E_l)$ for each l, and $f(E) = \bigcup_{l=0}^{\infty} f(E_l)$.

Thus, by 2 of Proposition 2.13, $m^*(f(E)) = \lim_{l \to \infty} m^*(f(E_l)) = 0$.

Corollary 3.10 (Saks' Theorem [20]): Given a real-valued function f

on [a, b], and $E \subseteq [a, b]$ such that f' exists on E, if f' = 0 a.e. on E, then m(f(E)) = 0.

Proof: Let E_1 , E_2 be subsets of E, $E = E_1 \cup E_2$, f' = 0 on E_1 and $m(E_2) = 0$. By Corollary 3.8, $m(f(E_1)) = 0$. By Corollary 3.9, $m(f(E_2)) = 0$. Thus, $m(f(E)) \le m(f(E_1)) + m(f(E_2)) = 0$.

Observation 3.7: Let f be the Cantor function and C the Cantor set. Then f'=0 a.e. on [0,1] and m(C)=0. Since f([0,1])=[0,1], by Saks' Theorem (Corollary 3.10), it must be that f is not differentiable at certain points in [0,1], and since f(C)=[0,1], by Corollary 3.9, it must be that f is not differentiable at certain points in C. Of course we know f is not differentiable at any point in C and f'=0 on $[0,1]\setminus C$ so that by Corollary 3.8, $m(f([0,1]\setminus C))=0$ which makes sense as $f([0,1]\setminus C)$ is countable.

The following proposition is the converse of Saks' Theorem (Corollary 3.10): m(f(E)) = 0 implies f' = 0 a.e. on E. Here again it is assumed f' exists everywhere on E. However, almost everywhere (a.e.) will suffice.

Proposition 3.18 (Serrin-Varberg's Theorem [22]): Given f, a real-valued function on [a, b], and $E \subseteq [a, b]$ such that f' exists on E, if m(f(E)) = 0, then f' = 0 a.e. on E.

Proof: Let $B = \{x \in E : |f'(x)| > 0\}$, and for every integer n > 0, and any $y \in (a, b)$, define

$$B_n = \{x \in B : \text{if } 0 < |x - y| < 1/n, \text{ then } |f(x) - f(y)| \ge |x - y|/n\}.$$

Clearly, we need to show m(B) = 0, and since $B = \bigcup_{n=1}^{\infty} B_n$, then it suffices to show $m(B_n) = 0$ for each n. However, since each B_n can be covered by a countable collection of intervals, each interval of length less than 1/n, it then suffices to show that if I is any interval of length less than 1/n and $A = I \cap B_n$, then m(A) = 0.

For this purpose, given $\epsilon > 0$, since $A \subseteq E$ so that m(f(A)) = 0, let $\{I_k\}$ be a countable collection of open intervals covering f(A), i.e., $f(A) \subseteq \bigcup_{k=1}^{\infty} I_k$, with $\sum_{k=1}^{\infty} m(I_k) < \epsilon$. In addition, let $A_k = f^{-1}(f(A) \cap I_k)$. Then $A = \bigcup_{k=1}^{\infty} A_k$, and since for each k, $A_k \subseteq A = I \cap B_n$, given $x, x' \in A_k$, $x \neq x'$, then |x - x'| < 1/n, and it must be that

$$|x - x'| \le n|f(x) - f(x')| < n m(I_k).$$

Thus,

$$m^*(A_k) \le \sup_{x,x' \in A_k} |x - x'| \le n \, m(I_k),$$

and then

$$m^*(A) \le \sum_{k=1}^{\infty} m^*(A_k) \le \sum_{k=1}^{\infty} n \, m(I_k) = n \sum_{k=1}^{\infty} m(I_k) < n\epsilon.$$

Hence, since $\epsilon > 0$ is arbitrary, it must be that m(A) = 0.

Corollary 3.11: Given a real-valued function f on [a, b], and $E \subseteq [a, b]$ such that f' exists on E, if f is constant on E, then f' = 0 a.e. on E.

Corollary 3.12 (Serrin-Varberg's Theorem (Alternate form)): Given a real-valued function f on [a, b], and $E \subseteq [a, b]$ such that f' exists a.e. on E, if m(f(E)) = 0, then f' = 0 a.e. on E. In particular, if f is of bounded variation on [a, b], and $E \subseteq [a, b]$ with m(f(E)) = 0, then f' = 0 a.e. on E.

Proof: Let E_1 , E_2 be subsets of E, $E = E_1 \cup E_2$, f' exists on E_1 and $m(E_2) = 0$. Since $m(f(E_1)) \leq m(f(E)) = 0$, then by Proposition 3.18, f' = 0 a.e. on E_1 . Thus, since $m(E_2) = 0$, then f' = 0 a.e. on E. If f is of bounded variation on [a, b], then by Corollary 3.3, f is differentiable a.e. on [a, b] and therefore on any subset E of [a, b].

Proposition 3.19 (Measurability of the derivative of a measurable function): Let f be a real-valued measurable function on [a, b], and E a measurable subset of [a, b]. If f' exists on E, then f' is a measurable function on E. Proof in [26].

Proposition 3.20: Let f be a real-valued measurable function on [a, b], and E a measurable subset of [a, b]. If f'(x) exists for each $x \in E$, then

$$m^*(f(E)) \le \int_E |f'(x)| dx.$$

Proof: Given $\epsilon > 0$, for each integer n > 0, define

$$E_n = \{ x \in E : (n-1) \epsilon \le |f'(x)| < n \epsilon \}.$$

Clearly, the E_n 's are pairwise disjoint and $E = \bigcup_{n=1}^{\infty} E_n$ so that $f(E) = \bigcup_{n=1}^{\infty} f(E_n)$. By Proposition 3.19, f' is measurable on E. Hence, each set E_n must be measurable. Since f'(x) exists for every $x \in E_n$, by Proposition 3.17, $m^*(f(E_n)) \leq n\epsilon m(E_n)$ for each n, and given an integer N > 0, it must be that $\sum_{n=1}^{N} (n-1)\epsilon m(E_n) \leq \int_{E} |f'(x)| dx$ by the definition of the Lebesgue integral, so that $\sum_{n=1}^{\infty} (n-1)\epsilon m(E_n) \leq \int_{E} |f'(x)| dx$. Thus,

$$m^*(f(E)) \le \sum_{n=1}^{\infty} m^*(f(E_n)) \le \sum_{n=1}^{\infty} n\epsilon \, m(E_n) = \sum_{n=1}^{\infty} ((n-1)\epsilon + \epsilon) m(E_n)$$

= $\sum_{n=1}^{\infty} (n-1)\epsilon \, m(E_n) + \sum_{n=1}^{\infty} \epsilon \, m(E_n) \le \int_E |f'(x)| dx + \epsilon \, m(E),$

where, in the last step, the countable additivity of m on measurable sets is used. Since ϵ is arbitrary and $m(E) < \infty$, then $m^*(f(E)) \le \int_E |f'(x)| dx$.

Proposition 3.21 (Absolutely continuous f maps zero-measure sets to zero-measure sets [20] - Absolutely continuous f maps measurable sets to measurable sets): Let f be an absolutely continuous function on [a,b]. If $E \subseteq [a,b]$ with m(E)=0, then m(f(E))=0. In addition, given any measurable subset E of [a,b], then f(E) is measurable.

Proof: Without any loss of generality assume $E \subseteq (a, b)$. Given $\epsilon > 0$, let $\delta > 0$ correspond to ϵ in the definition of the absolute continuity of f. Since m(E) = 0, then by Proposition 2.1, there is a collection $\{I_k\} = \{(a_k, b_k)\}$ of nonoverlapping open intervals covering E, i.e., $E \subseteq \bigcup_{k=1}^{\infty} I_k$, with $\sum_{k=1}^{\infty} (b_k - a_k) = \sum_{k=1}^{\infty} m(I_k) < \delta$, $I_k \subseteq (a, b)$ for each k. For each k, since f is continuous, let c_k and d_k be points in $[a_k, b_k]$ where f attains its minimum and maximum, respectively. Assuming without any loss of generality that $c_k < d_k$, then $\{(c_k, d_k)\}$ is a collection of nonoverlapping open intervals, and since again f is continuous, by the intermediate value theorem [18], it follows that

$$f(E) \subseteq f(\bigcup_{k=1}^{\infty} (a_k, b_k)) = \bigcup_{k=1}^{\infty} f((a_k, b_k)) \subseteq \bigcup_{k=1}^{\infty} f([c_k, d_k]).$$

Thus,

$$m^*(f(E)) \le \sum_{k=1}^{\infty} m(f([c_k, d_k])) = \sum_{k=1}^{\infty} (f(d_k) - f(c_k)).$$

Finally, given an integer N > 0, then it must be that

$$\sum_{k=1}^{N} (d_k - c_k) < \sum_{k=1}^{\infty} (d_k - c_k) \le \sum_{k=1}^{\infty} (b_k - a_k) < \delta$$

so that $\sum_{k=1}^{N} (f(d_k) - f(c_k)) < \epsilon$. N arbitrary then implies $m^*(f(E)) \le \sum_{k=1}^{\infty} (f(d_k) - f(c_k)) \le \epsilon$. Thus, $m^*(f(E)) = 0$ since ϵ is arbitrary.

Assume now E is a measurable subset of [a, b].

By v of Proposition 2.15, there is a set F that is the union of a countable collection of closed sets, $F \subseteq E$ with $m^*(E \setminus F) = 0$, i.e., $E = K \cup (\bigcup_{n=1}^{\infty} F_n)$, where $m^*(K) = 0$, $F = \bigcup_{n=1}^{\infty} F_n$, and F_n is closed for each n, thus compact (Proposition 2.3). Note then that $f(E) = f(K \cup (\bigcup_{n=1}^{\infty} F_n)) = f(K) \cup (\bigcup_{n=1}^{\infty} f(F_n))$. Since m(K) = 0, then m(f(K)) = 0 as just proved above. Thus, f(K) is measurable. Also since f is continuous and F_n is compact for each n, it must be that $f(F_n)$ is compact for each n [18] and thus measurable (Proposition 2.14). It then follows that f(E) is the union of a countable collection of measurable sets and therefore it must be measurable.

Proposition 3.22 (Banach-Zarecki Theorem): Let f be a real-valued function on [a, b]. Then f is absolutely continuous on [a, b] if and only if it satisfies the following three conditions:

- i. f is continuous on [a, b].
- ii. f is of bounded variation on [a, b].
- iii. f maps sets of measure zero to sets of measure zero.

Proof: The necessity was established in Observation 3.3, Proposition 3.10, and Proposition 3.21. For the sufficiency, assume f satisfies all three conditions. Given $[c, d] \subseteq [a, b]$, we show

$$|f(d) - f(c)| \le \int_c^d |f'(x)| dx.$$

By condition ii, f is of bounded variation on [a, b], so that by Corollary 3.3, f is differentiable a.e. on [a, b] and therefore on [c, d]. Accordingly, let E_1 , E_2 be subsets of [c, d], $[c, d] = E_1 \cup E_2$, f' exists on E_1 and $m(E_2) = 0$. By condition iii, it then must be that $m(f(E_2)) = 0$.

Assume without any loss of generality that f(c) < f(d). By condition i, f

is continuous on [a, b], so that by the intermediate value theorem [18], given y, f(c) < y < f(d), there must be x, c < x < d, with f(x) = y. Thus, $[f(c), f(d)] \subseteq f([c, d])$, and since f is measurable on [a, b] (f is continuous on [a, b]) and E_1 is measurable ($E_1 = [c, d] \setminus E_2$), by Proposition 3.20, we get

$$|f(d) - f(c)| \leq m(f([c, d])) = m(f(E_1) \cup f(E_2))$$

$$\leq m^*(f(E_1)) + m(f(E_2)) = m^*(f(E_1)) + 0$$

$$= m^*(f(E_1)) \leq \int_{E_1} |f'(x)| dx = \int_c^d |f'(x)| dx.$$

By Corollary 3.3, since f is of bounded variation, it must be that f' is integrable over [a,b] and so is |f'| by Proposition 2.31. Given $\epsilon > 0$, by Proposition 2.38, there is $\delta > 0$ such that if A is a measurable set with $m(A) < \delta$, then $\int_A |f'(x)| dx < \epsilon$. Accordingly, for any integer n > 0 and any disjoint collection of open intervals $(x_i, x_i') \subseteq [a, b], i = 1, \ldots, n$, with $\sum_{i=1}^n (x_i' - x_i) < \delta$, let $A = \bigcup_{i=1}^n (x_i' - x_i)$. Since $m(A) < \delta$, then

$$\sum_{i=1}^{n} |f(x_i') - f(x_i)| \le \sum_{i=1}^{n} \int_{x_i}^{x_i'} |f'(x)| dx = \int_A |f'(x)| dx < \epsilon.$$

Thus, f is absolutely continuous.

Proposition 3.23 (Inverse function theorem): Let f be a strictly monotonic continuous function on [a, b]. Then I = f([a, b]) is a closed interval with endpoints f(a), f(b), and f^{-1} , the inverse function of f, exists on I, and is strictly monotonic and continuous on I. Given $x_0 \in [a, b]$ such that f is differentiable at x_0 with $f'(x_0) \neq 0$, then f^{-1} is differentiable at $y_0 = f(x_0)$ with

$$(f^{-1})'(y_0) = 1/f'(x_0).$$

Proof: Without any loss of generality, assume f is increasing on [a, b]. Since f is strictly increasing and continuous, f is one-to-one and by the intermediate value theorem [18], its range is I = [f(a), f(b)] = f([a, b]). Thus, f^{-1} exists on I and is strictly increasing from I onto [a, b]. By Corollary 3.2, f^{-1} is continuous on I. With $y_0 = f(x_0)$, y = f(x), by the continuity of f^{-1} , if $y \to y_0$, it must be that $x \to x_0$. Thus,

$$\frac{f^{-1}(y) - f^{-1}(y_0)}{y - y_0} = \frac{x - x_0}{f(x) - f(x_0)} \to 1/f'(x_0)$$

as $y \to y_0$, since f is differentiable at x_0 , and $f'(x_0) \neq 0$. Hence, $(f^{-1})'(y_0)$ exists and equals $1/f'(x_0)$.

Proposition 3.24 (Zarecki's criterion for an absolutely continuous inverse [5]): Let f be a monotonic continuous function on [a, b]. Then I = f([a, b]) is a closed interval with endpoints f(a), f(b), and f^{-1} exists and is absolutely continuous on I if and only if $\{x : f'(x) = 0\}$ has measure zero. Whenever f^{-1} is absolutely continuous on the closed interval I, then

$$(f^{-1})' = 1/(f'(f^{-1}))$$
 a.e. on I .

Proof: Without any loss of generality, assume f is increasing on [a, b]. If f^{-1} exists or if $m^*(\{x : f'(x) = 0\}) = 0$, then f is strictly increasing. Thus, assume f is strictly increasing. By Proposition 3.23, I is closed, I = [f(a), f(b)], and f^{-1} exists on I and is strictly increasing and continuous on I.

Assume $\{x: f'(x) = 0\}$ has measure zero. As already established, f^{-1} is continuous on I, and since it is increasing, it is of bounded variation on I. Thus, by Proposition 3.22, it suffices to show that f^{-1} maps sets of measure zero to sets of measure zero. For this purpose, let $E \subseteq I$ be of measure zero, and $F = f^{-1}(E)$ so that f(F) = E. Since f is increasing, it is of bounded variation on [a, b] as well, and by Corollary 3.12, f' = 0 a.e. on F. Accordingly, let F_1, F_2 be subsets of $F, F = F_1 \cup F_2, f' = 0$ on F_1 and $m(F_2) = 0$. Since $F_1 \subseteq \{x: f'(x) = 0\}$, then $m(F_1) = 0$. Thus, m(F) = 0.

Assume now f^{-1} is absolutely continuous on I. By Corollary 3.8, since f' = 0 on $E = \{x : f'(x) = 0\}$, then m(f(E)) = 0. Thus, by Proposition 3.21, $m(E) = m(f^{-1}(f(E))) = 0$.

Finally, whenever f^{-1} is absolutely continuous on I, define F_1 , F_2 , F_3 , disjoint subsets of [a,b], $[a,b] = F_1 \cup F_2 \cup F_3$, as follows. $F_1 = \{x: f'(x) \neq 0\}$, $F_2 = \{x: f'(x) = 0\}$, $F_3 = \{x: f'(x) \text{ does not exist}\}$. Since f is of bounded variation on [a,b], f is differentiable a.e. on [a,b], thus, $m(F_3) = 0$. Also, since f^{-1} is absolutely continuous, then $m(F_2) = 0$ as just proved above. Hence, since by Proposition 3.23, for each $x \in F_1$, f^{-1} is differentiable at y = f(x) with $(f^{-1})'(y) = 1/f'(x)$, then $(f^{-1})' = 1/(f'(f^{-1}))$ a.e. on I.

Proposition 3.25 (Composition of absolutely continuous functions): Let g be an absolutely continuous monotonic function from an interval [a, b] into an interval [c, d], and let f be an absolutely continuous function on [c, d]. Then the function $h = f \circ g$ is absolutely continuous on [a, b].

Proof: Let $\epsilon > 0$ be given. It follows easily that since f is absolutely continuous, then there is $\rho > 0$ such that for any integer n > 0 and for any nonempty subset A of $\{1, \ldots, n\}$ it must be that $\sum_{i \in A} |f(y_i') - f(y_i)| < \epsilon$ for disjoint open intervals $(y_i, y_i') \subseteq [c, d]$, $i \in A$, with $\sum_{i \in A} (y_i' - y_i) < \rho$. For ρ as just described, since g is also absolutely continuous, then there is $\delta > 0$ such that for any integer n > 0 it must be that $\sum_{i=1}^{n} |g(x_i') - g(x_i)| < \rho$ for disjoint open intervals $(x_i, x_i') \subseteq [a, b]$, $i = 1, \ldots, n$, with $\sum_{i=1}^{n} (x_i' - x_i) < \delta$. Accordingly, for any integer n > 0 let $(x_i, x_i') \subseteq [a, b]$, $i = 1, \ldots, n$, be any collection of disjoint open intervals with $\sum_{i=1}^{n} (x_i' - x_i) < \delta$. Setting $A = \{i : 1 \le i \le n, g(x_i') \ne g(x_i)\}$, if $A \ne \emptyset$, then the collection of open intervals $(g(x_i), g(x_i'))$, $i \in A$, if g is increasing; $(g(x_i'), g(x_i))$, $i \in A$, if g is decreasing; must be pairwise disjoint by the monoticity of g with $\sum_{i \in A} |g(x_i') - g(x_i)| < \rho$. Thus, if $A \ne \emptyset$, it must be that $S_A = \sum_{i \in A} |f(g(x_i')) - f(g(x_i))| < \epsilon$. Setting $S_A = 0$ if $A = \emptyset$, and since $|f(g(x_i')) - f(g(x_i))| = 0$ for $i \notin A$, then

$$\sum_{i=1}^{n} |f(g(x_i')) - f(g(x_i))| = S_A + 0 = S_A < \epsilon.$$

Thus, $h = f \circ g$ is absolutely continuous on [a, b].

Proposition 3.26 (Chain rule [22]): Given real-valued functions F, f on [c,d], F'=f a.e. on [c,d], and a function $u:[a,b]\to [c,d]$, u and $F\circ u$ differentiable a.e. on [a,b], if F maps zero-measure sets to zero-measure sets, then

$$(F \circ u)' = (f \circ u)u'$$
 a.e. on $[a, b]$.

Proof: Let $A = \{x \in [c,d] : F'(x) = f(x)\}$, $B = [c,d] \setminus A$, and $C = \{t \in [a,b] : u(t) \in B\}$. Clearly, mB = 0. Letting $D = [a,b] \setminus C$, since u is differentiable a.e. on [a,b], then it is differentiable a.e. on D. Since $u(D) \subseteq A$ and F is differentiable on A, the composite function $F \circ u$ is differentiable a.e. on D. Indeed it is differentiable exactly at the points in D where u is differentiable. Thus, by the usual chain rule of calculus, $(F \circ u)'(t) = F'(u(t))u'(t) = f(u(t))u'(t)$, for $t \in D$ at which u' exists, i.e., $(F \circ u)' = (f \circ u)u'$ a.e. on D.

Note that if mC = 0, then the proof is complete.

Thus, assuming $mC \neq 0$, we show $(F \circ u)' = (f \circ u)u'$ a.e. on C. Note $f \circ u$ is defined on C. Since $u(C) \subseteq B$, then m(u(C)) = mB = 0, and since u' exists

a.e. on C, then by Corollary 3.12, u'=0 a.e. on C so that $(f \circ u)u'=0$ a.e. on C. In addition, since F maps zero-measure sets to zero-measure sets, then m(F(u(C)))=0, and since $(F \circ u)'$ exists a.e. on C, again by Corollary 3.12, $(F \circ u)'=0$ a.e. on C. Thus, $(F \circ u)'=0=(f \circ u)u'$ a.e. on C.

Observation 3.8: With B the subset of [c,d] of measure zero on which $F' \neq I$ f, and $C = \{t \in [a, b] : u(t) \in B\}$, then for the case $mC \neq 0$ in the proof of Proposition 3.26 above it was proved that u'=0 a.e. on C, and since $f\circ u$ is defined on C, then $(f \circ u)u' = 0$ a.e. on C as well. Since it was also proved that $(F \circ u)' = 0$ a.e. on C, then it was concluded that $(F \circ u)' = 0 = (f \circ u)u'$ a.e. on C. However, it can happen that when using the chain rule as described in Proposition 3.26 above and in Corollary 3.13 below, although F' = f on $[c,d] \setminus B$, f may not be defined everywhere on B. Thus, $f \circ u$ may not be defined on C as required in the proof of Proposition 3.26 above when $mC \neq 0$. However, what matters here is that both u' and $(F \circ u)'$ are zero a.e. on C. Therefore, assuming $mC \neq 0$, when computing $(F \circ u)'$ with the chain rule as suggested in Proposition 3.26 above and in Corollary 3.13 below, if $(F \circ u)'$ is set to zero at any point in [a,b] at which u' is zero (whether or not $f \circ u$ is defined there), and computed or left undefined according to the chain rule elsewhere, then $(F \circ u)'$ so obtained will be correct a.e. on [a, b]. Accordingly, assuming $mC \neq 0$, one should keep in mind that if $(F \circ u)'$ is not computed as just suggested, so that $(F \circ u)'$ might be left undefined at points where $f \circ u$ is not defined although u' is zero, one could end up with $(F \circ u)'$ not defined on a set of nonzero measure in [a, b]. Actually, instead of computing $(F \circ u)'$ as just suggested, we do something simpler. Since, as mentioned above, what matters here is that both u' and $(F \circ u)'$ are zero a.e. on C, without any loss of generality, we simply set f equal to 1 at points in B where it is not defined and proceed with the chain rule to compute $(F \circ u)'$, as $f \circ u$ is then defined on C so that $(f \circ u)u'$ is zero at points in C where u' is zero, thus zero a.e. on C. More precisely, we define a new function \hat{f} on [c,d] by setting \hat{f} equal to f at points in [c, d] where f exists, and to 1 where it does not. In what follows, we will refer to f as f extended to all of [c,d]. This function is then defined everywhere in [c, d], equals f a.e. on [c, d], and takes the place of f in the chain rule although it is still called f there. Finally, note that above when we say anything about computing $(F \circ u)'$ with the chain rule, it is not $(F \circ u)'$ that is necessarily computed but a function that happens to be equal to $(F \circ u)'$ a.e. on [a, b].

Corollary 3.13 (Chain rule (Alternate form) [22]): Given an absolutely continuous function F on [c, d], and a real-valued function f on [c, d], F' = f a.e. on [c, d], if $u : [a, b] \to [c, d]$ is a function such that u and $F \circ u$ are differentiable a.e. on [a, b], then

$$(F \circ u)' = (f \circ u)u'$$
 a.e. on $[a, b]$.

Proof: From Proposition 3.26 and Proposition 3.21.

Proposition 3.27 (Change of variable for Lebesgue integral [22]): Given a function f, Lebesgue integrable over [c, d], and a function $u : [a, b] \rightarrow [c, d]$, differentiable a.e. on [a, b], then the following two conditions are equivalent, where $F(x) = \int_c^x f(t)dt$, $x \in [c, d]$:

i. $F \circ u$ is absolutely continuous on [a, b].

ii. $(f \circ u)u'$ is Lebesgue integrable over [a, b] and for all $\alpha, \beta \in [a, b]$ it must be that

$$\int_{u(\alpha)}^{u(\beta)} f(x)dx = \int_{\alpha}^{\beta} f(u(t))u'(t)dt,$$

with $\int_{u(\alpha)}^{u(\beta)} f(x)dx = -\int_{u(\beta)}^{u(\alpha)} f(x)dx = -\int_{[u(\beta),u(\alpha)]} f(x)dx$ if $u(\beta) < u(\alpha)$, and $\int_{\alpha}^{\beta} f(u(t))u'(t)dt = -\int_{\beta}^{\alpha} f(u(t))u'(t)dt = -\int_{[\beta,\alpha]} f(u(t))u'(t)dt$ if $\beta < \alpha$.

Proof:

 $i \Rightarrow ii$:

Since F is absolutely continuous on [c,d] (Proposition 3.11), F'=f a.e. on [c,d] (Proposition 3.7), u is differentiable a.e. on [a,b], and $F \circ u$, being absolutely continuous on [a,b], must be differentiable a.e. on [a,b] (Corollary 3.5), then by Corollary 3.13 (chain rule), $(F \circ u)' = (f \circ u)u'$ a.e. on [a,b] (here and in the corollaries that follow, without any loss of generality, f is interpreted as f extended to all of [c,d] (Observation 3.8 about the chain rule)). Note, by Corollary 3.5, since $F \circ u$ is absolutely continuous on [a,b], then $(f \circ u)u'$ is Lebesgue integrable over [a,b], and by Corollary 3.6 (Fundamental Theorem of Lebesgue integral calculus), applied to the absolutely continuous function $F \circ u$, for all $\alpha, \beta \in [a,b]$ it must be that

$$\int_{\alpha}^{\beta} f(u(t))u'(t)dt = \int_{\alpha}^{\beta} (F \circ u)'(t)dt = (F \circ u)(\beta) - (F \circ u)(\alpha)$$
$$= F(u(\beta)) - F(u(\alpha)) = \int_{u(\alpha)}^{u(\beta)} f(x)dx.$$

 $ii \Rightarrow i$:

Since $(f \circ u)u'$ is Lebesgue integrable over [a,b], and, in particular, for $x \in [a,b]$

$$F(u(x)) - F(u(a)) = \int_{u(a)}^{u(x)} f(s)ds = \int_{a}^{x} f(u(t))u'(t)dt,$$

by Proposition 3.12, $F \circ u = F(u)$ must be absolutely continuous on [a, b].

Corollary 3.14 (Change of variable for Lebesgue integral (Alternate form I) [22]): Given a function f, Lebesgue integrable over [c,d], and a function $u:[a,b] \to [c,d]$, monotonic and absolutely continuous on [a,b], then $(f \circ u)u'$ is Lebesgue integrable over [a,b] and for all $\alpha, \beta \in [a,b]$ it must be that

$$\int_{u(\alpha)}^{u(\beta)} f(x)dx = \int_{\alpha}^{\beta} f(u(t))u'(t)dt.$$

Proof: Since u is clearly differentiable a.e. on [a, b], and F, $F(x) = \int_c^x f(t)dt$, $x \in [c, d]$, is absolutely continuous so that the composition $F \circ u$ is absolutely continuous on [a, b] by Proposition 3.25, then by Proposition 3.27, $(f \circ u)u'$ is Lebesgue integrable over [a, b] and for all α , $\beta \in [a, b]$ it must be that

$$\int_{u(\alpha)}^{u(\beta)} f(x)dx = \int_{\alpha}^{\beta} f(u(t))u'(t)dt.$$

Corollary 3.15 (Change of variable for Lebesgue integral (Alternate form II) [22]): Given a function f, bounded and measurable on [c, d], and a function $u : [a, b] \to [c, d]$, absolutely continuous on [a, b], then $(f \circ u)u'$ is Lebesgue integrable over [a, b] and for all $\alpha, \beta \in [a, b]$ it must be that

$$\int_{u(\alpha)}^{u(\beta)} f(x)dx = \int_{\alpha}^{\beta} f(u(t))u'(t)dt.$$

Proof: By Proposition 2.32, f is Lebesgue integrable over [c,d]. Since u is clearly differentiable a.e. on [a,b], and by Observation 3.6, with $F(x) = \int_c^x f(t)dt$, $x \in [c,d]$, it must be that $F \circ u$ is absolutely continuous on [a,b], then by Proposition 3.27, $(f \circ u)u'$ is Lebesgue integrable over [a,b] and for all $\alpha, \beta \in [a,b]$ it must be that

$$\int_{u(\alpha)}^{u(\beta)} f(x)dx = \int_{\alpha}^{\beta} f(u(t))u'(t)dt.$$

Corollary 3.16 (Change of variable for Lebesgue integral over a measurable set [9]:) Given A, a measurable subset of [0,1], and a function $\gamma:[0,1]\to[0,1]$, γ absolutely continuous on [0,1], $\dot{\gamma}>0$ a.e. on [0,1], $\gamma(0)=0$, $\gamma(1)=1$, then γ^{-1} exists and is absolutely continuous on [0,1], and $\tilde{A}=\gamma^{-1}(A)$ is a measurable subset of [0,1]. Accordingly, given a function f, Lebesgue integrable over [0,1], then $(f\circ\gamma)\dot{\gamma}$ is Lebesgue integrable over \tilde{A} and

 $\int_{A} f(x)dx = \int_{\tilde{A}} f(\gamma(t))\dot{\gamma}(t)dt.$

Proof: Clearly γ is strictly increasing and thus γ^{-1} exists and is absolutely continuous on [0,1] by Proposition 3.24. By Proposition 3.21, $\tilde{A} = \gamma^{-1}(A)$ is then a measurable subset of [0,1].

Define $I_A: [0,1] \to \mathbf{R}$ by $I_A(t) = 1$ if $t \in A$, $I_A(t) = 0$ if $t \in [0,1] \setminus A$, and $I_{\tilde{A}}: [0,1] \to \mathbf{R}$ by $I_{\tilde{A}}(t) = 1$ if $t \in \tilde{A}$, $I_{\tilde{A}}(t) = 0$ if $t \in [0,1] \setminus \tilde{A}$. Note $I_{\tilde{A}} = I_A \circ \gamma$.

Also note $I_A \cdot f$ is Lebesgue integrable over [0, 1], since it equals f on A and 0 on $[0, 1] \setminus A$. It follows then by Corollary 3.14 that

$$\int_{0}^{1} I_{A}(x) f(x) dx = \int_{\gamma(0)}^{\gamma(1)} I_{A}(x) f(x) dx = \int_{0}^{1} I_{A}(\gamma(t)) f(\gamma(t)) \dot{\gamma}(t) dt,$$

i.e.,

$$\int_{A} f(x)dx = \int_{0}^{1} I_{\tilde{A}}(t)f(\gamma(t))\dot{\gamma}(t)dt = \int_{\tilde{A}} f(\gamma(t))\dot{\gamma}(t)dt.$$

4 Functional Data and Shape Analysis and its Connections to Lebesgue Integration and Absolute Continuity

Observation 4.1: In what follows, we review some important aspects of functional data and shape analysis of the type in [23], while at the same time pointing out its dependence on Lesbesgue integration, absolute continuity and the connections between them. As in [23] where absolutely continuous functions on [0, 1] are generalized to functions of range $\mathbf{R}^{\mathbf{n}}$, \mathbf{R} the set of real numbers, n a positive integer, we consider absolutely continuous functions on [0, 1] but restrict ourselves to those with range in $\mathbf{R}^1 = \mathbf{R}$. We denote by AC[0, 1] the set of such functions. With two absolutely continuous functions on [0, 1] considered equal if they differ by a constant, we note that the

principal goal in [23] is essentially that of presenting tools for analyzing the shapes of absolutely continuous functions and defining a distance metric for computing a distance between any two of them. Specializing to AC[0,1], a crucial aspect of the approach in [23] is then that of identifying a bijective correspondence between functions in AC[0,1] and functions in $L^2[0,1]$, and taking advantage of this correspondence to compute easily the distance between functions in AC[0,1] (the definition of this distance in terms of the so-called Fisher-Rao metric appears below) by computing the distance between the corresponding functions in $L^2[0,1]$. Actually, as mentioned above, the goal of this approach is not so much that of computing the distance between functions in AC[0,1] but of computing the distance between their shapes. More precisely, in this approach, each function in AC[0,1] is associated with its unique (a.e. on [0, 1]) so-called square-root slope function (SRSF) in $L^2[0,1]$, and vice versa, and a distance metric is defined for computing the distance between the shapes of any two functions in AC[0,1]in terms of the L^2 distances between SRSF's of reparametrizations of the two functions. This distance, although computed in $L^2[0,1]$, is a measure of how much one of the absolutely continuous functions must be reparametrized (with so-called warping functions) to align as much as possible with the other one. Since given two functions in AC[0,1] that are not equal, the possibility exists that one function can be reparametrized to align exactly with the other one, i.e., become exactly the other one, the set of reparametrization functions or warping functions then induces a quotient space of $L^2[0,1]$. Accordingly, a distance metric is defined in [23] that computes the distance between any two equivalence classes in the quotient space of $L^2[0,1]$ by the set of warping functions, thus computing the distance between the shapes of the two corresponding functions in AC[0,1].

Definition 4.1 (SRSF representation of functions [23]): Given $f \in AC[0,1]$, the real-valued square-root slope function (SRSF) q of f, is defined for each $t \in [0,1]$ at which f' exists by

$$q(t) = \operatorname{sign}(f'(t))\sqrt{|f'(t)|}.$$

Observation 4.2: By Corollary 3.5, f' exists a.e. on [0,1]. Thus q is defined a.e. on [0,1]. We note that q, the SRSF of f, is the 1-dimensional version of the **square-root velocity function (SRVF)** q of an absolutely continuous function f, $f:[0,1] \to \mathbb{R}^n$, defined as follows. Let $F:\mathbb{R}^n \to \mathbb{R}^n$ be the

continuous map defined by $F(v) = v/\sqrt{|v|}$ if $|v| \neq 0$, F(v) = 0 otherwise, $|\cdot|$ the Euclidean norm. Then the SRVF q of f, $q : [0,1] \to \mathbf{R}^n$, is defined for each $t \in [0,1]$ at which f' exists by

$$q(t) = F(f'(t)) = f'(t)/\sqrt{|f'(t)|}$$

if $|f'(t)| \neq 0$, 0 (in \mathbb{R}^n) otherwise.

See [10], [23] for a rigorous development of the SRVF.

Proposition 4.1 (Square integrability of SRSF [23]): Given $f \in AC[0,1]$, the SRSF q of f is square-integrable over [0,1], i.e., $q \in L^2[0,1]$, with $\int_0^1 |q(t)|^2 dt = \int_0^1 |f'(t)| dt$, i.e., $||q||_2^2 = \text{length of } f$.

Proof: By Corollary 3.5, f' is measurable and Lebesgue integrable over [0, 1]. Note $h(t) = |q(t)|^2 = |\operatorname{sign}(f'(t))\sqrt{|f'(t)|}|^2 = |f'(t)|$ for each $t \in [0, 1]$ at which f' exists. Thus h is measurable and Lebesgue integrable over [0, 1] (Proposition 2.31) so that $q \in L^2[0, 1]$ and $\int_0^1 |q(t)|^2 dt = \int_0^1 |f'(t)| dt$.

Observation 4.3: As noted in Observation 2.21, a Lebesgue integrable function over a measurable set E can be undefined on a subset of E of measure zero. That can be the case above for functions f' and $|q|^2$ with E = [0, 1] which we know exist a.e. on [0, 1]. However, without any loss of generality, in the spirit of Observation 3.8 about the chain rule, f' and q will eventually be interpreted below as f' and q extended to all of [0, 1]. Finally, note the length of f above is measured in \mathbf{R} , a 1-dimensional space.

Proposition 4.2 (Reconstruction of an absolutely continuous function from its SRSF [23]): Given $f \in AC[0,1]$, let q be the SRSF of f. Then for each $t \in [0,1]$ it must be that $f(t) = f(0) + \int_0^t q(s)|q(s)|ds$.

Proof: Note that for each $s \in [0, 1]$ at which f' exists, then

$$q(s)|q(s)| = \operatorname{sign}(f'(s))\sqrt{|f'(s)|}|\operatorname{sign}(f'(s))\sqrt{|f'(s)|}|$$

= $\operatorname{sign}(f'(s))\sqrt{|f'(s)|}\sqrt{|f'(s)|}$
= $\operatorname{sign}(f'(s))|f'(s)| = f'(s).$

By Proposition 3.12, for each $t \in [0,1]$ it must be that $f(t) = f(0) + \int_0^t f'(s) ds$. Thus, for each $t \in [0,1]$ it must be that $f(t) = f(0) + \int_0^t q(s)|q(s)|ds$. **Proposition 4.3** ($L^2[0,1]$'s equivalence with the set of all SRSF's [23]): Let q be in $L^2[0,1]$ and C any real number. Let h(t) = q(t)|q(t)| for each $t \in [0,1]$ at which q exists. Then h is defined a.e. on [0,1], h is measurable and Lebesgue integrable over [0,1], and the function f defined for each $t \in [0,1]$ by $f(t) = C + \int_0^t h(s)ds$ is absolutely continuous on [0,1] with q equal to the SRSF of f a.e. on [0,1].

Proof: As q is defined a.e. on [0,1], then so is h. In addition, since $|h|=|q|^2$ is measurable and Lebesgue integrable over [0,1], then so is h (Proposition 2.31). By Proposition 3.12, f is then absolutely continuous on [0,1]. Let \hat{q} be the SRSF of f. Then for each $t \in [0,1]$ at which f' exists it must be that $\hat{q}(t) = \text{sign}(f'(t))\sqrt{|f'(t)|}$ and \hat{q} is defined a.e. on [0,1]. Since by Proposition 3.7, f' = h a.e. on [0,1], then it must also be that $\hat{q}(t) = \text{sign}(h(t))\sqrt{|h(t)|}$ for almost all $t \in [0,1]$. But $\text{sign}(h(t))\sqrt{|h(t)|} = \text{sign}(q(t)|q(t)|)\sqrt{q(t)^2} = \text{sign}(q(t))|q(t)| = q(t)$ for each $t \in [0,1]$ at which q exists and therefore for almost all $t \in [0,1]$. Thus, $q = \hat{q}$ a.e. on [0,1].

Definition 4.2: Under the composition of functions operation, the **admissible class** Γ **of warping functions** is a semigroup of functions (not every element has an inverse) defined by

$$\Gamma = \{ \gamma | \gamma : [0,1] \to [0,1], \ \gamma \text{ absolutely continuous on } [0,1], \\ \dot{\gamma} \ge 0 \text{ a.e. on } [0,1], \ \gamma(0) = 0, \ \gamma(1) = 1 \},$$

where $\dot{\gamma}$ is the derivative of γ .

The group Γ_0 of invertible warping functions, $\Gamma_0 \subset \Gamma$, is defined by

$$\Gamma_0 = \{ \gamma | \gamma \in \Gamma, \ \dot{\gamma} > 0 \text{ a.e. on } [0, 1] \}.$$

Observation 4.4: The functions in Γ and Γ_0 play an important role in functional data and shape analysis as they are used to reparametrize an absolutely continuous function by warping its domain during the process of aligning its shape to the shape of another absolutely continuous function. As demonstrated in [10], [23], it is Γ and Γ_0 that induce a quotient space

of $L^2[0,1]$ with a well-defined distance metric. More on this below. We note, given $\gamma \in \Gamma$, since γ is continuous, $\gamma(0) = 0$, $\gamma(1) = 1$, $\gamma : [0,1] \to [0,1]$, then by the intermediate value theorem [18], $\gamma([0,1]) = [0,1]$. We note, given $\gamma \in \Gamma_0$, γ is strictly increasing, thus has an inverse γ^{-1} which is also in Γ_0 as $\gamma^{-1}(0) = 0$, $\gamma^{-1}(1) = 1$, γ^{-1} is absolutely continuous on [0,1] by Proposition 3.24, and $(\gamma^{-1})' > 0$ a.e. on [0,1], also from Proposition 3.24, since γ (the inverse of γ^{-1}) is absolutely continuous on [0,1].

Note, given γ , $\tilde{\gamma} \in \Gamma$, then $\gamma \circ \tilde{\gamma}$ is absolutely continuous on [0,1] by Proposition 3.25 and clearly $(\gamma \circ \tilde{\gamma})(0) = 0$, $(\gamma \circ \tilde{\gamma})(1) = 1$. Accordingly, if γ , $\tilde{\gamma} \in \Gamma_0$, in order to conclude that $\gamma \circ \tilde{\gamma} \in \Gamma_0$, we prove $(\gamma \circ \tilde{\gamma})' > 0$ a.e. on [0,1]. For this purpose let $A = \{t \in [0,1] : \dot{\gamma}(t) > 0\}$, $B = [0,1] \setminus A$, $C = \tilde{\gamma}^{-1}(B)$. Clearly, mB = 0 and since $\tilde{\gamma}^{-1}$ is absolutely continuous on [0,1] as just proved above, then mC = 0 by Proposition 3.21. Let $D = [0,1] \setminus C$. Accordingly, we only need to prove $(\gamma \circ \tilde{\gamma})' > 0$ a.e. on D. Clearly, $\dot{\tilde{\gamma}}$ exists (and is positive) a.e. on D. Since $\tilde{\gamma}(D) \subseteq A$, and $\dot{\gamma}$ exists (and is positive) on A, then $(\gamma \circ \tilde{\gamma})'$ exists a.e. on D. Indeed it exists exactly at the points in D where $\dot{\tilde{\gamma}}$ exists. Thus, by the usual chain rule of calculus, $(\gamma \circ \tilde{\gamma})'(t) = \dot{\gamma}(\tilde{\gamma}(t))\dot{\tilde{\gamma}}(t)$ for $t \in D$ at which $\dot{\tilde{\gamma}}$ exists. Since as mentioned above $\dot{\gamma}(\tilde{\gamma}(t))$ exists and is positive for all $t \in D$, and $\dot{\tilde{\gamma}}$ exists and is positive a.e. on D, then $(\gamma \circ \tilde{\gamma})' = (\dot{\gamma} \circ \tilde{\gamma})\dot{\tilde{\gamma}} > 0$ a.e. on D.

Finally, given $\gamma, \ \tilde{\gamma} \in \Gamma$, we show $\gamma \circ \tilde{\gamma} \in \Gamma$. It suffices to show $(\gamma \circ \tilde{\gamma})' \geq 0$ a.e. on [0,1]. For this purpose let $A = \{t \in [0,1] : \dot{\gamma}(t) \geq 0\}$, $B = [0,1] \setminus A$, $C = \{t \in [a,b] : \tilde{\gamma}(t) \in B\}$. Clearly, mB = 0. Letting $G = [a,b] \setminus C$, then we can show that $(\gamma \circ \tilde{\gamma})' \geq 0$ a.e. on G, in the same manner we showed above for $\gamma, \ \tilde{\gamma} \in \Gamma_0$ that $(\gamma \circ \tilde{\gamma})' > 0$ a.e. on G. Thus, in order to complete the proof we show $(\gamma \circ \tilde{\gamma})' = 0$ a.e. on G. Since $\tilde{\gamma}(C) \subseteq B$, then $m(\tilde{\gamma}(C)) = mB = 0$, and since γ is absolutely continuous on [0,1], then $m(\gamma(\tilde{\gamma}(C))) = 0$ by Proposition 3.21. Note $(\gamma \circ \tilde{\gamma})'$ exists a.e. on G as $\gamma \circ \tilde{\gamma}$ is absolutely continuous on [0,1]. That $(\gamma \circ \tilde{\gamma})' = 0$ a.e. on G now follows follows from Corollary 3.12.

Proposition 4.4 (SRSF of a warped absolutely continuous function [23]): Given $f \in AC[0,1]$ and $\gamma \in \Gamma$, then $f \circ \gamma \in AC[0,1]$ and $(f \circ \gamma)(0) = f(0)$. With q the SRSF of f, without any loss of generality, in the spirit of Observation 3.8 about the chain rule, interpreting f' and q as f' and q extended to all of [0,1], it then follows that the SRSF of $f \circ \gamma$ equals $(q \circ \gamma)\sqrt{\gamma}$ a.e. on [0,1].

Proof: Clearly, $(f \circ \gamma)(0) = f(\gamma(0)) = f(0)$. That $f \circ \gamma \in AC[0,1]$ follows directly from Proposition 3.25. Accordingly, it then follows from Corollary 3.13 (chain rule) that $(f \circ \gamma)' = (f' \circ \gamma)\dot{\gamma}$ a.e. on [0,1]. Thus, the SRSF of $f \circ \gamma$ which is defined for each $t \in [0,1]$ at which $(f \circ \gamma)'$ exists as $\operatorname{sign}((f \circ \gamma)'(t))\sqrt{|(f \circ \gamma)'(t)|}$ must equal

$$sign((f' \circ \gamma)(t)\dot{\gamma}(t))\sqrt{|(f' \circ \gamma)(t)\dot{\gamma}(t)|} = sign(f'(\gamma(t)))\sqrt{|f'(\gamma(t))|}\sqrt{\dot{\gamma}(t)}$$
$$= q(\gamma(t))\sqrt{\dot{\gamma}(t)}$$

for almost all $t \in [0, 1]$.

Observation 4.5: Note the SRSF q of f is defined (Definition 4.1) for each $t \in [0,1]$ at which f' exists. However, although the SRSF of $f \circ \gamma$ equals $(q \circ \gamma)\sqrt{\dot{\gamma}}$ a.e. on [0,1], it is not necessarily true that the SRSF of $f \circ \gamma$ exists at each $t \in [0,1]$ for which $q(\gamma(t))\sqrt{\dot{\gamma}(t)}$ exists or if it exists it is equal to it.

Observation 4.6: An isometry is a distance-preserving transformation between two metric spaces. Here we describe in a nonrigorous manner isometries (and differentials as well) in the context of differential and Riemannian geometry. Let M, N be spaces and let φ be a mapping from M into N, with M, N, φ satisfying certain smoothness properties (in the language of differential geometry, M and N are smooth or differentiable manifolds which are spaces that locally resemble Euclidean, Hilbert or Banach spaces, and φ is differentiable (generalized to smooth manifolds); here and in what follows, differentiability in the context of smooth manifolds is assumed to be of all orders). Given $\epsilon > 0$, $p \in M$, assume $\alpha : (-\epsilon, \epsilon) \to M$ can be defined, $\alpha(0) = p$, α a curve in M, differentiable (generalized to smooth manifolds) so that $\alpha'(0)$ makes sense. Then $\alpha'(0)$ is considered to be a tangent vector to the curve α at t=0, and to M at p. Accordingly, the set of all tangent vectors to M at p is called the **tangent space** of M at p and denoted by T_pM . Similarly, given $q \in N$, the set of all tangent vectors to N at q is called the tangent space of N at q and denoted by T_qN . With α as above, define $\beta:(-\epsilon,\epsilon)\to N$ by $\beta=\varphi\circ\alpha$. Then $\beta(0)=\varphi(p),\,\beta$ is a curve in N, and we assume it is differentiable (generalized to smooth manifolds) so that $\beta'(0)$ makes sense and is then in $T_{\varphi(p)}N$. The mapping $d\varphi_p: T_pM \to T_{\varphi(p)}N$ given by $d\varphi_p(\alpha'(0)) = \beta'(0)$ is a linear mapping called the differential of φ at p. Finally, assume there is a correspondence on M,

smooth in some manner (see below), that associates to each point p in M an inner product $<,>_p$ on the tangent space T_pM . Similarly, assume there is a correspondence on N, smooth in the same manner, that associates to each point q in N an inner product $<,>_q$ on the tangent space T_qN . If φ as above is bijective and satisfies certain smoothness properties (in the language of differential geometry, φ is a **diffeomorphism**: φ is bijective, and φ and φ^{-1} are differentiable (generalized to smooth manifolds)), then φ is called an **isometry** if $< u, v>_p = < d\varphi_p(u), d\varphi_p(v)>_{\varphi(p)}$, for all $p \in M$ and all $u, v \in T_pM$, where the inner product on the left is the one on T_pM and the inner product on the right is the one on $T_{\varphi(p)}N$. On the other hand, if φ is differentiable and satisfies $< u, v>_p = < d\varphi_p(u), d\varphi_p(v)>_{\varphi(p)}$, for all $p \in M$ and all $u, v \in T_pM$, but is not a diffeomorphism, then φ is called a **semi-isometry**.

In the language of Riemannian geometry, the smooth correspondence above between points in a smooth manifold and inner products on tangent spaces of the space at the points is called a **Riemannian metric** or **structure**. Smooth manifolds equipped with such a structure are called **Riemannian manifolds**. Using the Riemannian structure, the length of a curve in a Riemannian manifold M is computed as follows. Given $\alpha:[0,1]\to M$, a curve or path in M, differentiable (generalized to smooth manifolds) on [0,1] so that $\alpha'(t)$ makes sense for $t\in[0,1]$ and is then in the tangent space $T_{\alpha(t)}M$, the length $L(\alpha)$ of the the path α is then given by

$$L(\alpha) = \int_0^1 \sqrt{\langle \alpha'(t), \alpha'(t) \rangle_{\alpha(t)}} dt,$$

where $\langle , \rangle_{\alpha(t)}$ is the inner product on the tangent space $T_{\alpha(t)}M$, and the smoothness of the Riemannian structure is such that $\sqrt{\langle \alpha'(t), \alpha'(t) \rangle_{\alpha(t)}}$, $t \in [0, 1]$, is integrable over [0, 1] so that $L(\alpha)$ is well defined. In addition, given $p, q \in M$, the **geodesic distance** d(p, q) between them is defined as the minimum of the lengths of all paths α in M, $\alpha : [0, 1] \to M$, differentiable (generalized to smooth manifolds) with $\alpha(0) = p$ and $\alpha(1) = q$, i.e.,

$$d(p,q) = \min_{\alpha:[0,1]\to M,\,\alpha \text{ differentiable on } [0,1],\,\alpha(0)=p,\,\alpha(1)=q} L(\alpha).$$

If a path α exists such that d(p,q) achieves its minimum at α , then α is called a **geodesic** in M between p and q. We note that geodesics in Euclidean spaces and $L^2[0,1]$ are given by straight lines. Thus, for example, given p,

q in $L^2[0,1]$, then $\alpha:[0,1]\to L^2[0,1]$ defined by $\alpha(t)=(1-t)p+tq$ for $t\in[0,1]$, is the geodesic between p and q and the distance d(p,q) is

$$\int_0^1 (\int_0^1 |p(s) - q(s)|^2 ds)^{1/2} dt = \int_0^1 ||p - q||_2 dt = ||p - q||_2.$$

Finally, we note that with the distance d(p,q) as defined above, it then follows that an isometry also as defined above is indeed a distance-preserving transformation. We show this in a nonrigorous manner. Given Riemannian manifolds M, N, let $\alpha:[0,1]\to M$ be a path from p to q in M, $\alpha(0)=p$, $\alpha(1)=q$, $\varphi:M\to N$ an isometry. Let $\beta=\varphi\circ\alpha$. Then $\beta:[0,1]\to N$, $\beta(0)=\varphi(p)$, $\beta(1)=\varphi(q)$, and β is a path from $\varphi(p)$ to $\varphi(q)$ in N. Since for any $t\in[0,1]$ the differential $d\varphi_{\alpha(t)}:T_{\alpha(t)}M\to T_{\varphi(\alpha(t))}N$ is given by $d\varphi_{\alpha(t)}(\alpha'(t))=\beta'(t)$, then

$$L(\beta) = \int_0^1 \sqrt{\langle \beta'(t), \beta'(t) \rangle_{\beta(t)}} dt$$

$$= \int_0^1 \sqrt{\langle d\varphi_{\alpha(t)}(\alpha'(t)), d\varphi_{\alpha(t)}(\alpha'(t)) \rangle_{\varphi(\alpha(t))}} dt$$

$$= \int_0^1 \sqrt{\langle \alpha'(t), \alpha'(t) \rangle_{\alpha(t)}} dt = L(\alpha)$$

since φ is an isometry. Similarly, given a path $\beta:[0,1]\to N$ from $\varphi(p)$ to $\varphi(q)$ in N, there is a path $\alpha:[0,1]\to M$ from p to q in M with $L(\alpha)=L(\beta)$. Thus, $d(p,q)=d(\varphi(p),\varphi(q))$.

See [6], [7], [11], [12], [23] for a more rigorous development of the concepts of smooth manifolds, Riemannian manifolds, differentials, isometries, etc.

Observation 4.7: In what follows, given $q \in L^2[0,1]$, $\gamma \in \Gamma$, we use (q,γ) as short notation for $(q \circ \gamma)\sqrt{\dot{\gamma}}$. Here again, without any loss of generality, in the spirit of Observation 3.8 about the chain rule, q is interpreted as q extended to all of [0,1]. As it will be shown below, $(q,\gamma) \in L^2[0,1]$ so that without any loss of generality, again in the spirit of Observation 3.8 about the chain rule, (q,γ) can be interpreted as (q,γ) extended to all of [0,1], and given $\overline{\gamma} \in \Gamma$, $((q,\gamma),\overline{\gamma})$ can be interpreted as $((q,\gamma),\overline{\gamma})$ extended to all of [0,1].

Proposition 4.5: Given $q \in L^2[0,1]$ and $\gamma \in \Gamma$, then $(q,\gamma) \in L^2[0,1]$. In addition, given $\overline{\gamma} \in \Gamma$, then $((q,\gamma),\overline{\gamma}) = (q,\gamma \circ \overline{\gamma})$ a.e. on [0,1], and if $\gamma \in \Gamma_0$, then $((q,\gamma),\gamma^{-1}) = q$ a.e. on [0,1].

Proof: Let $h(t) = |q(t)|^2$ for each $t \in [0,1]$ at which q exists. Then h is Lebesgue integrable over [0,1] and by Corollary 3.14, $(h \circ \gamma)\dot{\gamma} = |q \circ \gamma|^2\dot{\gamma}$ is Lebesgue integrable over [0,1]. Thus, $(q,\gamma) = (q \circ \gamma)\sqrt{\dot{\gamma}} \in L^2[0,1]$. Now, if $\overline{\gamma} \in \Gamma$, then

$$\begin{array}{lll} ((q,\gamma),\overline{\gamma}) & = & ((q\circ\gamma)\sqrt{\dot{\gamma}},\overline{\gamma}) = (((q\circ\gamma)\sqrt{\dot{\gamma}})\circ\overline{\gamma})\sqrt{\dot{\overline{\gamma}}} \\ & = & ((q\circ\gamma\circ\overline{\gamma})\sqrt{\dot{\gamma}\circ\overline{\gamma}})\sqrt{\dot{\overline{\gamma}}} = (q\circ(\gamma\circ\overline{\gamma}))\sqrt{(\dot{\gamma}\circ\overline{\gamma})\dot{\overline{\gamma}}} \\ & = & (q\circ(\gamma\circ\overline{\gamma}))\sqrt{(\gamma\circ\overline{\gamma})'} = (q,\gamma\circ\overline{\gamma}) \end{array}$$

a.e. on [0,1] using Corollary 3.13 (chain rule) as $\gamma \circ \overline{\gamma} \in AC[0,1]$, by interpreting $\dot{\gamma}$ as $\dot{\gamma}$ extended to all of [0,1] (Observation 3.8 about the chain rule). Finally, if $\gamma \in \Gamma_0$, then

$$\begin{array}{lcl} ((q,\gamma),\gamma^{-1}) & = & ((q\circ\gamma)\sqrt{\dot{\gamma}},\gamma^{-1}) = (((q\circ\gamma)\sqrt{\dot{\gamma}})\circ\gamma^{-1})\sqrt{(\gamma^{-1})'} \\ \\ & = & ((q\circ\gamma\circ\gamma^{-1})\sqrt{\dot{\gamma}\circ\gamma^{-1}})\sqrt{(\gamma^{-1})'} = q\sqrt{(\dot{\gamma}\circ\gamma^{-1})(\gamma^{-1})'} \\ \\ & = & q\sqrt{(\dot{\gamma}\circ\gamma^{-1})/(\dot{\gamma}\circ\gamma^{-1})} = q \end{array}$$

a.e. on [0,1] using Proposition 3.24.

Definition 4.3: The **action of** Γ_0 **on** $L^2[0,1]$ is the operation that takes any element $\gamma \in \Gamma_0$ and any element q of $L^2[0,1]$, and computes $(q,\gamma) = (q \circ \gamma)\sqrt{\dot{\gamma}}$. The **action of** Γ **on** $L^2[0,1]$ is similarly defined.

Proposition 4.6 (Action of Γ on $L^2[0,1]$ is by semi-isometries. Action of Γ_0 on $L^2[0,1]$ is by isometries [23]): For each $\gamma \in \Gamma$, let $\varphi^{\gamma} : L^2[0,1] \to L^2[0,1]$ be defined for $q \in L^2[0,1]$ by $\varphi^{\gamma}(q) = (q,\gamma) = (q \circ \gamma)\sqrt{\dot{\gamma}}$. Then φ^{γ} is differentiable and

$$< d\varphi^{\gamma}(u), d\varphi^{\gamma}(v) > = <(u, \gamma), (v, \gamma) > = < u, v >$$

for any $u, v \in L^2[0, 1]$, where <, > is the $L^2[0, 1]$ inner product and $d\varphi^{\gamma}$ is the differential of φ^{γ} , with <, > and $d\varphi^{\gamma}$ the same at every $q \in L^2[0, 1]$. Thus, φ^{γ} is a semi-isometry and the action of Γ on $L^2[0, 1]$ is said to be by semi-isometries. If $\gamma \in \Gamma_0$, then φ^{γ} is a diffeomorphism. Thus, φ^{γ} is an isometry and the action of Γ_0 on $L^2[0, 1]$ is said to be by isometries.

Proof: If $\gamma \in \Gamma$, from Proposition 4.5 it follows that the range of φ^{γ} is indeed in $L^2[0,1]$. Since the tangent space of $L^2[0,1]$ at any point is $L^2[0,1]$ itself, it follows that <,> is the same at every $q \in L^2[0,1]$. Given $u, v \in L^2[0,1]$, from Proposition 2.41 (Hölder's inequality), $u \cdot v \in L^1$. Let h(s) = u(s)v(s) for each $s \in [0,1]$ at which u and v exist. By Corollary 3.14 (change of variable),

$$\langle u, v \rangle = \int_0^1 u(s)v(s)ds = \int_{\gamma(0)}^{\gamma(1)} h(s)ds = \int_0^1 h(\gamma(t))\dot{\gamma}(t)dt$$

$$= \int_0^1 u(\gamma(t))\sqrt{\dot{\gamma}(t)}v(\gamma(t))\sqrt{\dot{\gamma}(t)}dt$$

$$= \langle (u, \gamma), (v, \gamma) \rangle = \langle d\varphi^{\gamma}(u), d\varphi^{\gamma}(v) \rangle$$

as φ^{γ} is linear so that it is differentiable and $d\varphi^{\gamma}$ acts on an element of $L^2[0,1]$ the same way φ^{γ} does. Thus, $d\varphi^{\gamma}$ is the same at every $q \in L^2[0,1]$, and in addition, φ^{γ} is a semi-isometry and the action of Γ on $L^2[0,1]$ is by semi-isometries. If $\gamma \in \Gamma_0$, then φ^{γ} is a bijection and its inverse $\varphi^{\gamma^{-1}}$ is linear so that it is differentiable. Thus, φ^{γ} is a diffeomorphism and therefore an isometry, and the action of Γ_0 on $L^2[0,1]$ is by isometries.

Corollary 4.1 (Action of Γ_0 on $L^2[0,1]$ is distance preserving [23]): Given $q_1, q_2 \in L^2$, and $\gamma \in \Gamma_0$, then $||q_1 - q_2||_2 = ||(q_1, \gamma) - (q_2, \gamma)||_2$.

Proof: $d(q_1, q_2) = ||q_1 - q_2||_2$ and $d((q_1, \gamma), (q_2, \gamma)) = ||(q_1, \gamma) - (q_2, \gamma)||_2$ (Observation 4.6). The action of Γ_0 on $L^2[0, 1]$ is by isometries (Proposition 4.6). Thus, $d(q_1, q_2) = d((q_1, \gamma), (q_2, \gamma))$ (Observation 4.6), and hence, $||q_1 - q_2||_2 = ||(q_1, \gamma) - (q_2, \gamma)||_2$.

Corollary 4.2 (Action of Γ_0 on $L^2[0,1]$ is norm preserving [23]): Given $q \in L^2$, and $\gamma \in \Gamma_0$, then $||q||_2 = ||(q,\gamma)||_2$.

Observation 4.8 (Action of Γ on $L^2[0,1]$ is distance and norm preserving): Corollary 4.1 and Corollary 4.2 can be shown to hold for all of Γ as follows. Given $q_1, q_2 \in L^2$, and $\gamma \in \Gamma$, then $q_1 - q_2 \in L^2$ and by Corollary 3.14 (change of variable),

$$||(q_1,\gamma)-(q_2,\gamma)||_2^2 = \int_0^1 |q_1(\gamma(t))\sqrt{\dot{\gamma}(t)}-q_2(\gamma(t))\sqrt{\dot{\gamma}(t)}|^2 dt$$

$$= \int_0^1 (q_1(\gamma(t)) - q_2(\gamma(t)))^2 \dot{\gamma}(t) dt$$

$$= \int_{\gamma(0)}^{\gamma(1)} (q_1(s) - q_2(s))^2 ds = \int_0^1 (q_1(s) - q_2(s))^2 ds$$

$$= ||q_1 - q_2||_2^2.$$

Definition 4.4: Let $AC^0[0,1] = \{f : f \in AC[0,1], f' > 0 \text{ a.e. on } [0,1]\}.$ The **Fisher-Rao metric** at any $f \in AC^0[0,1]$ is defined as the inner product

$$\ll u, v \gg_f = \frac{1}{4} \int_0^1 \dot{u}(t)\dot{v}(t) \frac{1}{f'(t)} dt.$$

for any $u, v \in T_f AC^0[0, 1]$.

Observation 4.9: The integral in the definition of the Fisher-Rao metric at $f \in AC^0[0,1]$ is well defined as u, v are functions on [0,1] that are absolutely continuous [21], hence \dot{u}, \dot{v}, f' exist a.e. on [0,1], f' > 0 a.e. on [0,1], thus $\dot{u}/\sqrt{f'}$, $\dot{v}/\sqrt{f'}$ exist a.e. on [0,1] and are in $L^2[0,1]$ (see below), so that $\dot{u}\dot{v}/f'$ is Lebesgue integrable over [0,1] by Proposition 2.41 (Hölder's inequality). In addition, this metric, as defined at elements of $AC^0[0,1]$, is known to have the behavior of a Riemannian metric [23]. In what follows, we assume $AC^0[0,1]$ is endowed with this metric.

Proposition 4.7: Given $f \in AC^0[0,1]$ and $\gamma \in \Gamma_0$, then $f \circ \gamma \in AC^0[0,1]$ and $(f \circ \gamma)(0) = f(0)$.

Proof: That $f \circ \gamma \in AC[0,1]$ and $(f \circ \gamma)(0) = f(0)$ was established in Proposition 4.4. Accordingly, in order to conclude that $f \circ \gamma \in AC^0[0,1]$ we prove $(f \circ \gamma)' > 0$ a.e. on [0,1]. For this purpose let $A = \{t \in [0,1] : f'(t) > 0\}$, $B = [0,1] \setminus A$, $C = \gamma^{-1}(B)$. Clearly, mB = 0 and since γ^{-1} is absolutely continuous on [0,1] (Observation 4.4), then mC = 0 by Proposition 3.21. Let $D = [0,1] \setminus C$. Accordingly, we only need to prove $(f \circ \gamma)' > 0$ a.e. on D. Clearly, $\dot{\gamma}$ exists (and is positive) a.e. on D. Since $\gamma(D) \subseteq A$, and f' exists (and is positive) on A, then $(f \circ \gamma)'$ exists a.e. on D. Indeed it exists exactly at the points in D where $\dot{\gamma}$ exists. Thus, by the usual chain rule of calculus, $(f \circ \gamma)'(t) = f'(\gamma(t))\dot{\gamma}(t)$ for $t \in D$ at which $\dot{\gamma}$ exists. Since as mentioned above $f'(\gamma(t))$ exists and is positive for all $t \in D$, and $\dot{\gamma}$ exists and is positive a.e. on D, then $(f \circ \gamma)' = (f' \circ \gamma)\dot{\gamma} > 0$ a.e. on D.

Definition 4.5: The action of Γ_0 on $AC^0[0,1]$ is the operation that takes any element $\gamma \in \Gamma_0$ and any element f of $AC^0[0,1]$, and computes $f \circ \gamma$.

Observation 4.10: In what follows, two functions in AC[0,1] are considered equal if they differ by a constant. Simpler yet, we assume all functions in AC[0,1] have the same value at zero. Since by Proposition 4.4, if $f \in AC[0,1]$, $\gamma \in \Gamma$, then $f \circ \gamma \in AC[0,1]$ and $(f \circ \gamma)(0) = f(0)$, and since in addition the SRSF of (f+C) is the same for any constant C, the latter is a reasonable assumption.

Proposition 4.8 (Action of Γ_0 on $AC^0[0,1]$ with Fisher-Rao metric is by isometries [23]): For each $\gamma \in \Gamma_0$, let $\varphi^{\gamma} : AC^0[0,1] \to AC^0[0,1]$ be defined for $f \in AC^0[0,1]$ by $\varphi^{\gamma}(f) = f \circ \gamma$. Then φ^{γ} is a diffeomorphism and

$$\ll d\varphi_f^{\gamma}(u), d\varphi_f^{\gamma}(v) \gg_{f \circ \gamma} = \ll u \circ \gamma, v \circ \gamma \gg_{f \circ \gamma} = \ll u, v \gg_f$$

for any $u, v \in T_fAC^0[0, 1]$, where \ll, \gg_f is the inner product that defines the Fisher-Rao metric at $f, \ll, \gg_{f \circ \gamma}$ is the inner product that defines it at $f \circ \gamma$, and $d\varphi_f^{\gamma}$ is the differential of φ^{γ} at f. Thus, φ^{γ} is an isometry and the action of Γ_0 on $AC^0[0, 1]$ is said to be by isometries.

Proof: If $\gamma \in \Gamma_0$, from Proposition 4.7, the range of φ^{γ} is indeed in $AC^0[0,1]$. As noted in Observation 4.9, given $f \in AC^0[0,1]$, $u, v \in T_fAC^0[0,1]$, then u, v are functions on [0,1] that are absolutely continuous [21], and $h = \dot{u}\dot{v}/f'$ is Lebesgue integrable over [0,1]. By Corollary 3.14 (change of variable), Corollary 3.13 (chain rule) as $u \circ \gamma$, $v \circ \gamma$, $f \circ \gamma \in AC[0,1]$, by interpreting h, \dot{u}, \dot{v}, f' as h, \dot{u}, \dot{v}, f' extended to all of [0,1] (Observation 3.8 about the chain rule), and noting that all denominators below are greater than zero a.e. on [0,1] (Proposition 4.7 and its proof), then

$$\ll u, v \gg_f = \frac{1}{4} \int_0^1 \dot{u}(s)\dot{v}(s) \frac{1}{f'(s)} ds = \frac{1}{4} \int_{\gamma(0)}^{\gamma(1)} h(s) ds$$

$$= \frac{1}{4} \int_0^1 h(\gamma(t))\dot{\gamma}(t) dt = \frac{1}{4} \int_0^1 \dot{u}(\gamma(t))\dot{v}(\gamma(t)) \frac{1}{f'(\gamma(t))} \dot{\gamma}(t) dt$$

$$= \frac{1}{4} \int_0^1 \dot{u}(\gamma(t))\dot{\gamma}(t)\dot{v}(\gamma(t))\dot{\gamma}(t) \frac{1}{f'(\gamma(t))\dot{\gamma}(t)} dt$$

$$= \frac{1}{4} \int_0^1 (u(\gamma(t)))'(v(\gamma(t)))' \frac{1}{(f(\gamma(t)))'} dt$$

$$= \ll u \circ \gamma, v \circ \gamma \gg_{f \circ \gamma} = \ll d\varphi_f^{\gamma}(u), d\varphi_f^{\gamma}(v) \gg_{f \circ \gamma}$$

as φ^{γ} is linear so that it is differentiable and $d\varphi_f^{\gamma}$ acts on an element of $T_fAC^0[0,1]$ the same way φ^{γ} does on an element of $AC^0[0,1]$. Since $\gamma \in \Gamma_0$, then φ^{γ} is a bijection and its inverse $\varphi^{\gamma^{-1}}$ is linear so that it is differentiable. Thus, φ^{γ} is a diffeomorphism and therefore an isometry, and the action of Γ_0 on $AC^0[0,1]$ is by isometries.

Proposition 4.9 (Fisher-Rao metric on $AC^0[0,1]$ under SRSF representation becomes $L^2[0,1]$ metric [23]): Given $f \in AC^0[0,1]$ and q the SRSF of f, define a mapping $F: AC^0[0,1] \to L^2[0,1]$ by $F(f) = q = \sqrt{f'}$. Then F is differentiable, and for any $v \in T_fAC^0[0,1]$, it must be that $F_f^*(v) = \dot{v}/(2\sqrt{f'}) \in T_qL^2[0,1] = L^2[0,1]$, where F_f^* is the differential of F at f. Given $v_1, v_2 \in T_fAC^0[0,1]$, then $F_f^*(v_1), F_f^*(v_2) = v_1, v_2 \gg_f$, where $F_f^*(v_1), F_f^*(v_2) = v_1, v_2 \gg_f$, and $F_f^*(v_1), F_f^*(v_2) = v_1, v_2 \gg_f$, where $F_f^*(v_1), F_f^*(v_2) = v_2, v_3 \gg_f$, where $F_f^*(v_1), F_f^*(v_2) = v_3, v_3 \gg_f$ is the inner product that defines the Fisher-Rao metric at $F_f^*(v_1), F_f^*(v_2) = v_3, v_3 \gg_f$

Proof: Let $L_0^1[0,1] = {\hat{f} : \hat{f} \in L^1[0,1], \hat{f} > 0 \text{ a.e. on } [0,1]}.$

Given $\hat{f} \in L_0^1[0,1]$, define a mapping $S: L_0^1[0,1] \to L^2[0,1]$ by $S(\hat{f}) = \sqrt{\hat{f}}$. In addition, given $f \in AC^0[0,1]$, define a mapping (the derivative mapping) $D: AC^0[0,1] \to L_0^1[0,1]$ by D(f) = f'.

With F as defined above, then $F = S \circ D$.

Given $v \in T_f AC^0[0, 1]$, then $D_f^*(v) = \dot{v} \in T_{f'} L_0^1[0, 1]$, where D_f^* is the differential of D at f, as D is linear so that it is differentiable and D_f^* acts on an element of $T_f AC^0[0, 1]$ the same way D acts on an element of $AC^0[0, 1]$.

Let $s: \mathbf{R} \to \mathbf{R}$ be the mapping defined by $s(x) = \sqrt{x}$, $x \in \mathbf{R}$, x > 0. Then s is differentiable for x > 0, and $s^*(y) = s'(x)y = y/(2\sqrt{x})$ for any $y \in \mathbf{R}$, where s^* is the differential of s. From this, following closely the definition of the differential of a differentiable function [11, 23], it then follows that S is differentiable function S and S is differentiable function S is differentiable function S and S is differentiable function S is differentiable function S and S is differentiable function S is differentiable function S is differentiable function S and S is differentiable function S is differen

ferentiable and given $w \in T_{\hat{f}}L_0^1[0,1]$, then $S_{\hat{f}}^*(w) = w/(2\sqrt{\hat{f}}) \in T_{\sqrt{\hat{f}}}L^2[0,1]$,

where $S_{\hat{f}}^*$ is the differential of S at \hat{f} .

Thus, $F = S \circ D$ is differentiable and its differential $F_f^*: T_fAC^0[0,1] \to T_qL^2[0,1]$ at $f \in AC^0[0,1]$ is $S_{D(f)}^* \circ D_f^* = S_{f'}^* \circ D_f^*$ [11].

Accordingly, given $v \in T_f AC^0[0,1]$, then $F_f^*(v) = S_{f'}^*(D_f^*(v)) = S_{f'}^*(\dot{v}) = \dot{v}/(2\sqrt{f'}) \in T_{\sqrt{f'}}L^2[0,1] = T_q L^2[0,1] = L^2[0,1]$.

Finally, given $v_1, v_2 \in T_f AC^0[0, 1]$, then

$$< F_f^*(v_1), F_f^*(v_2) > = < \dot{v}_1/(2\sqrt{f'}), \dot{v}_2/(2\sqrt{f'}) > = \frac{1}{4} \int_0^1 \dot{v}_1(t)\dot{v}_2(t) \frac{1}{f'(t)} dt$$

= $\ll v_1, v_2 \gg_f$.

Observation 4.11 (Distance between functions in AC[0,1]): Given f_1 , $f_2 \in AC[0,1]$, let q_1, q_2 be the SRSF's of f_1, f_2 , respectively. We note that computing the distance between f_1 and f_2 with the Fisher-Rao metric as defined above may not be possible as a path in AC[0,1] from f_1 to f_2 might contain functions whose derivatives are not positive a.e. on [0,1]. Even if this was not the case, the minimization involved would be nontrivial. Accordingly, motivated by Proposition 4.9 above, the convention is to say that the **Fisher-Rao distance** between f_1 and f_2 is $d_{FR}(f_1, f_2) = ||q_1 - q_2||_2$, i.e., the L^2 distance between q_1 and q_2 . In addition, since the geodesic from q_1 to q_2 is a straight line, given $s \in [0, 1]$, then $q = (1 - s)q_1 + sq_2$ is a function in this geodesic, and by Proposition 4.3, a function $f \in AC[0,1]$ can be computed for each $t \in [0,1]$ by $f(t) = C + \int_0^t q(x)|q(x)|dx$, where $C = f_1(0) = f_2(0)$, with the SRSF of f equal to q a.e. on [0,1]. Doing this for enough functions on the straight line joining q_1 and q_2 , a collection of functions can be obtained in AC[0,1] that are then said to approximate a geodesic (based on the Fisher-Rao metric) from f_1 to f_2 .

Definition 4.6: Given $q \in L^2[0,1]$, define the **orbit** $[q]_{\Gamma_0}$ **of** q **under** Γ_0 by $[q]_{\Gamma_0} = \{\overline{q} : \overline{q} = (q,\gamma) = (q \circ \gamma)\sqrt{\dot{\gamma}} \text{ a.e. on } [0,1], \text{ some } \gamma \in \Gamma_0\}$. Denote by $cl([q]_{\Gamma_0})$ the closure in $L^2[0,1]$ of $[q]_{\Gamma_0}$.

Observation 4.12: In what follows, given $q_1, q_2 \in L^2[0, 1], q_1 \in [q_2]_{\Gamma_0}$ so that $q_1 = (q_2, \gamma)$ a.e. on [0, 1] for some $\gamma \in \Gamma_0$, without any loss of generality we may simply say $q_1 = (q_2, \gamma)$. Accordingly, given $q_1, q_2 \in L^2[0, 1], q_1 \in [q_2]_{\Gamma_0}$ so that $q_1 = (q_2, \gamma)$ for some $\gamma \in \Gamma_0$, then it follows (Proposition 4.5) that $[q_1]_{\Gamma_0} \subseteq [q_2]_{\Gamma_0}$, and $q_2 = (q_1, \gamma^{-1})$ so that $[q_2]_{\Gamma_0} \subseteq [q_1]_{\Gamma_0}$ and thus $[q_1]_{\Gamma_0} = [q_2]_{\Gamma_0}$. Using similar arguments, given $q_1, q_2 \in L^2[0, 1],$ an equivalence relation \sim can be defined and justified on $L^2[0, 1]$ for which $q_1 \sim q_2$ if q_1 and q_2 are in the same orbit under Γ_0 . Accordingly, with this equivalence relation a quotient space is obtained which is the set of all orbits of elements of $L^2[0, 1]$ under Γ_0 and which we denote by $L^2[0, 1]/\Gamma_0$. An attempt then can be made as follows to define a distance function d between

elements of $L^2[0,1]/\Gamma_0$ that would make $L^2[0,1]/\Gamma_0$ a metric space. Given $q_1, q_2 \in L^2[0,1]$, let

$$\begin{array}{lcl} d([q_1]_{\Gamma_0},[q_2]_{\Gamma_0}) & = & \inf_{\gamma_1,\gamma_2\in\Gamma_0}||(q_1,\gamma_1)-(q_2,\gamma_2)||_2 \\ & = & \inf_{\gamma\in\Gamma_0}||q_1-(q_2,\gamma)||_2 = \inf_{\gamma\in\Gamma_0}||(q_1,\gamma)-q_2||_2, \end{array}$$

where the bottom equations follow from Corollary 4.1 (action of Γ_0 on $L^2[0,1]$ is distance preserving) again using Proposition 4.5 where appropriate. Of the properties that d must satisfy to be a distance function all have been established [23] except one: $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$ if and only if $[q_1]_{\Gamma_0} = [q_2]_{\Gamma_0}$. Unfortunately, as demonstrated in [10], the orbits as defined are not closed in $L^2[0,1]$, which allows for examples with $[q_1]_{\Gamma_0} \neq [q_2]_{\Gamma_0}$ but $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$.

Proposition 4.10 ([10]): Given $q_1, q_2 \in L^2[0, 1]$, then $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$ if and only if $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$. In particular, if $q_1 \in cl([q_2]_{\Gamma_0})$ so that $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$, then $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$.

Proof: If $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$, fix $\overline{q}_1 \in [q_1]_{\Gamma_0}$ and note $[\overline{q}_1]_{\Gamma_0} = [q_1]_{\Gamma_0}$ (Observation 4.12) so that $d([\overline{q}_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = 0$. Then given integer n > 0, there is $\gamma_n \in \Gamma_0$ such that $||\overline{q}_1 - (q_2, \gamma_n)||_2 < 1/n$. Thus, $\overline{q}_1 \in cl([q_2]_{\Gamma_0})$. Since \overline{q}_1 is arbitrary in $[q_1]_{\Gamma_0}$ then $[q_1]_{\Gamma_0} \subseteq cl([q_2]_{\Gamma_0})$, thus $cl([q_1]_{\Gamma_0}) \subseteq cl([q_2]_{\Gamma_0})$. Similarly, $cl([q_2]_{\Gamma_0}) \subseteq cl([q_1]_{\Gamma_0})$, thus $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$. Assume $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$. Then, in particular, $q_1 \in cl([q_2]_{\Gamma_0})$ so that given integer n > 0, there is $\gamma_n \in \Gamma_0$ with $||q_1 - (q_2, \gamma_n)||_2 < 1/n$. Thus, $d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}) = \inf_{\gamma \in \Gamma_0} ||q_1 - (q_2, \gamma)||_2 = 0$.

Observation 4.13: Using arguments similar to those in the proof of Proposition 4.10 above, given $q_1, q_2 \in L^2[0, 1]$, an equivalence relation \sim can be defined and justified on $L^2[0, 1]$ for which $q_1 \sim q_2$ if q_1 and q_2 are in the closure of the same orbit under Γ_0 . Accordingly, with this equivalence relation a quotient space is obtained which is the set of all closures of orbits of elements of $L^2[0, 1]$ under Γ_0 and which we denote by $L^2[0, 1]/\sim$. In what follows, we extend the function d above to the quotient space $L^2[0, 1]/\sim$.

Corollary 4.3 (Distance between equivalence classes in $L^2[0,1]/\sim$ [10], [23]): Given $q_1, q_2 \in L^2[0,1]$, let

$$d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0})) = \inf_{\overline{q}_1 \in cl([q_1]_{\Gamma_0}), \overline{q}_2 \in cl([q_2]_{\Gamma_0})} ||\overline{q}_1 - \overline{q}_2||_2.$$

Then $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0})) = \inf_{\gamma_1, \gamma_2 \in \Gamma_0} ||(q_1, \gamma_1) - (q_2, \gamma_2)||_2 = \inf_{\gamma \in \Gamma_0} ||q_1 - (q_2, \gamma)||_2 = \inf_{\gamma \in \Gamma_0} ||(q_1, \gamma) - q_2||_2 = d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}), \text{ and } d \text{ is a distance function between elements of } L^2[0, 1]/\sim, \text{ so that } L^2[0, 1]/\sim \text{ is a metric space with this distance function.}$

Proof: Note

$$\inf_{\overline{q}_1 \in cl([q_1]_{\Gamma_0}), \overline{q}_2 \in cl([q_2]_{\Gamma_0})} ||\overline{q}_1 - \overline{q}_2||_2 = \inf_{\gamma_1, \gamma_2 \in \Gamma_0} ||(q_1, \gamma_1) - (q_2, \gamma_2)||_2.$$

Thus, $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0})) = \inf_{\gamma_1, \gamma_2 \in \Gamma_0} ||(q_1, \gamma_1) - (q_2, \gamma_2)||_2 = \inf_{\gamma \in \Gamma_0} ||q_1 - (q_2, \gamma)||_2 = \inf_{\gamma \in \Gamma_0} ||(q_1, \gamma) - q_2||_2 = d([q_1]_{\Gamma_0}, [q_2]_{\Gamma_0}),$ as previously noted in Observation 4.12.

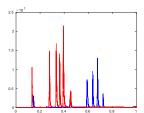
That d is a distance function follows from Proposition 4.10 and results about properties of this distance function in [23].

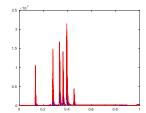
Observation 4.14: Given f_1 , $f_2 \in AC[0,1]$, and q_1 , q_2 , the SRSF's of f_1 , f_2 , respectively, we note that q_1 and q_2 remain unchanged after translations of f_1 and f_2 (by translations we mean f_1 and f_2 become $f_1 + c_1$ and $f_2 + c_2$, respectively, for constants c_1 , c_2) so that the distance between the equivalence classes of q_1 and q_2 , defined by d above, is the same before and after the translations. That this is true follows from the definition of the SRSF. For scalar multiplications of f_1 and f_2 , the distance between the equivalence classes of q_1 and q_2 before and after the scalar multiplications can be approximated or computed exactly, if possible, by the same elements of Γ_0 as the following proposition shows. Accordingly, it is customary to normalize q_1 and q_2 so that $||q_1||_2 = ||q_2||_2 = 1$ and then compute the distance between their equivalence classes with d as above, as from the comments just made doing so is compatible with the requirement that the shapes of f_1 and f_2 be invariant under translation and scalar multiplication.

Proposition 4.11 ([23]): Given $q_1, q_2 \in L^2[0, 1]$, and $\gamma^*, \gamma \in \Gamma_0$ for which $||q_1 - (q_2, \gamma^*)||_2 \le ||q_1 - (q_2, \gamma)||_2$, then $||bq_1 - (cq_2, \gamma^*)||_2 \le ||bq_1 - (cq_2, \gamma)||_2$, for any b, c, bc > 0.

Proof: With <, > as the L^2 inner product, note

$$||q_1 - (q_2, \gamma^*)||_2^2 = ||q_1||_2^2 - 2 < q_1, (q_2, \gamma^*) > + ||(q_2, \gamma^*)||_2^2,$$





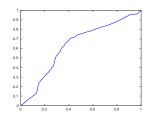


Figure 1: Function alignment by warping that is obtained from the computation of $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0}))$.

and

$$||q_1 - (q_2, \gamma)||_2^2 = ||q_1||_2^2 - 2 < q_1, (q_2, \gamma) > + ||(q_2, \gamma)||_2^2.$$

Thus, $||q_1 - (q_2, \gamma^*)||_2 \le ||q_1 - (q_2, \gamma)||_2$ and $||q_2||_2 = ||(q_2, \gamma^*)||_2 = ||(q_2, \gamma)||_2$, bc > 0, imply $-2bc < q_1, (q_2, \gamma^*) > \le -2bc < q_1, (q_2, \gamma) >$. Accordingly, since $||cq_2||_2 = ||(cq_2, \gamma^*)||_2 = ||(cq_2, \gamma)||_2$, then

$$||bq_1||_2^2 - 2 < bq_1, (cq_2, \gamma^*) > + ||(cq_2, \gamma^*)||_2^2$$

$$\leq ||bq_1||_2^2 - 2 < bq_1, (cq_2, \gamma) > + ||(cq_2, \gamma)||_2^2,$$

so that $||bq_1 - (cq_2, \gamma^*)||_2 \le ||bq_1 - (cq_2, \gamma)||_2$.

Observation 4.15: Figure 1 illustrates an instance of approximately computing $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0}))$ as expressed in Corollary 4.3 above. Here q_1 , q_2 are the SRSF's of functions f_1 , f_2 , respectively, plotted in the lefmost diagram, f_1 in red, f_2 in blue, q_1 , q_2 normalized so that $||q_1||_2 = ||q_2||_2 = 1$. The distance (about 0.1436) was approximately computed (in about 154 seconds) with adapt-DP [2], a fast linear Dynamic Programming algorithm. The resulting warping function $\gamma \in \Gamma_0$ that approximately minimizes $||q_1 - (q_2, \gamma)||_2$ is plotted in the rightmost diagram, and f_1 and $f_2 \circ \gamma$ are plotted in the middle diagram in which they appear essentially aligned. The functions f_1 and f_2 were given in the form of sets of 19,693 and 19,763 points, respectively, with nonuniform domains in [0,1]. A copy of adapt-DP with usage instructions and data files for the same example in Figure 1 can be obtained using links: https://doi.org/10.18434/T4/1502501 http://math.nist.gov/~JBernal /Fast_Dynamic_Programming.zip

Definition 4.7: Given $q \in L^2[0,1]$, define the **orbit** $[q]_{\Gamma}$ **of** q **under** Γ by $[q]_{\Gamma} = \{\overline{q} : \overline{q} = (q,\gamma) = (q \circ \gamma)\sqrt{\dot{\gamma}} \text{ a.e. on } [0,1], \text{ some } \gamma \in \Gamma\}.$

Observation 4.16: In what follows, we present results found mostly in [10] for the purpose of showing that given $q \in L^2[0,1]$, then there exist $w \in L^2[0,1]$, $\gamma \in \Gamma$, such that $q = (w,\gamma)$, |w| constant a.e. on [0,1], $cl([w]_{\Gamma_0}) = [w]_{\Gamma}$ so that $q \in cl([w]_{\Gamma_0})$, and thus $cl([q]_{\Gamma_0}) = cl([w]_{\Gamma_0}) = [w]_{\Gamma}$. We note that this result doesn't change how $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0}))$ in Corollary 4.3 is computed for $q_1, q_2 \in L^2[0,1]$. It should still be done by computing $\inf_{\gamma \in \Gamma_0} ||q_1 - (q_2, \gamma)||_2$ or $\inf_{\gamma \in \Gamma_0} ||(q_1, \gamma) - q_2||_2$ as implied by Corollary 4.3.

Proposition 4.12: $A_0 = \{q \in L^2[0,1] : ||q||_2 = 1, q > 0 \text{ a.e. on } [0,1]\}$ has closure in $L^2[0,1]$ equal to $A = \{q \in L^2[0,1] : ||q||_2 = 1, q \ge 0 \text{ a.e. on } [0,1]\}.$

Proof: Clearly $A_0 \subset A$. Let $\epsilon > 0$ be given. Given $q \in A \setminus A_0$, then a measurable subset B of [0,1] exists, m(B) > 0, on which q = 0. Let $C = [0,1] \setminus B$. Then q > 0 a.e. on C and $\int_C q(t)^2 dt = \int_0^1 q(t)^2 dt = 1$. Choose b > 0, b < 1 with $1 - b < \epsilon/2$, and set $a = ((1 - b^2)/m(B))^{1/2}$. Define a function \hat{q} on [0,1] by $\hat{q} = bq$ on C and $\hat{q} = a$ on B. Then $\hat{q} > 0$ a.e. on [0,1] and $\int_0^1 \hat{q}(t)^2 dt = \int_C (bq(t))^2 dt + \int_B a^2 dt = b^2 \cdot 1 + a^2 m(B) = b^2 + (1-b^2) = 1$ so that $\hat{q} \in A_0$. Note $\int_0^1 (q(t) - \hat{q}(t))^2 dt = \int_C (q(t) - bq(t))^2 dt + \int_B a^2 dt = (1-b)^2 + a^2 m(B) = (1-b)^2 + (1-b^2) = 1 - 2b + b^2 + 1 - b^2 = 2 - 2b = 2(1-b) < 2\epsilon/2 = \epsilon$ so that q is in the closure of A_0 in $L^2[0,1]$ and this is true for every q in $A \setminus A_0$. Finally, if $q \notin A$, we show q is not in the closure of A_0 in $L^2[0,1]$. If $||q||_2 \neq 1$, then clearly q is not in the closure. Thus, assume $||q||_2 = 1$. Since $q \notin A$, then a measurable subset B of [0,1] exists, m(B) > 0, on which q < 0. Thus, $\int_B q(t)^2 > 0$ (i of Proposition 2.34) so that $\int_B (q(t) - \hat{q}(t))^2 dt > \int_B q(t)^2 dt$ for any $\hat{q} \in A_0$. Thus, q can not be in the closure of A_0 in $L^2[0,1]$ and A must

Corollary 4.4 (SRSF's of functions in Γ_0 and Γ ; orbit of the constant function equal to 1 [10]): $Q_0 = \{\overline{q} : \overline{q} = \sqrt{\gamma} \text{ a.e. on } [0,1], \text{ some } \gamma \in \Gamma_0\}$ has closure in $L^2[0,1]$ equal to $Q = \{\overline{q} : \overline{q} = \sqrt{\gamma} \text{ a.e. on } [0,1], \text{ some } \gamma \in \Gamma\}$. In addition, with $A_0 = \{q \in L^2[0,1] : ||q||_2 = 1, q > 0 \text{ a.e. on } [0,1]\}$, $A = \{q \in L^2[0,1] : ||q||_2 = 1, q \geq 0 \text{ a.e. on } [0,1]\}$, and q_0 the constant function equal to 1 on [0,1], then $[q_0]_{\Gamma_0} = Q_0 = A_0$ and $cl([q_0]_{\Gamma_0}) = Q = A$.

then be the closure of A_0 in $L^2[0,1]$.

Proof: If $\gamma \in \Gamma_0$ and $\overline{q} = \sqrt{\dot{\gamma}}$ a.e. on [0,1], then $\int_0^1 \overline{q}(t)^2 dt = \int_0^1 \dot{\gamma}(t) dt = \gamma(1) - \gamma(0) = 1$. Also $\overline{q} > 0$ a.e. on [0,1] since $\gamma \in \Gamma_0$ so that $\overline{q} \in A_0$. Thus, $Q_0 \subseteq A_0$. On the other hand, if $q \in A_0$, then q > 0 a.e. on [0,1], $q \in L^2[0,1]$, $||q||_2 = 1$. By Proposition 4.3, γ defined for each $t \in [0,1]$ by $\gamma(t) = \int_0^t q(s)|q(s)|ds = \int_0^t q(s)^2 ds$ is absolutely continuous on [0,1] with q equal to the SRSF of γ a.e. on [0,1]. Clearly $\gamma(0) = 0$, $\gamma(1) = ||q||_2 = 1$, $\dot{\gamma} = q^2$ a.e. on [0,1], thus $\gamma \in \Gamma_0$ and $\sqrt{\dot{\gamma}} = q$ a.e. on [0,1] so that $q \in Q_0$. Thus $Q_0 = A_0$. Similarly, Q = A so that the closure of Q_0 in $L^2[0,1]$ is Q by Proposition 4.12. Finally, $[q_0]_{\Gamma_0} = \{\overline{q} : \overline{q} = (q_0, \gamma) = (q_0 \circ \gamma)\sqrt{\dot{\gamma}} = \sqrt{\dot{\gamma}}$ a.e. on [0,1], some $\gamma \in \Gamma_0\} = Q_0 = A_0$, and since, as just proved, the closure of Q_0 in $L^2[0,1]$ is Q, then $cl([q_0]_{\Gamma_0}) = Q = A$.

Corollary 4.5 ([10]): With q_0 the constant function equal to 1 on [0,1], given $q_1, q_2 \in L^2[0,1], ||q_1||_2 = ||q_2||_2 = 1$, if either (i) $q_1 \ge 0$ a.e. on [0,1] and $q_2 \ge 0$ a.e. on [0,1], or (ii) $q_1 \le 0$ a.e. on [0,1] and $q_2 \le 0$ a.e. on [0,1], then in the case of (i) it must be that $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0}) = cl([q_0]_{\Gamma_0})$, and in the case of (ii) it must be that $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0}) = cl([-q_0]_{\Gamma_0})$. In both cases a sequence $\{\gamma_n\}$ exists in Γ_0 with $(q_1, \gamma_n) \to q_2$ in $L^2[0, 1]$.

Proof: With $A = \{q \in L^2[0,1] : ||q||_2 = 1, q \geq 0 \text{ a.e. on } [0,1]\}$, if (i) is true, then $q_1, q_2 \in A = cl([q_0]_{\Gamma_0})$ (Corollary 4.4) so that by Proposition 4.10, $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0}) = cl([q_0]_{\Gamma_0})$. On the other hand, if (ii) is true, then using similar arguments as above with $-q_0 = -1$ taking the place of q_0 , it then follows that $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0}) = cl([-q_0]_{\Gamma_0})$. In both cases $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$ implies the existence of $\{\gamma_n\}$.

Corollary 4.6 ([10]): Given $q_1, q_2 \in L^2[0,1]$, and a sequence of numbers $t_0 = 0 < t_1 < \ldots < t_n = 1$, such that for each $i, i = 1, \ldots, n$, $\int_{t_{i-1}}^{t_i} q_1(t)^2 dt = \int_{t_{i-1}}^{t_i} q_2(t)^2 dt$, and either $q_1 \geq 0$ and $q_2 \geq 0$ a.e. on $[t_{i-1}, t_i]$, or $q_1 \leq 0$ and $q_2 \leq 0$ a.e. on $[t_{i-1}, t_i]$, then $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$.

Proof: Given $i, 1 \leq i \leq n$, then a sequence $\{\lambda_n^i\}$ exists of absolutely continuous functions, $\lambda_n^i : [t_{i-1}, t_i] \to [t_{i-1}, t_i]$, $\dot{\lambda}_n^i > 0$ a.e. on $[t_{i-1}, t_i]$, $\lambda_n^i(t_{i-1}) = t_{i-1}$, $\lambda_n^i(t_i) = t_i$ for each n such that $(q_1, \lambda_n^i) \to q_2$ in $L^2[t_{i-1}, t_i]$. Here (q_1, λ_n^i) is understood to be $(q_1 \circ \lambda_n^i) \sqrt{\dot{\lambda}_n^i}$ and $L^2[t_{i-1}, t_i]$ the set of square-integrable functions over $[t_{i-1}, t_i]$. Proof of the existence of $\{\lambda_n^i\}$ along the

lines of that of Corollary 4.5 with $[t_{i-1}, t_i]$ taking the place of [0, 1] and the value of $\int_{t_{i-1}}^{t_i} q_1(t)^2 dt = \int_{t_{i-1}}^{t_i} q_2(t)^2 dt$ not necessarily equal to 1.

Finally, define a sequence of functions $\{\gamma_n\}$, $\gamma_n:[0,1]\to[0,1]$, by setting $\gamma_n(t)=\lambda_n^i(t)$ if $t\in[t_{i-1},t_i]$ for each n. It follows γ_n is absolutely continuous, $\gamma_n(0)=0$, $\gamma_n(1)=1$, $\dot{\gamma}_n>0$ a.e. on [0,1] for each n. Thus $\{\gamma_n\}\subset\Gamma_0$ and since $(q_1,\lambda_n^i)\to q_2$ in $L^2[t_{i-1},t_i]$ for each i, then $(q_1,\gamma_n)\to q_2$ in $L^2[0,1]$. Thus, $q_2\in cl([q_1]_{\Gamma_0})$ and by Proposition 4.10, then $cl([q_1]_{\Gamma_0})=cl([q_2]_{\Gamma_0})$.

Corollary 4.7 ([10]): Given $q_1, q_2 \in L^2[0, 1]$, and two sequences of numbers $t_0 = 0 < t_1 < \ldots < t_n = 1, t'_0 = 0 < t'_1 < \ldots < t'_n = 1$, such that for each i, $i = 1, \ldots, n$, $\int_{t_{i-1}}^{t_i} q_1(t)^2 dt = \int_{t'_{i-1}}^{t'_i} q_2(t)^2 dt$, and either $q_1 \ge 0$ a.e. on $[t_{i-1}, t_i]$ and $q_2 \ge 0$ a.e. on $[t'_{i-1}, t'_i]$, or $q_1 \le 0$ a.e. on $[t_{i-1}, t_i]$ and $q_2 \le 0$ a.e. on $[t'_{i-1}, t'_i]$, then $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$.

Proof: Let γ be the piecewise linear element of Γ_0 for which $\gamma(t_i') = t_i$, $i = 0, \ldots, n$, and let $w = (q_1, \gamma)$. It then follows by Corollary 3.14 (change of variable) that for each $i, i = 1, \ldots, n$, $\int_{t_{i-1}'}^{t_i'} w(t)^2 dt = \int_{t_{i-1}'}^{t_i'} (q_1(\gamma(t)))^2 \dot{\gamma}(t) dt = \int_{t_{i-1}}^{t_i} q_1(s)^2 ds = \int_{t_{i-1}'}^{t_i'} q_2(t)^2 dt$, and since $w \geq 0$ a.e. on $[t_{i-1}, t_i']$ if $q_1 \geq 0$ a.e. on $[t_{i-1}, t_i]$, and $w \leq 0$ a.e. on $[t_{i-1}, t_i']$ if $q_1 \leq 0$ a.e. on $[t_{i-1}, t_i]$, then w and q_2 satisfy the hypothesis of Corollary 4.6 for the sequence $\{t_n'\}$ so that $cl([w]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$. Since $w = (q_1, \gamma), \gamma \in \Gamma_0$, then $w \in [q_1]_{\Gamma_0}$ so that by Observation 4.12, $[w]_{\Gamma_0} = [q_1]_{\Gamma_0}$ and therefore $cl([q_1]_{\Gamma_0}) = cl([q_2]_{\Gamma_0})$.

Proposition 4.13 ([10]): Given $q \in L^2[0,1]$, then $[q]_{\Gamma} \subseteq cl([q]_{\Gamma_0})$.

Proof: The proposition is first proved for step functions on [0,1]. Accordingly, we assume q is a step function and $\gamma \in \Gamma$.

Let $t_0 = 0 < t_1 < \ldots < t_n = 1$ be the set of numbers that define the partition associated with q as a step function. For each $i, i = 0, \ldots, n$, let $t_i' \in [0, 1]$ be such that $\gamma(t_i') = t_i$ with $t_0' = 0$ and $t_n' = 1$. Note $t_0' = 0 < t_1' < \ldots < t_n' = 1$, as γ is a nondecreasing function from [0, 1] onto [0, 1].

Let $w = (q, \gamma)$. It then follows by Corollary 3.14 (change of variable) that for each i, i = 1, ..., n, $\int_{t'_{i-1}}^{t'_i} w(t)^2 dt = \int_{t'_{i-1}}^{t'_i} (q(\gamma(t)))^2 \dot{\gamma}(t) dt = \int_{t_{i-1}}^{t_i} q(s)^2 ds$, and either $q \geq 0$ a.e. on $[t_{i-1}, t_i]$ and $w \geq 0$ a.e. on $[t'_{i-1}, t'_i]$, or $q \leq 0$ a.e. on $[t_{i-1}, t_i]$ and $w \leq 0$ a.e. on $[t'_{i-1}, t'_i]$. Thus, by Corollary 4.7,

 $cl([q]_{\Gamma_0}) = cl([w]_{\Gamma_0})$ so that, in particular, $w = (q, \gamma) \in cl([q]_{\Gamma_0})$ and therefore, since γ is arbitrary in Γ , then $[q]_{\Gamma} \subseteq cl([q]_{\Gamma_0})$.

Finally, we assume q is any function in $L^2[0,1]$ and $\gamma \in \Gamma$. Given $\epsilon > 0$, by Proposition 2.44 (density of step functions in L^p), there is a step function v on [0,1] such that $||q-v||_2 < \epsilon/3$. As just proved above, $(v,\gamma) \in cl([v]_{\Gamma_0})$ so that for some $\overline{\gamma} \in \Gamma_0$ it must be that $||(v,\gamma)-(v,\overline{\gamma})||_2 < \epsilon/3$. Thus, by Corollary 4.1 and Observation 4.8 (action of Γ_0 and Γ is distance preserving)

$$\begin{aligned} ||(q,\gamma) - (q,\overline{\gamma})||_2 &= ||(q,\gamma) - (v,\gamma)||_2 + ||(v,\gamma) - (v,\overline{\gamma})||_2 \\ &+ ||(v,\overline{\gamma}) - (q,\overline{\gamma})||_2 \\ &= ||q - v||_2 + ||(v,\gamma) - (v,\overline{\gamma})||_2 + ||v - q||_2 \\ &< \epsilon/3 + \epsilon/3 + \epsilon/3 = \epsilon \end{aligned}$$

so that $(q, \gamma) \in cl([q]_{\Gamma_0})$ and therefore, since γ is arbitrary in Γ , then $[q]_{\Gamma} \subseteq cl([q]_{\Gamma_0})$.

Proposition 4.14 (Constant-speed parametrization of an absolutely continuous function [24]): Given $f \in AC[0,1]$, then there exist $h \in AC[0,1]$, $\gamma \in \Gamma$, such that $|h'| = L = \int_0^1 |f'(t)| dt$ (the length of f) a.e. on [0,1] and $f = h \circ \gamma$ on [0,1].

Proof: Given $f \in AC[0,1]$, let $L = \int_0^1 |f'(t)| dt$. If L = 0 then f is constant on [0, 1] (i of Proposition 2.34, Proposition 3.8). Otherwise, define $\gamma : [0,1] \to [0,1]$ by $\gamma(t) = (1/L) \int_0^t |f'(s)| ds$ for each $t \in [0,1]$. Accordingly, $\gamma(0) = 0$, $\gamma(1) = (1)$, $\gamma \in AC[0,1]$ by Proposition 3.11, and $\dot{\gamma}(t) = (1/L)|f'(t)|$ a.e. on [0,1] by Proposition 3.7 so that $\dot{\gamma} \geq 0$ a.e. on [0,1]. Thus $\gamma \in \Gamma$. Given $s \in [0,1]$, then for some $t \in [0,1]$ it must be that $\gamma(t) = s$. Define $h : [0,1] \to \mathbf{R}$ by h(s) = f(t). The function h is well defined for if $s = \gamma(t_1) = \gamma(t_2)$, $t_1 < t_2 \in [0,1]$, then $0 = \int_0^{t_2} |f'(x)| dx - \int_0^{t_1} |f'(x)| dx = \int_{t_1}^{t_2} |f'(x)| dx$. Thus, by i of Proposition 2.34, f' = 0 a.e. on $[t_1, t_2]$ so that by Proposition 3.8 f is constant on $[t_1, t_2]$ and, in particular, $f(t_1) = f(t_2)$. Clearly $h(\gamma(t)) = f(t)$ for each $t \in [0, 1]$. Note for $s_1, s_2 \in [0, 1]$, $s_1 < s_2$, then $s_1 = \gamma(t_1)$, $s_2 = \gamma(t_2)$, t_1 , $t_2 \in [0, 1]$, $t_1 < t_2$, and

$$|h(s_2) - h(s_1)| = |f(t_2) - f(t_1)| = |\int_{t_1}^{t_2} f'(x) dx| \le \int_{t_1}^{t_2} |f'(x)| dx = L \cdot (s_2 - s_1).$$

From this inequality it follows clearly that $h \in AC[0,1]$ (Definition 3.5). Accordingly, h is differentiable a.e. on [0,1] and $|h'| \leq L$ a.e. on [0,1] also

from the inequality. Note that by Corollary 3.14 (change of variable) and Corollary 3.13 (chain rule), then

$$\int_0^1 |h'(s)| ds = \int_0^1 |h'(\gamma(t))| \dot{\gamma}(t) dt = \int_0^1 |f'(t)| dt = L.$$

By i of Proposition 2.34, then |h'| = L a.e. on [0, 1].

Corollary 4.8: Given $q \in L^2[0,1]$, then there exist $w \in L^2[0,1]$, $\gamma \in \Gamma$, such that $|w| = \sqrt{L}$ a.e. on [0,1] and $q = (w,\gamma)$ a.e. on [0,1], where $L = \int_0^1 |f'(t)| dt$ (the length of f), $f \in AC[0,1]$, the SRSF of f equal to q a.e. on [0,1]. In particular, if $||q||_2 = 1$ so that L = 1, then |w| = 1 a.e. on [0,1].

Definition 4.8: A function $q \in L^2[0,1]$, is said to be in **standard form** if for measurable subsets A, B of [0,1], with $A \cap B = \emptyset$, $A \cup B = [0,1]$, then

$$q(t) = \begin{cases} 1 & \text{for } t \in A \\ -1 & \text{for } t \in B. \end{cases}$$

Clearly, if q is in standard form, then $||q||_2 = 1$. Let $SF[0,1] = \{q : q \in L^2[0,1], q \text{ in standard form}\}.$

Proposition 4.15 ([10]): Given $q, w \in SF[0, 1]$, if $q \neq w$ in L^2 , i.e., if $m(\{t : t \in [0, 1], q(t) \neq w(t)\}) > 0$, then $w \notin cl([q]_{\Gamma_0})$. Thus $cl([w]_{\Gamma_0}) \cap cl([q]_{\Gamma_0}) = \emptyset$. Proof in [10] using Corollary 3.16 (Change of variable for Lebesgue integral over a measurable set) and Observation 2.25 (Schwarz's inequality over a measurable set).

Corollary 4.9: (Uniqueness of constant-speed parametrization): Given $\tilde{q} \in L^2[0,1]$, $||\tilde{q}||_2 = 1$, if for γ , $\tilde{\gamma} \in \Gamma$, and q, $w \in SF[0,1]$, $\tilde{q} = (q, \gamma)$ and $\tilde{q} = (w, \tilde{\gamma})$, then q = w a.e. on [0, 1].

Proof: By Proposition 4.13, $[q]_{\Gamma} \subseteq cl([q]_{\Gamma_0})$ and $[w]_{\Gamma} \subseteq cl([w]_{\Gamma_0})$. Thus, $\tilde{q} \in cl([q]_{\Gamma_0}) \cap cl([w]_{\Gamma_0})$ so that by Proposition 4.15, q = w a.e. on [0, 1].

Proposition 4.16 ([10]): Given $w \in SF[0,1]$, then $cl([w]_{\Gamma_0}) = [w]_{\Gamma}$.

Proof: From Proposition 4.13, we know $[w]_{\Gamma} \subseteq cl([w]_{\Gamma_0})$. Thus, it suffices

to show $cl([w]_{\Gamma_0}) \subseteq [w]_{\Gamma}$. For this purpose, let \tilde{q} be in $cl([w]_{\Gamma_0})$. Clearly $||\tilde{q}||_2 = 1$, and by Corollary 4.8, for some $q \in SF[0,1]$, and some $\gamma \in \Gamma$, it must be that $\tilde{q} = (q, \gamma)$ a.e. on [0,1]. By Proposition 4.13, $[q]_{\Gamma} \subseteq cl([q]_{\Gamma_0})$. Thus, $\tilde{q} \in cl([q]_{\Gamma_0}) \cap cl([w]_{\Gamma_0})$ so that by Proposition 4.15, q = w a.e. on [0,1], and therefore \tilde{q} is in $[w]_{\Gamma}$. Thus $cl([w]_{\Gamma_0}) \subseteq [w]_{\Gamma}$.

Corollary 4.10 ([10]): Given $q \in L^2[0,1]$, if $q \neq 0$ a.e. on [0,1], then $cl([q]_{\Gamma_0}) = [q]_{\Gamma}$.

Proof: If $||q||_2 = 1$, then by Corollary 4.8, for some $w \in SF[0,1]$, and some $\gamma \in \Gamma$, it must be that $q = (w, \gamma)$ a.e. on [0, 1]. Since $q \neq 0$ a.e on [0,1], then $(w,\gamma)=(w\circ\gamma)\sqrt{\dot{\gamma}}\neq 0$ a.e. on [0,1], and therefore $\dot{\gamma}\neq 0$ a.e. on [0, 1]. Thus, $\gamma \in \Gamma_0$ so that $[q]_{\Gamma_0} = [w]_{\Gamma_0}$ and $(q, \gamma^{-1}) = ((w, \gamma), \gamma^{-1}) = w$ a.e. on [0,1] (Proposition 4.5). Accordingly, $cl([q]_{\Gamma_0}) = cl([w]_{\Gamma_0}) = [w]_{\Gamma} =$ $[(q, \gamma^{-1})]_{\Gamma}$ (Proposition 4.16). Given $\tilde{q} \in [(q, \gamma^{-1})]_{\Gamma}$, then for some $\tilde{\gamma} \in \Gamma$, $\tilde{q} = ((q, \gamma^{-1}), \tilde{\gamma}) = (q, \gamma^{-1} \circ \tilde{\gamma})$ a.e. on [0, 1] (Proposition 4.5), and since $\gamma^{-1} \circ \tilde{\gamma} \in \Gamma$ (Observation 4.4), then $\tilde{q} \in [q]_{\Gamma}$. On the other hand, given $\tilde{q} \in [q]_{\Gamma}$, then for some $\tilde{\gamma} \in \Gamma$, $\tilde{q} = (q, \tilde{\gamma}) = (q, \gamma^{-1} \circ \gamma \circ \tilde{\gamma}) = ((q, \gamma^{-1}), \gamma \circ \tilde{\gamma})$ a.e. on [0,1] (Proposition 4.5), and since $\gamma \circ \tilde{\gamma} \in \Gamma$ (Observation 4.4), then $\tilde{q} \in [(q, \gamma^{-1})]_{\Gamma}$. Thus $[(q, \gamma^{-1})]_{\Gamma} = [q]_{\Gamma}$ and therefore $cl([q]_{\Gamma_0}) = [q]_{\Gamma}$. If $||q||_2 \neq 1$, then clearly $||q||_2 \neq 0$, $||q||_2 \neq 0$ a.e. on [0,1], and as just proved $cl([q/||q||_2]_{\Gamma_0}) = [q/||q||_2]_{\Gamma}$. Given $\tilde{q} \in cl([q]_{\Gamma_0})$, then for a sequence $\{\gamma_n\}\subset \Gamma_0, (q,\gamma_n)\to \tilde{q} \text{ in } L^2$. Thus $(q/||q||_2,\gamma_n)\to \tilde{q}/||q||_2 \text{ in } L^2$ implying $\tilde{q}/||q||_2 = (q/||q||_2, \gamma)$ for some $\gamma \in \Gamma$, and therefore $\tilde{q} = (q, \gamma)$ so that $\tilde{q} \in [q]_{\Gamma}$. On the other hand, given $\tilde{q} \in [q]_{\Gamma}$, then for some $\gamma \in \Gamma$, $\tilde{q}=(q,\gamma)$. Thus $\tilde{q}/||q||_2=(q/||q||_2,\gamma)$ implying for a sequence $\{\gamma_n\}\subset\Gamma_0$, $(q/||q||_2,\gamma_n) \rightarrow \tilde{q}/||q||_2$ in L^2 , and therefore $(q,\gamma_n) \rightarrow \tilde{q}$ in L^2 so that $\tilde{q} \in cl([q]_{\Gamma_0})$. Thus $cl([q]_{\Gamma_0}) = [q]_{\Gamma}$.

Observation 4.17: As noted in [10], given f_1 , $f_2 \in AC[0,1]$, and their SRSF's q_1 , $q_2 \in L^2[0,1]$, respectively, if $\tilde{q}_1 \in cl([q_1]_{\Gamma_0})$, $\tilde{q}_2 \in cl([q_2]_{\Gamma_0})$ exist such that $d(cl([q_1]_{\Gamma_0}), cl([q_2]_{\Gamma_0})) = ||\tilde{q}_1 - \tilde{q}_2||_2$, assuming without any loss of generality that $q_1 \neq 0$ a.e. on [0,1], $q_2 \neq 0$ a.e. on [0,1] (Corollary 4.8), then by Corollary 4.10 above there exist γ_1 , $\gamma_2 \in \Gamma$, such that $\tilde{q}_1 = (q_1, \gamma_1)$ and $\tilde{q}_2 = (q_2, \gamma_2)$. The pair γ_1 , γ_2 is called an **optimal matching** for f_1 , f_2 . In particular, it is proved in [10] that if at least one of $cl([q_1]_{\Gamma_0})$, $cl([q_2]_{\Gamma_0})$ contains the SRSF of a piecewise linear function, then \tilde{q}_1 , \tilde{q}_2 exist as above

and therefore there is an optimal matching for f_1 , f_2 . This is actually proved in [10] for absolutely continuous functions f_1 , f_2 with range \mathbf{R}^n .

Summary

In order to understand the theory of functional data and shape analysis as presented in Srivastava and Klassen's textbook "Functional and Shape Data Analysis" [23], it is important to understand the basics of Lebesgue integration and absolute continuity, and the connections between them. In this paper of the survey type, we have tried to provide a way to do exactly that. We have reviewed fundamental concepts and results about Lebesgue integration and absolute continuity, some results connecting the two notions, most of the material borrowed from Royden's "Real Analysis" [16] and Rudin's "Principles of Mathematical Analysis" [18]. Additional important material was obtained from Saks' [20], and Serrin and Varberg's [22] seminal papers. In addition, we have presented fundamental concepts and results about functional data and shape analysis in 1-dimensional space, in the process shedding light on its dependence on Lebesgue integration and absolute continuity, and the connections between them, most of the material borrowed from Srivastava and Klassen's aforementioned textbook. Additional material presented at the end of the paper was obtained from Lahiri, Robinson and Klassen's outstanding manuscript [10].

Acknowledgements

I am most grateful to Professor James F. Lawrence of George Mason University and the National Institute of Standards and Technology for the many insightful conversations on the subjects of Lebesgue integration and absolute continuity, and to Professor Eric Klassen of Florida State University for his generosity in always providing answers to my questions about his remarkable work on shape analysis.

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Index of Terms

Each entry crossreferenced to one of the following: Dx.y (Definition x.y), Px.y (Proposition x.y), Cx.y (Corollary x.y), Ox.y (Observation x.y). Given x.y, y is then the number of the Definition, Proposition, Corollary or Observation in Section x in which the entry can be found. For example, the entry "Borel" is associated in the index with D2.3 which means it can be

found in Definition 3 of Section 2.

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