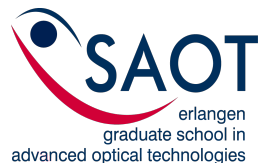


Automatic No-Reference Quality Assessment for Retinal Fundus Images Using Vessel Segmentation

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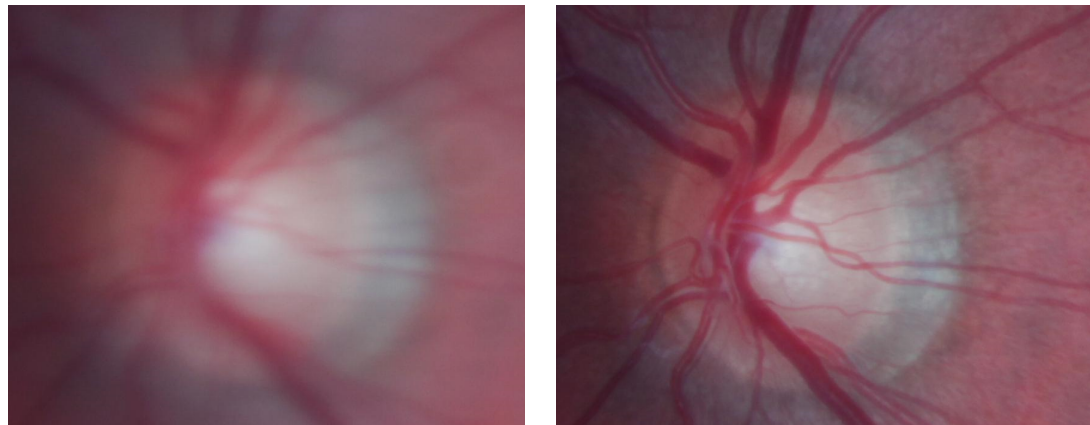
TECHNISCHE FAKULTÄT

Introduction



Motivation

- Image quality assessment is essential for retinal image analysis
- **Example:** Analysis of anatomical structures for manual, computer aided or fully automatic diagnoses



e. g. segmentation/analysis of optic disk (cup-to-disk ratio) for glaucoma diagnosis: sharp image structures required

- **Goal: objective and automatic quality assessment**

How to assess image quality?

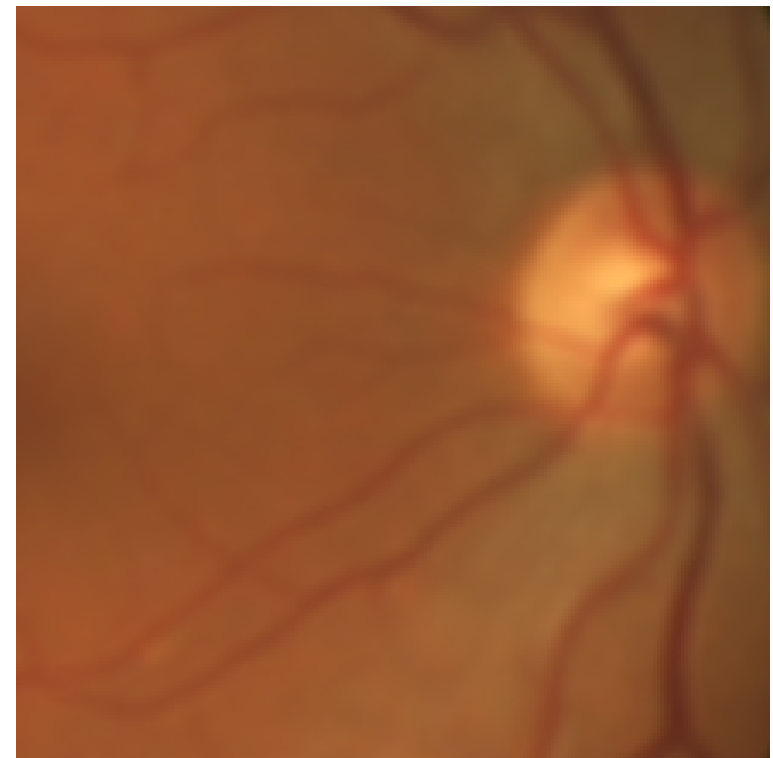
- Qualitative assessment: Ask an expert
⇒ Subjective, inter- and intra-observer variance
- Quantitative assessment:
 - Ground truth: peak-signal-to-noise ratio (PSNR), structural similarity (SSIM)
⇒ Not available in practice
 - In the absence of a ground truth: no-reference quality assessment
⇒ Objective and reproducible
- No-reference quality assessment
 - Classification-based approaches (supervised)
Niemeijer et al., Med. Image Anal., 2006
Paulus et al., Int. J. of Computer Assisted Radiology & Surgery, 2010
 - **No-reference quality metrics (unsupervised)**

Objective Image Quality Features

Features for quality assessment:

- **Blur/sharpness**

Goal in this work: quantitative assessment of image noise and blur

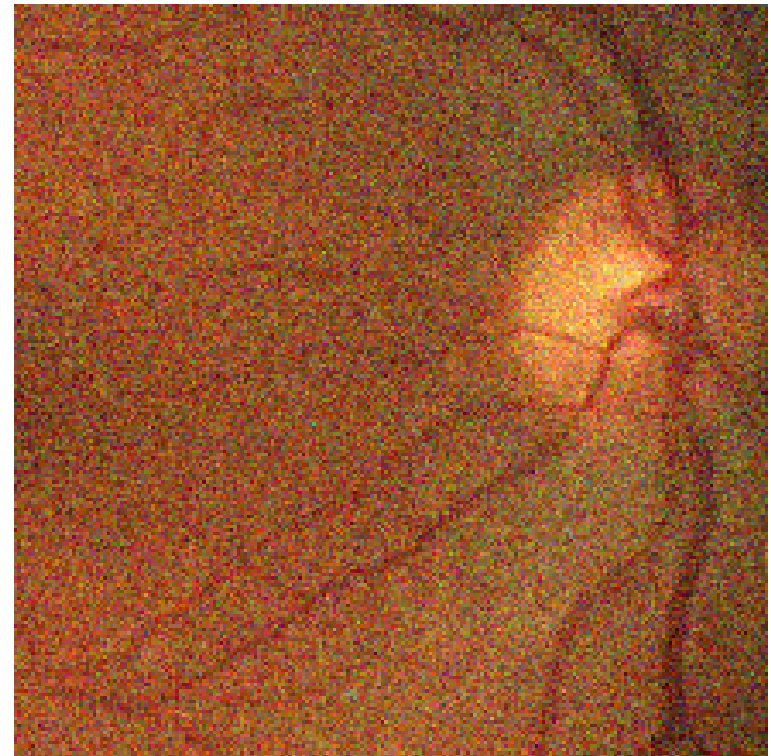


Objective Image Quality Features

Features for quality assessment:

- **Blur/sharpness**
- **Noise**

Goal in this work: quantitative assessment of image noise and blur



Objective Image Quality Features

Features for quality assessment:

- **Blur/sharpness**
- **Noise**
- Illumination/contrast
- High-level medical features:
visibility of blood vessels ...
- ...

Goal in this work: quantitative assessment of image noise and blur



No-Reference Quality Metric for Noise and Blur



No-Reference Quality Metric for Noise and Blur¹

- Decompose image I of size $M \times N$ in distinct patches P of size $n \times n$ (typical parameter: $n = 8$).
- Important quantities:
 - Local gradient matrix

$$\mathbf{G} = \begin{pmatrix} P_x(1, 1) & P_y(1, 1) \\ \vdots & \vdots \\ P_x(n, n) & P_y(n, n) \end{pmatrix} \quad (1)$$

- Singular value decomposition (SVD) of \mathbf{G} :

$$\mathbf{G} = \mathbf{U}\mathbf{S}\mathbf{V}^\top = \mathbf{U} \begin{pmatrix} s_1 & 0 \\ 0 & s_2 \end{pmatrix} \mathbf{V}^\top \quad (2)$$

¹X. Zhu and P. Milanfar, Automatic Parameter Selection for Denoising Algorithms Using a No-Reference Measure of Image Content, IEEE Transactions on Image Processing, 2010.

Automatic Quality Assessment – Algorithm

1. Calculate **coherence** for each patch:

$$R = \frac{S_1 - S_2}{S_1 + S_2}$$

(3)



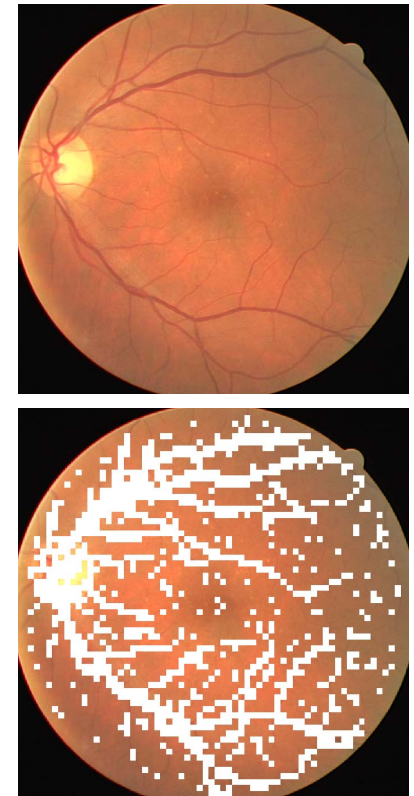
Automatic Quality Assessment – Algorithm

1. Calculate **coherence** for each patch:

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(3)

2. Detect **anisotropic patches** (thresholding: $R > \tau$)



Automatic Quality Assessment – Algorithm

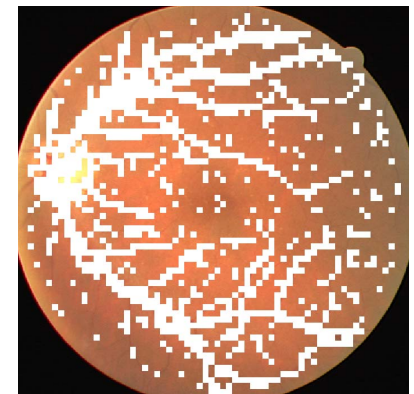
1. Calculate **coherence** for each patch:

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3. For each anisotropic patch: Calculate **local** score

$$q(\mathbf{P}) = s_1 \cdot R \quad (4)$$



Automatic Quality Assessment – Algorithm

1. Calculate **coherence** for each patch:

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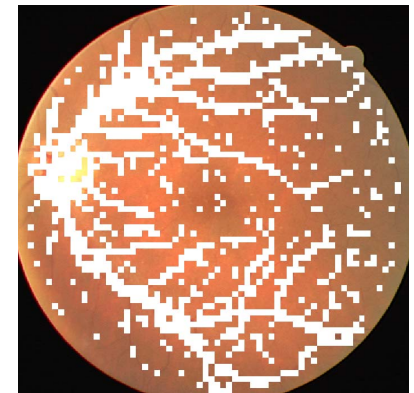
3. For each anisotropic patch: Calculate **local** score

$$q(\mathbf{P}) = s_1 \cdot R \quad (4)$$

4. Calculate **global** score for noise and blur:

$$Q = \frac{1}{MN} \sum_{i,j:\mathcal{P}(i,j)=1} q(\mathbf{P}_{ij}) \quad (5)$$

High $Q \Rightarrow$ better quality (in terms of blur and noise)

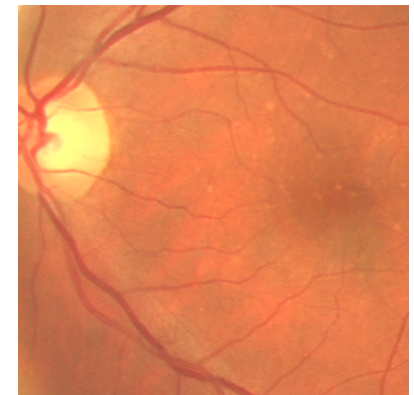


Quality Assessment Using Vessel Segmentation



Vessel Segmentation Guidance

- Limitation of metric Q : **false-positive** and **false-negative** patch detections



Vessel Segmentation Guidance

- Limitation of metric Q : **false-positive** and **false-negative** patch detections
- **Appropriate guidance**: vessel tree visible in fundus images

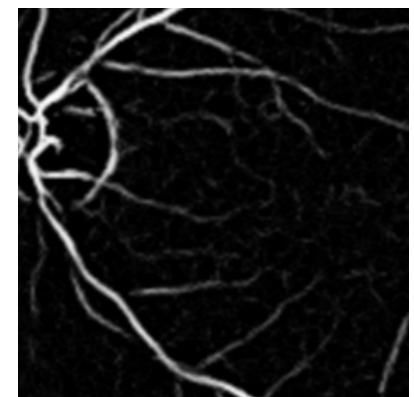
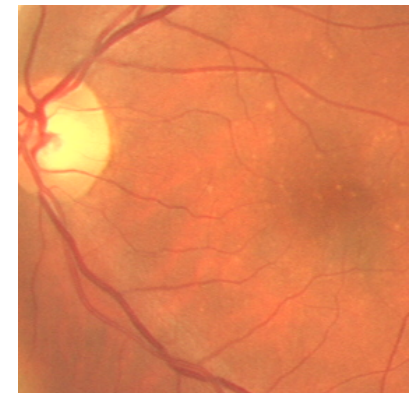
Vessel tree is detected by **vesselness** measure

(Frangi et al., Multiscale vessel enhancement filtering, MICCAI 1998)

$$V = \exp\left(-\frac{\lambda_1^2}{\lambda_2^2}\right) \left(1 - \exp\left(-(\lambda_1^2 + \lambda_2^2)\right)\right) \quad (6)$$

λ_1, λ_2 : Eigenvalues of pixel-wise **Hessian matrix**

$$\mathbf{H} = \begin{pmatrix} \frac{\partial^2 I}{\partial x^2} & \frac{\partial^2 I}{\partial x \partial y} \\ \frac{\partial^2 I}{\partial x \partial y} & \frac{\partial^2 I}{\partial y^2} \end{pmatrix} \quad (7)$$



Weighted Quality Score

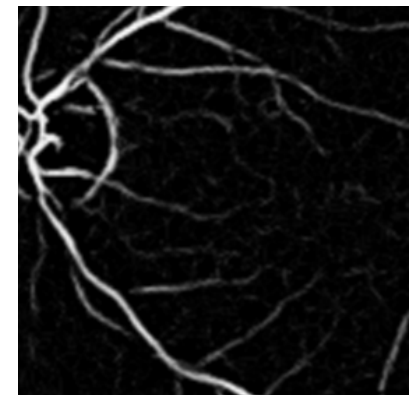
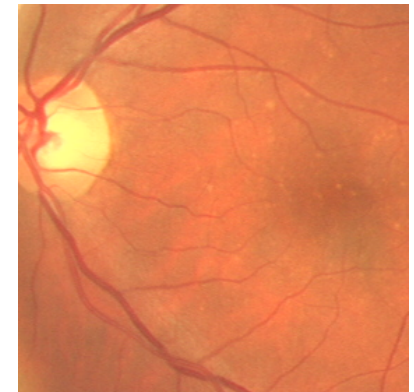
- **Basic idea:** Detected patch on a blood vessel (boundary) is more reliable
- **Weighted quality score** according to vesselness

$$Q_v = \sum_{i,j:\mathcal{P}(i,j)=1} \tilde{\Sigma}_{ij} \cdot q(\mathbf{P}_{ij}) \quad (8)$$

- Weighting factor $\tilde{\Sigma}_{ij}$: **local variance of vesselness** in patch \mathbf{P}_{ij}

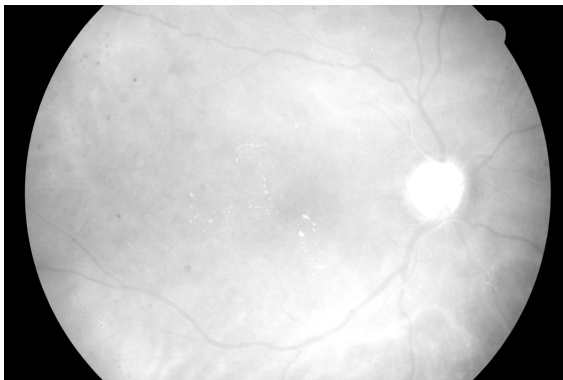
Blood vessel boundary

\Rightarrow high $\tilde{\Sigma}_{ij} \Rightarrow$ high reliability of $q(\mathbf{P}_{ij})$

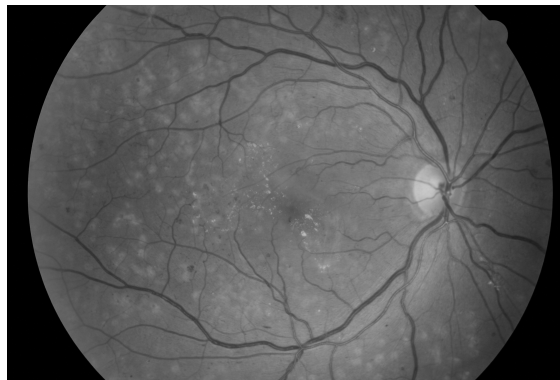


Application to Color Fundus Images

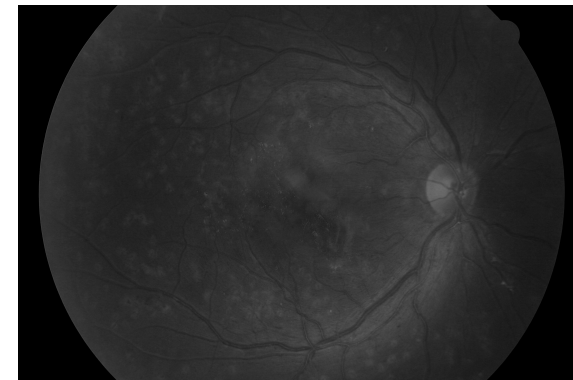
- Quality metric defined for single-channel images
- **Color fundus images:** extraction of green channel for quality assessment
⇒ good contrast/illumination compared to red and blue channel



Red
(Oversaturated)



Green



Blue
(Underexposed)

Experimental Evaluation

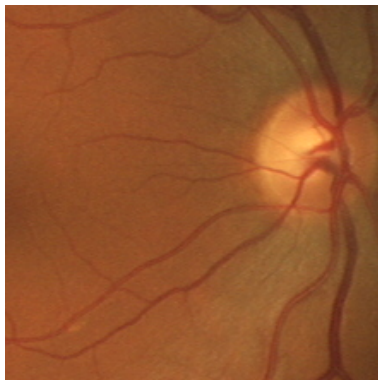


Experimental Evaluation

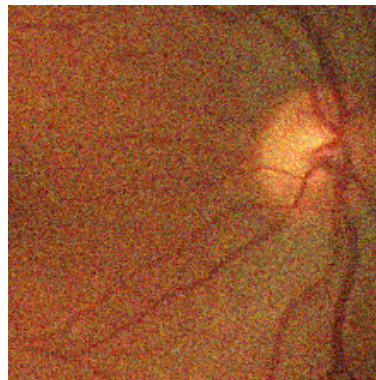
- **Synthetic images:** correlation analysis
 - Ground truth data available
 - How good agrees no-reference quality assessment to established full-reference quality metrics?
- **Real fundus images:**
 - Quality classification
 - Agreement to human camera operator

Synthetic Images – Correlation Analysis

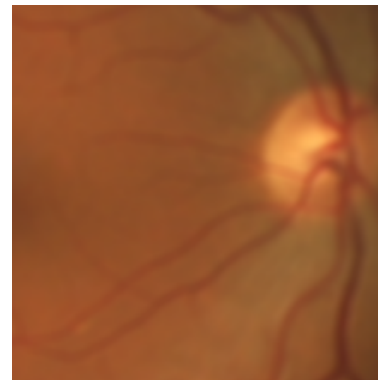
- 40 images out of the DRIVE database: simulation of artificial Gaussian noise and Gaussian blur
 - Agreement (correlation) between no-reference and full-reference metrics:
 - Full-ref. metrics: peak-signal-to-noise ratio (PSNR), structural similarity (SSIM)
 - Spearman's rank correlation (Spearman's ρ) to assess agreement
- ⇒ High correlation ⇒ good agreement to full-reference assessment



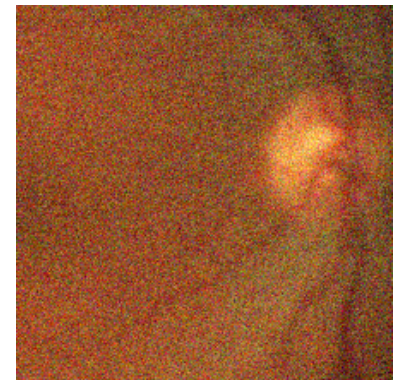
Ground truth



Noisy image



Blurred image

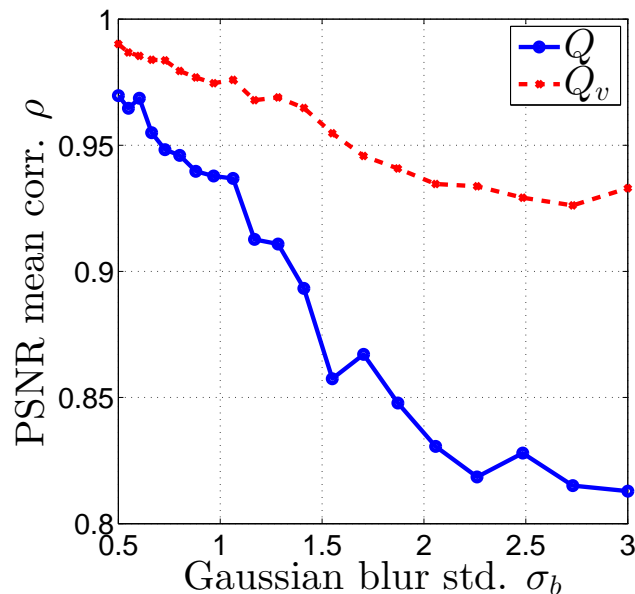


Noise and blur

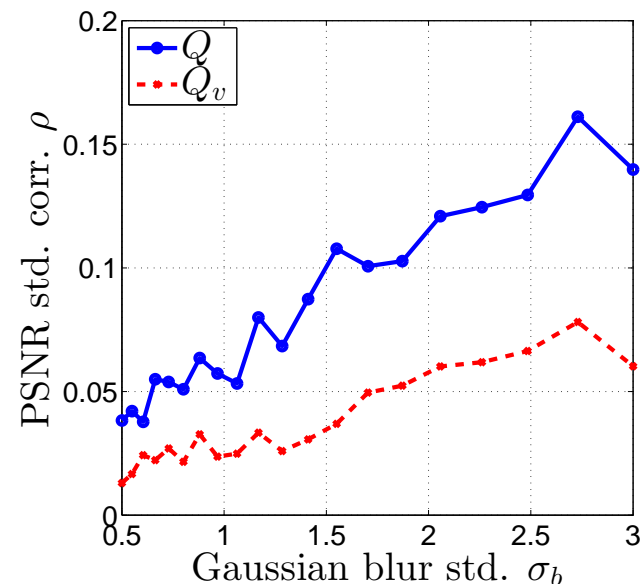
Synthetic Images – Correlation Analysis (cont.)

Spearman's ρ versus amount of **Gaussian blur**:

- Gaussian blur: 7×7 kernel (fixed), $\sigma_b = 0 \dots 3.0$
- Agreement $Q, Q_v \leftrightarrow$ **PSNR** (averaged over 40 images)



Mean ρ

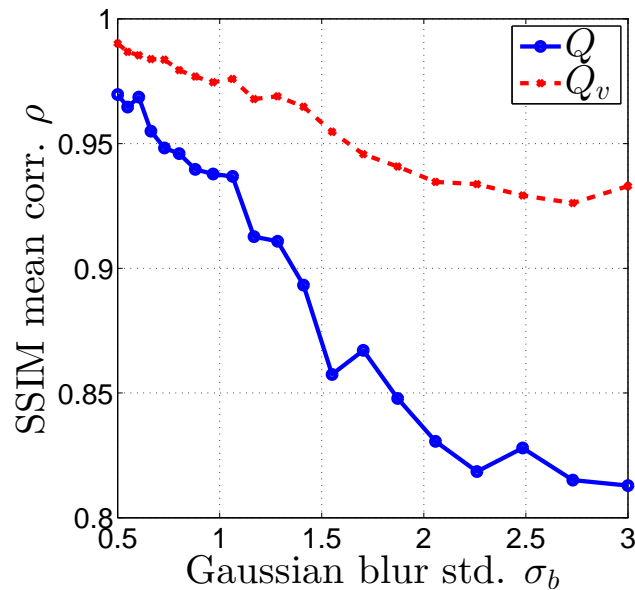


Standard deviation ρ

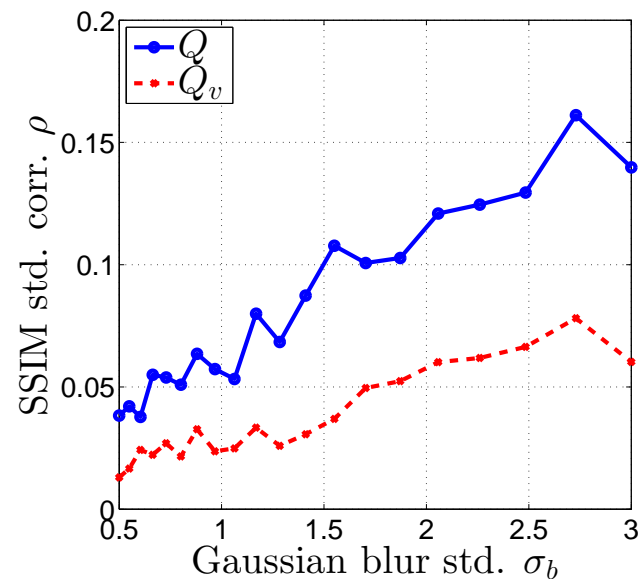
Synthetic Images – Correlation Analysis (cont.)

Spearman's ρ versus amount of **Gaussian blur**:

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Mean ρ

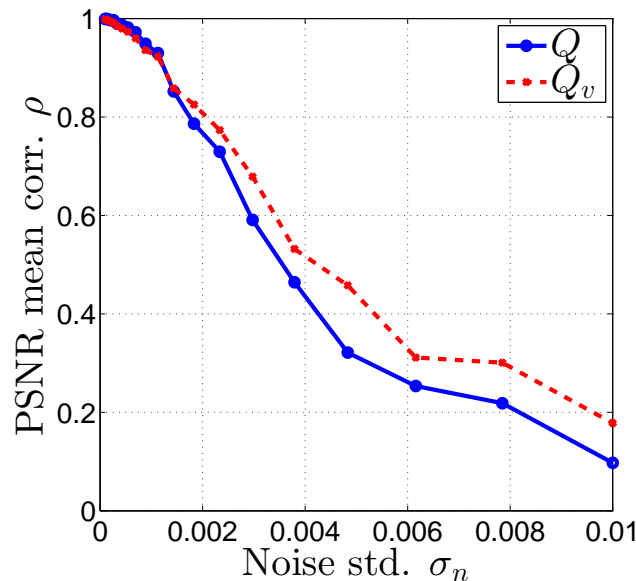


Standard deviation ρ

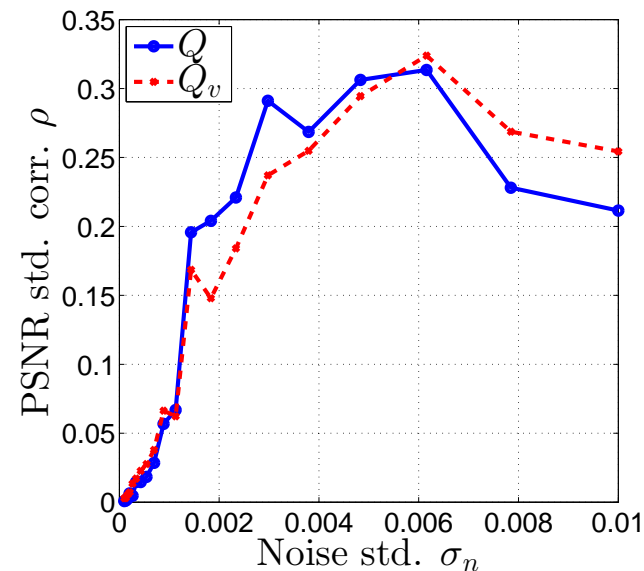
Synthetic Images – Correlation Analysis (cont.)

Spearman's ρ versus amount of **Gaussian noise**:

- Gaussian noise: $\sigma_n = 0 \dots 0.01$ (normalized intensities: $[0, 1]$)
- Agreement Q , $Q_v \leftrightarrow$ **PSNR** (averaged over 40 images)



Mean ρ

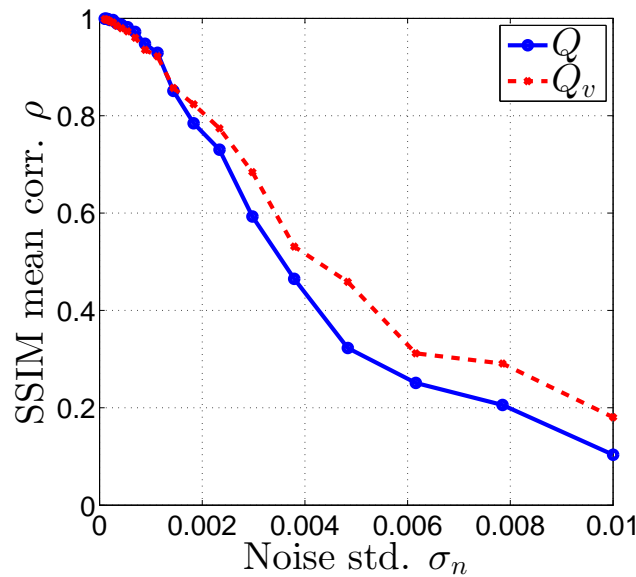


Standard deviation ρ

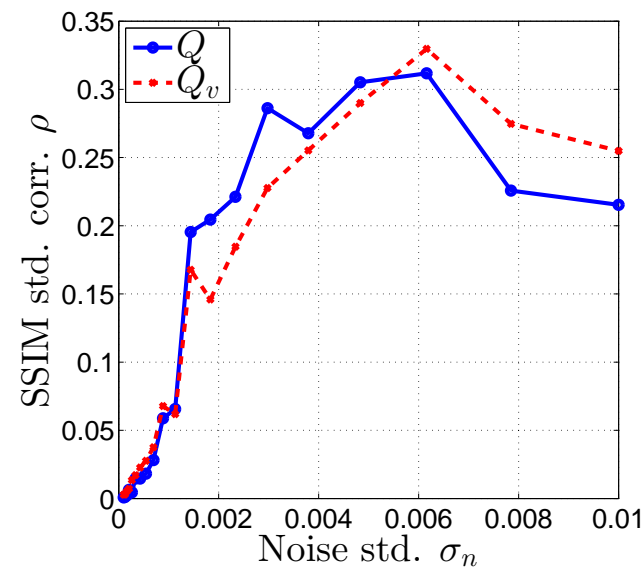
Synthetic Images – Correlation Analysis (cont.)

Spearman's ρ versus amount of **Gaussian noise**:

- Gaussian noise: $\sigma_n = 0 \dots 0.01$ (normalized intensities: $[0, 1]$)
- Agreement $Q, Q_v \leftrightarrow$ **SSIM** (averaged over 40 images)



Mean ρ



Standard deviation ρ

Synthetic Images – Correlation Analysis (cont.)

Overall correlation: simultaneously varying blur and noise

- 40 ground truth images (DRIVE database)
- 20 levels of Gaussian blur: $\sigma_b = 0 \dots 3.0$
- 20 levels of Gaussian noise: $\sigma_n = 0 \dots 0.01$

Spearman's ρ over the whole experiment:

Full-ref. metric	$\rho(Q)$	$\rho(Q_v)$
PSNR	0.8227	0.8920
SSIM	0.8412	0.9076

⇒ Higher correlation for proposed Q_v metric

Real Images

High-resolution fundus (HRF) image database

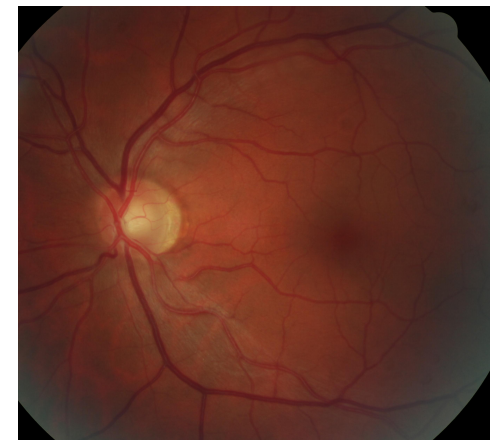
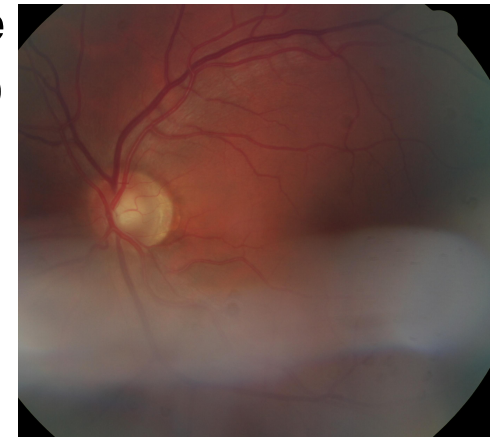
(<http://www5.cs.fau.de/research/data/fundus-images/>)

Canon CR-1 fundus camera, 45 degree field of view

- 18 pairs of fundus images: good/bad image per pair (36 images)
- Poor quality due to de-focused camera
- In case of poor quality: acquisition was repeated

Experimental evaluation:

- Quality classification
- Agreement to camera operator



Real Images – Quality Classification

Quality classification implemented as thresholding:

- 2-class problem (class label: y):
 $y = 1$ (good quality) and $y = -1$ (poor quality)
- Decision rule for quality metric x and threshold τ_0 :

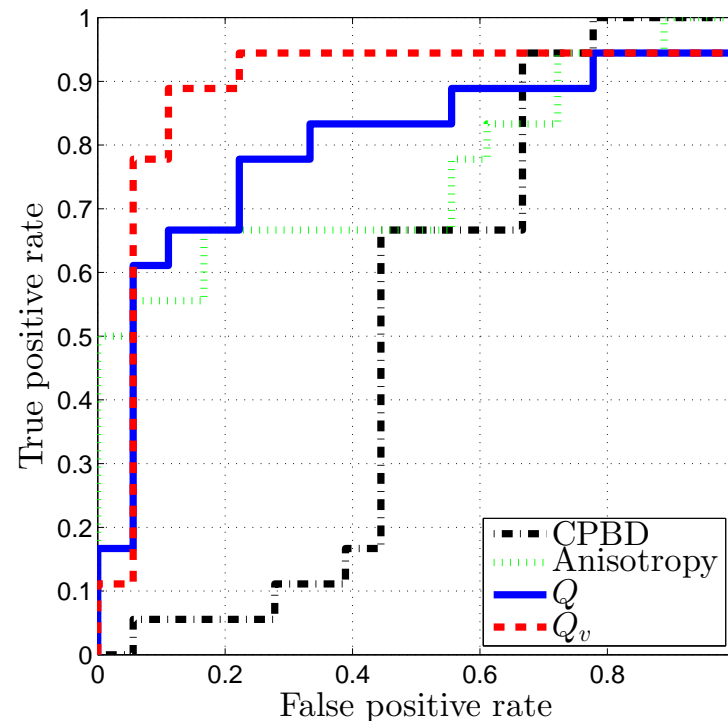
$$y = \begin{cases} -1 & x < \tau_0 & \text{(poor quality)} \\ +1 & x \geq \tau_0 & \text{(good quality)} \end{cases} \quad (9)$$

- **Comparison:**

- Proposed Q_v metric
- Standard Q metric Zhu and Milanfar, 2010
- Anisotropy blind quality metric Gabarda and Cristóbal, 2007
- Cumulative probability of blur detection (CPBD) Narvekar and Karam, 2011

Real Images – Quality Classification (cont.)

- ROC analysis for different classification approaches:



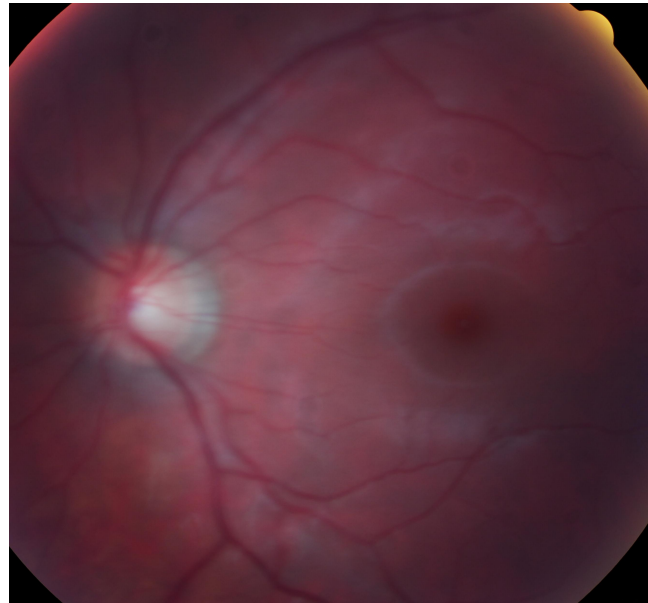
⇒ Good performance of Q_v in terms of **area under ROC curve: 88.3 %**

Agreement with Human Observer

- **Pair-wise agreement** with human observer (good vs. bad image):
16 of 18 pairs (**88.9 %**)



sharp: $Q_v = 0.0240$



defocused: $Q_v = 0.0017$

Agreement with Human Observer (cont.)

- Comparison of pair-wise agreement for different metrics (based on 18 image pairs):

No-ref. Metric	Agreement [%]
CPBD	55.6
Anisotropy	94.4
Q	83.3
Q_V	88.9

⇒ Competitive performance of proposed Q_V metric

Summary and Conclusion

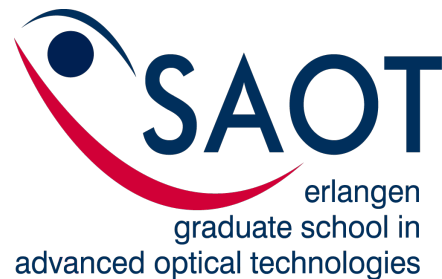


Summary and Conclusion

- No-reference image quality metric to quantify noise and sharpness
⇒ Unsupervised approach (opposed to classification-based approaches)
- Quality assessment guided by the blood vessel tree
⇒ Reliable quality score for fundus images
 - High correlation to full-reference quality metrics
 - Quality classification: 88.3% area under ROC curve
 - Agreement to human camera operator: 88.9%
- Applications:
 - Numerical score for image noise/sharpness (e. g. auto-focusing)
 - Feature for quality classification

Acknowledgments

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Thank you for your attention!